

HTU418B

STANDARD ultrasonic sensors with 2 switching outputs

en 05-2017/02 50124995

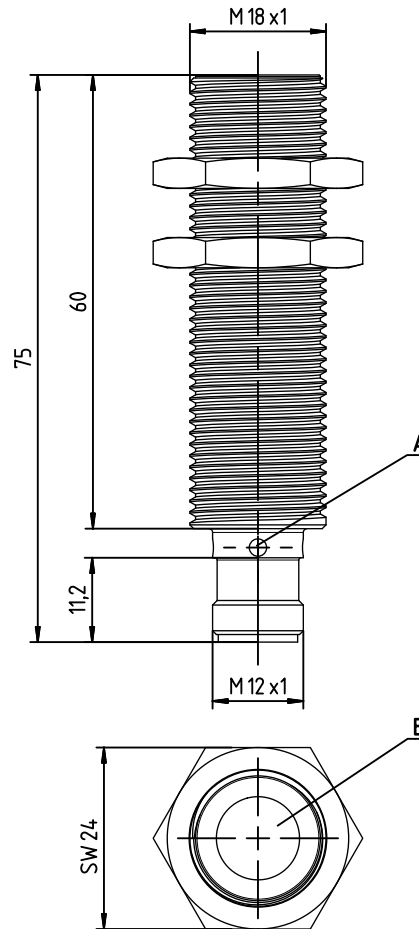


25 ... 400mm
150 ... 1300mm



- Largely surface-independent function, ideal for the detection of liquids, bulk materials, transparent media, ...
- Small dead zone at long range
- Adjustment of the switching point can be taught for each switching output
- NO/NC function reversible
- 2 switching outputs (PNP)
- **NEW** – Stable all-metal design

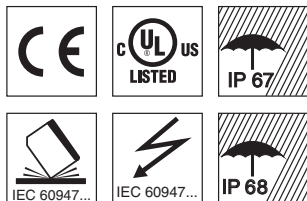
Dimensioned drawing



- A Indicator diodes
B Active sensor surface

Electrical connection

15-30V DC+	1	br/BN
Teach-IN	2	ws/WH
GND	3	bl/BU
OUT 1	4	sw/BK
OUT 2	5	gr/GY



Accessories:

(available separately)

- Mounting systems
- Mounting adapter M18-M30: BTX-D18M-D30 (Part no. 50125860)
- Cables with M12 connector (K-D ...)
- Teach adapter PA1/XTSX-M12 (Part no. 50124709)

We reserve the right to make changes • PAL_HTU418B4T4_en_50124995.fm

Specifications

Ultrasonic specifications

Scanning range ¹⁾
Adjustment range
Ultrasonic frequency
Typ. opening angle
Resolution switching output
Direction of beam
Reproducibility
Switching hysteresis
Temperature drift

Timing

Switching frequency
Response time
Delay before start-up

Electrical data

Operating voltage U_B ⁴⁾
Residual ripple
Open-circuit current
Switching output
Function
Output current
Switching range adjustment

Changeover NO/NC

Indicators

Yellow LED
Yellow LED, flashing
Green LED

Mechanical data

Housing
Weight
Ultrasonic transducer
Connection type
Fitting position

Environmental data

Ambient temp. (operation/storage)
Protective circuit ⁶⁾
VDE safety class
Degree of protection
Standards applied
Certifications

- 1) at 20°C
- 2) Target: plate 20mm x 20mm
- 3) Target: plate 100mm x 100mm
- 4) For UL applications: for use in class 2 circuits according to NEC only
- 5) The ceramic material of the ultrasonic transducer contains lead zirconium titanate (PZT)
- 6) 1=short-circuit and overload protection, 2=polarity reversal protection, 3=wire break and inductive protection
- 7) These proximity switches shall be used with UL Listed Cable assemblies rated 30V, 0.5A min, in the field installation, or equivalent (categories: CYJV/CYJV7 or PVVA/PVVA7)
- 8) Ambient temperature 85°C. Use same supply source for all circuits.

HTU418B-400/4T4...

25 ... 400mm ²⁾
25 ... 400mm
310kHz
9°
0.5mm
axial
 $\pm 0.15\%$ of full scale value ¹⁾
5mm ¹⁾
0.17%/K

7Hz
71ms
< 300ms

15 ... 30V DC (incl. $\pm 10\%$ residual ripple)
 $\pm 10\%$ of U_B
 ≤ 50 mA
2x PNP transistor
2 x NO contact, reversible
max. 150mA
teach-in (pin 2):
for OUT1: connect to GND for 2 ... 7s
for OUT2: connect to GND for 7 ... 12s
teach-in (pin 2):
for OUT1: connect to U_B for 2 ... 7s
for OUT2: connect to U_B for 7 ... 12s

OUT1: object detected
teach-in / teaching error
object within scanning range

all-metal brass, nickel-plated
50g
piezoceramic ⁵⁾
M12 connector, 5-pin
any

-25°C ... +70°C/-30°C ... +85°C
1, 2, 3
III
IP 67 and IP 68
EN 60947-5-2
UL 508, C22.2 No.14-13 ⁴⁾ ⁷⁾ ⁸⁾

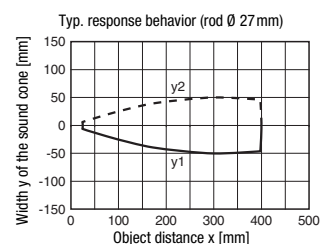
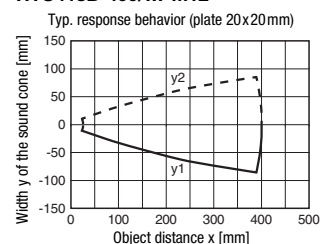
HTU418B-1300/4T4...

150 ... 1300mm ³⁾
150 ... 1300mm
200kHz
16°
1mm
axial
 $\pm 0.15\%$ of full scale value ¹⁾
10mm ¹⁾
0.17%/K

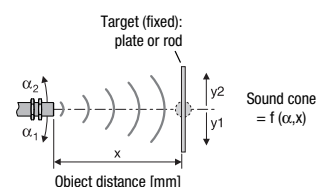
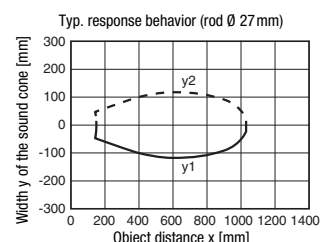
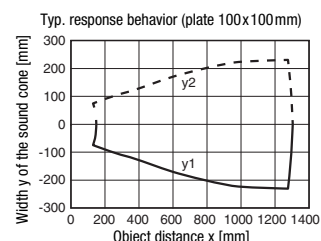
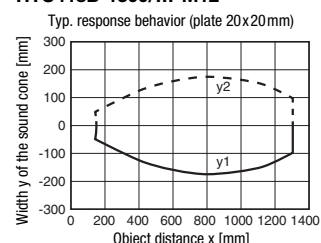
8Hz
62ms
< 300ms

Diagrams

HTU418B-400/...-M12



HTU418B-1300/...-M12



Remarks

Operate in accordance with intended use!

- ⚠ This product is not a safety sensor and is not intended as personnel protection.
- ⚠ The product may only be put into operation by competent persons.
- ⚠ Only use the product in accordance with the intended use.

HTU418B

STANDARD ultrasonic sensors with 2 switching outputs

Part number code

H	T	U	4	1	8	B	-	1	3	0	0	.	X	3	/	4	T	4	-	M	1	2
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Operating principle

HTU Ultrasonic sensor, scanning principle, with background suppression

DMU Ultrasonic sensor, distance measurement

Series

418B 418B Series, cylindrical M18 construction

Scanning range in mm

400 25 ... 400

1300 150 ... 1300

Equipment (optional)

X "Advanced" design

3 Teach button on the sensor

Pin assignment of connector pin 4 / black cable wire (OUT1)

4 PNP output, NO contact preset

P PNP output, NC contact preset

L IO-Link communication or push-pull (SIO)

Pin assignment of connector pin 2 / white cable wire (Teach-IN)

T Teach input

Pin assignment of connector pin 5 / gray cable wire (OUT2)

4 PNP output, NO contact preset

P PNP output, NC contact preset

V Analog voltage output 1 ... 10V

C Analog current output 4 ... 20mA

X Connection not assigned (n. c. - not connected)

Connection technology

M12 M12 connector, 5-pin

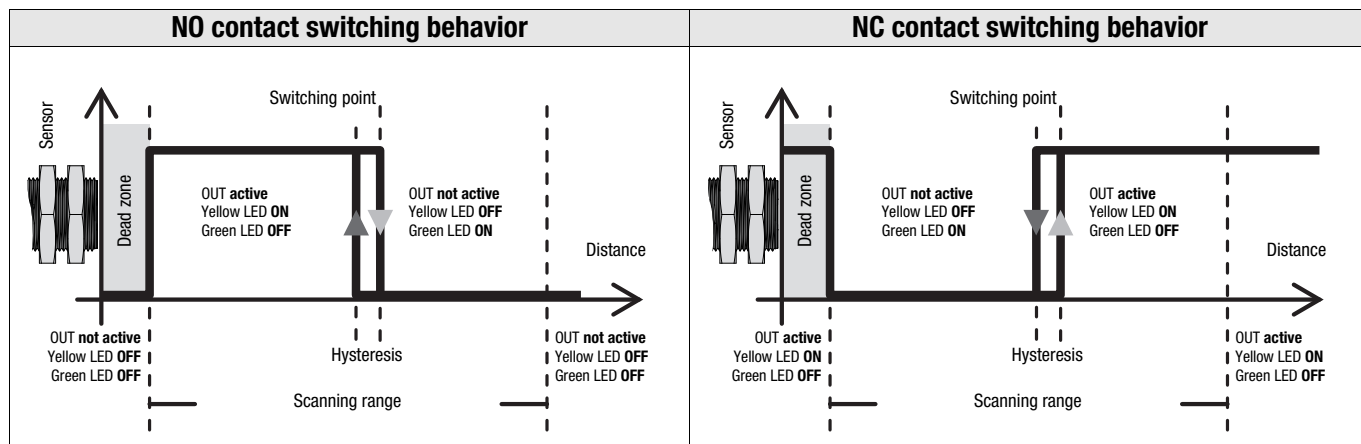
Order guide

The sensors listed here are preferred types; current information at www.leuze.com.

	Designation	Part no.
Scanning range		
25 ... 400mm	HTU418B-400/4T4-M12	50124268
150 ... 1300mm	HTU418B-1300/4T4-M12	50124272

Device functions and indicators

All sensor settings are taught via the **Teach-IN** input. Device status and switching states are indicated by a green and a yellow LED as follows:



Notice!

In measurement operation, the yellow and green LED only indicate the behavior of output **OUT1**. The behavior of output **OUT2** is not indicated.

Adjusting the switching points via the teach input

The switching points of the sensor outputs **OUT1/OUT2** are set to 400mm or 1000mm on delivery.

By means of a simple teach event, the two switching points can be individually taught to an arbitrary distance within the scanning range. The Leuze **PA1/XTSX-M12** teach adapter can be used for this purpose. The adapter can also be used to easily switch the output function from NO contact to NC contact.

1-point teach of output OUT1	1-point teach of output OUT2
1. Place object at desired switching distance.	1. Place object at desired switching distance.
2. For the adjustment of output OUT1 , connect input Teach-IN to GND for 2 ... 7s (Leuze teach adapter: position "Teach-GND"). The current state of output OUT1 is frozen during the teach event.	2. For the adjustment of output OUT2 , connect input Teach-IN to GND for 7 ... 12s (Leuze teach adapter: position "Teach-GND"). The current state of output OUT2 is frozen during the teach event.
3. The yellow LED flashes at 3Hz and then remains on . The current object distance has been taught as the new switching point.	3. The yellow LED flashes at 3Hz . The current object distance has been taught as the new switching point.
4. Error-free teach: switching behavior according to the diagram shown above. Faulty teach (object may be too close or too far away – please note scanning range): yellow LED flashes at 5Hz until an error-free teach event is performed. The output OUT1 is inactive as long as there is a teach error.	4. Error-free teach: switching behavior according to the diagram shown above. Faulty teach (object may be too close or too far away – please note scanning range): yellow LED flashes at 5Hz until an error-free teach event is performed. The output OUT2 is inactive as long as there is a teach error.

Adjusting the switching function (NC/NO) via the teach input

The switching function of both sensor outputs is set to normally open (NO) on delivery.

If the switching function is changed, the switching output is changed to the opposite state (toggled).

Changeover of the switching function of output OUT1	Changeover of the switching function of output OUT2
1. To change the switching function, connect input Teach-IN to U_B for 2 ... 7s (Leuze teach adapter: position "Teach-U _B "). The current state of output OUT1 remains frozen while the adjustment is performed.	1. To change the switching function, connect input Teach-IN to U_B for 7 ... 12s (Leuze teach adapter: position "Teach-U _B "). The current state of output OUT2 remains frozen while the adjustment is performed.
2. The green and yellow LED flash alternately at 2Hz . The switching function has been reversed. The switching behavior corresponds to the diagram shown above.	2. The green and yellow LED flash alternately at 5Hz . The switching function has been reversed. The switching behavior corresponds to the diagram shown above.



Notice!

Please note that the **switching point** is taught when **GND** is connected and the **output function** is reversed when **U_B** is connected. If no sensor action is desired, pin 2 must remain unconnected!