



Operating Manual
mic+ Ultrasonic Sensors
with one switching output
and one analogue output

mic+25/DIU/TC
mic+35/DIU/TC
mic+130/DIU/TC
mic+340/DIU/TC
mic+600/DIU/TC

Product description

- The mic+ Sensor with one analogue output and one switching output measures the distance to an object within the detection zone contactless. A signal proportional to distance is created and the switching output is set according to the adjusted detect distance.
- The sensor automatically detects the load put to the analogue output and switches to current output or voltage output respectively.
- All settings are done with two push-buttons and a three-digit LED-display (TouchControl).
- Three-colour LEDs indicate all operation conditions.
- Choosing between rising and falling output characteristic as well as output function NOC and NCC is possible.
- The sensors are adjustable manually

- via TouchControl or via Teach-in procedure.
- Useful additional functions are set in the Add-on-menu.
- Using the LinkControl adapter (optional accessory) all TouchControl and additional sensor parameter settings can be adjusted by a Windows® Software.

The mic+ Sensors have a blind zone in which distance measurement is not possible. The operating range indicates the distance of the sensor that can be applied with normal reflectors with sufficient function reserve. When using good reflectors, such as a calm water surface, the sensor can also be used up to its maximum range. Objects that strongly absorb (e.g. plastic foam) or diffusely reflect sound (e.g. pebble stones) can also reduce the defined operating range.

Safety Notes

- Read the operating instructions prior to start-up.
- Connection, installation and adjustment works may only be carried out by expert personnel.
- No safety component in accordance with the EU Machine Directive

Proper Use

mic+ ultrasonic sensors are used for non-contact detection of objects.

Synchronisation

If the assembly distances shown in Fig. 1 for two or more sensors are exceeded the integrated synchronisation should be used. Connect Sync/Com-channels (pin 5 at the units receptacle) of all sensors (10 maximum).

| mic+25... | ≥0.35 m | ≥2.50 m |
|------------|---------|----------|
| mic+35... | ≥0.40 m | ≥2.50 m |
| mic+130... | ≥1.10 m | ≥8.00 m |
| mic+340... | ≥2.00 m | ≥18.00 m |
| mic+600... | ≥4.00 m | ≥30.00 m |

Fig. 1: Assembly distances, indicating synchronisation/multiplex

Multiplex mode

The Add-on-menu allows to assign an individual address »01« to »10« to each sensor connected via the Sync/Com-channel (Pin5). The sensors perform the ultrasonic measurement sequentially from low to high address. Therefore any influence between the sensors is rejected. The address »00« is reserved to synchronisation mode and deactivates the multiplex mode. To use synchronised mode all sensors must be set to address »00«.

Installation

- ➔ Assemble the sensor at the installation location.
- ➔ Plug in the connector cable to the M12 connector, see Fig. 2.

| | | | colour |
|---|----------|----------|--------|
| 1 | + | + | brown |
| 3 | - | - | blue |
| 4 | D | D | black |
| 2 | I/U | I/U | white |
| 5 | Sync/Com | Sync/Com | grey |

Fig. 2: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cable

Start-up

- ➔ Connect the power supply.
- ➔ Set the parameters of the sensor manually via TouchControl (see Fig. 3 and Diagram 1)
- ➔ or use the Teach-in procedure to adjust the detect points (see Diagram 2).

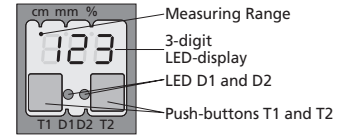


Fig. 3: TouchControl/LED display

Factory setting

- Rising analogue characteristic
- Window limits for the analogue output set to blind zone and operating range
- Switching output on NOC

- Detecting distance at operating range
- Measurement range set to maximum range

Maintenance

mic+ Sensors work maintenance free. Small amounts of dirt on the surface do not influence function. Thick layers of dirt and caked-on dirt affect sensor function and therefore must be removed.

Notes

- mic+ Sensors have internal temperature compensation. Because the sensors heat up on their own, the temperature compensation reaches its optimum working point after approx. 30 minutes of operation.
- If an object is within the set window limits of the analogue output, then LED D1 lights up green, if the object is outside the window limits, then LED D1 lights up red.
- The load put to the analogue output is detected automatically when turning supply voltage on.
- During normal operating mode, a yellow LED D2 signals that the switching output has connected.
- During normal operating mode, the measured distance value is displayed on the LED-indicator in mm (up to 999 mm) or cm (from 100 cm). Scale switches automatically and is indicated by a point on top of the digits. Alternatively a percentage scale may be set in the add-on menu. In this connection 0% and 100% correspond to the set window limits of the analogue output.
- During Teach-in mode, the hysteresis loops are set back to factory settings.
- If no push-buttons are pressed for 20 seconds during parameter setting mode the made changes are stored and the sensor returns to normal operating mode.

Show parameters

- ➔ In normal operating mode shortly push T1. The LED display shows »PAR.«

Each time you tap push-button T1 the actual settings of the analogue output are shown.

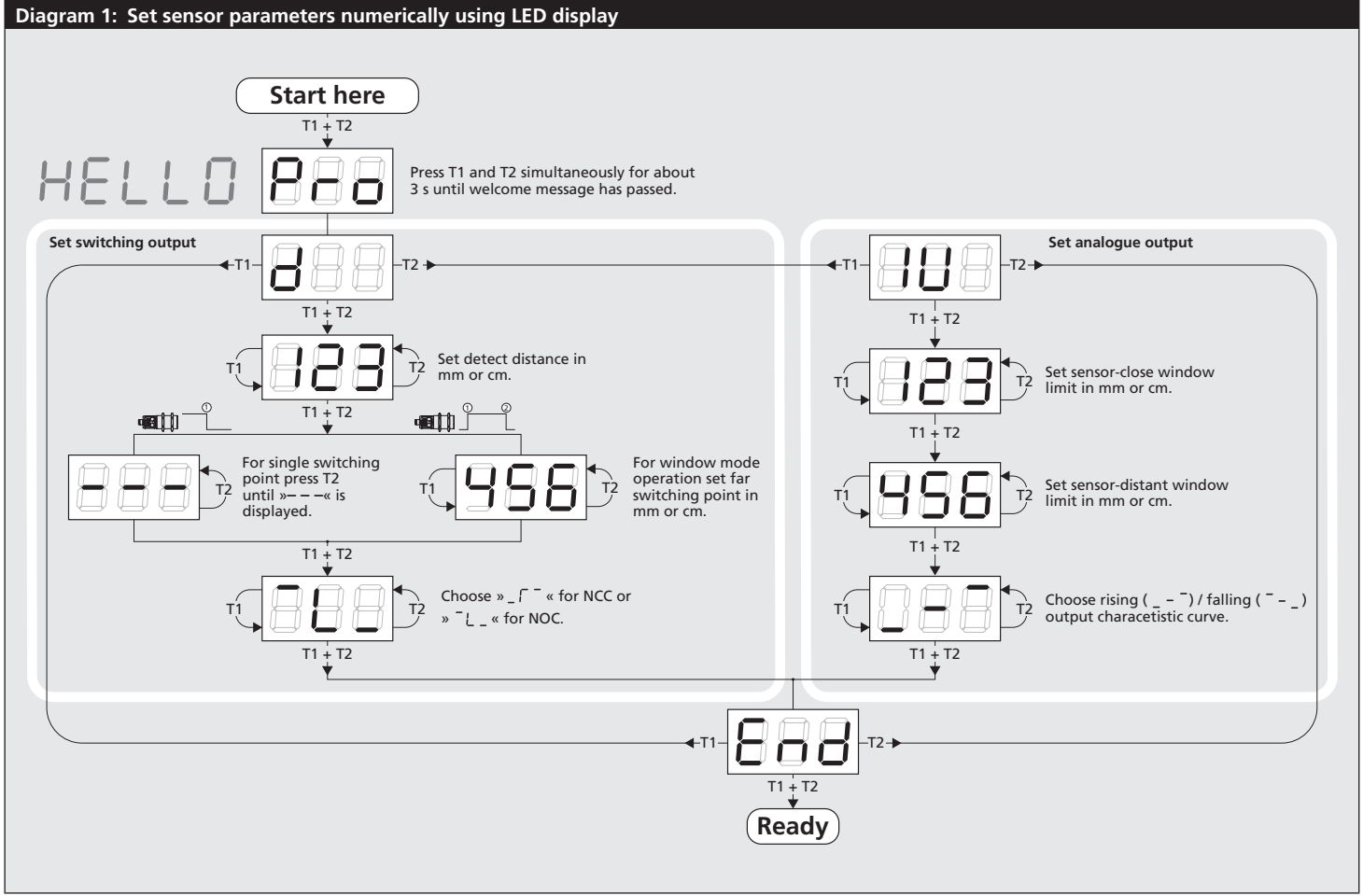


Diagram 2: Set sensor parameters via Teach-in procedure

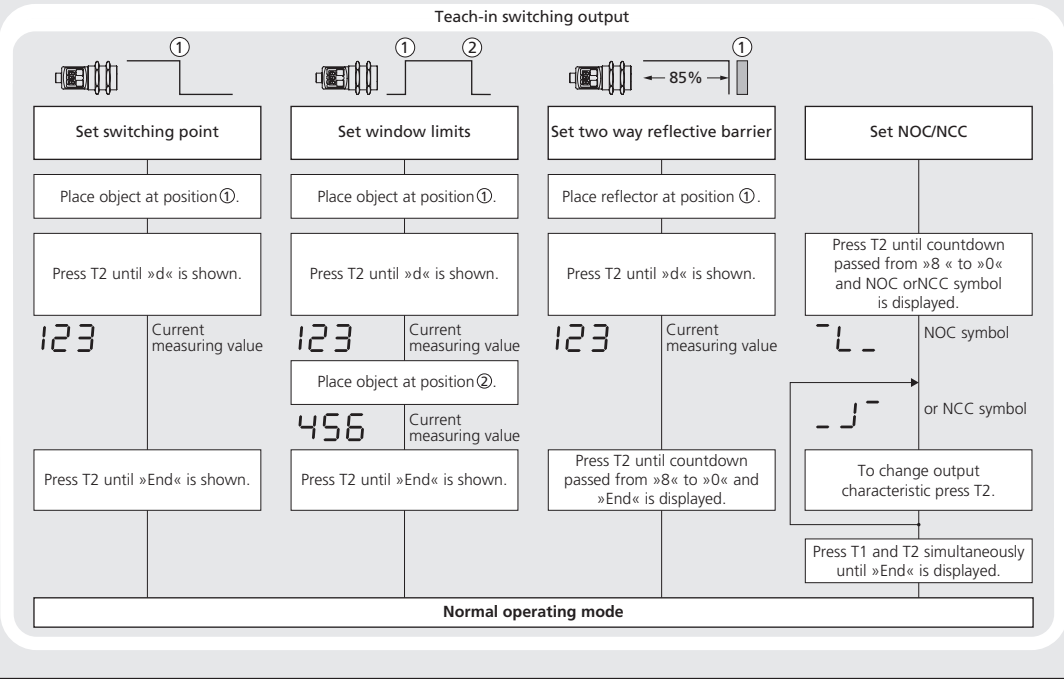


Diagram 3: Key lock and factory setting

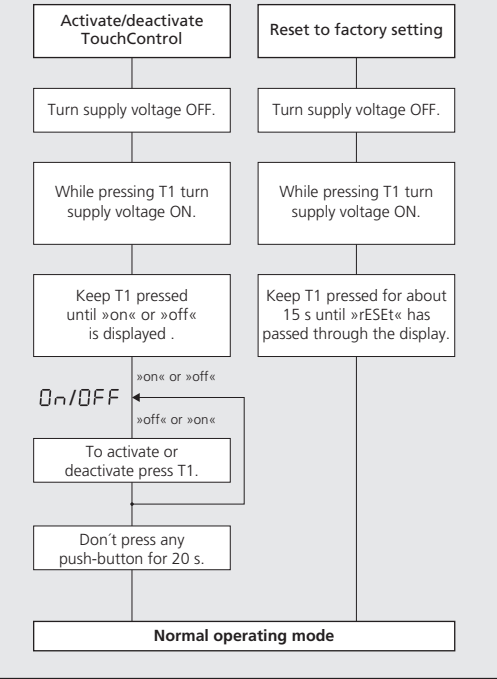
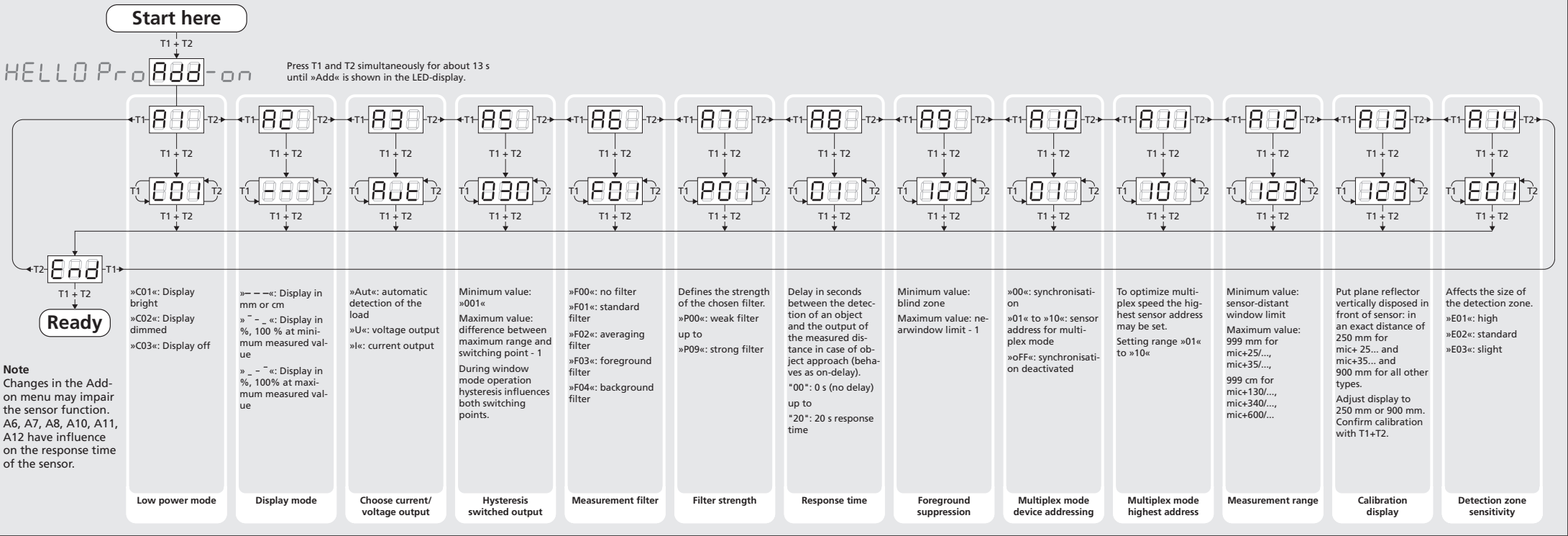





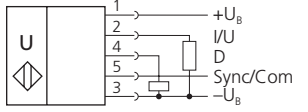
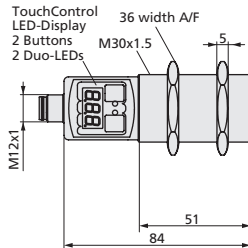
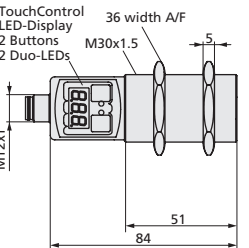
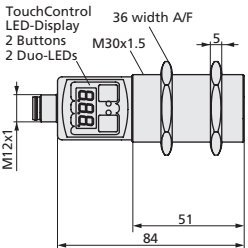
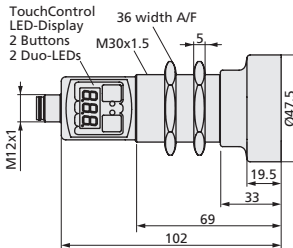
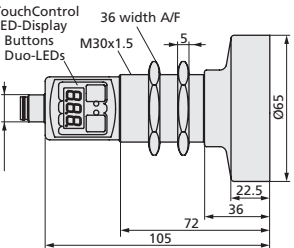
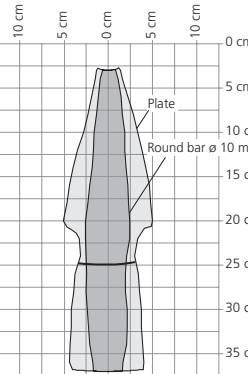
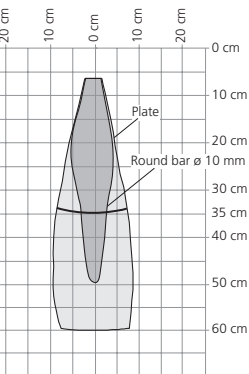
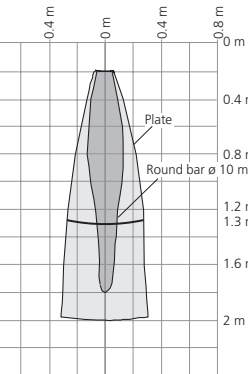
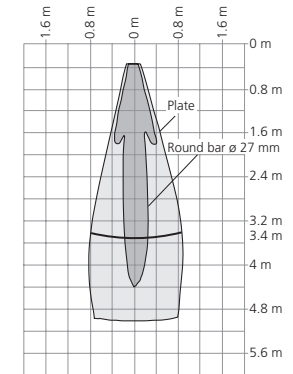
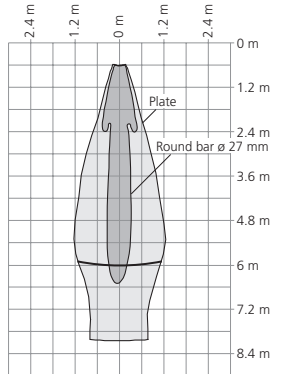


Diagram 4: Useful additional functions in Add-on menu (for experienced users only, settings not required for standard applications)



| | mic+25...  | mic+35...  | mic+130...  | mic+340...  | mic+600...  |
|---|---|---|---|---|---|
|  |  |  |  |  |  |
| blind zone | 0 to 30 mm | 0 bis 65 mm | 0 to 200 mm | 0 to 350 mm | 0 to 600 mm |
| operating range | 250 mm | 350 mm | 1,300 mm | 3,400 mm | 6,000 mm |
| maximum range | 350 mm | 600 mm | 2,000 mm | 5,000 mm | 8,000 mm |
| angle of beam spread | see detection zone | see detection zone | see detection zone | see detection zone | see detection zone |
| transducer frequency | 320 kHz | 400 kHz | 200 kHz | 120 kHz | 80 kHz |
| resolution | 0.025 to 0.10 mm, depending on the analogue window | 0.025 to 0.17 mm, depending on the analogue window | 0.18 to 0.57 mm, depending on the analogue window | 0.18 to 1.50 mm, depending on the analogue window | 0.18 to 2.40 mm, depending on the analogue window |
| detection zones for different objects: The dark grey areas represent the zone where it is easy to recognise the normal reflector (round bar). This indicates the typical operating range of the sensors. The light grey areas represent the zone where a very large reflector – for instance a plate – can still be recognised. The requirement here is for an optimum alignment to the sensor. It is not possible to evaluate ultrasonic reflections outside this area. |  |  |  |  |  |
| reproducibility | ±0.15 % | ±0.15 % | ±0.15 % | ±0.15 % | ±0.15 % |
| accuracy | ±1 % (Temperature drift internal compensated, may be deactivated ³⁾ , 0.17%/K without compensation) 9 to 30 V DC, short-circuit-proof, Class 2 | ±1 % (Temperature drift internal compensated, may be deactivated ³⁾ , 0.17%/K without compensation) 9 to 30 V DC, short-circuit-proof, Class 2 | ±1 % (Temperature drift internal compensated, may be deactivated ³⁾ , 0.17%/K without compensation) 9 to 30 V DC, short-circuit-proof, Class 2 | ±1 % (Temperature drift internal compensated, may be deactivated ³⁾ , 0.17%/K without compensation) 9 to 30 V DC, short-circuit-proof, Class 2 | ±1 % (Temperature drift internal compensated, may be deactivated ³⁾ , 0.17%/K without compensation) 9 to 30 V DC, short-circuit-proof, Class 2 |
| operating voltage U_B | ±10 % | ±10 % | ±10 % | ±10 % | ±10 % |
| voltage ripple | ≤ 80 mV | ≤ 80 mV | ≤ 80 mV | ≤ 80 mV | ≤ 80 mV |
| no-load supply current | ≤ 80 mA | ≤ 80 mA | ≤ 80 mA | ≤ 80 mA | ≤ 80 mA |
| housing | Brass sleeve, nickel-plated, plastic parts: PBT, TPU; Ultrasonic transducer: polyurethane foam, epoxy resin with glass content | Brass sleeve, nickel-plated, plastic parts: PBT, TPU; Ultrasonic transducer: polyurethane foam, epoxy resin with glass content | Brass sleeve, nickel-plated, plastic parts: PBT, TPU; Ultrasonic transducer: polyurethane foam, epoxy resin with glass content | Brass sleeve, nickel-plated, plastic parts: PBT, TPU; Ultrasonic transducer: polyurethane foam, epoxy resin with glass content | Brass sleeve, nickel-plated, plastic parts: PBT, TPU; Ultrasonic transducer: polyurethane foam, epoxy resin with glass content |
| class of protection to EN 60529 | IP 67 | IP 67 | IP 67 | IP 67 | IP 67 |
| norm conformity | EN 60947-5-2 | EN 60947-5-2 | EN 60947-5-2 | EN 60947-5-2 | EN 60947-5-2 |
| type of connection | 5-pin initiator plug, PBT | 5-pin initiator plug, PBT | 5-pin initiator plug, PBT | 5-pin initiator plug, PBT | 5-pin initiator plug, PBT |
| controls | 2 push-buttons (TouchControl) | 2 push-buttons (TouchControl) | 2 push-buttons (TouchControl) | 2 push-buttons (TouchControl) | 2 push-buttons (TouchControl) |
| indicators | 3-digit LED display, 2 three-colour LEDs with TouchControl and LinkControl | 3-digit LED display, 2 three-colour LEDs with TouchControl and LinkControl | 3-digit LED display, 2 three-colour LEDs with TouchControl and LinkControl | 3-digit LED display, 2 three-colour LEDs with TouchControl and LinkControl | 3-digit LED display, 2 three-colour LEDs with TouchControl and LinkControl |
| programmable | with TouchControl and LinkControl | with TouchControl and LinkControl | with TouchControl and LinkControl | with TouchControl and LinkControl | with TouchControl and LinkControl |
| operating temperature | -25 to +70 °C | -25 to +70 °C | -25 to +70 °C | -25 to +70 °C | -25 to +70 °C |
| storage temperature | -40 to +85 °C | -40 to +85 °C | -40 to +85 °C | -40 to +85 °C | -40 to +85 °C |
| weight | 150 g | 150 g | 150 g | 210 g | 270 g |
| switching hysteresis¹⁾ | 3 mm | 5 mm | 20 mm | 50 mm | 100 mm |
| switching frequency²⁾ | 25 Hz | 12 Hz | 8 Hz | 4 Hz | 3 Hz |
| response time²⁾ | 32 ms | 64 ms | 92 ms | 172 ms | 240 ms |
| time delay before availability | <300 ms | <300 ms | <300 ms | <380 ms | <450 ms |
| order No. | mic+25/DIU/TC | mic+35/DIU/TC | mic+130/DIU/TC | mic+340/DIU/TC | mic+600/DIU/TC |
| switching output | pnp, $U_B = 2 \text{ V}$, $I_{max} = 200 \text{ mA}$ switchable NOC/NCC, short-circuit-proof | pnp, $U_B = 2 \text{ V}$, $I_{max} = 200 \text{ mA}$ switchable NOC/NCC, short-circuit-proof | pnp, $U_B = 2 \text{ V}$, $I_{max} = 200 \text{ mA}$ switchable NOC/NCC, short-circuit-proof | pnp, $U_B = 2 \text{ V}$, $I_{max} = 200 \text{ mA}$ switchable NOC/NCC, short-circuit-proof | pnp, $U_B = 2 \text{ V}$, $I_{max} = 200 \text{ mA}$ switchable NOC/NCC, short-circuit-proof |
| current output 4 to 20 mA | $R_L \leq 100 \Omega$ at $9 \text{ V} \leq U_B \leq 20 \text{ V}$; $R_L \leq 500 \Omega$ at $U_B \geq 20 \text{ V}$ Rising/falling output characteristic | $R_L \leq 100 \Omega$ at $9 \text{ V} \leq U_B \leq 20 \text{ V}$; $R_L \leq 500 \Omega$ at $U_B \geq 20 \text{ V}$ Rising/falling output characteristic | $R_L \leq 100 \Omega$ at $9 \text{ V} \leq U_B \leq 20 \text{ V}$; $R_L \leq 500 \Omega$ at $U_B \geq 20 \text{ V}$ Rising/falling output characteristic | $R_L \leq 100 \Omega$ at $9 \text{ V} \leq U_B \leq 20 \text{ V}$; $R_L \leq 500 \Omega$ at $U_B \geq 20 \text{ V}$ Rising/falling output characteristic | $R_L \leq 100 \Omega$ at $9 \text{ V} \leq U_B \leq 20 \text{ V}$; $R_L \leq 500 \Omega$ at $U_B \geq 20 \text{ V}$ Rising/falling output characteristic |
| voltage output 0 to 10 V | $R_L \geq 100 \text{ k}\Omega$ at $U_B \geq 15 \text{ V}$, short-circuit-proof Rising/falling output characteristic | $R_L \geq 100 \text{ k}\Omega$ at $U_B \geq 15 \text{ V}$, short-circuit-proof Rising/falling output characteristic | $R_L \geq 100 \text{ k}\Omega$ at $U_B \geq 15 \text{ V}$, short-circuit-proof Rising/falling output characteristic | $R_L \geq 100 \text{ k}\Omega$ at $U_B \geq 15 \text{ V}$, short-circuit-proof Rising/falling output characteristic | $R_L \geq 100 \text{ k}\Omega$ at $U_B \geq 15 \text{ V}$, short-circuit-proof Rising/falling output characteristic |

¹⁾ Can be programmed via TouchControl and LinkControl.²⁾ With TouchControl and LinkControl, the selected filter setting and the maximum range influence the switching frequency and the response time.³⁾ Can be deactivated via LinkControl.