



## Ultrasonic sensor with one analogue output

### Product Description

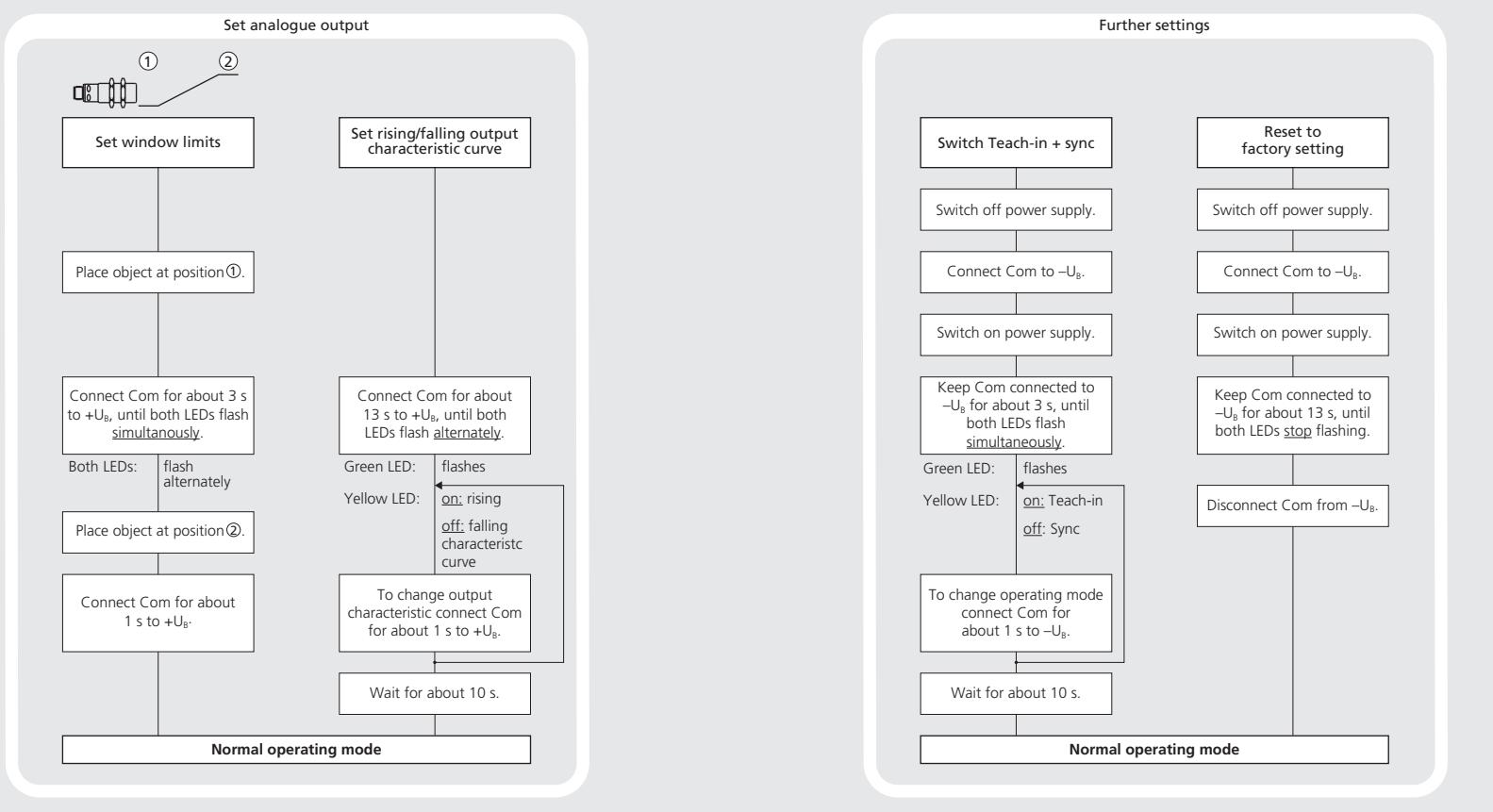
The pico+ sensor offers a non-contact measurement of the distance to an object that has to be present within the sensor's detection zone. Depending on the set window limits, a distance-proportional analogue signal is output.

The window limits of the analogue output and its characteristic can be adjusted via Teach-in procedure. Two LEDs indicate the state of the analogue output.

### Operating Manual

pico+15/I	pico+15/WK/I
pico+25/I	pico+25/WK/I
pico+35/I	pico+35/WK/I
pico+100/I	pico+100/WK/I
pico+15/U	pico+15/WK/U
pico+25/U	pico+25/WK/U
pico+35/U	pico+35/WK/U
pico+100/U	pico+100/WK/U

### Diagram 1: Set sensor parameters via Teach-in procedure



### Safety Notes

- Read the operating manual prior to start-up.
- Connection, installation and adjustment works should be carried out by expert personnel only.
- No safety component in accordance with the EU Machine Directive, use in the area of personal and machine protection not permitted

### Proper Use

pico+ ultrasonic sensors are used for non-contact detection of objects.

### Installation

- ➔ Mount the sensor at the installation site.
- ➔ Connect a connection cable to the M12 device plug, see Fig. 1.



colour
brown
blue
black
white
grey

Fig. 1: Pin assignment with view onto sensor plug and colour coding of the microsonic connection cable

### Start-Up

- ➔ Connect the power supply.
- ➔ Set the sensor parameters using the Teach-in procedure, see Diagram 1.

### Factory Setting

pico+ sensors are delivered factory made with the following settings:

- Rising analogue characteristic curve between the blind zone and the operating range

- Multifunctional input »Com« set to »Teach-in« and »Synchronisation«

### Synchronisation

If the assembly distance falls below the values shown in fig. 2, the internal synchronization should be used. For this purpose set the switched outputs of all sensors in accordance to the diagram »Sensor adjustment with Teach-in procedure« at first. Then set the multifunctional output »Com« to »synchronization« (see »Further settings«, Diagram 1). Finally connect pin 5 of the sensors plug of all sensors.

### Maintenance

microsonic sensors are maintenance-free. In case of excess caked-on dirt we recommend to clean the white sensor surface.

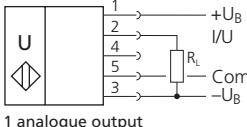
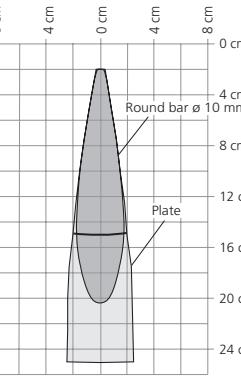
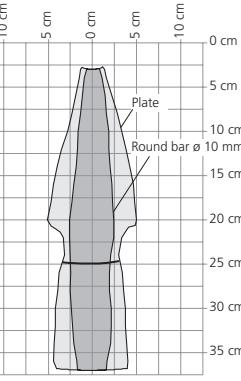
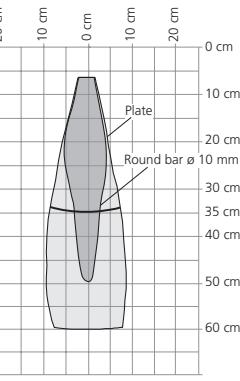
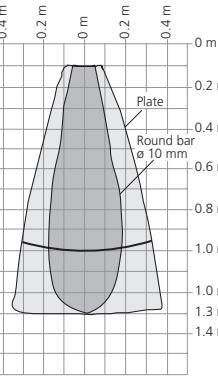
pico+15...	≥0.25 m	≥1.30 m
pico+25...	≥0.35 m	≥2.50 m
pico+35...	≥0.40 m	≥2.50 m
pico+100...	≥0.70 m	≥4.00 m

Fig. 2: Assembly distances, indication synchronisation

### Notes

- The sensors of the pico+ family have a blind zone. Within this zone a distance measurement is not possible.
- Every time the power supply is switched on, the sensor detects its actual operating temperature and transmits it to the internal temperature compensation. The adjusted value is taken over after 120 seconds.
- In the normal operating mode, an illuminated yellow LED signals the object is within the window limits.
- If synchronisation is activated the Teach-in is disabled (see »Further settings«, Diagram 1).
- The sensor can be reset to its factory setting (see »Further settings«, Diagram 1).
- Optionally all Teach-in and additional sensor parameter settings can be adjusted via the LinkControl adapter (optional accessory) and the LinkControl software for Windows®.

## Technical data

	pico+15... 	pico+25... 	pico+35... 	pico+100... 
<b>1 analogue output</b>				
<b>blind zone</b>	20 mm	30 mm	65 mm	120 mm
<b>operating range</b>	150 mm	250 mm	350 mm	1.000 mm
<b>maximum range</b>	250 mm	350 mm	600 mm	1.300 mm
<b>angle of beam spread</b>	see detection zone	see detection zone	see detection zone	see detection zone
<b>transducer frequency</b>	380 kHz	320 kHz	400 kHz	200 kHz
<b>resolution</b>	0.069 mm	0.069 to 0.1 mm, depending on the analogue window	0.069 to 0.17 mm, depending on the analogue window	0.069 to 0.38 mm, depending on the analogue window
<b>detection zones</b>				
<b>reproducibility</b>	±0.15 %	±0.15 %	±0.15 %	±0.15 %
<b>accuracy</b>	±1 % (Temperature drift internal compensated)			
<b>no-load current consumption</b>	<40 mA	<40 mA	<40 mA	<40 mA
<b>operating voltage ripple</b>	±10 %	±10 %	±10 %	±10 %
<b>housing</b>	brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content	brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content	brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content	brass sleeve, nickel-plated, plastic parts: PBT; ultrasonic transducer: polyurethane foam, epoxy resin with glass content
<b>max. tightening torque of nuts</b>	15 Nm	15 Nm	15 Nm	15 Nm
<b>class of protection to EN 60529</b>	IP 67	IP 67	IP 67	IP 67
<b>norm conformity</b>	EN 60947-5-2	EN 60947-5-2	EN 60947-5-2	EN 60947-5-2
<b>type of connection</b>	5-pin M12 initiator plug			
<b>controls</b>	Teach-in via pin 5 (Com)			
<b>scope for setting</b>	Teach-in, LinkControl	Teach-in, LinkControl	Teach-in, LinkControl	Teach-in, LinkControl
<b>indicators</b>	LED green, LED yellow			
<b>synchronisation</b>	internal synchronisation up to 10 sensors			
<b>operating temperature</b>	-25 to +70 °C			
<b>storage temperature</b>	-40 to +85 °C			
<b>response time</b> <sup>1)</sup>	32 ms	32 ms	64 ms	80 ms
<b>time delay before availability</b>	<300 ms	<300 ms	<300 ms	<300 ms
<b>analogue output 4 to 20 mA</b>	$R_L \leq 500 \Omega$ , rising/falling characteristic			
<b>operating voltage <math>U_B</math></b>	10 to 30 V DC for $R_L \leq 100 \Omega$ 20 to 30 V DC for $R_L > 100 \Omega$	10 to 30 V DC for $R_L \leq 100 \Omega$ 20 to 30 V DC for $R_L > 100 \Omega$	10 to 30 V DC for $R_L \leq 100 \Omega$ 20 to 30 V DC for $R_L > 100 \Omega$	10 to 30 V DC for $R_L \leq 100 \Omega$ 20 to 30 V DC for $R_L > 100 \Omega$
<b>order no. directly radiating</b>	pico+15/I	pico+25/I	pico+35/I	pico+100/I
<b>weight</b>	30 g	30 g	35 g	30 g
<b>order no. angular head</b>	pico+15/WK/I	pico+25/WK/I	pico+35/WK/I	pico+100/WK/I
<b>weight</b>	35 g	35 g	35 g	35 g
<b>analogue output 0 to 10 V</b>	$R_L \geq 100 \text{ k}\Omega$ , short circuit proof, rising/falling characteristic	$R_L \geq 100 \text{ k}\Omega$ , short circuit proof, rising/falling characteristic	$R_L \geq 100 \text{ k}\Omega$ , short circuit proof, rising/falling characteristic	$R_L \geq 100 \text{ k}\Omega$ , short circuit proof, rising/falling characteristic
<b>operating voltage <math>U_B</math></b>	15 to 30 V DC, terminal reverse polarity protected, Cl. 2	15 to 30 V DC, terminal reverse polarity protected, Cl. 2	15 to 30 V DC, terminal reverse polarity protected, Cl. 2	15 to 30 V DC, terminal reverse polarity protected, Cl. 2
<b>order no. directly radiating</b>	pico+15/U	pico+25/U	pico+35/U	pico+100/U
<b>weight</b>	30 g	30 g	30 g	30 g
<b>order no. angular head</b>	pico+15/WK/U	pico+25/WK/U	pico+35/WK/U	pico+100/WK/U
<b>weight</b>	35 g	35 g	35 g	35 g

<sup>1)</sup> With LinkControl, the selected filter setting influences the response time.



Enclosure Type 1  
For use only in industrial  
machinery NFPA 79 applications.  
The proximity switches shall be used with a Listed (CYJ/W) cable/connector assembly rated minimum 32 Vdc, minimum 290 mA, in the final installation.

