

mitsubishi

Mitsubishi Programmable Controller

CC-Link IE Field Network High-Speed Counter Module User's Manual



-NZ2GFCF-D62PD2

MODEL

●SAFETY PRECAUTIONS●

(Read these precautions before using this product.)

Before using this product, please read this manual and the relevant manuals carefully and pay full attention to safety to handle the product correctly.

The precautions given in this manual are concerned with this product only. For the safety precautions of the programmable controller system, refer to the user's manual for the CPU module used.

In this manual, the safety precautions are classified into two levels: " WARNING" and " CAUTION".

WARNING

Indicates that incorrect handling may cause hazardous conditions, resulting in death or severe injury.

CAUTION

Indicates that incorrect handling may cause hazardous conditions, resulting in minor or moderate injury or property damage.

Under some circumstances, failure to observe the precautions given under " CAUTION" may lead to serious consequences.

Observe the precautions of both levels because they are important for personal and system safety.

Make sure that the end users read this manual and then keep the manual in a safe place for future reference.

[Design Precautions]

WARNING

- In the case of a communication failure in the network, data in the master module are held. Check Data link status (each station) (SW00B0 to SW00B7) and configure an interlock circuit in the program to ensure that the entire system will operate safely.
- When the module is disconnected due to a communication failure in the network or the CPU module is in the STOP status, all outputs are held or turned off according to the parameter setting. Configure an interlock circuit in the program to ensure that the entire system will always operate safely even in such a case. If not, an accident may occur due to an incorrect output or malfunction.
- Outputs may remain on or off due to a failure of the module. Configure an external circuit for monitoring output signals that could cause a serious accident.
- Do not use any "use prohibited" signals as a remote input or output signal. These signals are reserved for system use. Do not write any data to the "use prohibited" area in the remote register. If these operations are performed, correct operation of the module cannot be guaranteed.

[Design Precautions]

CAUTION

- Do not install the communication cables together with the main circuit lines or power cables. Keep a distance of 100mm or more between them. Failure to do so may result in malfunction due to noise.
- Do not install the control lines together with the main circuit lines or power cables. Keep a distance of 150mm or more between them. Failure to do so may result in malfunction due to noise.

[Installation Precautions]

WARNING

- Shut off the external power supply (all phases) used in the system before mounting or removing a module. Failure to do so may result in electric shock or cause the module to fail or malfunction.

[Installation Precautions]

CAUTION

- Use the module in an environment that meets the general specifications in the user's manual for the module. Failure to do so may result in electric shock, fire, malfunction, or damage to or deterioration of the product.
- Do not directly touch any conductive parts and electronic components of the module. Doing so can cause malfunction or failure of the module.
- Securely fix the module with a DIN rail.
- After the first use of the extension module, do not connect/disconnect the module more than 50 times (in accordance with IEC 61131-2).
- To connect an extension module to a main module, engage the respective connectors and securely lock the module joint levers. Incorrect connection may cause malfunction, failure, or drop of the module.
- Securely connect the cable connectors. Poor contact may cause malfunction.

[Wiring Precautions]

WARNING

- Shut off the external power supply (all phases) used in the system before wiring. Failure to do so may result in electric shock or cause the module to fail or malfunction.

[Wiring Precautions]

CAUTION

- Ground the shield cable for the pulse input on the encoder side (relay box) with a ground resistance of 100Ω or less. Failure to do so may cause malfunction.
- Individually ground the FG terminal of the programmable controller with a ground resistance of 100Ω or less. Failure to do so may result in electric shock or malfunction.
- Check the rated voltage and terminal layout before wiring to the module, and connect the cables correctly. Connecting a power supply with a different voltage rating or incorrect wiring may cause a fire or failure.
- Prevent foreign matter such as dust or wire chips from entering the module. Such foreign matter can cause a fire, failure, or malfunction.
- Place the cables in a duct or clamp them. If not, dangling cable may swing or inadvertently be pulled, resulting in damage to the module or cables or malfunction due to poor contact.
- Do not install the communication cables together with the main circuit lines or power cables. Keep a distance of 100mm or more between them. Failure to do so may result in malfunction due to noise.
- Do not install the control lines together with the main circuit lines or power cables. Keep a distance of 150mm or more between them. Failure to do so may result in malfunction due to noise.
- When disconnecting the cable from the module, do not pull the cable by the cable part. For the cable with connector, hold the connector part of the cable. For the cable connected to the terminal block, loosen the terminal screw. Pulling the cable connected to the module may result in malfunction or damage to the module or cable.
- When an overcurrent caused by an error of an external device or a failure of the programmable controller flows for a long time, it may cause smoke and fire. To prevent this, configure an external safety circuit, such as a fuse.
- Connectors for external devices must be crimped with the tool specified by the manufacturer, or must be correctly soldered. Securely connect the connector to the module.
- Mitsubishi programmable controllers must be installed in control panels. Wiring and replacement of a module must be performed by qualified maintenance personnel with knowledge of protection against electric shock. For wiring methods, refer to "INSTALLATION AND WIRING" in this manual.

[Startup and Maintenance Precautions]

WARNING

- Do not touch any terminal while power is on. Doing so will cause electric shock or malfunction.
- Shut off the external power supply (all phases) used in the system before cleaning the module or retightening the terminal block screws or connector screws. Failure to do so may cause the module to fail or malfunction.

[Startup and Maintenance Precautions]

CAUTION

- Do not disassemble or modify the module. Doing so may cause failure, malfunction, injury, or a fire.
- Do not drop or apply strong shock to the module. Doing so may damage the module.
- Shut off the external power supply (all phases) used in the system before mounting or removing a module. Failure to do so may cause the module to fail or malfunction.
- Before handling the module or the cable to be connected to the module, touch a conducting object such as a grounded metal to discharge the static electricity from the human body. Failure to do so may cause the module to fail or malfunction.
- Startup and maintenance of a control panel must be performed by qualified maintenance personnel with knowledge of protection against electric shock. Lock the control panel so that only qualified maintenance personnel can operate it.

[Disposal Precautions]

CAUTION

- When disposing of this product, treat it as industrial waste.

●CONDITIONS OF USE FOR THE PRODUCT●

(1) Mitsubishi programmable controller ("the PRODUCT") shall be used in conditions;

- i) where any problem, fault or failure occurring in the PRODUCT, if any, shall not lead to any major or serious accident; and
- ii) where the backup and fail-safe function are systematically or automatically provided outside of the PRODUCT for the case of any problem, fault or failure occurring in the PRODUCT.

(2) The PRODUCT has been designed and manufactured for the purpose of being used in general industries.

MITSUBISHI SHALL HAVE NO RESPONSIBILITY OR LIABILITY (INCLUDING, BUT NOT LIMITED TO ANY AND ALL RESPONSIBILITY OR LIABILITY BASED ON CONTRACT, WARRANTY, TORT, PRODUCT LIABILITY) FOR ANY INJURY OR DEATH TO PERSONS OR LOSS OR DAMAGE TO PROPERTY CAUSED BY the PRODUCT THAT ARE OPERATED OR USED IN APPLICATION NOT INTENDED OR EXCLUDED BY INSTRUCTIONS, PRECAUTIONS, OR WARNING CONTAINED IN MITSUBISHI'S USER, INSTRUCTION AND/OR SAFETY MANUALS, TECHNICAL BULLETINS AND GUIDELINES FOR the PRODUCT.

("Prohibited Application")

Prohibited Applications include, but not limited to, the use of the PRODUCT in;

- Nuclear Power Plants and any other power plants operated by Power companies, and/or any other cases in which the public could be affected if any problem or fault occurs in the PRODUCT.
- Railway companies or Public service purposes, and/or any other cases in which establishment of a special quality assurance system is required by the Purchaser or End User.
- Aircraft or Aerospace, Medical applications, Train equipment, transport equipment such as Elevator and Escalator, Incineration and Fuel devices, Vehicles, Manned transportation, Equipment for Recreation and Amusement, and Safety devices, handling of Nuclear or Hazardous Materials or Chemicals, Mining and Drilling, and/or other applications where there is a significant risk of injury to the public or property.

Notwithstanding the above, restrictions Mitsubishi may in its sole discretion, authorize use of the PRODUCT in one or more of the Prohibited Applications, provided that the usage of the PRODUCT is limited only for the specific applications agreed to by Mitsubishi and provided further that no special quality assurance or fail-safe, redundant or other safety features which exceed the general specifications of the PRODUCTS are required. For details, please contact the Mitsubishi representative in your region.

INTRODUCTION

Thank you for purchasing the CC-Link IE Field Network high-speed counter module (hereafter abbreviated as high-speed counter module).

This manual describes the operating procedure, system configuration, parameter settings, functions, and troubleshooting of the high-speed counter module.

Before using this product, please read this manual and the relevant manuals carefully and develop familiarity with the functions and performance of the high-speed counter module to handle the product correctly.

When applying the program examples introduced in this manual to an actual system, ensure the applicability and confirm that it will not cause system control problems.

■Target module: NZ2GFCF-D62PD2

Remark

Unless otherwise specified, this manual describes the program examples in which the remote I/O signals and remote registers are assigned for a high-speed counter module as follows.

- Remote input signal: RX00 to RX4F
- Remote output signal: RY00 to RY4F
- Remote register: RWr0 to RWr3F, RWw0 to RWw3F

For the assignment of remote I/O signals and remote registers, refer to the following.

 User's manual for the master/local module used

RELEVANT MANUALS

(1) CC-Link IE Field Network (relevant) manuals

When using the CC-Link IE Field Network for the first time, refer to CC-Link IE Field Network Master/Local Module User's Manual first. The following shows the structure of the CC-Link IE Field Network manuals.

Manual name <manual number (model code)>	Description
MELSEC-Q CC-Link IE Field Network Master/Local Module User's Manual <SH-080917ENG, 13JZ47>	Overview of the CC-Link IE Field Network, and specifications, procedures before operation, system configuration, installation, wiring, settings, functions, programming, and troubleshooting of the QJ71GF11-T2
MELSEC-L CC-Link IE Field Network Master/Local Module User's Manual <SH-080972ENG, 13JZ54>	Overview of the CC-Link IE Field Network, and specifications, procedures before operation, system configuration, installation, wiring, settings, functions, programming, and troubleshooting of the LJ71GF11-T2

(2) Operating manual

Manual name <manual number (model code)>	Description
GX Works2 Version 1 Operating Manual (Common) <SH-080779ENG, 13JU63>	System configuration, parameter settings, and online operations of GX Works2, which are common to Simple projects and Structured projects

CONTENTS

SAFETY PRECAUTIONS	1
CONDITIONS OF USE FOR THE PRODUCT	5
INTRODUCTION	6
RELEVANT MANUALS	7
MANUAL PAGE ORGANIZATION	11
TERM	12
PACKING LIST	14
CHAPTER 1 HIGH-SPEED COUNTER MODULE	15
1.1 Application	16
1.2 Features	17
CHAPTER 2 PART NAMES	21
CHAPTER 3 SPECIFICATIONS	25
3.1 General Specifications	25
3.2 Performance Specifications	27
3.2.1 The input waveform and the phase difference between phase A pulse and phase B pulse	30
3.3 Calculating Current Consumption	32
3.4 Function List	33
3.5 List of Remote I/O Signals	35
3.6 List of Remote Register	39
3.7 List of Remote Buffer Memory	41
CHAPTER 4 THE PROCEDURE BEFORE OPERATION	51
CHAPTER 5 SYSTEM CONFIGURATION	53
5.1 High-Speed Counter Module System Configuration	53
5.2 Applicable Systems	54
CHAPTER 6 INSTALLATION AND WIRING	55
6.1 Station Number Setting	55
6.2 Installation Environment and Installation Position	56
6.2.1 Installation environment	56
6.2.2 Installation position	56
6.2.3 Installation direction	57
6.3 Installation	58
6.3.1 Connecting extension modules	58
6.3.2 Mounting the modules on a DIN rail	60
6.4 Wiring with Terminal Block for Module Power Supply and FG	63
6.5 Wiring of Ethernet Cable	65
6.6 Wiring of Connectors for External Devices	68
6.6.1 Wiring precautions	68

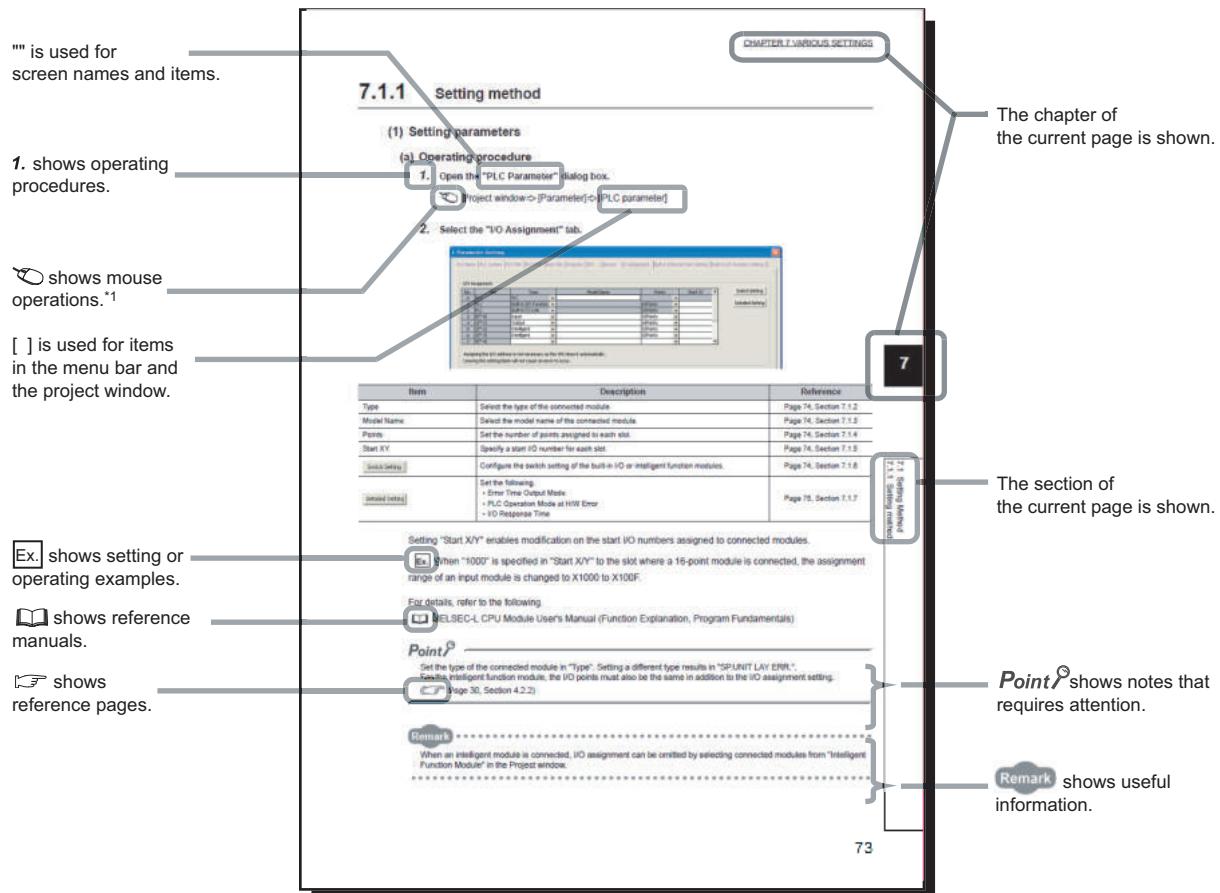
6.6.2	Connectors for external devices	70
6.6.3	I/O interfaces with external devices	71
6.6.4	Encoders that can be connected	75
6.7	Wiring Example (Between a High-Speed Counter Module and an Encoder)	76
6.8	Wiring Example (Between a Controller and External Input Terminals)	78
6.9	Wiring Example (with Coincidence Output Terminals)	79
<hr/> CHAPTER 7 VARIOUS SETTINGS		80
7.1	Parameter Setting	80
7.2	Changing the Parameter	86
7.2.1	Changing the network configuration	86
7.2.2	Changing the parameter without changing the network configuration	88
7.3	Operation Mode List	90
<hr/> CHAPTER 8 FUNCTIONS		92
8.1	Pulse Input Modes and Counting Methods	92
8.1.1	Types of pulse input modes	92
8.1.2	Counting method setting	94
8.2	Counter Format Selection	95
8.2.1	Linear counter function	95
8.2.2	Ring counter function	97
8.3	Comparison Output Function	102
8.3.1	Operation overview of the coincidence output function and the cam switch function	102
8.3.2	Coincidence output function	103
8.3.3	Preset/replace (at coincidence output) function	114
8.3.4	Cam switch function	117
8.4	Preset/replace Function	122
8.5	Latch Counter Function by Latch Counter Input Terminal	127
8.6	Counter Function Selection	129
8.7	Count Disable Function	131
8.8	Latch Counter Function (Counter Function Selection)	133
8.9	Sampling Counter Function	136
8.10	Periodic Pulse Counter Function	139
8.11	Count Disable/preset/replace Function	142
8.12	Latch Counter/preset/replace Function	145
8.13	Frequency Measurement Function	148
8.14	Rotation Speed Measurement Function	152
8.15	Pulse Measurement Function	156
8.16	PWM Output Function	160
8.17	Output HOLD/CLEAR Setting Function	167
8.18	Cyclic Data Update Watch Function	168
8.19	Error Notification Function	169
8.20	Function at the Extension Module Installation	172
8.21	CC-Link IE Field Network Diagnostic Function	175

CHAPTER 9 PROGRAMMING	178
9.1 Precautions for Programming	178
9.2 Procedure for Programming	180
9.3 Program Example	181
CHAPTER 10 MAINTENANCE AND INSPECTION	203
CHAPTER 11 TROUBLESHOOTING	205
11.1 Checking for the Error Codes and the Warning Codes	205
11.2 Error Code List	208
11.3 Checking the LEDs	224
11.4 Unit Test	227
11.5 Troubleshooting for Each Phenomenon	228
11.5.1 When the setting on the operation mode setting is the normal mode	228
11.5.2 When the setting on the operation mode setting is the frequency measurement mode	234
11.5.3 When the setting on the operation mode setting is the rotation speed measurement mode	234
11.5.4 When the setting on the operation mode setting is the pulse measurement mode	234
11.5.5 When the setting on the operation mode setting is the PWM output mode	235
APPENDICES	236
Appendix 1 Details of Remote I/O Signals	236
Appendix 1.1 Details of remote input signals	236
Appendix 1.2 Details of remote output signals	249
Appendix 2 Details of Remote Registers	255
Appendix 3 Details of Remote Buffer Memory Addresses	267
Appendix 4 Internal Control Cycle and Response Delay Time	283
Appendix 5 EMC and Low Voltage Directives	286
Appendix 5.1 Measures to comply with the EMC directive	286
Appendix 5.2 Requirements to compliance with the low voltage directive	291
Appendix 6 Checking Serial Number and Function Version	292
Appendix 7 External Dimensions	293
INDEX	294
REVISIONS	298
WARRANTY	299

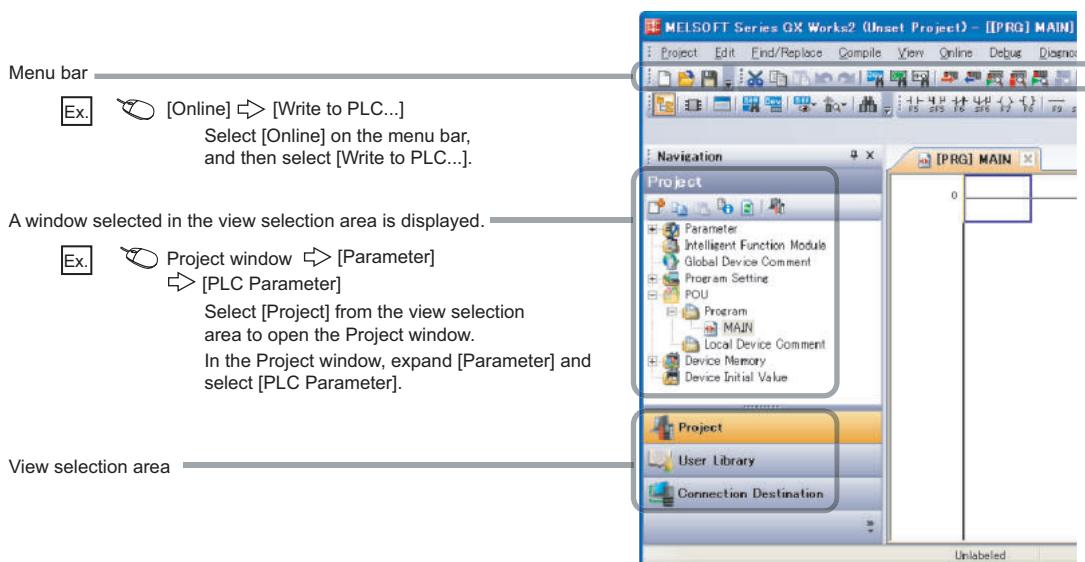
MANUAL PAGE ORGANIZATION

In this manual, pages are organized and the symbols are used as shown below.

The following illustration is for explanation purpose only, and should not be referred to as an actual documentation



*1 The mouse operation example is provided below.



TERM

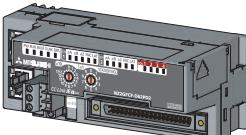
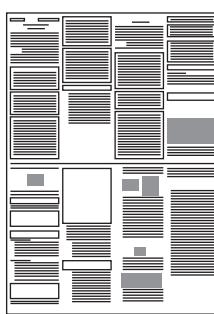
Unless otherwise specified, this manual uses the following terms.

Term	Description
CC-Link IE Field Network	A high-speed and large-capacity open field network that is based on Ethernet (1000BASE-T)
GX Works2	The product name of the software package for the MELSEC programmable controllers
REMFR	The abbreviation for ZP.REMFR. This dedicated instruction is used in programs of the master/local module.
REMTO	The abbreviation for ZP.REMTO. This dedicated instruction is used in programs of the master/local module.
Intelligent device station	A station that deals with bit data and word data. The station can communicate with the master station and other local stations. The station cannot communicate with other remote I/O stations, remote device stations and intelligent device stations. The station can perform the cyclic transmission and transient transmission.
Cyclic transmission	A function by which data are periodically exchanged among stations on the same network using link devices (RX, RY, RWw, and RWr)
Slave station	A generic term for stations other than a master station: local station, remote I/O station, remote device station, and intelligent device station
Data link	A generic term for cyclic transmission and transient transmission
Transient transmission	A function of communication with another station, which is used when requested by a dedicated instruction or GX Works2
Network module	A generic term for the following modules: <ul style="list-style-type: none"> • CC-Link IE Field Network module • CC-Link IE Controller Network module • Ethernet interface module • MELSECNET/H module • MELSECNET/10 module
Buffer memory	A memory in an intelligent function module, where data (such as setting values and monitoring values) are stored
Programming tool	Another term for GX Works2
Master/local module	A generic term for the CC-Link IE Field Network master/local module
Master station	A station that controls CC-Link IE Field Network. The station can communicate with all stations. Only one master station can be used in a network. The station can perform the cyclic transmission and transient transmission.
Remote I/O station	A station that deals with bit data. The station can communicate with the master station and other local stations. The station cannot communicate with other remote I/O stations, remote device stations and intelligent device stations. The station can perform the cyclic transmission.
Remote device station	A station that deals with bit data and word data. The station can communicate with the master station and other local stations. The station cannot communicate with other remote I/O stations, remote device stations and intelligent device stations. The station can perform the cyclic transmission.
Remote buffer memory	Buffer memory in a remote device station
Remote register (RW _r)	Word data input from a slave station to the master station (For some areas in a local station, data are output in the opposite direction.)  User's manual for the master/local module used
Remote register (RWw)	Word data output from the master station to a slave station (For some areas in a local station, data are output in the opposite direction.)  User's manual for the master/local module used
Remote output (RY)	Bit data output from the master station to a slave station (For some areas in a local station, data are output in the opposite direction.)  User's manual for the master/local module used
Remote input (RX)	Bit data input from a slave station to the master station (For some areas in a local station, data are output in the opposite direction.)  User's manual for the master/local module used
Link device	A device (RX, RY, RW _r , or RWw) in a module on CC-Link IE Field Network

Term	Description
Link special relay (SB)	Bit data that indicates the operating status and data link status of a module on CC-Link IE Field Network
Link special register (SW)	Bit data that indicates the operating status and data link status of a module on CC-Link IE Field Network
Routing	A process of selecting paths for communication with other networks. On CC-Link IE Field Network, set a network route with the routing parameter in advance to communicate with a station that is set a different network number. A high-speed counter module does not need to set the routing parameter. Communications with other networks are performed according to the routing parameters set to the master station.
Local station	A station that includes a CPU module and can communicate with the master station and other local stations. This station can create simplified CC-Link IE Controller Network by combining the master station and other local stations. The station can perform the cyclic transmission and transient transmission.
Disconnection	A process of stopping data link if a data link error occurs
Main module	A module with the CC-Link IE Field Network communication function, which can be used as a single remote module. Extension modules can be connected to this module.
High-speed counter module	The abbreviation for the CC-Link IE Field Network high-speed counter module
Dedicated instruction	An instruction that simplifies programming for using functions of intelligent function modules
Extension module	A remote module that does not support the CC-Link IE Field Network communication function. This module cannot be used as a single module. However, connecting the module to the main module will increase the number of I/O points per station.
Extension I/O module	A generic term for extension modules where a digital signal can be input or output
Relay station	A station that includes two or more network modules. Data are passed through this station to stations on other networks.
Return	A process of restarting data link when a station recovers from an error
Reserved station	A station reserved for future use. This station is not actually connected, but counted as a connected station.

PACKING LIST

The following items are included in the package of this product. Before use, check that all the items are included.

High-speed counter module	
	
Module	Before Using the Product

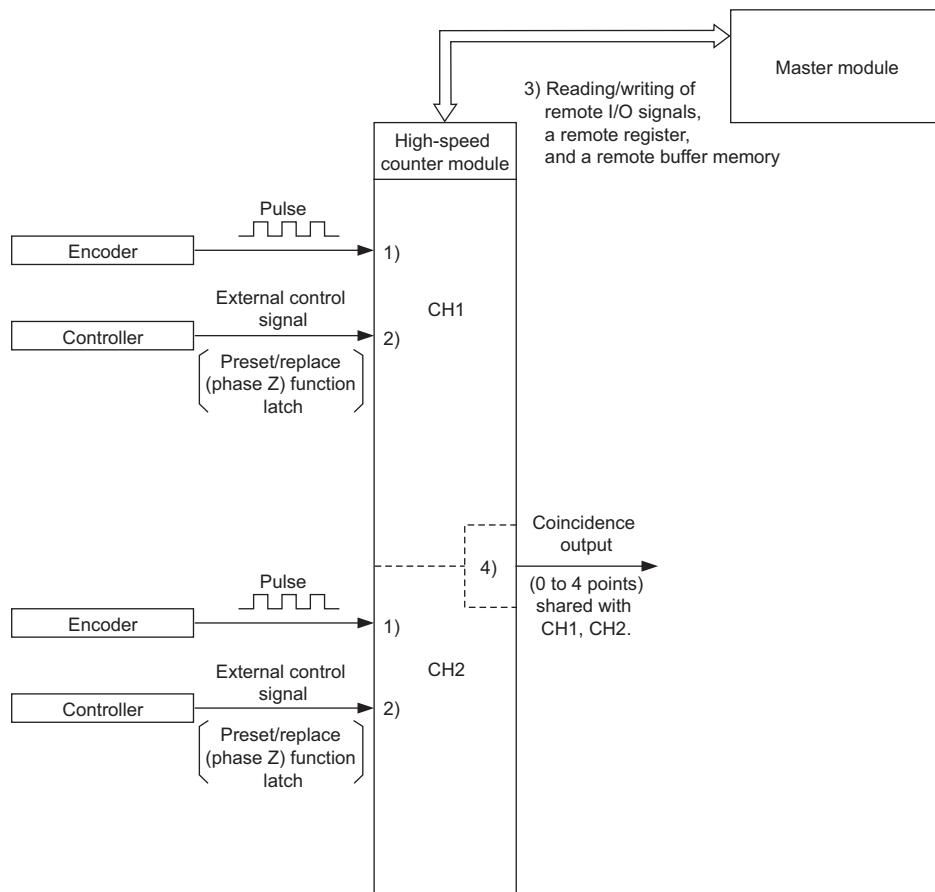
CHAPTER 1 HIGH-SPEED COUNTER MODULE

This chapter describes the operation, the application, and the features of the high-speed counter module.

The high-speed counter module is a remote device station of the CC-Link IE Field Network whose maximum counting speed of input pulse is 8Mpps (with differential input and 4 multiples of 2 phases).

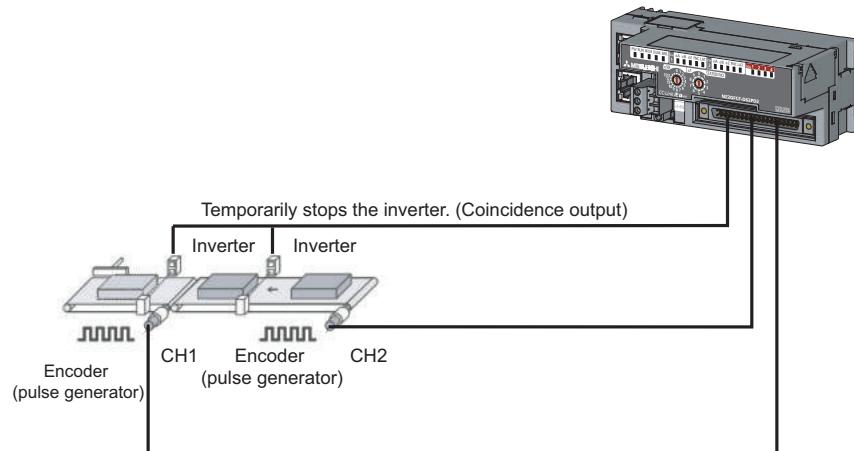
The module has two channels and functions including the preset/replace function by external input or input from a master module, the latch counter function, counter function selection, external coincidence output by coincidence detection.

The following illustration shows the operation overview of the high-speed counter module.



1.1 Application

This module performs controls which are applicable to various applications by executing various functions according to count values of pulses input from the external device. The following describes an application example.



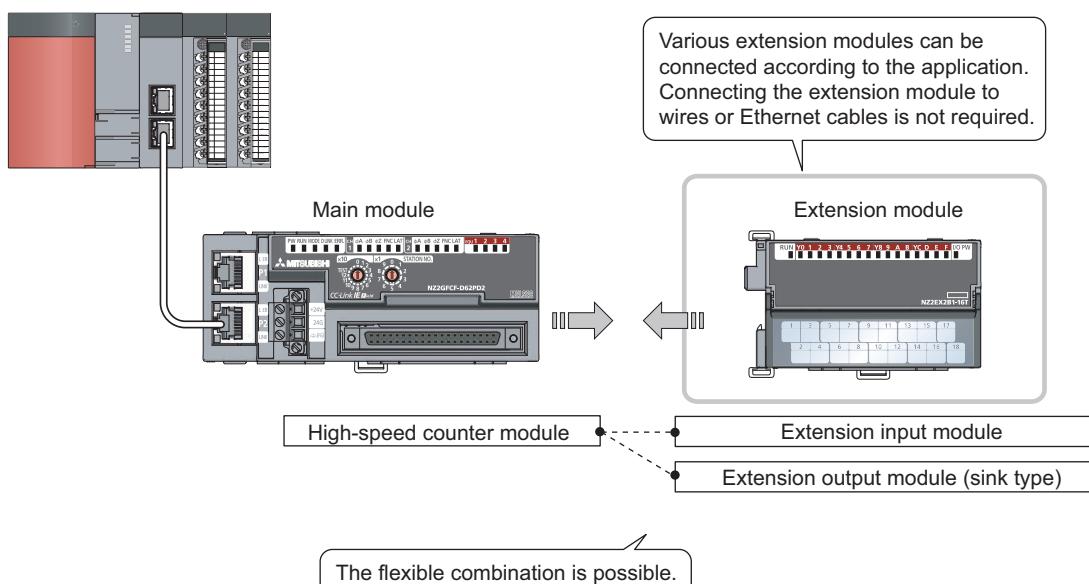
1.2 Features

(1) Available flexible system configuration

Adopting the connection block type enables the combination of the main module and extension module.

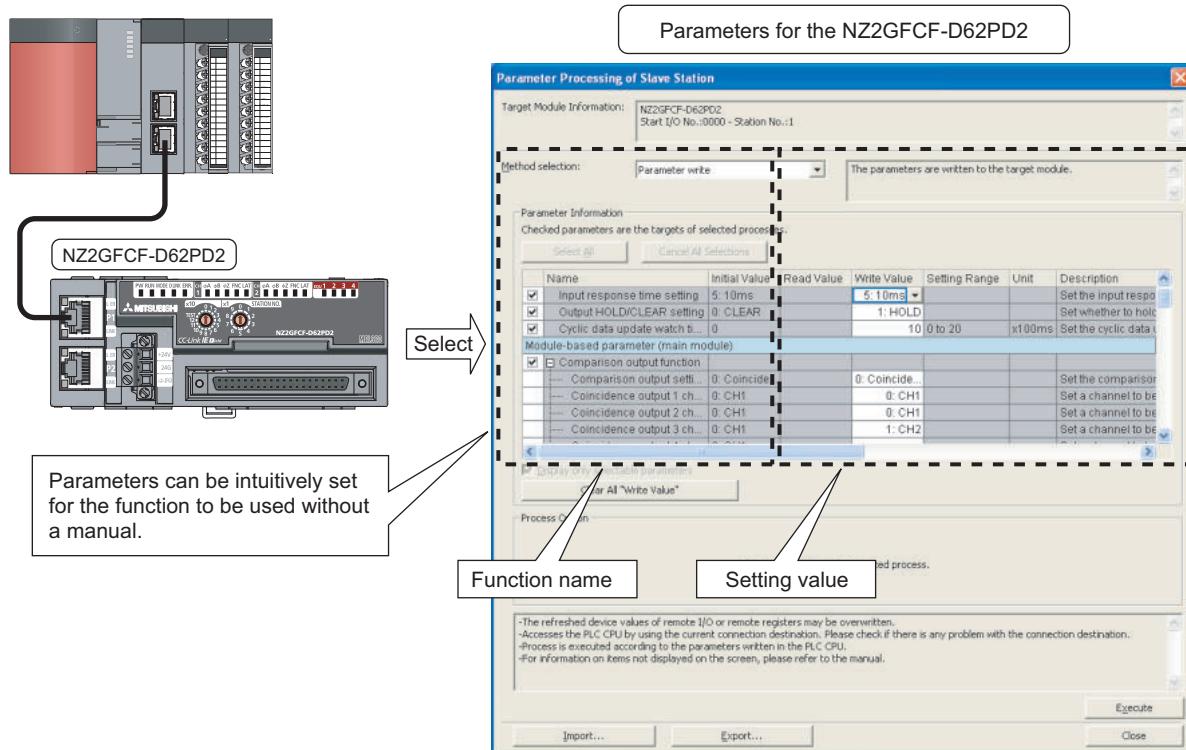
Because various extension modules can be connected, a flexible configuration can be achieved.

In addition, a poor contact of the extension module can be found promptly because the main module always monitors the connection status of the extension module.



(2) Easy setting with CC IE Field configuration of GX Works2

Programming is reduced since the parameter can be configured on the window with the CC IE Field configuration of GX Works2. In addition, setting status and operation status of modules can be checked easily.



(3) Easy station number setting

Because of the rotary switch on the front of the module, setting and checking the station number are easy.

(4) Error history function

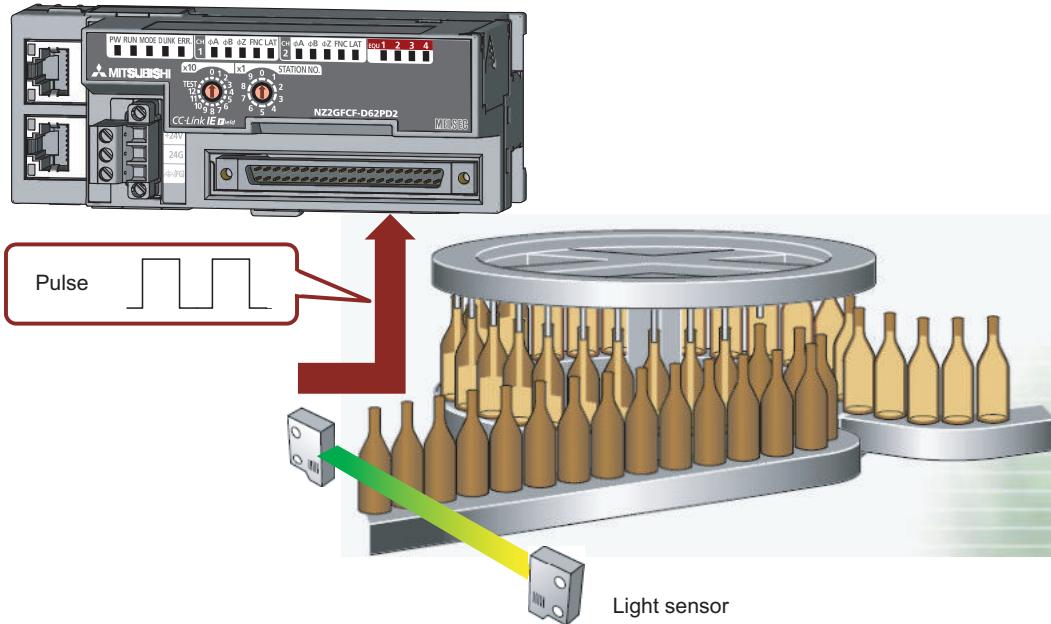
The history of 15 errors and occurrence time can be stored in the module.

The error history helps the investigation for the cause when a problem occurs.

(5) Pulse measurement function

Pulses can be measured with 100ns measurement resolution. The pulse width (ON width/OFF width) can be precisely measured. Various pulse measurement applications such as the workpiece length measurement or the transport/processing speed management of various types of transport equipment and processing equipment are available.

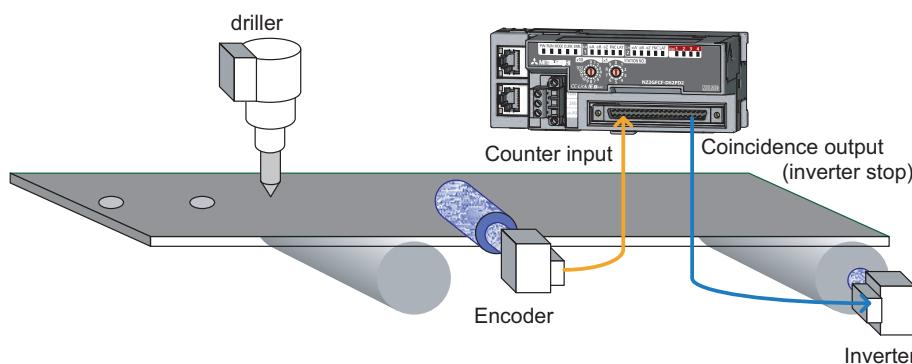
Example: Filling process (container type identification control)



(6) Coincidence output function

This function compares a preset value with the input count value. If they match, the function outputs a signal and thus the fixed-feed control is possible.

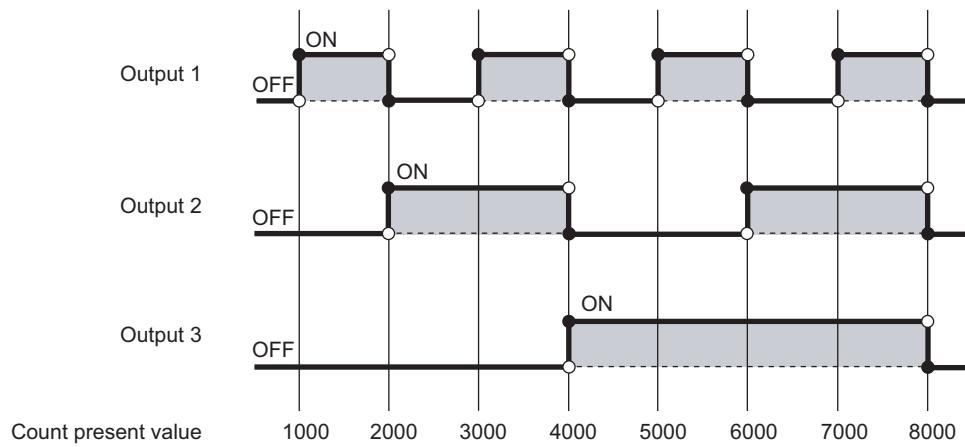
Control example: Drilling process (fixed-feed control)



(7) Cam switch function

According to the input count present value, the ON/OFF status of output can be set for every preset point without any program. More precise ON/OFF control is available without scan time effect.

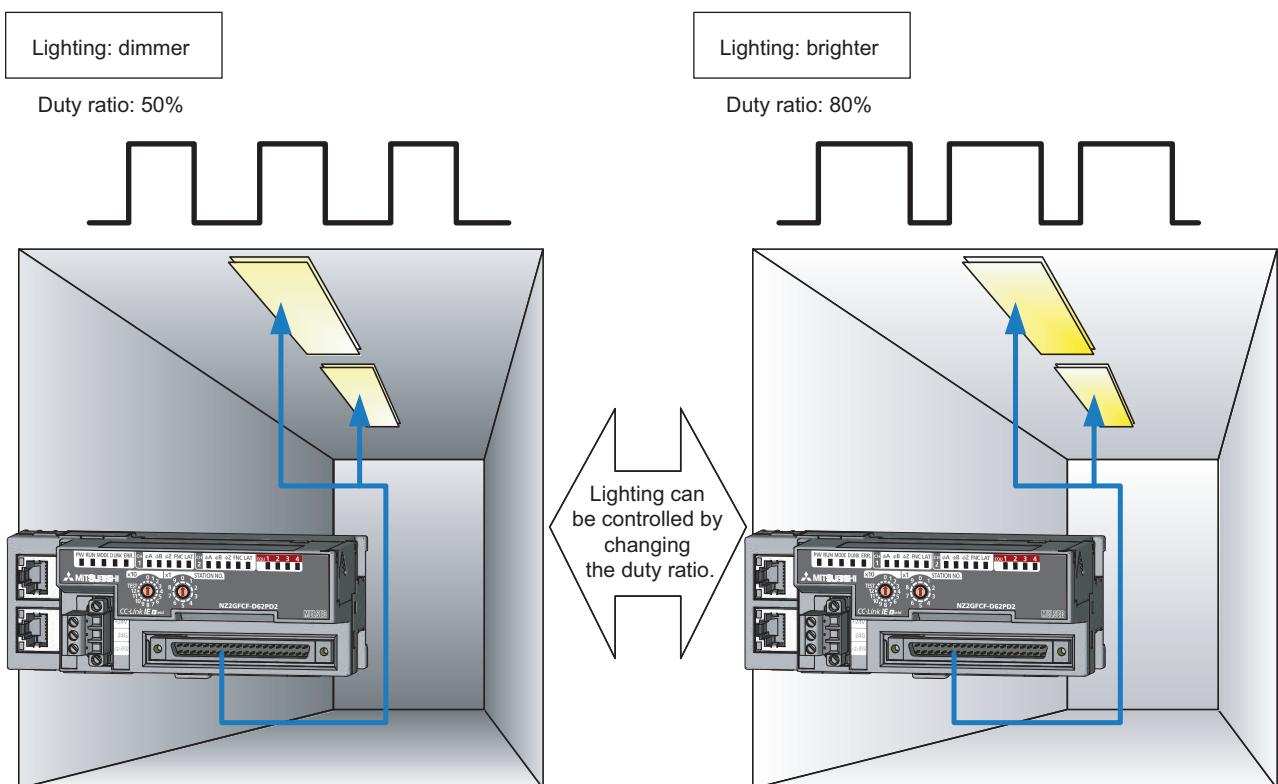
An extension output module is required for using this function.



(8) PWM output function

Up to 200kHz of the PWM waveform can be output. The duty ratio can be set by 0.1μs and this enables precise output control. The PWM output function enables controls such as dimming control according to duty ratio modification.

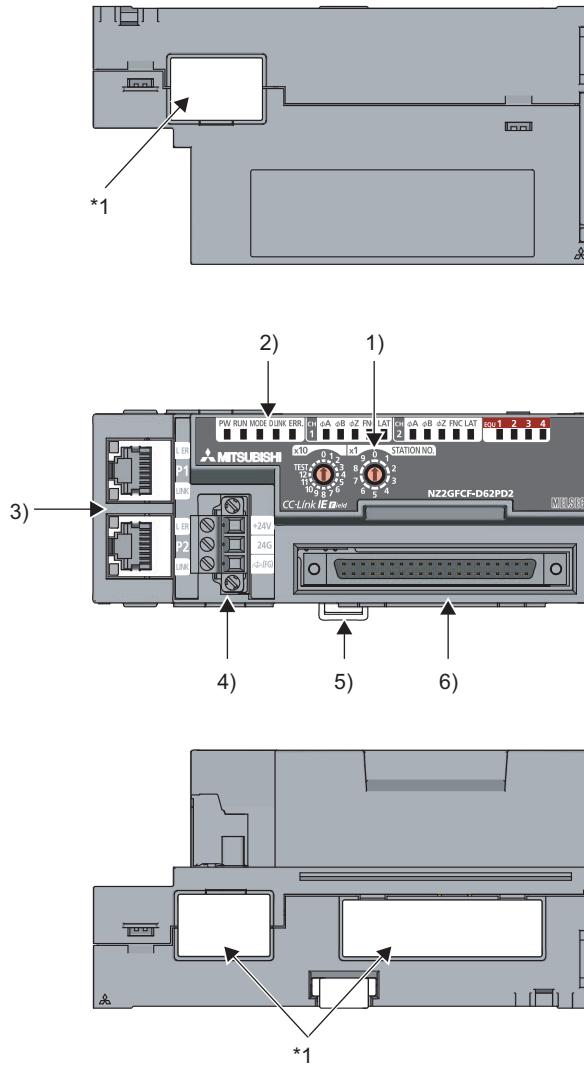
Example: Lighting control



CHAPTER 2 PART NAMES

This chapter describes the part names of the high-speed counter module.

2



*1 Do not remove this seal because it is used for a maintenance purpose.

No.	Name	Description
1)	Station number setting switch	<p>A rotary switch for the following setting and test</p> <ul style="list-style-type: none"> • Station Number Setting (☞ Page 55, Section 6.1) • Unit Test (☞ Page 227, Section 11.4) <p>When operating the station number setting switch, use a slotted screwdriver with 3.5mm or less width of the tip.</p>
	PW LED (green)	Indicates the power supply status of the module.
	ON	Power supply ON
	OFF	Power supply OFF
	RUN LED (green)	Indicates the operating status of the module.
	ON	Operating normally
	OFF	When a major error occurs
	MODE LED (green)	Indicates the mode status of the module.
	ON	In online mode
	Flashing	In unit test mode
	OFF	At the unit test completion
	D LINK LED (green)	Indicates the data communication status between the module and the master module.
	ON	Data link in operation (cyclic transmission in progress)
	Flashing	Data link in operation (cyclic transmission stopped)
	OFF	Data link not performed (disconnected)
2)	ERR. LED (red)	Indicates the error status of the module.
	ON	A moderate error or major error has occurred.
	Flashing	A minor error (warning) has occurred.
	OFF	Operating normally
	CH1φA/φB/φZ LED CH2φA/φB/φZ LED (green)	Indicates the input status of the pulse input terminals in phase A, B, and Z.
	ON	At voltage application
	OFF	At no voltage application
	CH1FNC/LAT LED CH2FNC/LAT LED (green)	Indicates the input status of the function/latch counter input terminal.
	ON	At voltage application
	OFF	At no voltage application
	EQU1 to EQU4 LED (green)	Indicates the output status of the coincidence output 1 to 4 terminals (EQU1 to EQU4).
	ON	Signal output ON
	OFF	Signal output OFF

No.	Name	Description					
3)	P1	PORT1 connector for CC-Link IE Field Network (RJ45 connector) Connect an Ethernet cable. (☞ Page 65, Section 6.5) There are no restrictions on the connection order of the cables for the "P1" connector and "P2" connector.					
		<table border="1"> <tr> <td>L ER LED (red)</td> <td>ON</td> <td>• The module has received abnormal data. • The module is performing loopback.</td> </tr> <tr> <td></td> <td>OFF</td> <td>• The module has received normal data. • The module is not performing loopback.</td> </tr> </table>		L ER LED (red)	ON	• The module has received abnormal data. • The module is performing loopback.	
L ER LED (red)	ON	• The module has received abnormal data. • The module is performing loopback.					
	OFF	• The module has received normal data. • The module is not performing loopback.					
LINK LED (green)	ON	Linkup in progress					
	OFF	Linkdown in progress					
P2	PORT2 connector for CC-Link IE Field Network (RJ45 connector) Connect an Ethernet cable. (☞ Page 65, Section 6.5) There are no restrictions on the connection order of the cables for the "P1" connector and "P2" connector.						
	<table border="1"> <tr> <td>L ER LED (red)</td> <td>ON</td> <td>(Same as the P1)</td> </tr> <tr> <td></td> <td>OFF</td> <td></td> </tr> </table>		L ER LED (red)	ON	(Same as the P1)		OFF
L ER LED (red)	ON	(Same as the P1)					
	OFF						
<table border="1"> <tr> <td>LINK LED (green)</td> <td>ON</td> <td>(Same as the P1)</td> </tr> <tr> <td></td> <td>OFF</td> <td></td> </tr> </table>		LINK LED (green)	ON	(Same as the P1)		OFF	
LINK LED (green)	ON	(Same as the P1)					
	OFF						
4)	Terminal block for module power supply and FG	A terminal block to connect the module power supply (24VDC) and FG.					
5)	DIN rail hook	A hook to mount a module on a DIN rail					
6)	Connectors for external devices (40 pins)	Connectors for encoders, controllers, and others (For the terminal layouts, refer to ☞ Page 71, Section 6.6.3.)					

Point 

When the phase Z of the encoder is connected to the phase Z pulse input terminal (Zn), a pulse is counted per rotation of the encoder. Therefore, lighting of the LEDs may be missed.

(1) Module status and LED status

The following table lists the correspondence between the module status and the LED status.

Module status	Data link status	LED status				
		PW LED	RUN LED	MODE LED	D LINK LED	ERR. LED
Disconnecting	Disconnection	ON	ON	ON	OFF	OFF
Data link in operation	Data link in operation	ON	ON	ON	ON	OFF
Reserved station specification in progress	Cyclic stop	ON	ON	ON	Flashing	OFF
Link stop	Cyclic stop	ON	ON	ON	Flashing	OFF
Communication error	Cyclic stop	ON	ON	ON	Flashing	OFF
Error	Major	—	ON	OFF	*1	*2
	Moderate	—	ON	ON	*1	*2
Warning	Minor	—	ON	ON	*1	*2
Unit test	In progress	—	ON	ON	Flashing	OFF
	Normal completion	—	ON	ON	OFF	OFF
	Abnormal completion	—	ON	ON	OFF	ON

*1 Either of ON or OFF.

*2 Either of ON, Flashing, or OFF.

*3 When the module is failed, the LED may not turn on.

CHAPTER 3 SPECIFICATIONS

This chapter describes the specifications of the high-speed counter module.

3.1 General Specifications

3

Item	Specifications					
Operating ambient temperature	0 to 55°C					
Storage ambient temperature	-25 to 75°C					
Operating ambient humidity	5 to 95%RF, non-condensing					
Storage ambient humidity						
Vibration resistance	Compliant with JIS B 3502 and IEC 61131-2	Under intermittent vibration	Frequency	Constant acceleration	Half amplitude	
			5 to 8.4Hz	—	3.5mm	
		Under continuous vibration	8.4 to 150Hz	9.8m/s ²	—	
			5 to 8.4Hz	—	1.75mm	
			8.4 to 150Hz	4.9m/s ²	—	
Shock resistance	Compliant with JIS B 3502 and IEC 61131-2 (147m/s ² , 3 times each in X, Y, and Z directions)					
Operating atmosphere	No corrosive gases					
Operating altitude ^{*1}	0 to 2000m					
Installation location	Inside a control panel ^{*2}					
Overvoltage category ^{*3}	II or less					
Pollution degree ^{*4}	2 or less					
Equipment class	Class I					

^{*1} Do not use or store the high-speed counter module under pressure higher than the atmospheric pressure of altitude 0m. Doing so may cause malfunction. When using the high-speed counter module under pressure, please consult your local Mitsubishi representative.

^{*2} If the environment satisfies the operating ambient temperature, operating ambient humidity and other conditions, the module can be used even outside the control panel.

^{*3} This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery within premises. Category II applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for the equipment with the rated voltage of 300V or less is 2500V.

^{*4} This index indicates the degree to which conductive material is generated in terms of the environment in which the equipment is used.

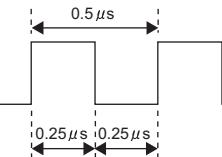
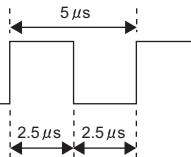
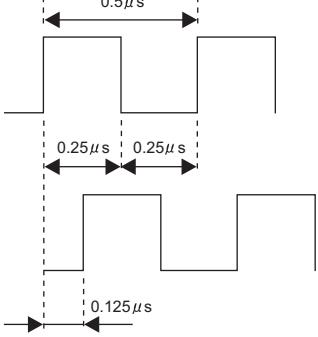
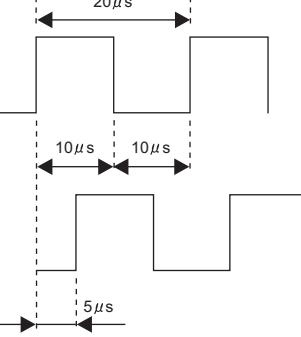
Pollution degree 2 is when only non-conductive pollution occurs. A temporary conductivity caused by condensing must be expected occasionally.

Point 

To use the high-speed counter module complying with the EMC Directive, refer to "EMC and Low Voltage Directives" in this manual. (☞ Page 286, Appendix 5)

3.2 Performance Specifications

The following table shows the performance specifications of the high-speed counter module.

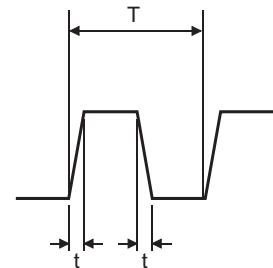
Item	Specifications	
Station type	Remote device station	
Availability of connecting extension module	Connectable (Max. one module)	
Counting speed switch setting ^{*1}	Differential input	DC input
	1 multiple	10kpps/100kpps/200kpps/500kpps/1Mpps/2Mpps 10kpps/100kpps/200kpps
	2 multiples	10kpps/100kpps/200kpps/500kpps/1Mpps/2Mpps/ 4Mpps 10kpps/100kpps/200kpps
	4 multiples	10kpps/100kpps/200kpps/500kpps/1Mpps/2Mpps/ 4Mpps/8Mpps 10kpps/100kpps/200kpps
Number of channels	2 channels	
Count input signal	Differential input	DC input
	Phase	1-phase input (1 multiple/2 multiples), 2-phase input (1 multiple/2 multiples/4 multiples), CW/CCW
	Signal level (ϕ A, ϕ B)	EIA Standards RS-422-A, differential line driver level (AM26LS31 [manufactured by Texas Instruments] or equivalent) 5/24VDC, 4 to 8mA
Counter	Differential input	DC input
	Counting speed (Maximum) ^{*2*3}	8Mpps (4 multiples of 2 phases) 200kpps
	Counting range	32-bit signed binary (-2147483648 to 2147483647)
	Format	Count, subtraction count Linear counter format, ring counter format Preset/replace function, latch counter function
Minimum count pulse width (μ s) (Duty ratio 50%)		
1-phase input (1 multiple/2 multiples), CW/CCW	 (Minimum pulse width in 2 multiples of 1 phase: 0.25μs)	 (Minimum pulse width in 2 multiples of 1 phase: 2.5μs)
2-phase input (1 multiple/2 multiples/4 multiples)	 (Minimum pulse width in 4 multiples of 2 phases: 0.125μs)	 (Minimum pulse width in 4 multiples of 2 phases: 5μs)
Coincidence detection	Comparison range	32-bit signed binary
	Comparison condition	Setting value < Count value Setting value = Count value Setting value > Count value
		Setting value (lower limit value) \leq Count value \leq Setting value (upper limit value)
		Count value < Setting value (lower limit value), Setting value (upper limit value) < Count value
	Interrupt	None

Item		Specifications	
External input	Phase Z	Differential input	DC input
		EIA Standards RS-422-A, differential line driver level (AM26LS31 [manufactured by Texas Instruments] or equivalent): 2 points	5/24VDC, 4 to 8mA: 2 points
	Function	5/24VDC, 7 to 12mA: 2 points	
External output	Latch counter	5/24VDC, 7 to 12mA: 2 points	
	Coincidence output	Transistor (sink type) output: 4 points 5 to 24VDC 0.1A/point, 0.4A/common	
	Measurement item	Pulse width (ON width/OFF width)	
Pulse measurement	Measurement resolution	100ns	
	Measurement points	2 points/channel	
	Number of output points	16 points	
Cam switch	Number of steps per output point	Maximum 16 steps/point	
	Control cycle	0.5ms	
	Difference between each output duration in a channel	Within the output response time of the extension output module	
	Output frequency range	DC and up to 200kHz	
PWM output	Duty ratio	Any ratio (Can be set by 0.1μs)	
	For external device connection	0.3mm ² (22 AWG) (A6CON1 and A6CON4) 0.088 to 0.24mm ² (28 to 24 AWG) (A6CON2)	
	For power supply	Core: 0.5 to 1.5mm ² (20 to 16 AWG)	
Applicable connector for external wiring		A6CON1, A6CON2, A6CON4 (sold separately)	
External power supply		24VDC (20.4 to 26.4VDC) Current consumption: 220mA	
Cyclic transmission	RX/RY points	80 points + 16 points × number of extension modules	
	RWr/RWw points	64 points	
Communication cable		An Ethernet cable that meets the 1000BASE-T standard: Category 5e or higher (double shielded, STP), straight cable	
External dimensions		133mm × 68mm × 50mm	
Weight		0.25kg	
External connection system	Communication part	RJ45 connector	
	Module power supply part	Terminal block for module power supply and FG Tightening torque range for terminal screw (M2.5 screw): 0.5 to 0.6N·m	
Applicable DIN rail		TH35-7.5Fe, TH35-7.5AI (compliant with IEC 60715)	
Applicable solderless terminal	Terminal block for module power supply and FG	TE 0.5-10 (Nichifu Co. Ltd.) [Applicable wire size: 0.5mm ²] TE 0.75-10 (Nichifu Co. Ltd.) [Applicable wire size: 0.75mm ²] TE 1.0-10 (Nichifu Co. Ltd.) [Applicable wire size: 0.9 to 1.0mm ²] TE 1.5-10 (Nichifu Co. Ltd.) [Applicable wire size: 1.25 to 1.5mm ²] AI 0.5-10WH (Phoenix Contact Co. Ltd.) [Applicable wire size: 0.5mm ²] AI 0.75-10GY (Phoenix Contact Co. Ltd.) [Applicable wire size: 0.75mm ²] AI 1-10RD (Phoenix Contact Co. Ltd.) [Applicable wire size: 1.0mm ²] AI 1.5-10BK (Phoenix Contact Co. Ltd.) [Applicable wire size: 1.5mm ²]	

- *1 Counting speed setting can be done using the parameter setting. (☞ Page 80, Section 7.1)
- *2 Note that the count may be done incorrectly by inputting pulses whose phase difference is small between the phase A pulse and phase B pulse. To check the input waveform of the phase A pulse and phase B pulse, or to check phase difference between the phase A pulse and phase B pulse, refer to the following:
☞ Page 30, Section 3.2.1
- *3 The counting speed is affected by the pulse rise/fall time. The applicable counting speed is listed below.
Note that the count may be done incorrectly by counting pulses with long rise/fall time.

Counting speed switch setting	8Mpps	4Mpps	1Mpps	500kpps	200kpps	100kpps	10kpps
Rise/fall time	Both 1- and 2-phase inputs						
$t = 0.125\mu s$	2Mpps	1Mpps	500kpps	200kpps	100kpps	10kpps	
$t = 0.25\mu s$ or less	1Mpps	1Mpps	500kpps	200kpps	100kpps	10kpps	
$t = 0.5\mu s$ or less	—	500kpps	500kpps	200kpps	100kpps	10kpps	
$t = 1.25\mu s$ or less	—	—	200kpps	200kpps	100kpps	10kpps	
$t = 2.5\mu s$ or less	—	—	—	100kpps	100kpps	10kpps	
$t = 25\mu s$ or less	—	—	—	—	10kpps	10kpps	
$t = 500\mu s$	—	—	—	—	—	500pps	

*Counting speed = $1/T$ (pps)



3.2.1 The input waveform and the phase difference between phase A pulse and phase B pulse

The count may be done incorrectly by inputting pulses whose phase difference is small between the phase A pulse and phase B pulse in 2-phase input.

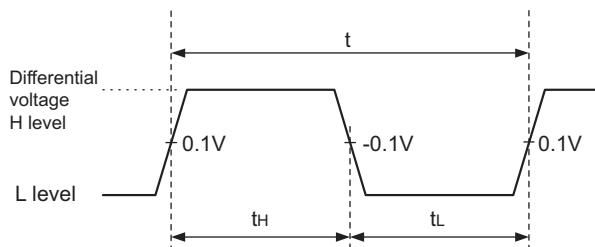
The following figures show the pulse waveform to be input and the phase difference between the phase A pulse and phase B pulse. (Though the following are the cases for the differential input, they are also applied to the DC input.)

Though the following are the pulse waveform to be input and the phase difference measured at the maximum counting speed of each pulse input condition, they are also applied to the case measured at under the maximum counting speed.

(1) Input waveform in 1-phase input

Input pulse waveform in 1-phase input must satisfy the condition shown below (the duty ratio is 50%).

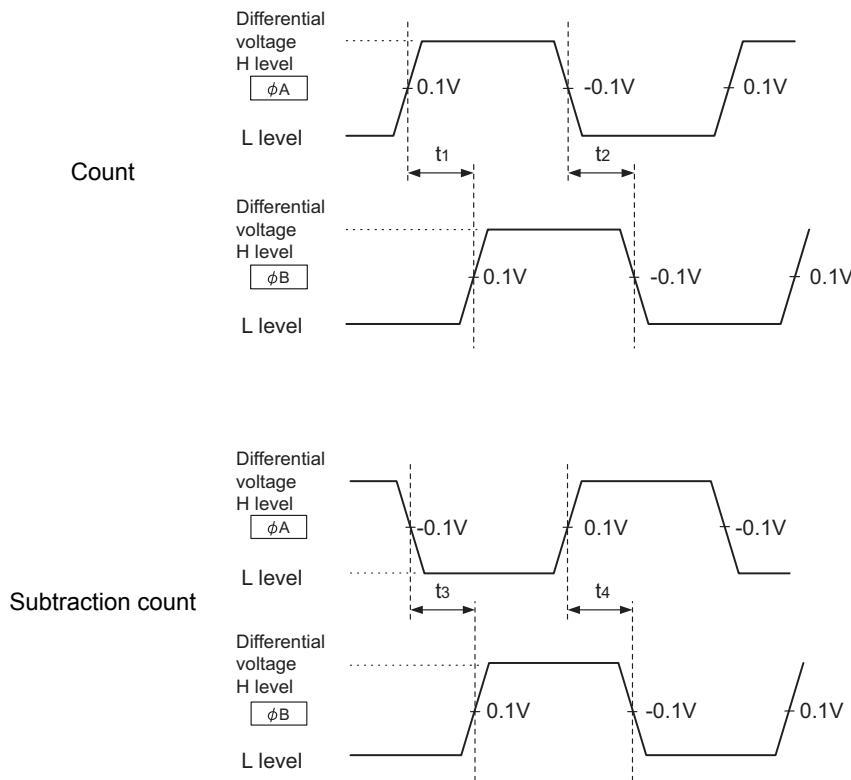
$$t (= t_H + t_L) \geq 0.5\mu s$$
$$t_H, t_L \geq 0.25\mu s (= 0.5 \times t)$$



(2) Phase difference in 2-phase input

Input pulse waveform in 2-phase input must satisfy the above condition (the condition required for 1-phase input) and the conditions shown below.

$$t_1, t_2, t_3, t_4 \geq 0.125\mu\text{s} (= 0.25 \times t)$$



3.3 Calculating Current Consumption

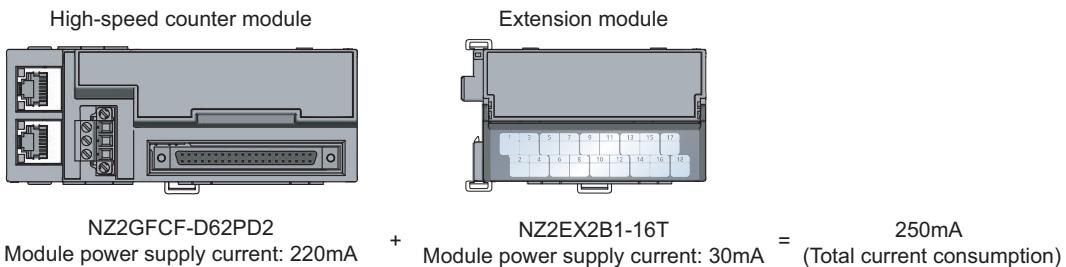
The total current consumption of the modules is calculated by summing the module power supply current in the main module and extension module.

The power supply current in the extension module must be within 30mA.

For the value of the module power supply current, refer to the specifications of each module.

- Performance specifications of the high-speed counter module (☞ Page 27, Section 3.2)
- Performance specifications of extension I/O module (☞ CC-Link IE Field Network Remote I/O Module User's Manual)

The value of the module power supply current in the extension module described in the specifications is the value of the module power supply current supplied from the main module.



3.4 Function List

The following table lists the functions of the high-speed counter module.

Function name	Description	Operation mode ^{*1}	Reference
Linear counter function	This function counts pulses between -2147483648 and 2147483647, and detects an overflow/underflow when the count value is outside the range.		Page 95, Section 8.2.1
Ring counter function	This function repeatedly counts pulses between the upper limit value and lower limit value of the ring counter.		Page 97, Section 8.2.2
Comparison output function	This function compares the count value with the preset comparison condition, and outputs ON/OFF signals when they match.		Page 102, Section 8.3
Coincidence output function	This function compares the present count value with the preset coincidence detection point or a detection area and outputs ON/OFF signals from the coincidence output terminal when they match.		Page 103, Section 8.3.2
Preset/replace (at coincidence output) function	This function replaces the count value with any preset numerical value at the rising edge of Coincidence output 1 and 2.		Page 114, Section 8.3.3
Cam switch function	This function compares the count value with the preset output status (ON/OFF address) of the coincidence output, and outputs ON/OFF signals from the extension output module when they match. The points for ON/OFF switch can be used up to 16 points. An extension output module is required for using this function.	Normal mode	Page 117, Section 8.3.4
Preset/replace function	This function replaces the count value with any preset numerical value. This function can be used with either of the following. <ul style="list-style-type: none">• CH□ Preset/replace command (RY21, RY39)• CH□ Phase Z input terminal (Z1, Z2) of the connector for external devices		Page 122, Section 8.4
Latch counter function	This function acquires the count value and stores it in the remote register.		—
Latch counter function by latch counter input terminal	This function stores the count value in the remote register. <ul style="list-style-type: none">• This function uses CH□ Latch counter input terminal (LATCH1, LATCH2) of the connector for external devices.		Page 127, Section 8.5
Latch counter function by counter function selection	This function stores the count value in the remote register. This function can be used with either of the following. <ul style="list-style-type: none">• CH□ Selected counter function start command (RY25, RY3D)• CH□ Function input terminal (FUNC1, FUNC2) of the connector for external devices		Page 133, Section 8.8

Function name	Description	Operation mode ^{*1}	Reference
Counter function selection	This function executes the counter function selection using both the program and CH□ Function input terminal (FUNC1, FUNC2) of the connector for external devices, or using either of them.	Normal mode	Page 129, Section 8.6
Count disable function	This function stops counting pulses while CH□ Count enable command (RY24, RY3C) is on.		Page 131, Section 8.7
Latch counter function	This function acquires the count value and stores it in the remote register.		Page 133, Section 8.8
Sampling counter function	This function counts pulses that are input during the preset sampling period.		Page 136, Section 8.9
Periodic pulse counter function	This function stores the present value and difference value to the corresponding remote registers by the preset cycle time.		Page 139, Section 8.10
Count disable/preset/replace function	According to the status change of CH□ Function input terminal (FUNC1, FUNC2) of the connector for external devices, this function executes the count disable function and preset/replace function without switching the functions.		Page 142, Section 8.11
Latch counter/preset/replace function	According to the status change of CH□ Function input terminal (FUNC1, FUNC2) of the connector for external devices, this function executes the latch counter function and preset/replace function without switching the functions.		Page 145, Section 8.12
Frequency measurement function	This function counts the pulses of the pulse input terminals in phase A and B, and automatically calculates the frequency.	Frequency measurement mode	Page 148, Section 8.13
Rotation speed measurement function	This function counts the pulses of the pulse input terminals in phase A and B, and automatically calculates the rotation speed.	Rotation speed measurement mode	Page 152, Section 8.14
Pulse measurement function	This function measures CH□ Function input terminal (FUNC1, FUNC2) or CH□ Latch counter input terminal (LATCH1, LATCH2) of the connector for external devices, and calculates the ON width.	Pulse measurement mode	Page 156, Section 8.15
PWM output function	This function outputs the specified PWM waveform from any coincidence output 1 to 4 terminals (EQU1 to EQU4).	PWM output mode	Page 160, Section 8.16
Output HOLD/CLEAR setting function	This function sets the output status of the extension output module (Y0 to YF) used as the output of Coincidence output (EQU1 to EQU4) and the cam switch function to HOLD or CLEAR.	Common to all modes	Page 167, Section 8.17
Cyclic data update watch function	This function monitors the cyclic data update interval. When the cyclic transmission remains to be stopped over the set watch time, this function holds or clears the value which is output just before.		Page 168, Section 8.18
Error notification function	When a moderate error or a major error occurs in the high-speed counter module, this function notifies the master station of the error using the remote register and the remote input signal.		Page 169, Section 8.19
Function at the extension module installation	One extension I/O module can be connected to one high-speed counter module. The cam switch function can be used by connecting the extension I/O module. In addition, functions unique to the extension I/O module can be used.		Page 172, Section 8.20
CC-Link IE Field Network diagnostic function	With this function, whether any network error occurs or not can be checked through GX Works2 connected to the CPU module.		Page 175, Section 8.21

*1 The operation mode can be set in the parameter setting. For details, refer to the following.

 Page 80, Section 7.1

3.5 List of Remote I/O Signals

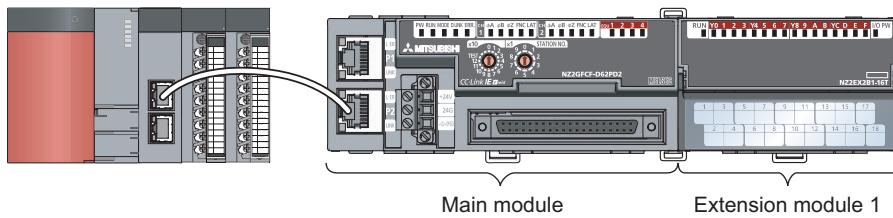
This section lists I/O signals for a master/local module.

In the example of the I/O signal assignment described in this section, the remote I/O signals of the main module are assigned to the I/O numbers of RX0 to RX4F and RY0 to RY4F.

Remote input (RX) indicates the input signal from the high-speed counter module to the master/local module.

Remote output (RY) indicates the output signal from the master/local module to the high-speed counter module.

The remote I/O signals of the main module and extension module are assigned as shown below.



Module	Remote input (RX)	Remote output (RY)
Main module	RX0 to RX4F	RY0 to RY4F
Extension module 1	RX50 to RX5F	RY50 to RY5F

For details on the remote I/O signals, refer to the following.

☞ Page 236, Appendix 1

Module type	Remote input signal direction: High-speed counter module → Master/local module		Remote output signal direction: Master/local module → High-speed counter module	
	Device number	Description	Device number	Description
Main module	RX0	Use prohibited	RY0	Use prohibited
	RX1	Use prohibited	RY1	Use prohibited
	RX2	Use prohibited	RY2	Use prohibited
	RX3	Use prohibited	RY3	Use prohibited
	RX4	Use prohibited	RY4	Use prohibited
	RX5	Use prohibited	RY5	Use prohibited
	RX6	Use prohibited	RY6	Use prohibited
	RX7	Warning status flag	RY7	Use prohibited
	RX8	Initial data processing request flag	RY8	Initial data processing completion flag
	RX9	Initial data setting completion flag	RY9	Initial data setting request flag
	RXA	Error status flag	RYA	Use prohibited
	RXB	Remote READY	RYB	Use prohibited
	RXC	Use prohibited	RYC	Use prohibited
	RXD	Use prohibited	RYD	Use prohibited
	RXE	Use prohibited	RYE	Use prohibited
	RXF	Use prohibited	RYF	Use prohibited

Module type	Remote input signal direction: High-speed counter module → Master/local module		Remote output signal direction: Master/local module → High-speed counter module	
	Device number	Description	Device number	Description
Main module	RX10	Coincidence output 1	RY10	Reset command (Coincidence output 1)
	RX11	Coincidence output 2	RY11	Reset command (Coincidence output 2)
	RX12	Coincidence output 3	RY12	Reset command (Coincidence output 3)
	RX13	Coincidence output 4	RY13	Reset command (Coincidence output 4)
	RX14	Setting change completed (Coincidence output 1)	RY14	Setting change request (Coincidence output 1)
	RX15	Setting change completed (Coincidence output 2)	RY15	Setting change request (Coincidence output 2)
	RX16	Setting change completed (Coincidence output 3)	RY16	Setting change request (Coincidence output 3)
	RX17	Setting change completed (Coincidence output 4)	RY17	Setting change request (Coincidence output 4)
	RX18	Use prohibited	RY18	Use prohibited
	RX19	Use prohibited	RY19	Use prohibited
	RX1A	Use prohibited	RY1A	Use prohibited
	RX1B	Use prohibited	RY1B	Use prohibited
	RX1C	Use prohibited	RY1C	Use prohibited
	RX1D	Use prohibited	RY1D	Use prohibited
	RX1E	Use prohibited	RY1E	Use prohibited
	RX1F	External power supply monitor state flag (for extension output module)	RY1F	External power supply monitor request flag (for extension output module)
	RX20	Use prohibited	RY20	CH1 Coincidence output enable command
	RX21	CH1 Preset/replace completion	RY21	CH1 Preset/replace command
	RX22	Use prohibited	RY22	CH1 Count down command
	RX23	CH1 External preset/replace (Z Phase) request detection	RY23	CH1 External preset/replace (Z Phase) request detection reset command
	RX24	Use prohibited	RY24	CH1 Count enable command
	RX25	CH1 Counter function detection	RY25	CH1 Selected counter function start command
	RX26	CH1 Cam switch execute/PWM output	RY26	CH1 Cam switch execute command/PWM output start command
	RX27	CH1 Setting change completed (Sampling counter/Periodic pulse counter)	RY27	CH1 Setting change request (Sampling counter/Periodic pulse counter)
	RX28	CH1 Update flag reset completed (Latch count value/Sampling count value/Periodic pulse count value)	RY28	CH1 Update flag reset command (Latch count value/Sampling count value/Periodic pulse count value)
	RX29	CH1 Update flag (Latch count value/Sampling count value/Periodic pulse count value)	RY29	Use prohibited
	RX2A	CH1 Latch count value update flag reset completed (Latch counter input terminal)	RY2A	CH1 Latch count value update flag reset command (Latch counter input terminal)
	RX2B	CH1 Latch count value update flag (Latch counter input terminal)	RY2B	Use prohibited
	RX2C	CH1 Update flag reset completed (Measured frequency value/Measured rotation speed value)	RY2C	CH1 Update flag reset command (Measured frequency value/Measured rotation speed value)
	RX2D	CH1 Update flag (Measured frequency value/Measured rotation speed value)	RY2D	Use prohibited
	RX2E	Use prohibited	RY2E	Use prohibited
	RX2F	Use prohibited	RY2F	Use prohibited

Module type	Remote input signal direction: High-speed counter module → Master/local module		Remote output signal direction: Master/local module → High-speed counter module	
	Device number	Description	Device number	Description
Main module	RX30	Use prohibited	RY30	CH1 Pulse measurement start command (Function input terminal)
	RX31	CH1 Measured pulse value update flag reset completed (Function input terminal)	RY31	CH1 Measured pulse value update flag reset command (Function input terminal)
	RX32	CH1 Measured pulse value update flag (Function input terminal)	RY32	CH1 Pulse measurement start command (Latch counter input terminal)
	RX33	CH1 Measured pulse value update flag reset completed (Latch counter input terminal)	RY33	CH1 Measured pulse value update flag reset command (Latch counter input terminal)
	RX34	CH1 Measured pulse value update flag (Latch counter input terminal)	RY34	Use prohibited
	RX35	CH1 ON width setting change completed (PWM output)	RY35	CH1 ON width setting change request (PWM output)
	RX36	CH1 Error status	RY36	CH1 Error reset command
	RX37	CH1 Warning status	RY37	Use prohibited
	RX38	Use prohibited	RY38	CH2 Coincidence output enable command
	RX39	CH2 Preset/replace completion	RY39	CH2 Preset/replace command
	RX3A	Use prohibited	RY3A	CH2 Count down command
	RX3B	CH2 External preset/replace (Z Phase) request detection	RY3B	CH2 External preset/replace (Z Phase) request detection reset command
	RX3C	Use prohibited	RY3C	CH2 Count enable command
	RX3D	CH2 Counter function detection	RY3D	CH2 Selected counter function start command
	RX3E	CH2 Cam switch execute/PWM output	RY3E	CH2 Cam switch execute command/PWM output start command
	RX3F	CH2 Setting change completed (Sampling counter/Periodic pulse counter)	RY3F	CH2 Setting change request (Sampling counter/Periodic pulse counter)
	RX40	CH2 Update flag reset completed (Latch count value/Sampling count value/Periodic pulse count value)	RY40	CH2 Update flag reset command (Latch count value/Sampling count value/Periodic pulse count value)
	RX41	CH2 Update flag (Latch count value/Sampling count value/Periodic pulse count value)	RY41	Use prohibited
	RX42	CH2 Latch count value update flag reset completed (Latch counter input terminal)	RY42	CH2 Latch count value update flag reset command (Latch counter input terminal)
	RX43	CH2 Latch count value update flag (Latch counter input terminal)	RY43	Use prohibited
	RX44	CH2 Update flag reset completed (Measured frequency value/Measured rotation speed value)	RY44	CH2 Update flag reset command (Measured frequency value/Measured rotation speed value)
	RX45	CH2 Update flag (Measured frequency value/Measured rotation speed value)	RY45	Use prohibited
	RX46	Use prohibited	RY46	Use prohibited
	RX47	Use prohibited	RY47	Use prohibited

Module type	Remote input signal direction: High-speed counter module → Master/local module		Remote output signal direction: Master/local module → High-speed counter module	
	Device number	Description	Device number	Description
Main module	RX48	Use prohibited	RY48	CH2 Pulse measurement start command (Function input terminal)
	RX49	CH2 Measured pulse value update flag reset completed (Function input terminal)	RY49	CH2 Measured pulse value update flag reset command (Function input terminal)
	RX4A	CH2 Measured pulse value update flag (Function input terminal)	RY4A	CH2 Pulse measurement start command (Latch counter input terminal)
	RX4B	CH2 Measured pulse value update flag reset completed (Latch counter input terminal)	RY4B	CH2 Measured pulse value update flag reset command (Latch counter input terminal)
	RX4C	CH2 Measured pulse value update flag (Latch counter input terminal)	RY4C	Use prohibited
	RX4D	CH2 ON width setting change completed (PWM output)	RY4D	CH2 ON width setting change request (PWM output)
	RX4E	CH2 Error status	RY4E	CH2 Error reset command
	RX4F	CH2 Warning status	RY4F	Use prohibited
Extension module 1	RX50 to RX5F	Remote input (RX) of the connected extension module is assigned.	RY50 to RY5F	Remote output (RY) of the connected extension module is assigned.



Do not use any "Use prohibited" remote I/O signals. If any of the signals are used, correct operation of the module cannot be guaranteed.

(1) Remote I/O signal of the extension module

The remote I/O signal differs depending on the model of the extension module.

- Extension I/O module
- Refer to the following.

CC-Link IE Field Network Remote I/O Module User's Manual

3.6 List of Remote Register

This section lists remote registers for a master/local module.

In the example of the remote register assignment described in this section, the remote registers of the main module are assigned to the remote registers of RWr0 to RWr3F and RWw0 to RWw3F.

The remote registers are assigned per station regardless of the main module or the extension module.

Remote register (RWr) is the information input from the high-speed counter module to the master/local module.

Remote register (RWw) is the information output from the master/local module to the high-speed counter module.

For details on the remote register, refer to the following.

☞ Page 255, Appendix 2

Remote register (RWr) signal direction: High-speed counter module → Master/local module		Remote register (RWw) signal direction: Master/local module → High-speed counter module	
Device number	Description	Device number	Description
RWr0	Counter value greater/smaller signal	RWw0	Point setting (Coincidence output 1)/ Lower limit value setting (Coincidence output 1)
RWr1	EQU1 to EQU4 terminal status	RWw1	
RWr2	Cam switch output signal	RWw2	Upper limit value setting (Coincidence output 1)
RWr3	Cam switch output terminal status	RWw3	
RWr4	Use prohibited	RWw4	Point setting (Coincidence output 2)/ Lower limit value setting (Coincidence output 2)
RWr5	Use prohibited	RWw5	
RWr6	Use prohibited	RWw6	Upper limit value setting (Coincidence output 2)
RWr7	Use prohibited	RWw7	
RWr8	Use prohibited	RWw8	Point setting (Coincidence output 3)/ Lower limit value setting (Coincidence output 3)
RWr9	Use prohibited	RWw9	
RWrA	Use prohibited	RWwA	Upper limit value setting (Coincidence output 3)
RWrB	Use prohibited	RWwB	
RWrC	Use prohibited	RWwC	Point setting (Coincidence output 4)/ Lower limit value setting (Coincidence output 4)
RWrD	Use prohibited	RWwD	
RWrE	Use prohibited	RWwE	Upper limit value setting (Coincidence output 4)
RWrF	Use prohibited	RWwF	
RWr10	CH1 Present value	RWw10	CH1 Ring counter lower limit value
RWr11		RWw11	
RWr12	CH1 Latch count value/Sampling count value/Periodic pulse count, difference value	RWw12	CH1 Ring counter upper limit value
RWr13		RWw13	
RWr14	CH1 Periodic pulse count, present value	RWw14	CH1 Preset value setting
RWr15		RWw15	
RWr16	CH1 Periodic pulse count value update check	RWw16	CH1 Time unit setting (Sampling counter/Periodic pulse counter)
RWr17		RWw17	CH1 Cycle setting (Sampling counter/Periodic pulse counter)
RWr18	CH1 Latch count value (Latch counter input terminal)	RWw18	CH1 Time unit setting (Frequency measurement/Rotation speed measurement)
RWr19		RWw19	CH1 Moving average count (Frequency measurement/Rotation speed measurement)
RWr1A	CH1 Measured frequency value/Measured rotation speed value	RWw1A	CH1 Number of pulses per rotation
RWr1B		RWw1B	
RWr1C	CH1 Measured pulse value (Function input terminal)	RWw1C	Use prohibited
RWr1D		RWw1D	CH1 PWM output assignment setting

Remote register (RW _r) signal direction: High-speed counter module → Master/local module		Remote register (RW _w) signal direction: Master/local module → High-speed counter module	
Device number	Description	Device number	Description
RWr1E	CH1 Measured pulse value (Latch counter input terminal)	RWw1E	CH1 ON width setting (PWM output)
RWr1F		RWw1F	
RWr20	CH1 Status	RWw20	CH1 Cycle setting (PWM output)
RWr21	CH1 External input status	RWw21	
RWr22	CH1 Latest error code	RWw22	Use prohibited
RWr23	CH1 Latest warning code	RWw23	Use prohibited
RWr24	Use prohibited	RWw24	Use prohibited
RWr25	Use prohibited	RWw25	Use prohibited
RWr26	Use prohibited	RWw26	Use prohibited
RWr27	Use prohibited	RWw27	Use prohibited
RWr28	CH2 Present value	RWw28	CH2 Ring counter lower limit value
RWr29		RWw29	
RWr2A	CH2 Latch count value/Sampling count value/ Periodic pulse count, difference value	RWw2A	CH2 Ring counter upper limit value
RWr2B		RWw2B	
RWr2C	CH2 Periodic pulse count, present value	RWw2C	CH2 Preset value setting
RWr2D		RWw2D	
RWr2E	CH2 Periodic pulse count value update check	RWw2E	CH2 Time unit setting (Sampling counter/Periodic pulse counter)
RWr2F		RWw2F	CH2 Cycle setting (Sampling counter/Periodic pulse counter)
RWr30	CH2 Latch count value (Latch counter input terminal)	RWw30	CH2 Time unit setting (Frequency measurement/Rotation speed measurement)
RWr31		RWw31	CH2 Moving average count (Frequency measurement/Rotation speed measurement)
RWr32	CH2 Measured frequency value/ Measured rotation speed value	RWw32	CH2 Number of pulses per rotation
RWr33		RWw33	
RWr34	CH2 Measured pulse value (Function input terminal)	RWw34	Use prohibited
RWr35		RWw35	CH2 PWM output assignment setting
RWr36	CH2 Measured pulse value (Latch counter input terminal)	RWw36	CH2 ON width setting (PWM output)
RWr37		RWw37	
RWr38	CH2 Status	RWw38	CH2 Cycle setting (PWM output)
RWr39	CH2 External input status	RWw39	
RWr3A	CH2 Latest error code	RWw3A	Use prohibited
RWr3B	CH2 Latest warning code	RWw3B	Use prohibited
RWr3C	Use prohibited	RWw3C	Use prohibited
RWr3D	Use prohibited	RWw3D	Use prohibited
RWr3E	Use prohibited	RWw3E	Use prohibited
RWr3F	Use prohibited	RWw3F	Use prohibited

Point

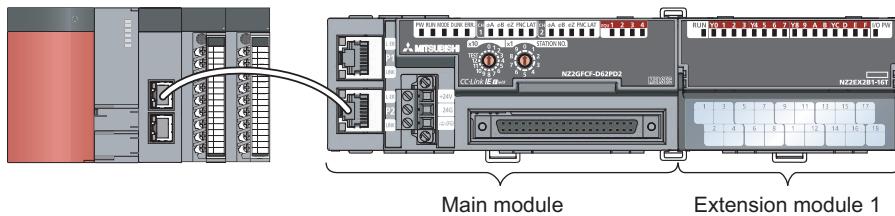
Do not read or write the data to/from any "Use prohibited" remote registers. If the data is read or written from/to any of the registers, correct operation of the module cannot be guaranteed.

The remote register information is not stored in the nonvolatile memory of the high-speed counter module. Thus, the remote register information is initialized by turning off then on the power supply of the high-speed counter module.

3.7 List of Remote Buffer Memory

This section lists remote buffer memory areas of the high-speed counter module.

The remote buffer memory areas of the main module and extension module are assigned as shown below.



Ex. Example of the remote buffer memory in the manual

Coincidence output comparison condition setting (address: 0102H)
 Setting item Address of a high-speed counter module

For details on the remote buffer memory, refer to the following.

- Details of Remote Buffer Memory Addresses (Page 267, Appendix 3)

For details on the remote buffer memory of the connected extension module, refer to the following.

- User's manual for the connected extension module

O: Available ×: Unavailable

Buffer memory address		Area	Description	Access method	
Decimal	Hexadecimal			CC IE Field configuration of GX Works2	REMFR instruction, REMTO instruction ^{*1}
0 to 255	0000 _H to 00FF _H	Parameter area	Station-based parameter data	O ^{*2}	O
256 to 511	0100 _H to 01FF _H		Module-based parameter data		
512 to 767	0200 _H to 02FF _H		Main module		
768 to 1279	0300 _H to 04FF _H		Extension module 1		
1280 to 1535	0500 _H to 05FF _H	Monitoring area	System area	×	O
1536 to 1791	0600 _H to 06FF _H		Module-based monitoring data		
1792 to 2047	0700 _H to 07FF _H		Main module		
2048 to 2559	0800 _H to 09FF _H		Extension module 1		
2560 to 4095	0A00 _H to 0FFF _H	Error history area	System area	O ^{*2}	O
4096 to 4351	1000 _H to 10FF _H	Module control data area	Station-based error history data	×	O
4352 to 4607	1100 _H to 11FF _H		Station-based control data		
4608 to 4863	1200 _H to 12FF _H		Module-based control data		
4864 to 5375	1300 _H to 14FF _H		System area		
5376 to 8191	1500 _H to 1FFF _H	Extended parameter area	Extension module 1	×	O
			Cam switch function parameter data		

*1 For the REMFR and REMTO instructions, refer to the following.

 User's manual for the master/local module used

*2 For the access method, refer to the following.

• Parameter area ( Page 80, Section 7.1)

• Error history area ( Page 205, Section 11.1)

Point

Do not access the system area using the REMFR or REMTO instruction. Doing so may cause the module to malfunction.

(1) Parameter area (address: 0000_H to $04FF_H$)

For the parameter area, parameters can be set using the CC IE Field configuration of GX Works2 or using the REMTO instruction.

The parameter in the parameter area is backed up to the nonvolatile memory.

The parameter backed up to the nonvolatile memory is read to the parameter area when the module power supply is turned off then on or the module returns from remote reset.

If the parameter is written from the parameter setting of the CC IE Field configuration of GX Works2, it is also written to the nonvolatile memory at that time. When the parameter is written using the REMTO instruction, it is written to the nonvolatile memory when Initial data setting request flag (RY9) is turned off then on. At this time, the parameter is written to the nonvolatile memory even though it is incorrect. When the power supply is turned off then on with an incorrect parameter written, the incorrect parameter is read from the nonvolatile memory and an error code is stored to CH□ Latest error code (RWr22, RWr3A). Take corrective action according to the error code list. ( Page 208, Section 11.2)

Type	Address		Description	Default ^{*1}	Read/ Write ^{*2}
	Decimal	Hexadecimal			
Station-based parameter data	0	0000_H	System area	—	—
	1	0001_H	Input response time setting	0005_H	R/W
	2	0002_H	Output HOLD/CLEAR setting	0000_H	R/W
	3	0003_H	Cyclic data update watch time setting	0	R/W
	4 to 255	0004_H to $00FF_H$	System area	—	—
Module-based parameter data (main module)	256	0100_H	Comparison output setting	0	R/W
	257	0101_H	Coincidence output channel assignment setting	0000_H	R/W
	258	0102_H	Coincidence output comparison condition setting	0000_H	R/W
	259	0103_H	Preset/replace setting at coincidence output	0000_H	R/W
	260	0104_H	Cam switch output unit assignment setting	0	R/W
	261	0105_H	Cam switch output channel assignment setting	0000_H	R/W
	262 to 287	0106_H to $011F_H$	System area	—	—
	288	0120_H	CH1 Operation mode setting	0	R/W
	289	0121_H	CH1 Count source selection	0	R/W
	290	0122_H	CH1 Pulse input mode	0	R/W
	291	0123_H	CH1 Counting speed setting	0	R/W
	292	0124_H	CH1 Counter format	0	R/W
	293	0125_H	CH1 Phase Z setting	0000_H	R/W
	294	0126_H	CH1 Counter function selection	0	R/W
	295	0127_H	CH1 Function input logic setting	0	R/W

Type	Address		Description	Default*1	Read/ Write*2
	Decimal	Hexadecimal			
Module-based parameter data (main module)	296	0128 _H	CH1 Latch counter input logic setting	0	R/W
	297	0129 _H	CH1 External control input response time setting	002A _H	R/W
	298	012A _H	CH1 Pulse measurement setting (Function input terminal)	0	R/W
	299	012B _H	CH1 Pulse measurement setting (Latch counter input terminal)	0	R/W
	300 to 319	012C _H to 013F _H	System area	—	—
	320	0140 _H	CH2 Operation mode setting	0	R/W
	321	0141 _H	CH2 Count source selection	0	R/W
	322	0142 _H	CH2 Pulse input mode	0	R/W
	323	0143 _H	CH2 Counting speed setting	0	R/W
	324	0144 _H	CH2 Counter format	0	R/W
	325	0145 _H	CH2 Phase Z setting	0000 _H	R/W
	326	0146 _H	CH2 Counter function selection	0	R/W
	327	0147 _H	CH2 Function input logic setting	0	R/W
	328	0148 _H	CH2 Latch counter input logic setting	0	R/W
	329	0149 _H	CH2 External control input response time setting	002A _H	R/W
	330	014A _H	CH2 Pulse measurement setting (Function input terminal)	0	R/W
	331	014B _H	CH2 Pulse measurement setting (Latch counter input terminal)	0	R/W
	332 to 511	014C _H to 01FF _H	System area	—	—
Module-based parameter data (extension module 1)	512 to 767	0200 _H to 02FF _H	The remote buffer memory of the connected extension module is assigned.	—	—
—	768 to 1279	0300 _H to 04FF _H	System area	—	—

*1 This is the value at default or initialization by Parameter area initialization command (address: 1002_H).

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable

Point

To activate the parameter data, turn off then on Initial data setting request flag (RY9). Writing the parameter data to the parameter area does not activate the parameter data.

(a) Parameter area of the extension module

The remote buffer memory differs depending on the model of the extension module.

- Extension input module (NZ2EX2B1-16D)

Address		Description	Default ^{*1}	Read/ Write ^{*2}
Decimal	Hexadecimal			
512	0200 _H	Extension module identification code	0000 _H	R/W
513 to 767	0201 _H to 02FF _H	System area	—	—

*1 This is the value at default or initialization by Parameter area initialization command (address: 1002_H).

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable

- Extension output module (NZ2EX2B1-16T)

Address		Description	Default ^{*1}	Read/ Write ^{*2}
Decimal	Hexadecimal			
512	0200 _H	Extension module identification code	0000 _H	R/W
513	0201 _H	System area	—	—
514	0202 _H	Number of ON times integration function enable	0000 _H	R/W
515 to 767	0203 _H to 02FF _H	System area	—	—

*1 This is the value at default or initialization by Parameter area initialization command (address: 1002_H).

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable

(2) Monitoring area (address: 0500_H to 09FF_H)

Type	Address		Name	Default ^{*1}	Read/ Write ^{*2}
	Decimal	Hexadecimal			
Station-based monitoring data	1280 to 1535	0500 _H to 05FF _H	System area	—	—
Module-based monitoring data (main module)	1536	0600 _H	Channel assignment (Coincidence output 1 to 4)	0000 _H	R
	1537 to 1567	0601 _H to 061F _H	System area	—	—
	1568	0620 _H	CH1 Operation mode	0	R
	1569	0621 _H	CH1 Selected counter function	0	R
	1570 to 1599	0622 _H to 063F _H	System area	—	—
	1600	0640 _H	CH2 Operation mode	0	R
	1601	0641 _H	CH2 Selected counter function	0	R
	1602 to 1791	0642 _H to 06FF _H	System area	—	—
Module-based monitoring data (extension module 1)	1792 to 2047	0700 _H to 07FF _H	The remote buffer memory of the connected extension module is assigned.	—	—
—	2048 to 2559	0800 _H to 09FF _H	System area	—	—

*1 This is the value for when the module power supply is turned off then on or at the remote reset.

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable

(a) Monitoring area of the extension module

The remote buffer memory differs depending on the model of the extension module.

- Extension input module (NZ2EX2B1-16D)

Address		Description	Default ^{*1}	Read/ Write ^{*2}
Decimal	Hexadecimal			
1792	0700 _H	Extension module identification code	0000 _H	R
1793 to 2047	0701 _H to 07FF _H	System area	—	—

*1 This is the value for when the module power supply is turned off then on or at the remote reset.

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable

- Extension output module (NZ2EX2B1-16T)

Address		Description	Default ^{*1}	Read/ Write ^{*2}
Decimal	Hexadecimal			
1792	0700 _H	Extension module identification code	0000 _H	R
1793 to 1807	0701 _H to 070F _H	System area	—	—
1808 to 1809	0710 _H to 0711 _H	Number of ON times integration value	Y0	0 R
1810 to 1811	0712 _H to 0713 _H		Y1	0 R
1812 to 1813	0714 _H to 0715 _H		Y2	0 R
1814 to 1815	0716 _H to 0717 _H		Y3	0 R
1816 to 1817	0718 _H to 0719 _H		Y4	0 R
1818 to 1819	071A _H to 071B _H		Y5	0 R
1820 to 1821	071C _H to 071D _H		Y6	0 R
1822 to 1823	071E _H to 071F _H		Y7	0 R
1824 to 1825	0720 _H to 0721 _H		Y8	0 R
1826 to 1827	0722 _H to 0723 _H		Y9	0 R
1828 to 1829	0724 _H to 0725 _H		YA	0 R
1830 to 1831	0726 _H to 0727 _H		YB	0 R
1832 to 1833	0728 _H to 0729 _H		YC	0 R
1834 to 1835	072A _H to 072B _H		YD	0 R
1836 to 1837	072C _H to 072D _H		YE	0 R
1838 to 1839	072E _H to 072F _H		YF	0 R
1840 to 2047	0730 _H to 07FF _H	System area	—	—

*1 This is the value for when the module power supply is turned off then on or at the remote reset.

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable

Point

Number of ON times integration value Y0 to Number of ON times integration value YF are written to a nonvolatile memory in the specified cycle.

(3) Error history area (address: 0A00_H to 0FFF_H)

Type	Address		Description	Default ^{*1}	Read/ Write ^{*2}	
	Decimal	Hexadecimal				
Station-based error history data	2560	0A00 _H	Error history 1	Error code	0000 _H	R
	2561	0A01 _H		Order of generation	0000 _H	R
	2562	0A02 _H		[Error time] First two digits of the year/Last two digits of the year	0000 _H	R
	2563	0A03 _H		[Error time] Month/Day	0000 _H	R
	2564	0A04 _H		[Error time] Hour/Minute	0000 _H	R
	2565	0A05 _H		[Error time] Second/00 _H (Fixed)	0000 _H	R
	2566	0A06 _H		Error code details 1	0000 _H	R
	2567	0A07 _H		Error code details 2	0000 _H	R
	2568	0A08 _H		Error code details 3	0000 _H	R
	2569	0A09 _H		Error code details 4	0000 _H	R
	2570	0A0A _H		Error code details 5	0000 _H	R
	2571	0A0B _H		Error code details 6	0000 _H	R
	2572	0A0C _H		Error code details 7	0000 _H	R
	2573	0A0D _H		Error code details 8	0000 _H	R
	2574	0A0E _H		Error code details 9	0000 _H	R
	2575	0A0F _H		Error code details 10	0000 _H	R
Station-based error history data	2576 to 2591	0A10 _H to 0A1F _H	Error history 2	Same as Error history 1.	—	—
	2592 to 2607	0A20 _H to 0A2F _H	Error history 3	Same as Error history 1.	—	—
	2608 to 2623	0A30 _H to 0A3F _H	Error history 4	Same as Error history 1.	—	—
	2624 to 2639	0A40 _H to 0A4F _H	Error history 5	Same as Error history 1.	—	—
	2640 to 2655	0A50 _H to 0A5F _H	Error history 6	Same as Error history 1.	—	—
	2656 to 2671	0A60 _H to 0A6F _H	Error history 7	Same as Error history 1.	—	—
	2672 to 2687	0A70 _H to 0A7F _H	Error history 8	Same as Error history 1.	—	—
	2688 to 2703	0A80 _H to 0A8F _H	Error history 9	Same as Error history 1.	—	—
	2704 to 2719	0A90 _H to 0A9F _H	Error history 10	Same as Error history 1.	—	—
	2720 to 2735	0AA0 _H to 0AAF _H	Error history 11	Same as Error history 1.	—	—
	2736 to 2751	0AB0 _H to 0ABF _H	Error history 12	Same as Error history 1.	—	—
	2752 to 2767	0AC0 _H to 0ACF _H	Error history 13	Same as Error history 1.	—	—
	2768 to 2783	0AD0 _H to 0ADF _H	Error history 14	Same as Error history 1.	—	—
	2784 to 2799	0AE0 _H to 0AEF _H	Error history 15	Same as Error history 1.	—	—
	2800 to 4095	0AF0 _H to 0FFF _H	System area	—	—	—

*1 This is the value at default or initialization by Error history clear command (address: 1000_H).

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable



The error history area is written to a nonvolatile memory when an error occurs.

(4) Module control data area (address: 1000_H to 14FF_H)

Type	Address		Description	Default ^{*1}	Read/ Write ^{*2}
	Decimal	Hexadecimal			
Station-based control data	4096	1000 _H	Error history clear command	0000 _H	R/W
	4097	1001 _H	Error history clear completed	0000 _H	R
	4098	1002 _H	Parameter area initialization command	0000 _H	R/W
	4099	1003 _H	Parameter area initialization completed	0000 _H	R
	4100	1004 _H	Module operation information initialization command	0000 _H	R/W
	4101	1005 _H	Module operation information initialization completed	0000 _H	R
	4102 to 4351	1006 _H to 10FF _H	System area	—	—
Module-based control data (main module)	4352 to 4607	1100 _H to 11FF _H	System area	—	—
Module-based control data (extension module 1)	4608 to 4863	1200 _H to 12FF _H	The remote buffer memory of the connected extension module is assigned.	—	—
—	4864 to 5375	1300 _H to 14FF _H	System area	—	—

*1 This is the value for when the module power supply is turned off then on or at the remote reset.

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable

(a) Module control data area of the extension module

The remote buffer memory differs depending on the model of the extension module.

- Extension input module (NZ2EX2B1-16D)

Address		Description	Default ^{*1}	Read/ Write ^{*2}
Decimal	Hexadecimal			
4608 to 4863	1200 _H to 12FF _H	System area	—	—

*1 This is the value for when the module power supply is turned off then on or at the remote reset.

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable

- Extension output module (NZ2EX2B1-16T)

Address		Description	Default ^{*1}	Read/ Write ^{*2}
Decimal	Hexadecimal			
4608	1200 _H	Number of ON times integration value clear Y0 to YF	0000 _H	R/W
4609	1201 _H	Number of ON times integration value clear completed Y0 to YF	0000 _H	R
4610 to 4863	1202 _H to 12FF _H	System area	—	—

*1 This is the value for when the module power supply is turned off then on or at the remote reset.

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable

(5) Extended parameter area (address: 1500_H to 1FFF_H)

Type	Address		Description	Default ^{*1}	Read/ Write ^{*2}
	Decimal	Hexadecimal			
Cam switch function parameter data	5376	1500 _H	Cam switch function, step type (Output 1)	0	R/W
	5377	1501 _H	Cam switch function, number of steps (Output 1)	0	R/W
	5378 to 5379	1502 _H to 1503 _H	Cam switch function, step No.1 setting (Output 1)	0	R/W
	5380 to 5381	1504 _H to 1505 _H	Cam switch function, step No.2 setting (Output 1)	0	R/W
	5382 to 5383	1506 _H to 1507 _H	Cam switch function, step No.3 setting (Output 1)	0	R/W
	5384 to 5385	1508 _H to 1509 _H	Cam switch function, step No.4 setting (Output 1)	0	R/W
	5386 to 5387	150A _H to 150B _H	Cam switch function, step No.5 setting (Output 1)	0	R/W
	5388 to 5389	150C _H to 150D _H	Cam switch function, step No.6 setting (Output 1)	0	R/W
	5390 to 5391	150E _H to 150F _H	Cam switch function, step No.7 setting (Output 1)	0	R/W
	5392 to 5393	1510 _H to 1511 _H	Cam switch function, step No.8 setting (Output 1)	0	R/W
	5394 to 5395	1512 _H to 1513 _H	Cam switch function, step No.9 setting (Output 1)	0	R/W
	5396 to 5397	1514 _H to 1515 _H	Cam switch function, step No.10 setting (Output 1)	0	R/W
	5398 to 5399	1516 _H to 1517 _H	Cam switch function, step No.11 setting (Output 1)	0	R/W
	5400 to 5401	1518 _H to 1519 _H	Cam switch function, step No.12 setting (Output 1)	0	R/W
	5402 to 5403	151A _H to 151B _H	Cam switch function, step No.13 setting (Output 1)	0	R/W
	5404 to 5405	151C _H to 151D _H	Cam switch function, step No.14 setting (Output 1)	0	R/W
	5406 to 5407	151E _H to 151F _H	Cam switch function, step No.15 setting (Output 1)	0	R/W
	5408 to 5409	1520 _H to 1521 _H	Cam switch function, step No.16 setting (Output 1)	0	R/W
	5410 to 5503	1522 _H to 157F _H	System area	—	—
	5504 to 5537	1580 _H to 15A1 _H	Cam switch output 2	Same as Cam switch output 1.	
	5538 to 5631	15A2 _H to 15FF _H	System area	—	—
	5632 to 5665	1600 _H to 1621 _H	Cam switch output 3	Same as Cam switch output 1.	
	5666 to 5759	1622 _H to 167F _H	System area	—	—
	5760 to 5793	1680 _H to 16A1 _H	Cam switch output 4	Same as Cam switch output 1.	
	5794 to 5887	16A2 _H to 16FF _H	System area	—	—
	5888 to 5921	1700 _H to 1721 _H	Cam switch output 5	Same as Cam switch output 1.	
	5922 to 6015	1722 _H to 177F _H	System area	—	—

Type	Address		Description	Default ^{*1}	Read/ Write ^{*2}
	Decimal	Hexadecimal			
Cam switch function parameter data	6016 to 6049	1780 _H to 17A1 _H	Cam switch output 6	Same as Cam switch output 1.	—
	6050 to 6143	17A2 _H to 17FF _H	System area	—	—
	6144 to 6177	1800 _H to 1821 _H	Cam switch output 7	Same as Cam switch output 1.	—
	6178 to 6271	1822 _H to 187F _H	System area	—	—
	6272 to 6305	1880 _H to 18A1 _H	Cam switch output 8	Same as Cam switch output 1.	—
	6306 to 6399	18A2 _H to 18FF _H	System area	—	—
	6400 to 6433	1900 _H to 1921 _H	Cam switch output 9	Same as Cam switch output 1.	—
	6434 to 6527	1922 _H to 197F _H	System area	—	—
	6528 to 6561	1980 _H to 19A1 _H	Cam switch output 10	Same as Cam switch output 1.	—
	6562 to 6655	19A2 _H to 19FF _H	System area	—	—
	6656 to 6689	1A00 _H to 1A21 _H	Cam switch output 11	Same as Cam switch output 1.	—
	6690 to 6783	1A22 _H to 1A7F _H	System area	—	—
	6784 to 6817	1A80 _H to 1AA1 _H	Cam switch output 12	Same as Cam switch output 1.	—
	6818 to 6911	1AA2 _H to 1AFF _H	System area	—	—
	6912 to 6945	1B00 _H to 1B21 _H	Cam switch output 13	Same as Cam switch output 1.	—
	6946 to 7039	1B22 _H to 1B7F _H	System area	—	—
	7040 to 7073	1B80 _H to 1BA1 _H	Cam switch output 14	Same as Cam switch output 1.	—
	7074 to 7167	1BA2 _H to 1BFF _H	System area	—	—
	7168 to 7201	1C00 _H to 1C21 _H	Cam switch output 15	Same as Cam switch output 1.	—
	7202 to 7295	1C22 _H to 1C7F _H	System area	—	—
	7296 to 7329	1C80 _H to 1CA1 _H	Cam switch output 16	Same as Cam switch output 1.	—
	7330 to 8191	1CA2 _H to 1FFF _H	System area	—	—

*1 This is the value at default or initialization by Parameter area initialization command (address: 1002_H).

*2 This shows whether read or write from programs is possible.

R: Readable

W: Writable

Point

The extended parameter data is written to a nonvolatile memory at the rising edge (off to on) of Initial data setting request flag (RY9) or when the parameters are set on the parameter setting window. However, the extended parameters cannot be set on the parameter setting window. Set the extended parameters from the program before setting parameters on the parameter setting window.

The activation timing of the extended parameter data differs depending on the data type. Refer to the pages where details of each data are described.

CHAPTER 4 THE PROCEDURE BEFORE OPERATION

This section describes the procedure before operation.

Check box



Setting a station number

Set the station number for a high-speed counter module.



Page 55, Section 6.1

4



Connection

When using an extension module, connect the extension module to the high-speed counter module.

Mount the high-speed counter module to a DIN rail.



Page 56, Section 6.2,
Page 58, Section 6.3



Wiring

Connect the high-speed counter module to a power supply, Ethernet cables, and external devices.



Page 63, Section 6.4,
Page 65, Section 6.5,
Page 68, Section 6.6



Parameter settings and programming

Set parameters and create a program.



Page 80, Section 7.1
Page 86, Section 7.2.1^{*1}

*1 To replace the module, refer to this section.

Point

To replace the module, follow the procedure described below.

- Stop the operation of the system and remove the high-speed counter module.
- Prepare a new high-speed counter module and perform the procedure above from "Setting a station number" to "Parameter settings and programming". (The network parameter of the master station does not need to be set again.)
- After checking the operation, restart the control.

Memo

CHAPTER 5 SYSTEM CONFIGURATION

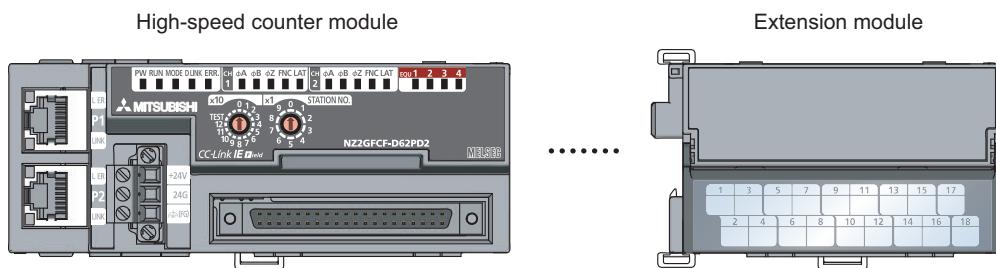
This chapter describes system configuration using a high-speed counter module.

For CC-Link IE Field Network configuration, refer to the following.

- >User's manual for the master/local module used

5.1 High-Speed Counter Module System Configuration

The following shows system configuration using a high-speed counter module.



5.2 Applicable Systems

(1) Applicable master station

When using a high-speed counter module, use the following products as a master station.

Model	First five digits of serial number
QJ71GF11-T2	
LJ71GF11-T2	"14102" or later

When a master station other than the above is used, the high-speed counter module cannot be used.

(2) Connectable modules

One extension module can be connected to one high-speed counter module.

Module	Model
Extension I/O module	NZ2EX2B1-16D
	NZ2EX2B1-16T

(3) Ethernet cable

For the specifications of the Ethernet cable, refer to the following.

 User's manual for the master/local module used

(4) Software package

GX Works2 is required for setting and diagnosing the high-speed counter module.

Software	Version
GX Works2	Version 1.98C or later

CHAPTER 6 INSTALLATION AND WIRING

This chapter describes the installation and wiring of the high-speed counter module.

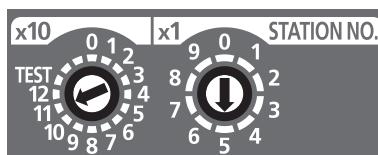
6.1 Station Number Setting

(1) Setting procedure

Set the station number with the rotary switch on the front of the module. The setting value of the station number becomes valid when the module is powered on. Thus, set the station number when the module is powered off.

- The hundreds and tens places of the station number are set with x10.
- The ones place of the station number is set with x1.

Ex. To set the station number to 115, set the switch as shown below.



(2) Setting range

Set the station number from 1 to 120. Setting the value other than 1 to 120 causes a communication error and the D LINK LED flashes.

Point

- Changing the station number setting switch while the module is powered on causes a minor error and flashes the ERR. LED.
Returning the station number setting switch to the previous setting eliminates the error after five seconds and turns off the ERR. LED.
- Do not set a station number duplicated with other station numbers. If the station number is duplicated, a communication error occurs and the D LINK LED does not turn on.

6.2 Installation Environment and Installation Position

6.2.1 Installation environment

(1) Installation location

Do not install the high-speed counter module to the place where:

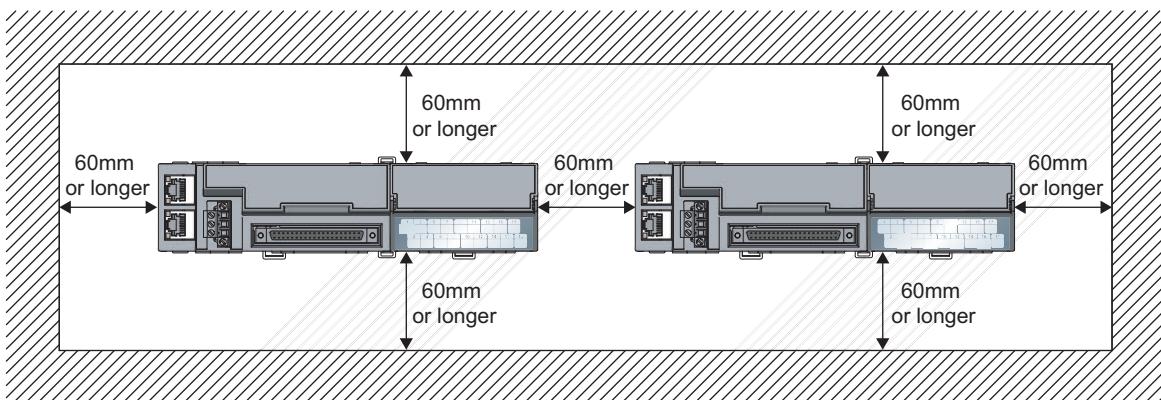
- Ambient temperature is outside the range of 0 to 55°C;
- Ambient humidity is outside the range of 5 to 95% RH;
- Condensation occurs due to rapid temperature change;
- Corrosive gas or combustible gas is present;
- Conductive powder such as dust and iron powder, oil mist, salinity, or organic solvent is filled;
- The high-speed counter module is exposed to direct sunlight;
- A strong electric field or strong magnetic field is generated; and
- The high-speed counter module is subject to vibration and shock.

(2) Installation surface

Install the high-speed counter module on the flat surface. When the installation surface is uneven, excessive force is applied to the printed-circuit board and may cause a defect.

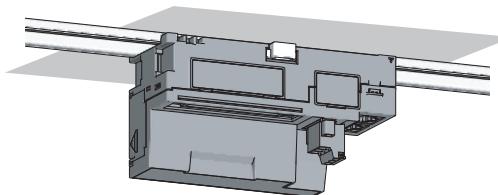
6.2.2 Installation position

When installing the high-speed counter module in a control panel, provide clearance of 60mm or longer between the module and the sides of the control panel or neighboring modules to ensure good ventilation and an easy module change.

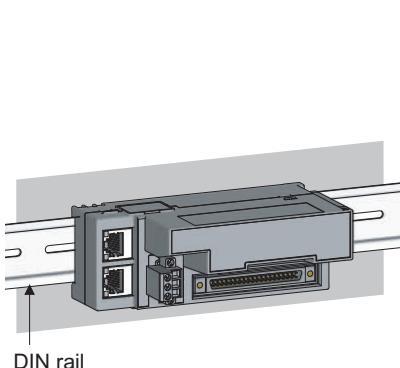


6.2.3 Installation direction

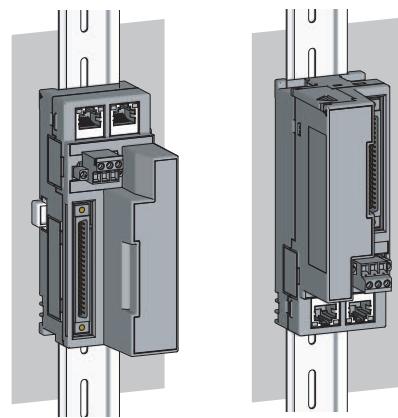
The high-speed counter module can be installed in six directions. Use the DIN rail to install the module.



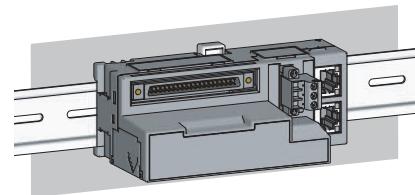
Downward installation



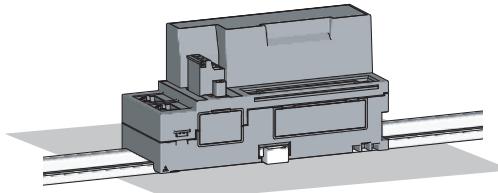
Horizontal installation



Vertical installation



Horizontal installation (upside down)

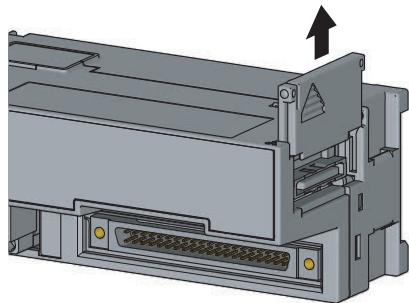


Upward installation

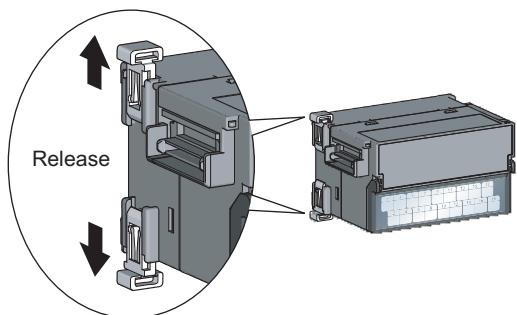
6.3 Installation

6.3.1 Connecting extension modules

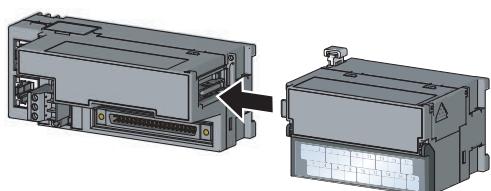
(1) Connecting procedure



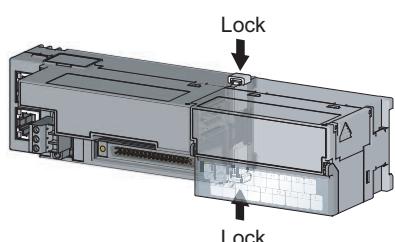
1. Remove the cover on the side of the module.
Do not dispose the removed cover, but store it.



2. Release the module joint levers (two points) on the side of the extension module. Slide the levers vertically.



3. Insert the connector of the extension module into that of the high-speed counter module so that they are securely engaged.



4. Lock the module joint levers (two points) on the side of the extension module. Slide the levers toward the module.
Check that the modules are securely connected.

(2) Disconnecting procedure

Disconnect the modules by reversing the procedure above.

Point

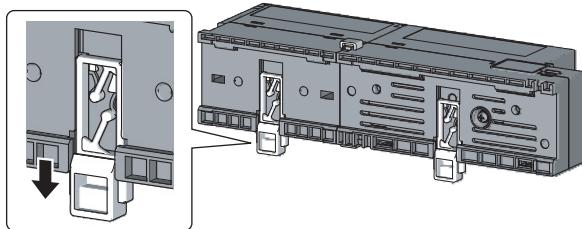
- Shut off the external power supply for the system in all phases before connecting or disconnecting extension modules.
- Lock the module joint levers securely. Failure to do so may cause malfunction, failure, or drop of the module.

6.3.2 Mounting the modules on a DIN rail

Point

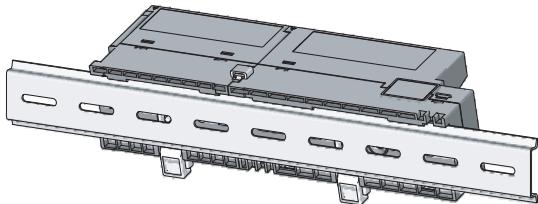
An example of the use of the DIN rail stopper is described in the following procedure. Fix the module according to the manual of the DIN rail stopper used.

(1) Mounting procedure

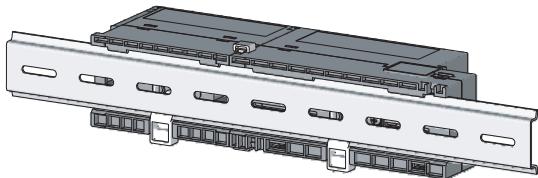


1. Pull down all DIN rail hooks on the back of the modules.

The hook should be pulled down until it clicks.

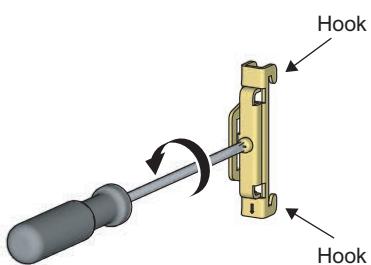


2. Hang the upper tabs of the modules on a DIN rail, and push the modules in position.

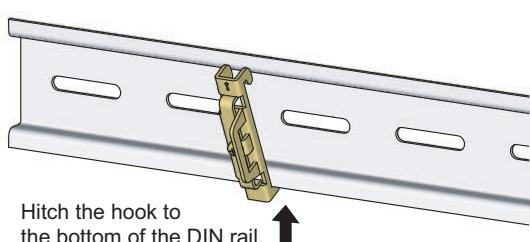


3. Lock the DIN rail hooks to the DIN rail to secure the modules in position.

Push each hook up until it clicks. If the hooks are beyond the reach, use a tool such as a screwdriver.

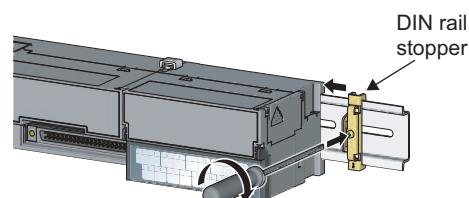
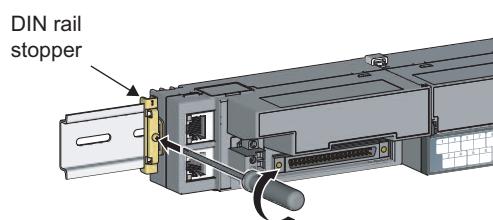
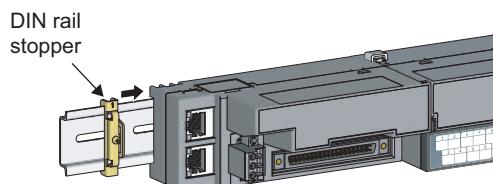
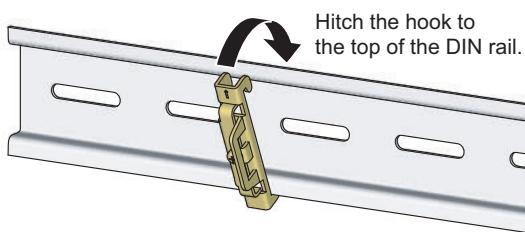


4. Loosen the screw on DIN rail stopper.



5. Hitch the bottom hook of the DIN rail stopper to the bottom of the DIN rail.

Hitch the hook according to the orientation of the arrow on the front of the stopper.



6. Hitch the upper hook of the DIN rail stopper to the top of the DIN rail.

7. Slide the DIN rail stopper up to the left side of the modules.

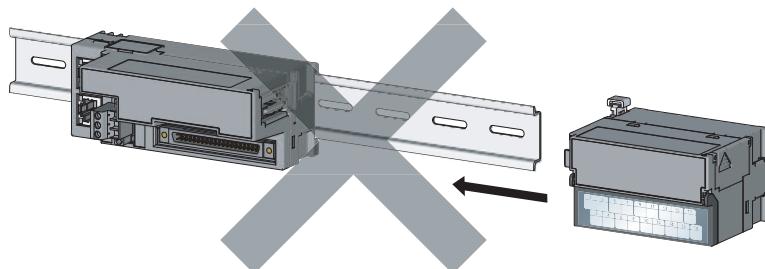
8. Hold the DIN rail stopper in the direction opposite to the arrow on the stopper and tighten the screw with a screwdriver.

9. Install the DIN rail stopper on the right side of the module in the same procedure.

Install the stopper upside down for the right side.

Point

- Do not slide modules from the edge of the DIN rail when mounting them. Doing so may damage the metal part located on the back of the module.



- Tighten the DIN rail mounting screws at intervals of 200mm or less.

(2) Removal procedure

Remove the modules from the DIN rail by reversing the procedure above.

(3) Applicable DIN rail model (compliant with IEC 60715)

- TH35-7.5Fe
- TH35-7.5Al

(4) Interval between DIN rail mounting screws

Tighten the screws at intervals of 200mm or less.

(5) DIN rail stopper

Use a stopper that is attachable to the DIN rail.

6.4 Wiring with Terminal Block for Module Power Supply and FG

(1) Tightening torque

Tighten the terminal block screws within the following specified torque range.

Tightening the screws too much may damage the module case.

Screw type	Tightening torque range
Terminal block mounting screw (M2.5 screw)	0.2 to 0.3N·m
Terminal screw (M2.5 screw)	0.5 to 0.6N·m

(2) Wire to be used

The following table describes the wire to be connected to the terminal block for module power supply and FG.

Diameter	Type	Material	Temperature rating
20 to 16 AWG	Stranded	Copper	75°C or more

For applicable solderless terminals, refer to the following.

Performance Specifications (☞ Page 27, Section 3.2)

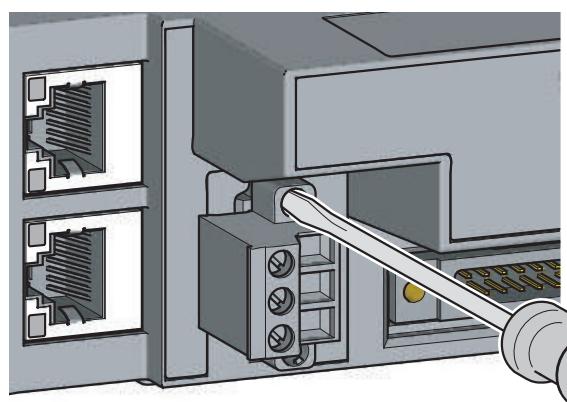
6

(3) Installing and removing the terminal block

To remove the terminal block, loosen the terminal block mounting screw with a slotted screwdriver.

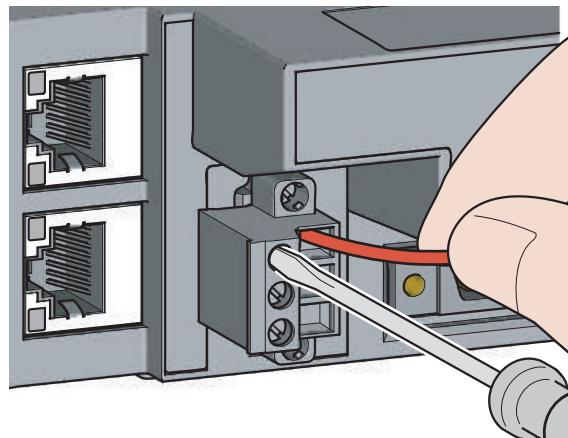
To install the terminal block, tighten the terminal block mounting screw.

Failure to secure the terminal block may cause drop, short circuit, malfunction.



(4) Connecting and disconnecting the cable

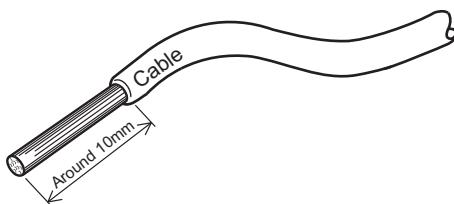
To connect the cable, insert the wire with the terminal screw loosened and tighten the screw. To disconnect the cable, pull out the wire with the terminal screw loosened with a slotted screwdriver.



(5) Processing method of the cable terminal

Strip the cable about 10mm from the top.

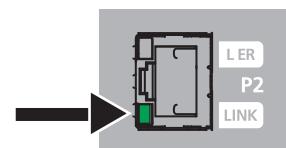
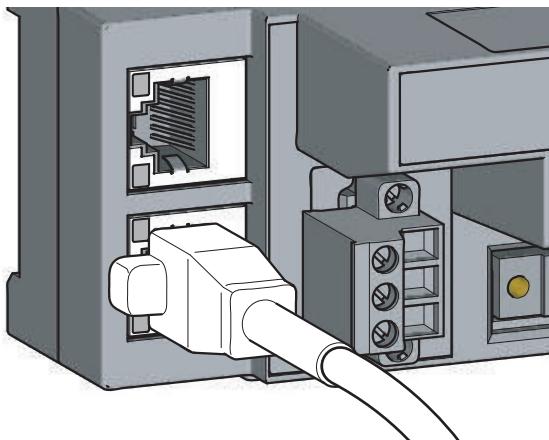
To use a bar solderless terminal, connect it to the stripped part.



6.5 Wiring of Ethernet Cable

(1) Connecting the Ethernet cable

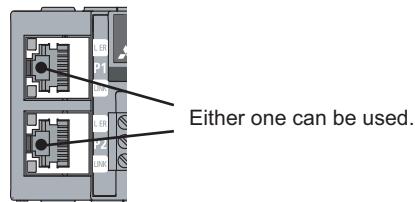
(a) Connecting



1. Power off the power supplies of the high-speed counter module and the external device.
2. Push the Ethernet cable connector into the high-speed counter module until it clicks. Pay attention to the connector's direction.
3. Power on the module.
4. Power on the external device.
5. Check that the LINK LED on the port into which the Ethernet cable is connected is on. The LINK LED may take a few seconds to turn on after power-on. If the LINK LED does not turn on, refer to the troubleshooting section and take a corrective action. (☞ Page 224, Section 11.3)

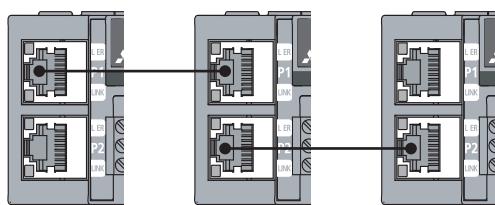
Point

- PORT1 and PORT2 need not to be distinguished. When only one connector is used in star topology, either PORT1 or PORT2 can be connected.

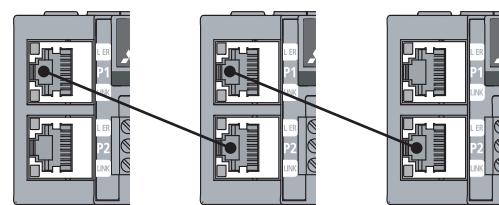


- When two connectors are used in line topology or ring topology, an Ethernet cable can be connected to the connectors in any combination. For example, the cable can be connected between PORT1s and between PORT1 and PORT2.

Connection between
PORT1s or PORT2s

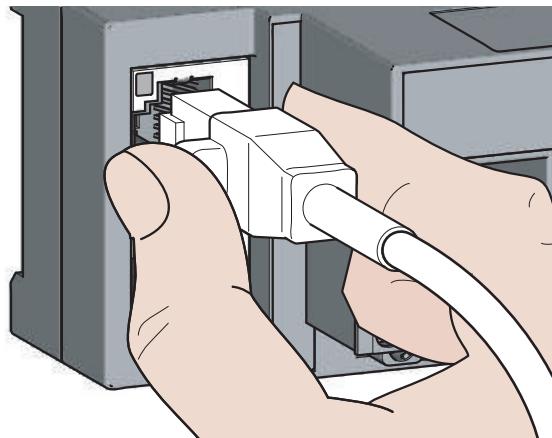


Connection between
PORT1 and PORT2



(b) Disconnecting

1. Power off the high-speed counter module.
2. Press the latch down and unplug the Ethernet cable.



(2) Precautions

(a) Laying Ethernet cables

- Place the Ethernet cable in a duct or clamp them. If not, dangling cable may swing or inadvertently be pulled, resulting in damage to the module or cables or malfunction due to poor contact.
- Do not touch the core of the connector of the cable or the module, and protect it from dirt and dust. If any oil from your hand, or any dirt or dust sticks to the core, it can increase transmission loss, causing data link to fail.
- Check the following:
 - The Ethernet cable is securely connected.
 - The Ethernet cable is not shorted.
 - The connectors are securely connected.

(b) Broken cable latch

Do not use Ethernet cables with broken latches. Doing so may cause the cable to unplug or malfunction.

(c) Connecting and disconnecting the Ethernet cable

Hold the connector part when connecting and disconnecting the Ethernet cable. Pulling the cable connected to the module may result in damage to the module or cable or malfunction due to poor contact.

(d) Connectors without the Ethernet cable

To prevent dust from entering the module, attach the provided connector cover.

(e) Maximum station-to-station distance (Maximum Ethernet cable length)

The maximum station-to-station distance is 100m. However, the distance may be shorter depending on the operating environment of the cable. For details, contact the manufacturer of the cables used.

(f) Bending radius of the Ethernet cable

There are restrictions on the bending radius of the Ethernet cable. Check the bending radius in the specifications of the Ethernet cables used.

6.6 Wiring of Connectors for External Devices

This section describes how to wire the high-speed counter module with an encoder or a controller.

6.6.1 Wiring precautions

To obtain the maximum performance from the functions of the high-speed counter module and improve the system reliability, an external wiring with high durability against noise is required.

Precautions for the external wiring are as follows.

(1) Wiring

- Terminals are prepared depending on the voltage of the signal to be input. Connecting to a terminal with a different voltage may cause malfunction of the module and failure of the connected devices.
- In 1-phase input, always connect a pulse input cable to the A-phase side.

(2) Connectors for external devices

- Securely connect the connectors for external devices (A6CON1/A6CON2/A6CON4) to the high-speed counter module connectors and securely tighten the two screws.
- When disconnecting the cable from the high-speed counter module, do not pull the cable by the cable part. Hold the connector part of the cable. Pulling the cable connected to the module may result in malfunction or damage to the module or cable.

(3) DC power supply

- Each DC power supply to be connected to the high-speed counter module, encoder, and controller must be connected to a different power supply.

(4) Measures against noise

- The high-speed counter module may incorrectly count the pulses when pulse-state noises are input.
- When inputting high-speed pulses, take the following measures against noise.

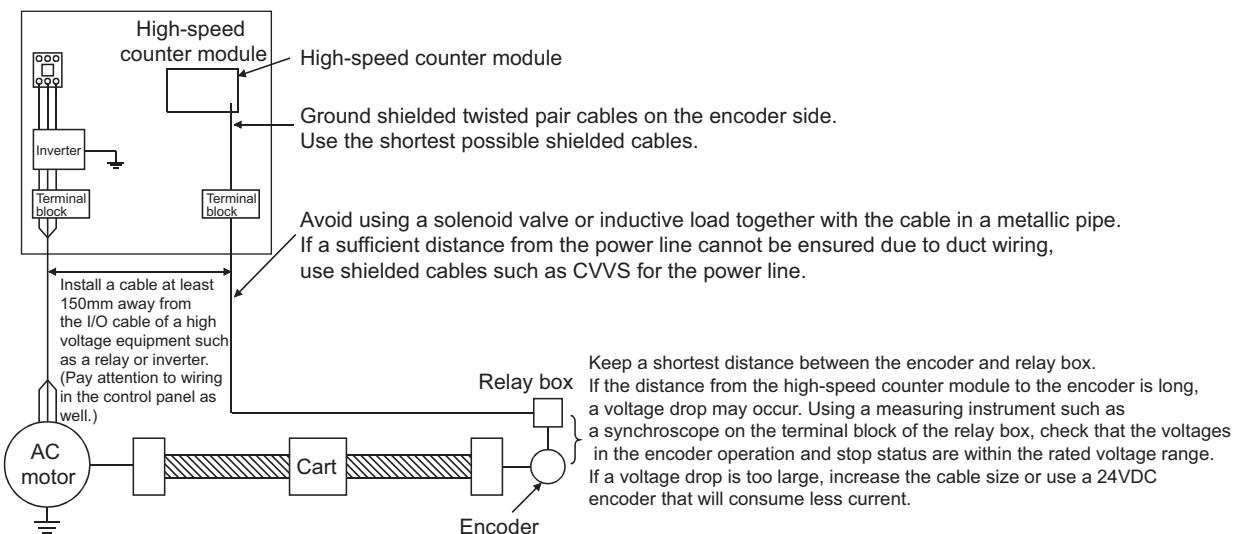
Measure 1

Use shielded twisted pair cables, and ground them on the encoder side with a ground resistance of 100Ω or less.

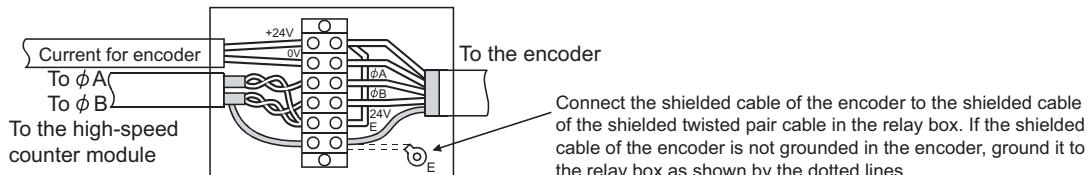
Measure 2

Use the shortest possible shielded twisted pair cables, placing them not parallel with noise-generating power cables or I/O cables and at a distance of 150mm or more.

- The following figure shows an example of a noise reduction measure.



- Ground the shielded twisted pair cable on the encoder side (relay box). (Wiring example: with a sink type encoder (24V))



6.6.2 Connectors for external devices

The connectors and crimp tools for use with the high-speed counter module must be purchased separately by the user.

The following tables list the connector types and the crimp tool.

(1) Precautions

- Tighten the connector screws within the following specified torque range.

Screw type	Tightening torque range
Connector screw (M2.6 screw)	0.20 to 0.29N·m

- Use copper wires having temperature rating of 75°C or more for the connectors.
- When required, use UL-approved connectors.

(2) Connector types^{*1}

Type	Model	Applicable wire size
Soldering type (straight out)	A6CON1	0.3mm ² (22 AWG) (stranded)
Crimp type (straight out)	A6CON2	0.088 to 0.24mm ² (28 to 24 AWG) (stranded)
Soldering type (straight out/diagonal out)	A6CON4	0.3mm ² (22 AWG) (stranded)

^{*1} The A6CON3 (pressure-displacement type, straight out) connector cannot be used for the high-speed counter module.

(3) Connector crimp tool

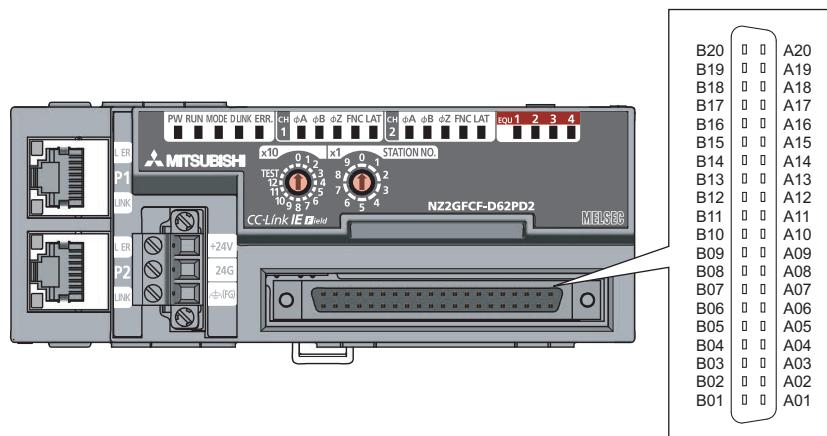
Type	Model	Applicable wire size	Contact
Crimp tool	FCN-363T-T005/H	0.088 to 0.24mm ² (28 to 24 AWG)	FUJITSU COMPONENT LIMITED http://www.fcl.fujitsu.com/en/

6.6.3 I/O interfaces with external devices

This section describes the high-speed counter module interfaces to connect with external devices.

(1) Terminal layouts and pin numbers of connectors for external devices

The following figure and table show the terminal layouts and the pin numbers of the high-speed counter module connector for external devices.



Pin number	Symbol	Pin number	Symbol
B20	A1-24V	A20	A1-5V
B19	A1-DIF	A19	A1-COM
B18	B1-24V	A18	B1-5V
B17	B1-DIF	A17	B1-COM
B16	Z1-24V	A16	Z1-5V
B15	Z1-DIF	A15	Z1-COM
B14	A2-24V	A14	A2-5V
B13	A2-DIF	A13	A2-COM
B12	B2-24V	A12	B2-5V
B11	B2-DIF	A11	B2-COM
B10	Z2-24V	A10	Z2-5V
B09	Z2-DIF	A09	Z2-COM
B08	FUNC1-24V	A08	LATCH1-24V
B07	FUNC1-5V	A07	LATCH1-5V
B06	CTRLCOM	A06	CTRLCOM
B05	FUNC2-24V	A05	LATCH2-24V
B04	FUNC2-5V	A04	LATCH2-5V
B03	EQU1	A03	EQU2
B02	EQUCOM	A02	EQUCOM
B01	EQU3	A01	EQU4

(2) List of I/O signal details

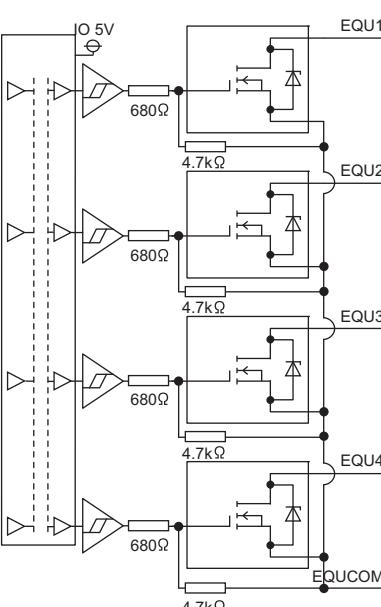
The following table lists the signals for the high-speed counter module connectors for external devices.

I/O classification	Symbol	Pin number	Signal name	Description
Input	A1-24V	B20	CH1 Phase A pulse input 24V (+)	<ul style="list-style-type: none"> This signal inputs + (plus) side of phase A pulse.
	A1-5V	A20	CH1 Phase A pulse input 5V (+)	
	A1-DIF	B19	CH1 Phase A pulse differential input (+)	
	A1-COM	A19	CH1 Phase A pulse input common (-)	
	B1-24V	B18	CH1 Phase B pulse input 24V (+)	<ul style="list-style-type: none"> This signal inputs - (minus) side of phase A pulse.
	B1-5V	A18	CH1 Phase B pulse input 5V (+)	
	B1-DIF	B17	CH1 Phase B pulse differential input (+)	
	B1-COM	A17	CH1 Phase B pulse input common (-)	
	Z1-24V	B16	CH1 Phase Z input 24V (+)	<ul style="list-style-type: none"> This signal inputs + (plus) side of phase Z. Turn on this signal to replace a count value by the external signal. The count value is replaced with the preset value when this signal becomes on (when "CH1 Z phase (Preset) trigger setting" is set to "0: Rising").
	Z1-5V	A16	CH1 Phase Z input 5V (+)	
	Z1-DIF	B15	CH1 Phase Z differential input (+)	
	Z1-COM	A15	CH1 Phase Z input common (-)	
	A2-24V	B14	CH2 Phase A pulse input 24V (+)	<ul style="list-style-type: none"> This signal inputs + (plus) side of phase A pulse.
	A2-5V	A14	CH2 Phase A pulse input 5V (+)	
	A2-DIF	B13	CH2 Phase A pulse differential input (+)	
	A2-COM	A13	CH2 Phase A pulse input common (-)	
	B2-24V	B12	CH2 Phase B pulse input 24V (+)	<ul style="list-style-type: none"> This signal inputs + (plus) side of phase B pulse.
	B2-5V	A12	CH2 Phase B pulse input 5V (+)	
	B2-DIF	B11	CH2 Phase B pulse differential input (+)	
	B2-COM	A11	CH2 Phase B pulse input common (-)	
	Z2-24V	B10	CH2 Phase Z input 24V (+)	<ul style="list-style-type: none"> This signal inputs + (plus) side of phase Z. Turn on this signal to replace a count value by the external signal. The count value is replaced with the preset value when this signal becomes on (when "CH2 Z phase (Preset) trigger setting" is set to "0: Rising").
	Z2-5V	A10	CH2 Phase Z input 5V (+)	
	Z2-DIF	B09	CH2 Phase Z differential input (+)	
	Z2-COM	A09	CH2 Phase Z input common (-)	
	FUNC1-24V	B08	CH1 Function input 24V	<ul style="list-style-type: none"> Turn on this signal to execute the selected counter function start command by the external signal.
	FUNC1-5V	B07	CH1 Function input 5V	
	FUNC2-24V	B05	CH2 Function input 24V	
	FUNC2-5V	B04	CH2 Function input 5V	
	LATCH1-24V	A08	CH1 Latch counter input 24V	<ul style="list-style-type: none"> Turn on this signal to latch a count value by the external signal. The count value is latched and stored in remote registers when this signal becomes on.
	LATCH1-5V	A07	CH1 Latch counter input 5V	
	LATCH2-24V	A05	CH2 Latch counter input 24V	
	LATCH2-5V	A04	CH2 Latch counter input 5V	
	CTRLCOM	A06, B06	Control input common	<ul style="list-style-type: none"> Common for function input Common for latch counter input It is common between channels.
Output	EQU1	B03	Coincidence output 1 (+)	<ul style="list-style-type: none"> With the coincidence output function activated, the high-speed counter module outputs a signal when the count value is matched with the preset comparison condition. When the PWM output function is used, the high-speed counter module outputs the PWM waveform.
	EQU2	A03	Coincidence output 2 (+)	
	EQU3	B01	Coincidence output 3 (+)	
	EQU4	A01	Coincidence output 4 (+)	
	EQUCOM	A02, B02	Coincidence output common (-)	<ul style="list-style-type: none"> It inputs 0V when Coincidence output 1 to 4 are used. Common for coincidence outputs It is common between channels.

(3) Interface with external devices

The following table lists the high-speed counter module interfaces to connect with external devices.

I/O clas-sifica-tion	Internal circuit	Pin number		Signal name	Operation	Input voltage (guaranteed value)	Operating current (guaranteed value)	Response time
		CH1	CH2					
Input		B19	B13	Phase A pulse differential input (+)	—	AM26C31 or equivalent	—	—
		A20	A14	Phase A pulse input 5V (+)	When ON	4.5 to 5.5V	4 to 8mA	—
				When OFF	2V or lower	1.0mA or lower	—	—
		B20	B14	Phase A pulse input 24V (+)	When ON	21.6 to 26.4V	4 to 6mA	—
		A19	A13	Phase A pulse input common (-)	—	—	—	—
		B17	B11	Phase B pulse differential input (+)	—	AM26C31 or equivalent	—	—
		A18	A12	Phase B pulse input 5V (+)	When ON	4.5 to 5.5V	4 to 8mA	—
				When OFF	2V or lower	1.0mA or lower	—	—
		B18	B12	Phase B pulse input 24V (+)	When ON	21.6 to 26.4V	4 to 6mA	—
				When OFF	5V or lower	1.0mA or lower	—	—
		A17	A11	Phase B pulse input common (-)	—	—	—	—
		B15	B09	Phase Z differential input (+)	When ON	AM26C31 or equivalent	—	—
				When OFF	AM26C31 or equivalent	—	—	—
		A16	A10	Phase Z input 5V (+)	When ON	4.5 to 5.5V	4 to 8mA	1.25µs or less
				When OFF	2V or lower	1.0mA or lower	2.5µs or less	—
		B16	B10	Phase Z input 24V (+)	When ON	21.6 to 26.4V	4 to 6mA	1.25µs or less
				When OFF	5V or lower	1.0mA or lower	2.5µs or less	—
		A15	A09	Phase Z input common (-)	—	—	—	—
		B07	B04	Function input 5V	When ON	4.5 to 5.5V	7 to 12mA	20µs or less
				When OFF	2V or lower	1.0mA or lower	100µs or less	—
		B08	B05	Function input 24V	When ON	21.6 to 26.4V	7 to 12mA	20µs or less
				When OFF	5V or lower	1.0mA or lower	100µs or less	—
		B06, A06		Control input common	—	—	—	—
		A07	A04	Latch counter input 5V	When ON	4.5 to 5.5V	7 to 12mA	20µs or less
				When OFF	2V or lower	1.0mA or lower	100µs or less	—
		A08	A05	Latch counter input 24V	When ON	21.6 to 26.4V	7 to 12mA	20µs or less
				When OFF	5V or lower	1.0mA or lower	100µs or less	—

I/O clas-sifica-tion	Internal circuit	Pin number		Signal name	Operation	Input voltage (guaranteed value)	Operating current (guaranteed value)	Response time
		CH1	CH2					
Output		B03	—	Coincidence output 1 (+)	<ul style="list-style-type: none"> Operating load voltage: 4.75 to 30VDC Maximum load current: 0.1A/point Maximum voltage drop at ON: 0.5V Response time <ul style="list-style-type: none"> OFF → ON: 1μs or less (rated load, resistive load) ON → OFF: 1μs or less (rated load, resistive load) 			
		A03	—	Coincidence output 2 (+)				
		B01	—	Coincidence output 3 (+)				
		A01	—	Coincidence output 4 (+)				
		B02, A02	B02, A02	Coincidence output common (-)				

*1 For EQU1 to EQU4, the assignment to CH1 or CH2 can be changed.

(4) ON/OFF status of input signals

The ON/OFF status of input signals depends on external wiring and the logic setting.

The following table shows an example of CH□ Function input terminal (FUNC1, FUNC2).

The ON/OFF status for other input signals is the same as CH□ Function input terminal (FUNC1, FUNC2).

Logic status ^{*1}	External wiring	ON/OFF status of CH□ Function input terminal (FUNC1, FUNC2) in terms of the high-speed counter module
Positive logic	No voltage applied	OFF
	Voltage applied	ON
Negative logic	No voltage applied	ON
	Voltage applied	OFF

*1 Configure the logic setting by CH□ Function input logic setting (address: 0127_H, 0147_H). For details on the setting, refer to the following.

 Page 267, Appendix 3

6.6.4 Encoders that can be connected

This section lists the encoders that can be connected to the high-speed counter module.

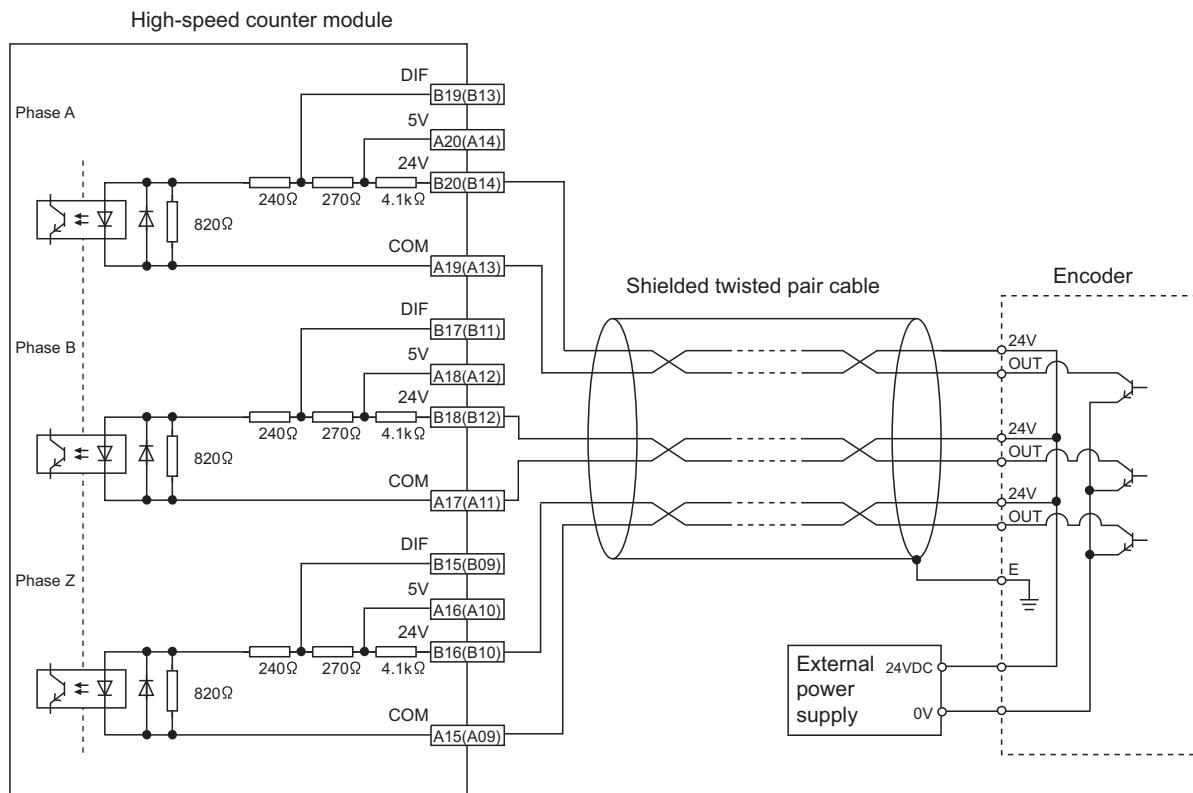
- Open collector output type encoders
- CMOS level voltage output type encoders
- Line driver output type encoders (AM26LS31 or equivalent)

Point

- Verify that the encoder output voltage meets the specifications of the high-speed counter module.
- TTL level voltage output type encoders cannot be used with the high-speed counter module.

6.7 Wiring Example (Between a High-Speed Counter Module and an Encoder)

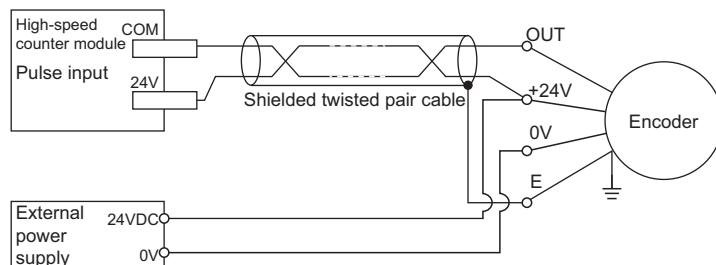
(1) Example of wiring with an open collector output type encoder (24VDC)



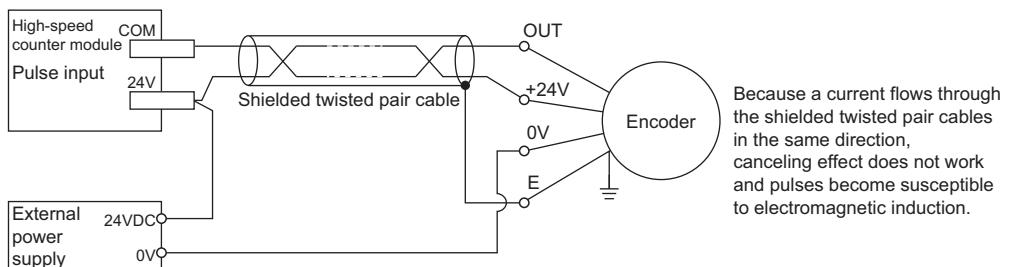
Point

When wiring the high-speed counter module and an encoder, separate power cables and signal cables. The following figure shows examples.

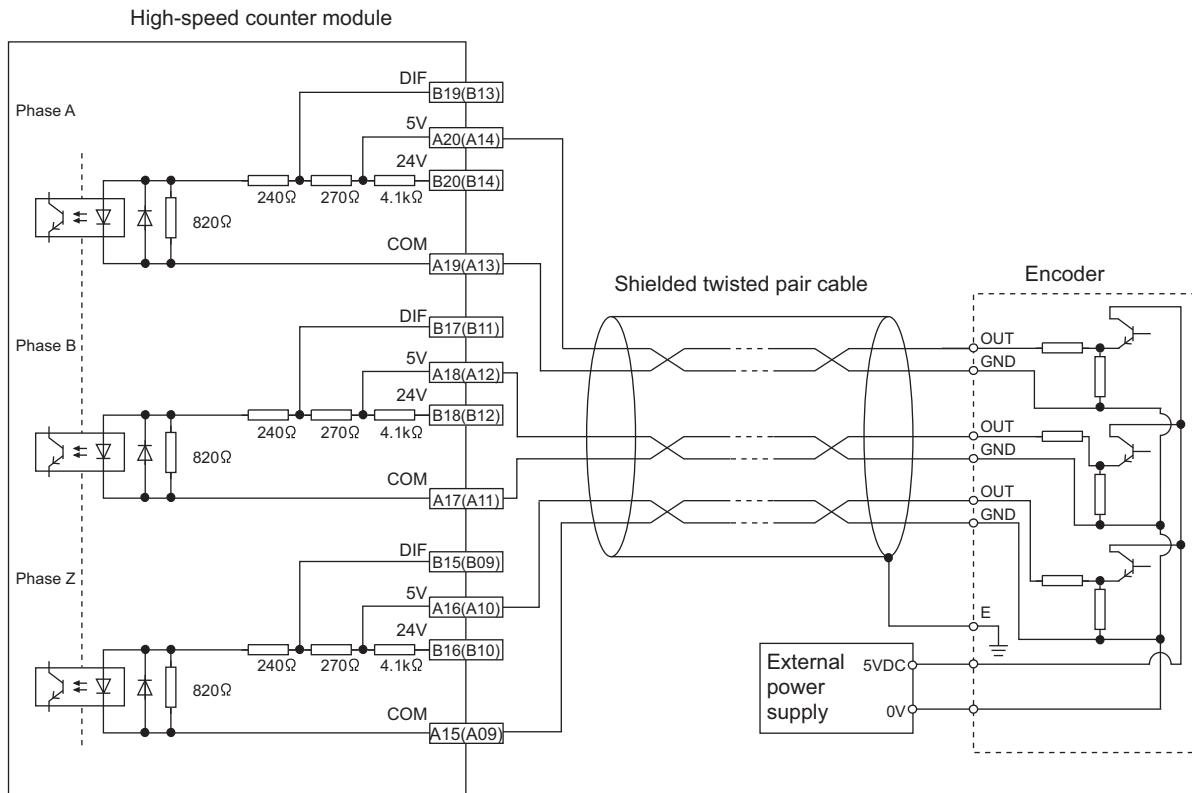
- Example of correct wiring



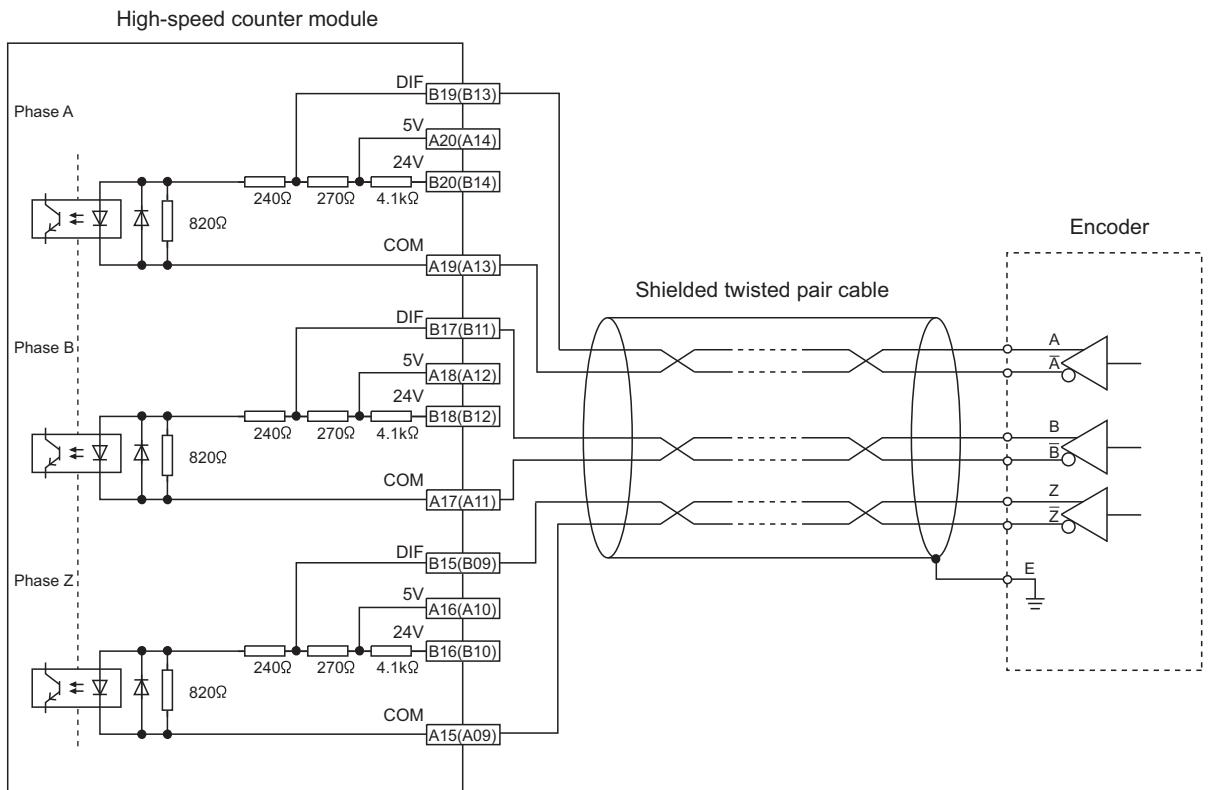
- Example of incorrect wiring



(2) Example of wiring with a voltage output type encoder (5VDC)

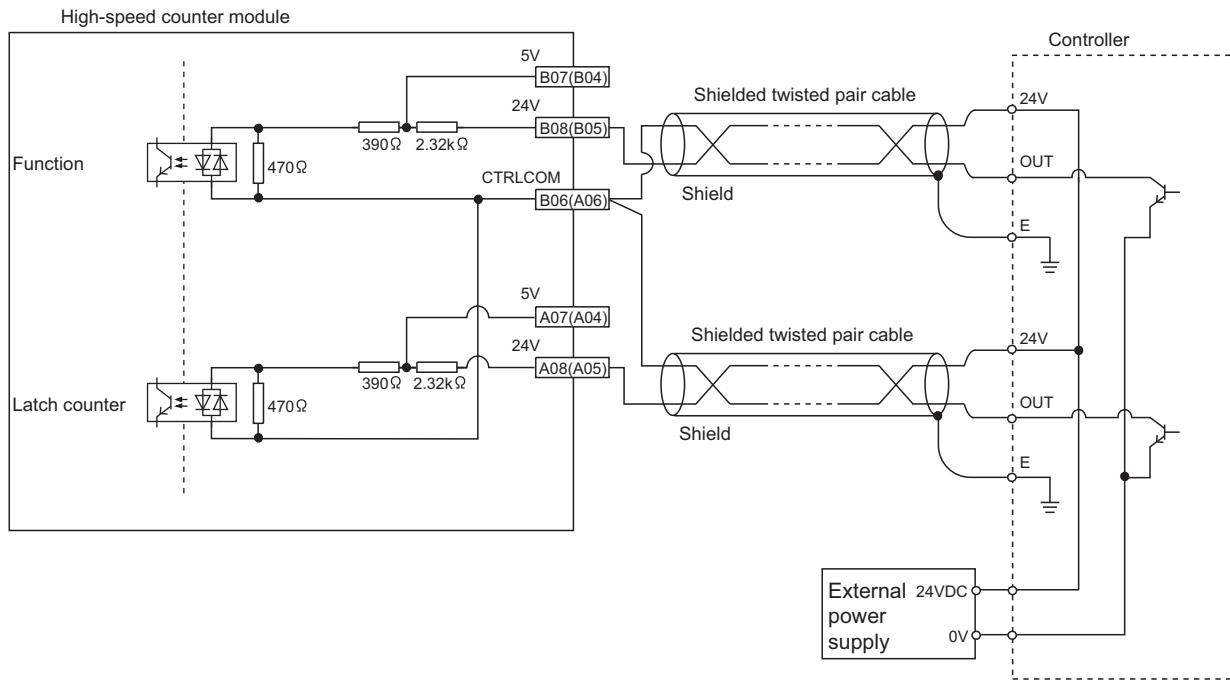


(3) Example of wiring with a line driver (equivalent to AM26LS31) encoder

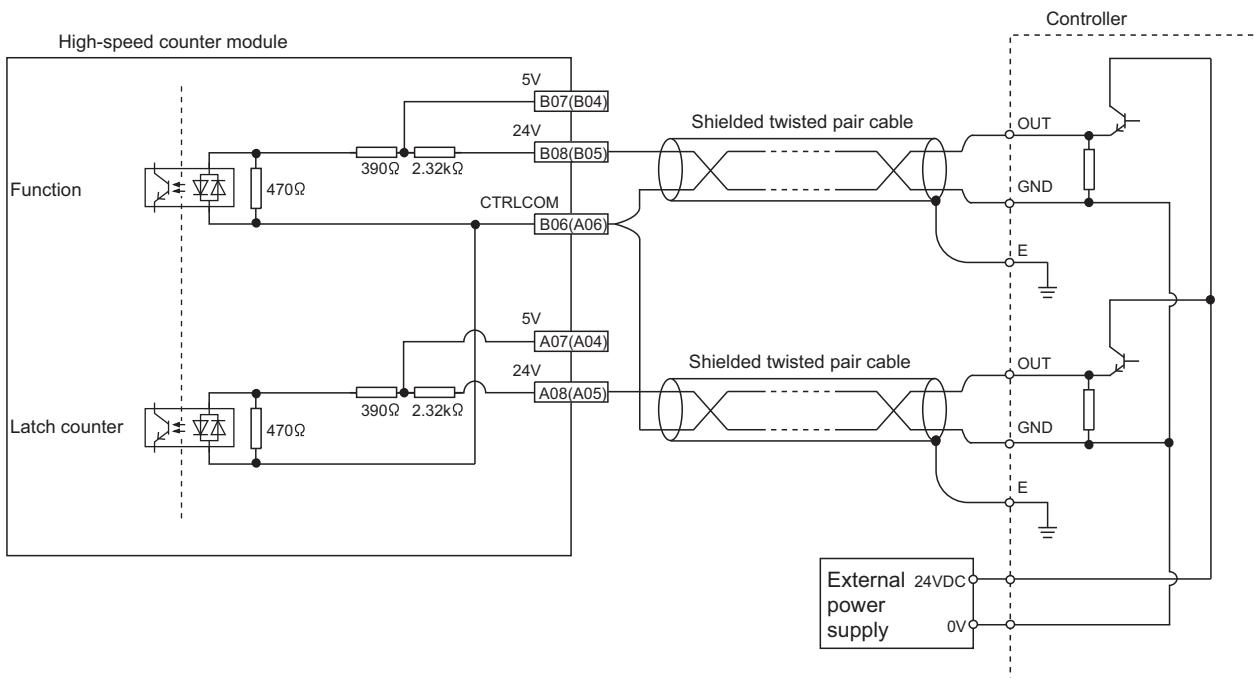


6.8 Wiring Example (Between a Controller and External Input Terminals)

(1) Example of wiring with a sink type controller

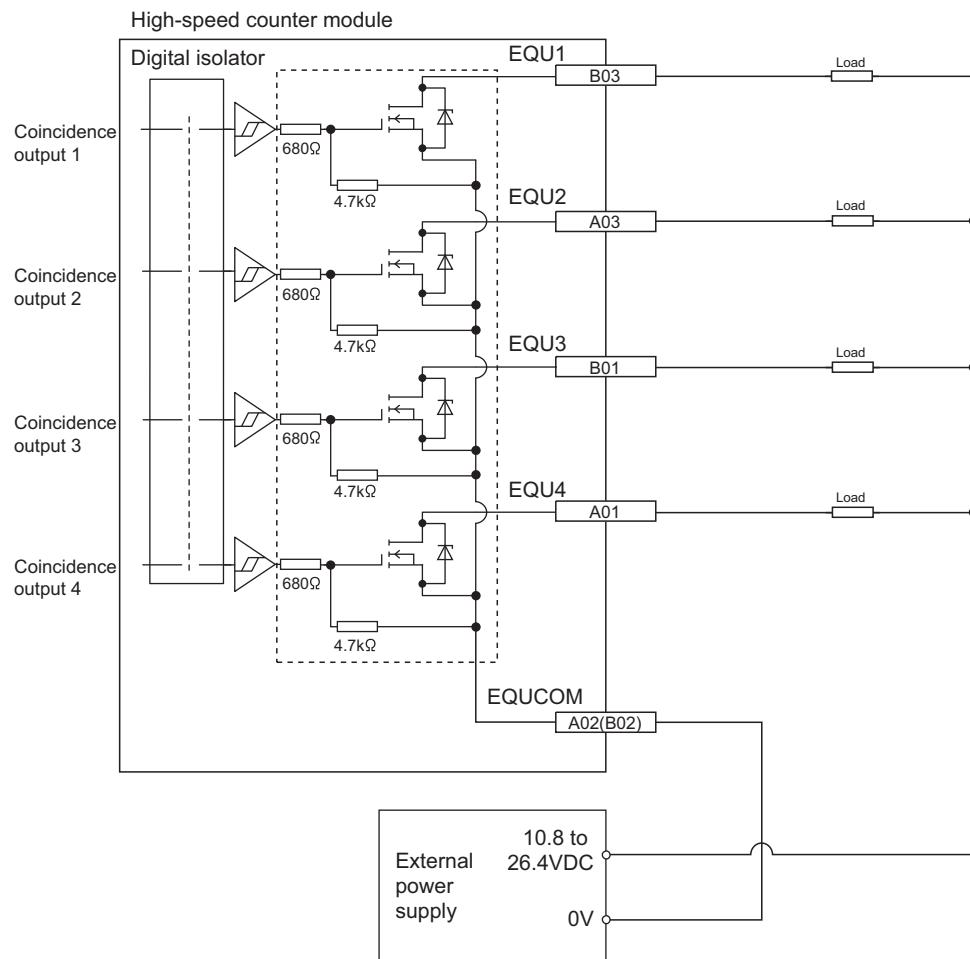


(2) Example of wiring with a source type controller



6.9 Wiring Example (with Coincidence Output Terminals)

(1) Example of wiring with coincidence output terminals (sink output type)



CHAPTER 7 VARIOUS SETTINGS

This chapter describes the setting procedures of the high-speed counter module.

7.1 Parameter Setting

Set the parameter of this module with the network parameter written to the CPU module of the master station. When the setting in GX Works2 and the parameter written to the CPU module do not match, the parameter cannot be read and written. For the setting procedure of the master station, refer to the following.

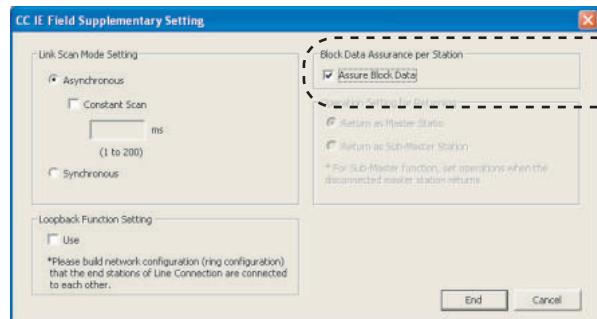
- User's manual for the master/local module used

Write and read the parameter setting of this module with the CPU module in the STOP status.

(Writing and reading are unavailable in the RUN status.)

Remark

- When points less than the ones of the high-speed counter module and extension module are set for the remote I/O signal and remote register, no error occurs. The cyclic transmission is performed for the data of the points set from the start.
- When using the high-speed counter module, do not invalidate Block Data Assurance per Station on the "CC IE Field Supplementary Setting" window.



For the block data assurance per station, refer to the following.

- User's manual for the master/local module used

- Do not set the parameter using the CCPASET instruction in the master station. Correct operation of the high-speed counter module cannot be guaranteed because the module operates with the block data assurance per station disabled when the CCPASET instruction is executed.

1. Display the "CC IE Field Configuration" window.

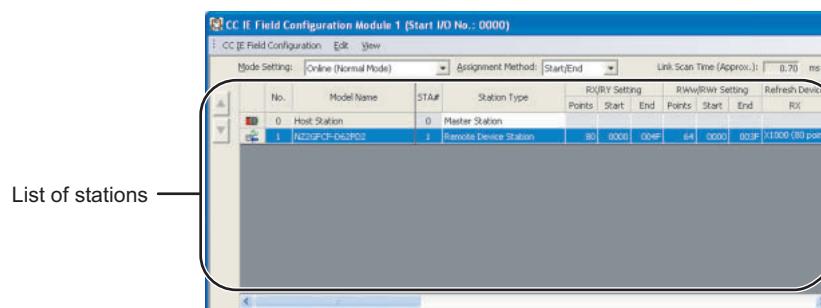
- When the master/local module is the QJ71GF11-T2

Project window \Rightarrow [Parameter] \Rightarrow [Network Parameter] \Rightarrow [Ethernet/CC IE/MELSECNET] \Rightarrow **CC IE Field Configuration Setting** button

- When the master/local module is the LJ71GF11-T2

Project window \Rightarrow [Parameter] \Rightarrow [Network Parameter] \Rightarrow [Ethernet/CC IE Field] \Rightarrow **CC IE Field Configuration Setting** button

2. Select the high-speed counter module in "List of stations" on the "CC IE Field Configuration" window.

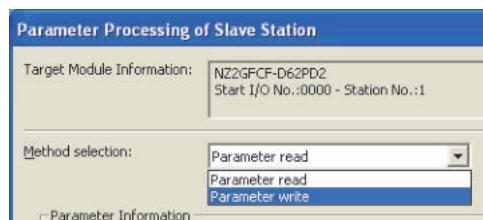


7

3. Open the "Parameter Processing of Slave Station" window.

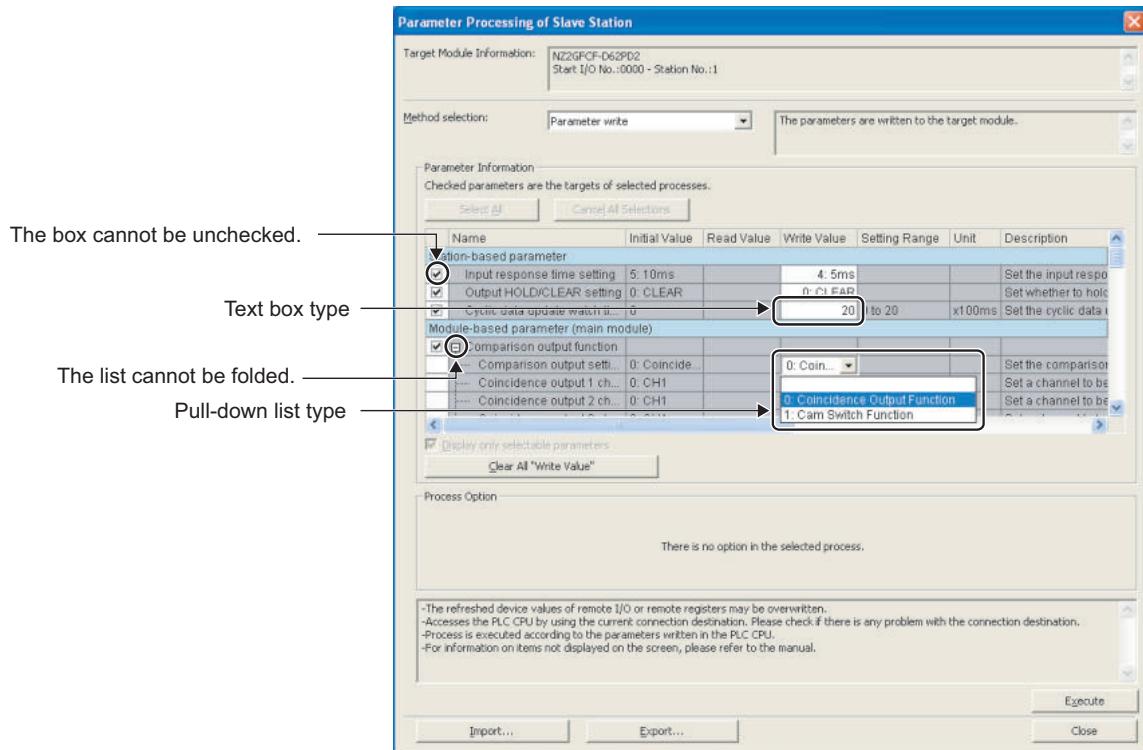
Project window \Rightarrow [CC IE Field Configuration] \Rightarrow [Parameter Processing of Slave Station]

4. Set "Parameter write" for "Method selection".



5. Double-click the item to change the setting, and input the setting value.

- Items to input from the pull-down list
Double-click the item to set to display the pull-down list. Select the item.
- Items to input from the text box
Double-click the item to set, and input the setting value.



Setting item	Setting details	Reference
Input response time setting	3: 2ms	Page 174, Section 8.20 (3)
	4: 5ms	
	5: 10ms	
	6: 20ms	
	7: 70ms	
Output HOLD/CLEAR setting	0: CLEAR	Page 167, Section 8.17
	1: HOLD	
Cyclic data update watch time setting	• 0 (Not monitor) • 1 to 20 (0.1 to 2 seconds, in increments of 100ms)	Page 168, Section 8.18
Comparison output setting	0: Coincidence Output Function 1: Cam Switch Function	Page 102, Section 8.3
Coincidence output 1 channel assignment setting	0: CH1	
	1: CH2	
Coincidence output 2 channel assignment setting	0: CH1	
	1: CH2	
Coincidence output 3 channel assignment setting	0: CH1	
	1: CH2	
Coincidence output 4 channel assignment setting	0: CH1	
	1: CH2	

Setting item	Setting details	Reference
Coincidence output 1 comparison condition setting	0: Coincidence Output 1: Within-range Output 2: Out-of-range Output	
Coincidence output 2 comparison condition setting	0: Coincidence Output 1: Within-range Output 2: Out-of-range Output	
Coincidence output 3 comparison condition setting	0: Coincidence Output 1: Within-range Output 2: Out-of-range Output	Page 102, Section 8.3
Coincidence output 4 comparison condition setting	0: Coincidence Output 1: Within-range Output 2: Out-of-range Output	
Preset/replace setting at coincidence output (Coincidence output 1)	0: Present value not replaced 1: Present value replaced	
Preset/replace setting at coincidence output (Coincidence output 2)	0: Present value not replaced 1: Present value replaced	Page 114, Section 8.3.3
Cam switch output unit assignment setting	0: No Assignment 1: Stage 1	
Cam switch output 1 channel assignment setting	0: CH1 1: CH2	
Cam switch output 2 channel assignment setting	0: CH1 1: CH2	
Cam switch output 3 channel assignment setting	0: CH1 1: CH2	
Cam switch output 4 channel assignment setting	0: CH1 1: CH2	
Cam switch output 5 channel assignment setting	0: CH1 1: CH2	
Cam switch output 6 channel assignment setting	0: CH1 1: CH2	
Cam switch output 7 channel assignment setting	0: CH1 1: CH2	Page 117, Section 8.3.4
Cam switch output 8 channel assignment setting	0: CH1 1: CH2	
Cam switch output 9 channel assignment setting	0: CH1 1: CH2	
Cam switch output 10 channel assignment setting	0: CH1 1: CH2	
Cam switch output 11 channel assignment setting	0: CH1 1: CH2	
Cam switch output 12 channel assignment setting	0: CH1 1: CH2	
Cam switch output 13 channel assignment setting	0: CH1 1: CH2	
Cam switch output 14 channel assignment setting	0: CH1 1: CH2	

Setting item	Setting details	Reference
Cam switch output 15 channel assignment setting	0: CH1	Page 117, Section 8.3.4
	1: CH2	
Cam switch output 16 channel assignment setting	0: CH1	Page 90, Section 7.3
	1: CH2	
Operation mode setting	0: Normal Mode	Page 90, Section 7.3
	1: Frequency Measurement Mode	
	2: Rotation Speed Measurement Mode	
	3: Pulse Measurement Mode	
	4: PWM Output Mode	
Count source selection	0: A Phase/B Phase	Page 269, Appendix 3 (6)
	1: Coincidence Output 1	
	2: Coincidence Output 2	
Pulse input mode	0: 1-Phase Multiple of 1	Page 92, Section 8.1.1
	1: 1-Phase Multiple of 2	
	2: CW/CCW	
	3: 2-Phase Multiple of 1	
	4: 2-Phase Multiple of 2	
Counting speed setting	5: 2-Phase Multiple of 4	Page 27, Section 3.2
	0: 10kpps	
	1: 100kpps	
	2: 200kpps	
	3: 500kpps	
	4: 1Mpps	
	5: 2Mpps	
Counter format	6: 4Mpps	Page 95, Section 8.2
	7: 8Mpps	
Z phase (Preset) trigger setting	0: Rising	Page 124, Section 8.4 (2)
	1: Falling	
External preset/replace (Z Phase) request detection setting	2: Rising + Falling	
	3: During ON	
	0: ON at detection	Page 124, Section 8.4 (2)
Counter function selection	1: Not ON at detection	
	0: Count Disable Function	Page 131, Section 8.7
Function input logic setting	1: Latch Counter Function	Page 133, Section 8.8
	2: Sampling Counter Function	Page 136, Section 8.9
	3: Periodic Pulse Counter Function	Page 139, Section 8.10
	4: Count disable/Preset/replace Function	Page 142, Section 8.11
	5: Latch counter/Preset/replace Function	Page 145, Section 8.12
Latch counter input logic setting	0: Positive Logic	Page 272, Appendix 3 (9)
	1: Negative Logic	

Setting item	Setting details			Reference
Z phase input response time setting	Setting	OFF → ON Response time	ON → OFF Response time	Page 273, Appendix 3 (10)
	0	0.25μs	2.5μs	
	1	0.1ms	0.1ms	
	2	1.0ms	1.0ms	
Function input response time setting	Setting	OFF → ON Response time	ON → OFF Response time	Page 273, Appendix 3 (10)
	0	0.02ms	0.1ms	
	1	0.1ms	0.1ms	
	2	1.0ms	1.0ms	
Latch counter input response time setting	Setting	OFF → ON Response time	ON → OFF Response time	Page 273, Appendix 3 (10)
	0	0.02ms	0.1ms	
	1	0.1ms	0.1ms	
	2	1.0ms	1.0ms	
Pulse measurement setting (Function input terminal)	0: Pulse ON Width			Page 156, Section 8.15
	1: Pulse OFF Width			
Pulse measurement setting (Latch counter input terminal)	0: Pulse ON Width			Page 156, Section 8.15
	1: Pulse OFF Width			

6. Click the  button to write the parameter to the high-speed counter module.

Point

- When using the extension module, also set the parameter of the extension module. For the parameter of the extension module, refer to the following.
 Manual for the extension module used
- Set all the items for the parameter. If any blank exists, the parameter cannot be written to the high-speed counter module.
- To read the parameter from the high-speed counter module, set "Parameter read" for "Method selection" and click the  button.
- When the following message is displayed, take corrective action for the error code in <>. (Page 208, Section 11.2)



- When the parameters are written, the contents in the extended parameter area are stored in the nonvolatile memory.
- When writing the parameters while Initial data processing request flag (RX8) is off, set values in the remote registers (RWw) beforehand. The values in the remote registers (RWw) related to the setting values of the parameters are checked at the writing. If the setting is incorrect, an error occurs.

7.2 Changing the Parameter

7.2.1 Changing the network configuration

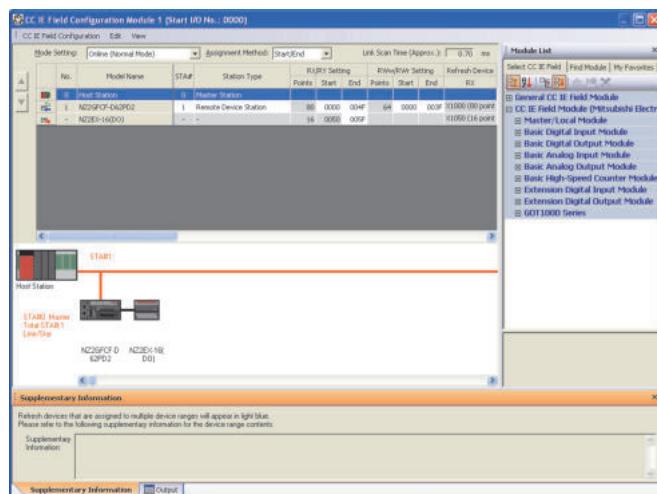
When changing the network configuration diverting the created project, set the parameter in the following procedure.

1. Power off the module.
2. Connect the modules again according to the desired network configuration.
3. Power on the module.
4. Display the "CC IE Field Configuration" window.
 - When the master/local module is the QJ71GF11-T2

Project window \Rightarrow [Parameter] \Rightarrow [Network Parameter] \Rightarrow [Ethernet/CC IE/MELSECNET] \Rightarrow  button

 - When the master/local module is the LJ71GF11-T2

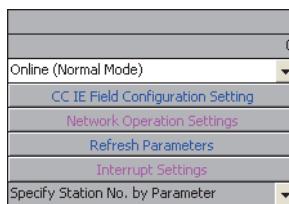
Project window \Rightarrow [Parameter] \Rightarrow [Network Parameter] \Rightarrow [Ethernet/CC IE Field] \Rightarrow  button
5. Drag and drop a module to set the slave station. Input a numerical value to set the station number of the station. Change the value as necessary.



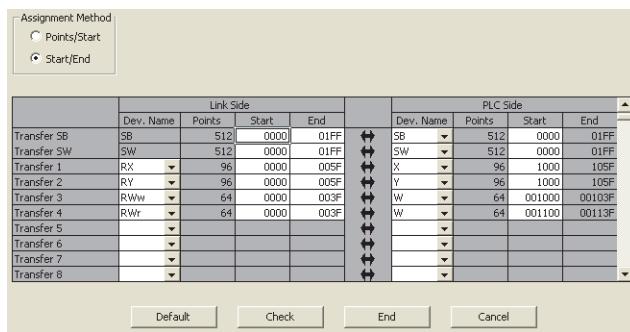
6. Close the "CC IE Field Configuration" window.

Project window \Rightarrow [CC IE Field Configuration] \Rightarrow [Close with Reflecting the Setting]

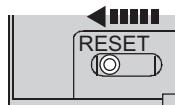
7. Click the  button to display the refresh parameter setting window.



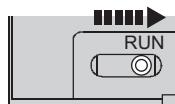
8. Set the refresh parameter. Change the value as necessary.



9. Write the set parameter to the CPU module of the master station and reset the CPU module.



10. Change the status of the CPU module of the master station to RUN.



11. The network configuration setting is now completed.

Set the module parameter of the slave station referring to procedure 4 or later in the following section.

- Parameter Setting ( Page 80, Section 7.1)

Point

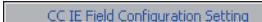
For the network configuration, match the settings in GX Works2 and the CPU module before setting the module parameter of the slave station. When they are not matched, the module parameter of the slave station cannot be written to the slave station.

7.2.2 Changing the parameter without changing the network configuration

To change only the created module parameter of the slave station without changing the network configuration, set the parameter in the following procedure.

1. Display the "CC IE Field Configuration" window.

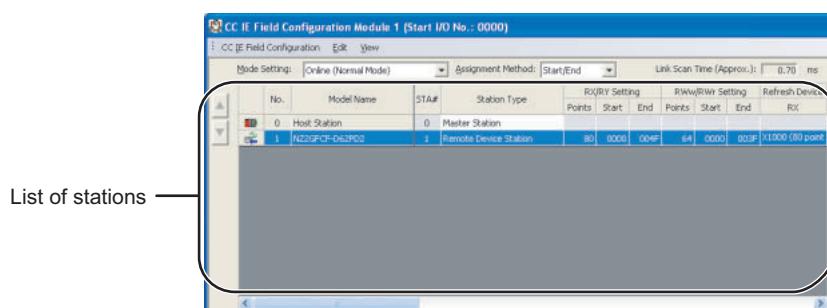
- When the master/local module is the QJ71GF11-T2

Project window \Rightarrow [Parameter] \Rightarrow [Network Parameter] \Rightarrow [Ethernet/CC IE/MELSECNET] \Rightarrow 

- When the master/local module is the LJ71GF11-T2

Project window \Rightarrow [Parameter] \Rightarrow [Network Parameter] \Rightarrow [Ethernet/CC IE Field] \Rightarrow 

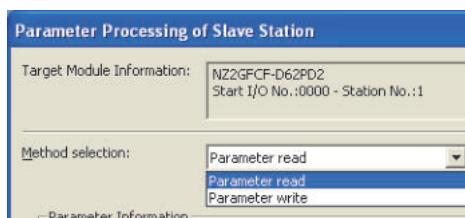
2. Select the high-speed counter module in "List of stations" on the "CC IE Field Configuration" window.



3. Open the "Parameter Processing of Slave Station" window.

 [CC IE Field Configuration] \Rightarrow [Parameter Processing of Slave Station]

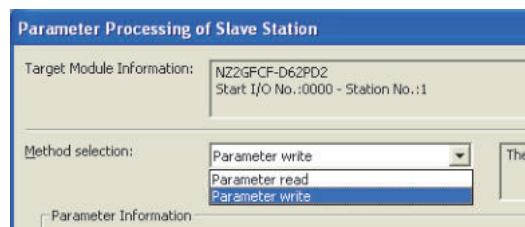
4. Set "Parameter read" for "Method selection".



5. Click the button to read the parameter from the high-speed counter module.

Name	Initial Value	Read Value	Write Value	Setting Range	Unit	Description
Station-based parameter						
<input checked="" type="checkbox"/> Input response time setting	5: 10ms	5: 10ms				Set the input response time
<input checked="" type="checkbox"/> Output HOLD/CLEAR setting	0: CLEAR	0: CLEAR				Set whether to hold or clear
<input checked="" type="checkbox"/> Cyclic data update watch ti...	0	0		0 to 20	x100ms	Set the cyclic data update time
Module-based parameter (main module)						
<input checked="" type="checkbox"/> Comparison output function						Set the comparison output function
Comparison output setti...	0: Coincide...	0: Coincide...				Set the comparison output setting
Coincidence output 1 ch...	0: CH1	0: CH1				Set a channel to be compared
Coincidence output 2 ch...	0: CH1	0: CH1				Set a channel to be compared

6. Set "Parameter write" for "Method selection".



7. Check the read parameter and select the item to be changed from "Write Value". Then set a new value. For the item not to be changed, set the same value as "Read Value" for "Write Value".

Name	Initial Value	Read Value	Write Value	Setting Range	Unit	Description
Station-based parameter						
<input checked="" type="checkbox"/> Input response time setting	5: 10ms	5: 10ms	3: 2ms			Set the input respo
<input checked="" type="checkbox"/> Output HOLD/CLEAR setting	0: CLEAR	0: CLEAR	0: CLEAR			Set whether to hold
<input checked="" type="checkbox"/> Cyclic data update watch ti...	0	0	10	0 to 20	x100ms	Set the cyclic data u
Module-based parameter (main module)						
<input checked="" type="checkbox"/> Comparison output function						Set the compariso
..... Comparison output setti...	0: Coincide...	0: Coincide...	0: Coincide...			Set the compariso
..... Coincidence output 1 ch...	0: CH1	0: CH1	0: CH1			Set a channel to be
..... Coincidence output 2 ch...	0: CH1	0: CH1	0: CH1			Set a channel to be

8. Click the button to write the parameter to the high-speed counter module.
The parameter change is completed.

7.3 Operation Mode List

This section lists the comparison output setting and counter function selection that can be combined with each operation mode.

○: Can be set/—: Cannot be set

Operation mode setting	Setting value *1	Function name	Comparison output setting *2		Counter function selection *3	Reference
			Coincidence	Cam		
Normal mode	0	This mode operates according to the combination of each function and setting.				
		Linear counter function	○	○	—	Page 95, Section 8.2.1
		Ring counter function	○	○	—	Page 97, Section 8.2.2
		Comparison output function				Page 102, Section 8.3
		Coincidence output function	○	—	—	Page 103, Section 8.3.2
		Preset/replace (at coincidence output) function	○	—	—	Page 114, Section 8.3.3
		Cam switch function	—	○	—	Page 117, Section 8.3.4
		Preset/replace function (using RY command or phase Z input terminal)	○	○	—	Page 122, Section 8.4
		Latch counter function by latch counter input terminal	○	○	—	Page 127, Section 8.5
		Count disable function	○	○	0	Page 131, Section 8.7
		Latch counter function (counter function selection)	○	○	1	Page 133, Section 8.8
		Sampling counter function	○	○	2	Page 136, Section 8.9
		Periodic pulse counter function	○	○	3	Page 139, Section 8.10
		Count disable/preset/replace function	○	○	4	Page 142, Section 8.11
		Latch counter/preset/replace function	○	○	5	Page 145, Section 8.12

Operation mode setting	Setting value *1	Function name	Comparison output setting *2		Counter function selection *3	Reference			
			Coinci-dence	Cam					
Dedicated mode	Frequency measurement mode	1	In this mode, the pulses of the pulse input terminals in phase A and B are counted and the frequency is automatically calculated.			Page 148, Section 8.13			
			Frequency measurement function	○	—				
	Rotation speed measurement mode	2	In this mode, the pulses of the pulse input terminals in phase A and B are counted and the rotation speed is automatically calculated.			Page 152, Section 8.14			
			Rotation speed measurement function	○	—				
Common	Pulse measurement mode	3	In this mode, the ON width or OFF width of pulses input to the function input terminal or latch counter input terminal is measured.			Page 156, Section 8.15			
			Pulse measurement function	○	—				
	PWM output mode	4	In this mode, the PWM waveform of 200kHz at a maximum is output from any coincidence output 1 to 4 terminals (EQU1 to EQU4).			Page 160, Section 8.16			
			PWM output function	○	—				
		—	Error notification function	○	○	—	Page 169, Section 8.19		
			Output HOLD/CLEAR setting function	○	○	—	Page 167, Section 8.17		
			Cyclic data update watch function	○	○	—	Page 168, Section 8.18		
			Function at the extension I/O module installation				Page 172, Section 8.20		
			Input function (extension input module)	○	—	—			
			Output function (extension output module)	○	○	—			
			Input response time setting function (extension input module)	○	—	—			
			External power supply monitoring function (extension output module)	○	○	—			
			Number of ON times integration function (extension output module)	○	—	—			

*1 The value set in CH□ Operation mode setting (address: 0120_H, 0140_H)

*2 The value set in Comparison output setting (address: 0100_H)

*3 The value set in CH□ Counter function selection (address: 0126_H, 0146_H)

CHAPTER 8 FUNCTIONS

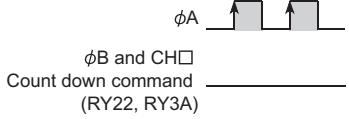
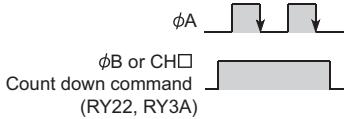
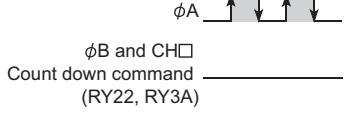
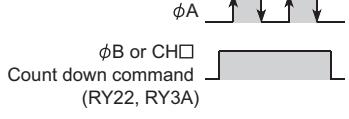
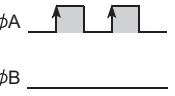
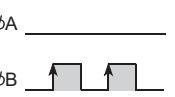
This chapter describes the high-speed counter module functions.

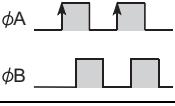
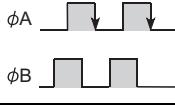
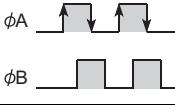
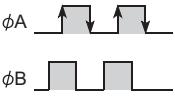
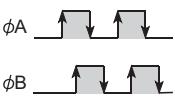
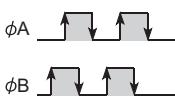
8.1 Pulse Input Modes and Counting Methods

8.1.1 Types of pulse input modes

There are six pulse input modes: 1-phase pulse input (1 multiple/2 multiples), CW/CCW pulse input, and 2-phase pulse input (1 multiple/2 multiples/4 multiples).

(1) Pulse input modes and count timing

Pulse input mode	Count timing		
1-phase multiple of 1	For counting up		Counts on the rising edge (\uparrow) of ϕA . ϕB and $CH\Box$ Count down command (RY22, RY3A) are off.
	For counting down		Counts on the falling edge (\downarrow) of ϕA . ϕB or $CH\Box$ Count down command (RY22, RY3A) is on.
1-phase multiple of 2	For counting up		Counts on the rising edge (\uparrow) and the falling edge (\downarrow) of ϕA . ϕB and $CH\Box$ Count down command (RY22, RY3A) are off.
	For counting down		Counts on the rising edge (\uparrow) and the falling edge (\downarrow) of ϕA . ϕB or $CH\Box$ Count down command (RY22, RY3A) is on.
CW/CCW	For counting up		Counts on the rising edge (\uparrow) of ϕA . ϕB is off.
	For counting down		ϕA is off. Counts on the rising edge (\uparrow) of ϕB .

Pulse input mode	Count timing		
2-phase multiple of 1	For counting up		Counts on the rising edge (↑) of φA while φB is off.
	For counting down		Counts on the falling edge (↓) of φA while φB is off.
2-phase multiple of 2	For counting up		Counts on the rising edge (↑) of φA while φB is off. Counts on the falling edge (↓) of φA while φB is on.
	For counting down		Counts on the rising edge (↑) of φA while φB is on. Counts on the falling edge (↓) of φA while φB is off.
2-phase multiple of 4	For counting up		Counts on the rising edge (↑) of φA while φB is off. Counts on the falling edge (↓) of φA while φB is on. Counts on the rising edge (↑) of φB while φA is on. Counts on the falling edge (↓) of φB while φA is off.
	For counting down		Counts on the rising edge (↑) of φA while φB is on. Counts on the falling edge (↓) of φA while φB is off. Counts on the rising edge (↑) of φB while φA is off. Counts on the falling edge (↓) of φB while φA is on.

Point

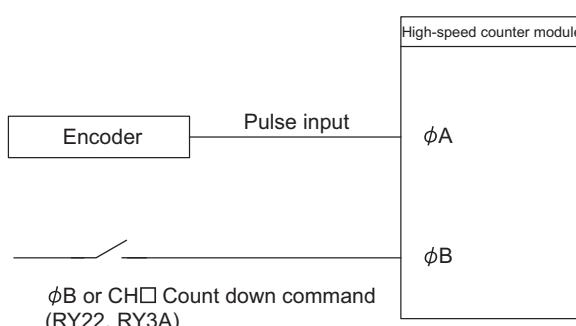
When using the phase B pulse input or CH□ Count down command (RY22, RY3A) for 1-phase pulse input, turn off the unused signals.

When the phase B pulse input or CH□ Count down command (RY22, RY3A) is on, countdown is performed with the phase A pulse input.

(a) 1-phase pulse input

For 1-phase pulse input, multiple of 1 or multiple of 2 can be selected as a counting method.

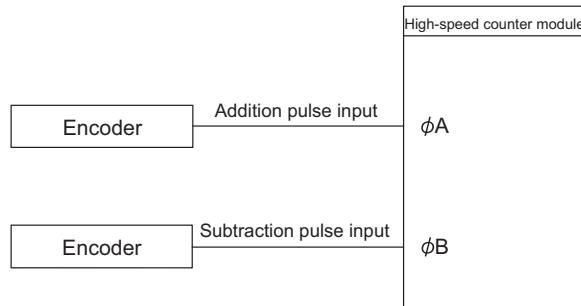
The following figure shows the relationship between phase A pulse input and phase B pulse input or CH□ Count down command (RY22, RY3A).



(b) CW/CCW pulse input

For CW/CCW pulse input, pulses can be counted up with the phase A pulse input and counted down with the phase B pulse input.

The following figure shows the relationship between phase A pulse input and phase B pulse input.

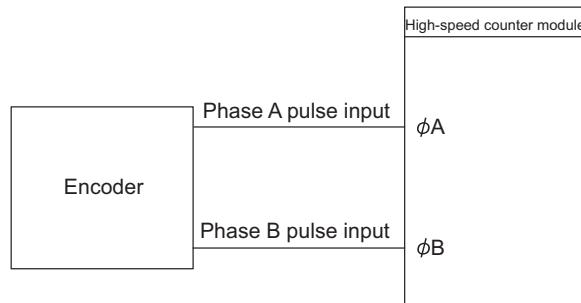


(c) 2-phase pulse input

For 2-phase pulse input, multiple of 1, multiple of 2, or multiple of 4 can be selected as a counting method.

The phase difference between phase A pulses and phase B pulses determines whether the pulses are counted up or down.

The following figure shows the relationship between phase A pulse input and phase B pulse input.



8.1.2 Counting method setting

Set the counting method in the CC IE Field configuration.

1. Set "Parameter write" for "Method selection".

"CC IE Field Configuration" window \Rightarrow Select a high-speed counter module in "List of stations"
 \Rightarrow [CC IE Field Configuration] \Rightarrow [Parameter Processing of Slave Station]

2. Set "CH□ Pulse input mode".

The screenshot shows a table in the 'CC IE Field Configuration' software. The table has two columns. The first column lists configuration parameters, and the second column shows their current values. The 'CH1 Pulse input mode' row is highlighted with a red box, indicating it is being selected. A dropdown menu is open next to the value '0: 1-Phase...', showing five options: 0: 1-Phase Multiple of 1, 1: 1-Phase Multiple of 2, 2: CW/CCW, 3: 2-Phase Multiple of 1, 4: 2-Phase Multiple of 2, and 5: 2-Phase Multiple of 4.

CH1 Pulse input mode	0: 1-Phase...
CH1 Counting speed setting	0: 10kpps
CH1 Counter format	0: Linear C...
CH1 Z phase (Preset) trigger setting	0: Rising
CH1 External preset/replace (Z Phase) r...	0: ON at de...
CH1 Counter function selection	0: Count Di...
CH1 Function input logic setting	0: Positive ...

8.2 Counter Format Selection

Set the counter format in the CC IE Field configuration.

1. Set "Parameter write" for "Method selection".

→ "CC IE Field Configuration" window ⇒ Select a high-speed counter module in "List of stations"
⇒ [CC IE Field Configuration] ⇒ [Parameter Processing of Slave Station]

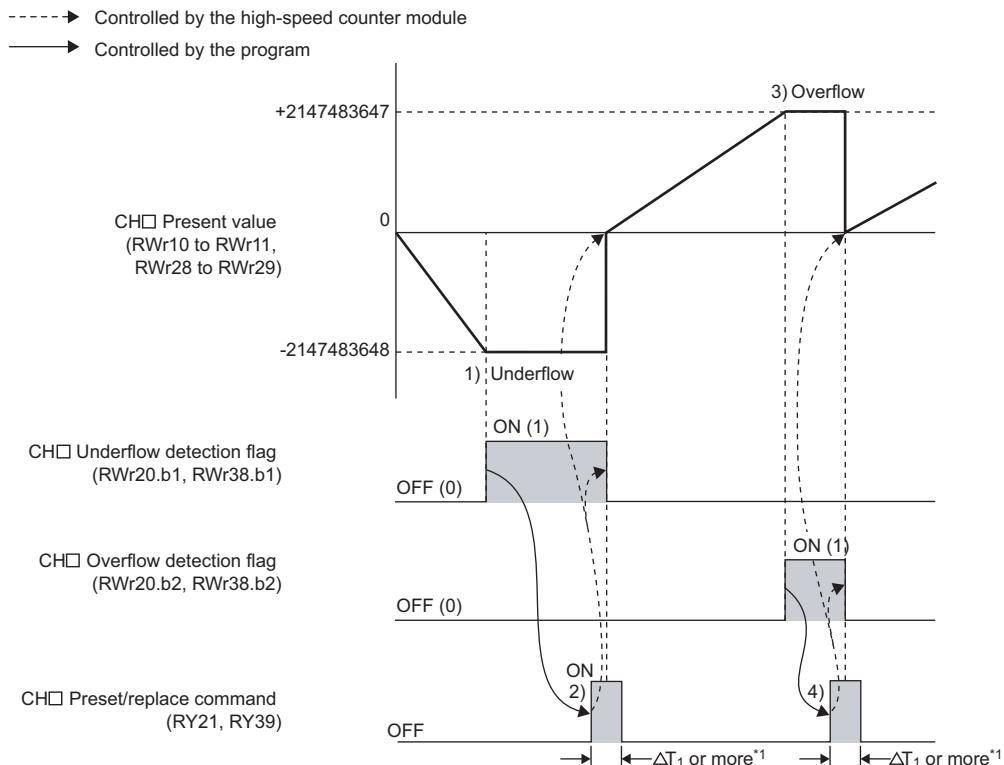
2. Set "CH□ Counter format".

CH1 Counter format	0: Linear C...	▼
CH1 Z phase (Preset) trigger setting	0: Rising	
CH1 External preset/replace (Z Phase) r...	0: ON at de...	
CH1 Counter function selection	0: Count Di... 1: Ring Counter	

8.2.1 Linear counter function

(1) Operation of the linear counter

- When the linear counter is selected, pulses are counted between -2147483648 (lower limit value) and 2147483647 (upper limit value).
- The preset/replace function and the comparison output function can be used together.
- The following figure shows the relationship between CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) of the counter and remote registers at overflow and underflow for the linear counter function.



No.	Description
1)	For counting down from the lower limit value (-2147483648) in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29), the underflow error occurs and CH□ Underflow detection flag (RWr20.b1, RWr38.b1) is changed to Detected (1) from Not detected (0). For details on the underflow error, refer to the following.  Page 96, Section 8.2.1 (2)
2)	When CH□ Preset/replace command (RY21, RY39) is turned off then on to clear the underflow error, the value in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) and CH□ Underflow detection flag (RWr20.b1, RWr38.b1) is changed to Not detected (0) from Detected (1). Counting in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) resumes.
3)	For counting up from the upper limit value (2147483647) in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29), the overflow error occurs and CH□ Overflow detection flag (RWr20.b2, RWr38.b2) is changed to Detected (1) from Not detected (0). For details on the overflow error, refer to the following.  Page 96, Section 8.2.1 (2)
4)	When CH□ Preset/replace command (RY21, RY39) is turned off then on to clear the overflow error, the value in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) and CH□ Overflow detection flag (RWr20.b2, RWr38.b2) is changed to Not detected (0) from Detected (1). Counting in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) resumes.

*1 For ΔT_1 , refer to Page 283, Appendix 4.

(2) Overflow error and underflow error

- When "0: Linear Counter" is selected for "CH□ Counter format", the underflow error occurs at counting down from -2147483648 (lower limit value) in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) and the overflow error occurs at counting up from 2147483647 (upper limit value).
- If the overflow error occurs, CH□ Overflow detection flag (RWr20.b2, RWr38.b2) is set to Detected (1) and CH□ Overflow/underflow error (error code: $\square 200_H$) is stored in CH□ Latest error code (RWr22, RWr3A). Then, the counting stops. The value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) does not change from 2147483647 even when pulses are input.
- If the underflow error occurs, CH□ Underflow detection flag (RWr20.b1, RWr38.b1) is set to Detected (1) and CH□ Overflow/underflow error (error code: $\square 200_H$) is stored in CH□ Latest error code (RWr22, RWr3A). Then, the counting stops. The value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) does not change from -2147483648 even when pulses are input.
- An overflow and underflow error is cleared by the preset/replace function. After CH□ Overflow detection flag (RWr20.b2, RWr38.b2) and CH□ Underflow detection flag (RWr20.b1, RWr38.b1) are set to Not detected (0), the counting resumes. Though, CH□ Latest error code (RWr22, RWr3A) is held until it is reset. Reset CH□ Latest error code (RWr22, RWr3A) by CH□ Error reset command (RY36, RY4E).

8.2.2 Ring counter function

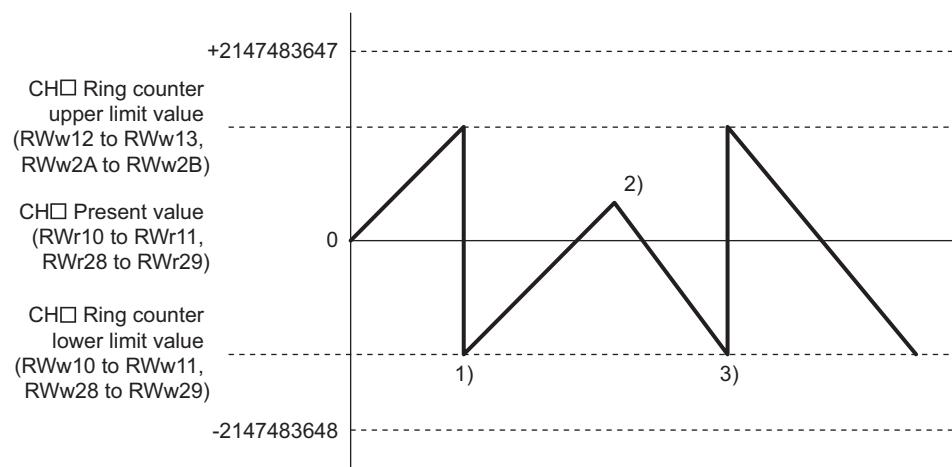
(1) Operation of the ring counter

When "1: Ring Counter" is selected for "CH□ Counter format", pulses are counted repeatedly within the range between CH□ Ring counter lower limit value (RWw10 to RWw11, RWw28 to RWw29) and CH□ Ring counter upper limit value (RWw12 to RWw13, RWw2A to RWw2B) specified by the user.

The overflow and underflow errors do not occur under the ring counter function.

The preset/replace function and the comparison output function can be used together under the ring counter function as well as under the linear counter function.

The following figure shows the relationship among CH□ Present value (RWr10 to RWr11, RWr28 to RWr29), CH□ Ring counter lower limit value (RWw10 to RWw11, RWw28 to RWw29), and CH□ Ring counter upper limit value (RWw12 to RWw13, RWw2A to RWw2B).



No.	Description
1)	When CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is counted up from "CH□ Ring counter upper limit value (RWw12 to RWw13, RWw2A to RWw2B) - 1", CH□ Ring counter lower limit value (RWw10 to RWw11, RWw28 to RWw29) is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29).
2)	Count-up pulse input is changed to count-down pulse input.
3)	When CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is counted down from CH□ Ring counter lower limit value (RWw10 to RWw11, RWw28 to RWw29), "CH□ Ring counter upper limit value (RWw12 to RWw13, RWw2A to RWw2B) - 1" is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29).

(2) Counting range of the ring counter

One of the following three counting ranges of the ring counter is determined by the relationship among CH□ Present value (RWr10 to RWr11, RWr28 to RWr29), CH□ Ring counter lower limit value (RWw10 to RWw11, RWw28 to RWw29), and CH□ Ring counter upper limit value (RWw12 to RWw13, RWw2A to RWw2B) at the time when CH□ Count enable command (RY24, RY3C) is turned on or when the preset/ replace function is performed.

- Ring counter lower limit value \leq Present value \leq Ring counter upper limit value (This range is normally used.)
- "Present value < Ring counter lower limit value" or "Ring counter upper limit value < Present value"
- Ring counter lower limit value = Ring counter upper limit value

Set the ring counter upper limit value and the ring counter lower limit value according to the condition "Ring counter lower limit value \leq Ring counter upper limit value". When CH□ Count enable command (RY24, RY3C) is turned off then on with the condition not satisfied, CH□ Ring counter upper/lower limit value setting error (error code: □210H) is stored in CH□ Latest error code (RWr22, RWr3A) and counting does not start. To start counting, set the ring counter upper limit value and the ring counter lower limit value according to the condition "Ring counter lower limit value \leq Ring counter upper limit value" and turn off then on CH□ Count enable command (RY24, RY3C). The OFF time must be longer than ΔT_1 .

For ΔT_1 , refer to Page 283, Appendix 4.

(a) Ring counter lower limit value \leq Present value \leq Ring counter upper limit value

- For counting up

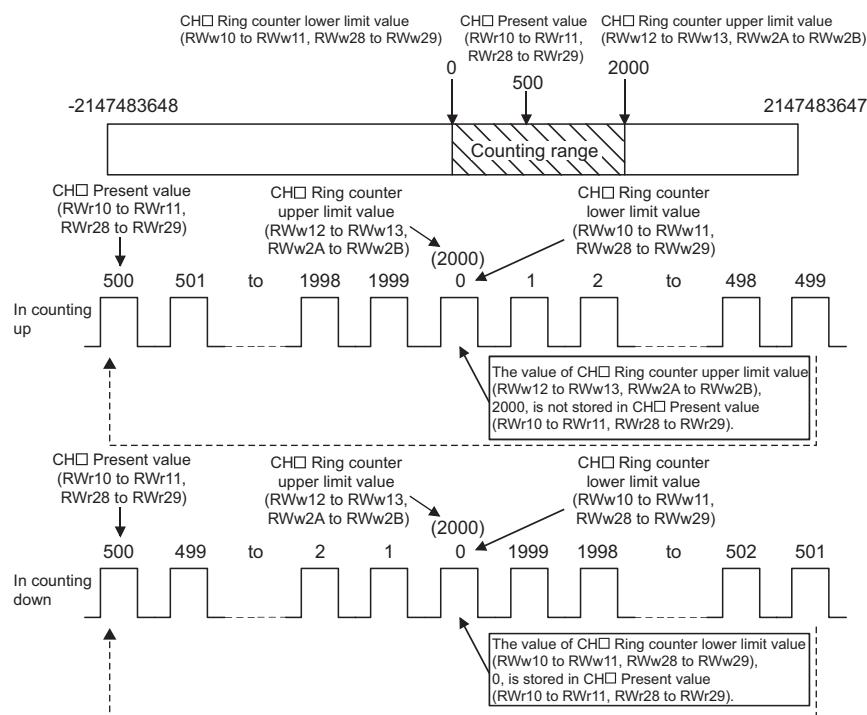
When the value in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) reaches CH□ Ring counter upper limit value (RW_w12 to RW_w13, RW_w2A to RW_w2B), the value in CH□ Ring counter lower limit value (RW_w10 to RW_w11, RW_w28 to RW_w29) is automatically stored in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29).

- For counting down

When the value in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) reaches CH□ Ring counter lower limit value (RW_w10 to RW_w11, RW_w28 to RW_w29), the value in CH□ Ring counter lower limit value (RW_w10 to RW_w11, RW_w28 to RW_w29) is held as the present value. The value "ring counter upper limit value - 1" is stored in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) at the next count-down pulse input.

Both for counting up and down, the value in CH□ Ring counter upper limit value (RW_w12 to RW_w13, RW_w2A to RW_w2B) is not stored in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29). (Except for the case that the present value equals to the ring counter upper limit value when CH□ Count enable command (RY24, RY3C) is turned off then on, or when the preset/replace function is performed. When pulses are counted up or down in the status, the operation is the same as that of when pulses are counted from CH□ Ring counter lower limit value (RW_w10 to RW_w11, RW_w28 to RW_w29>.)

For example, if CH□ Count enable command (RY24, RY3C) is turned on when CH□ Ring counter lower limit value (RW_w10 to RW_w11, RW_w28 to RW_w29) is 0, CH□ Ring counter upper limit value (RW_w12 to RW_w13, RW_w2A to RW_w2B) is 2000, and CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) is 500, the counting range and the CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) change as follows.



(b) "Present value < Ring counter lower limit value" or "Ring counter upper limit value < Present value"

- For counting up

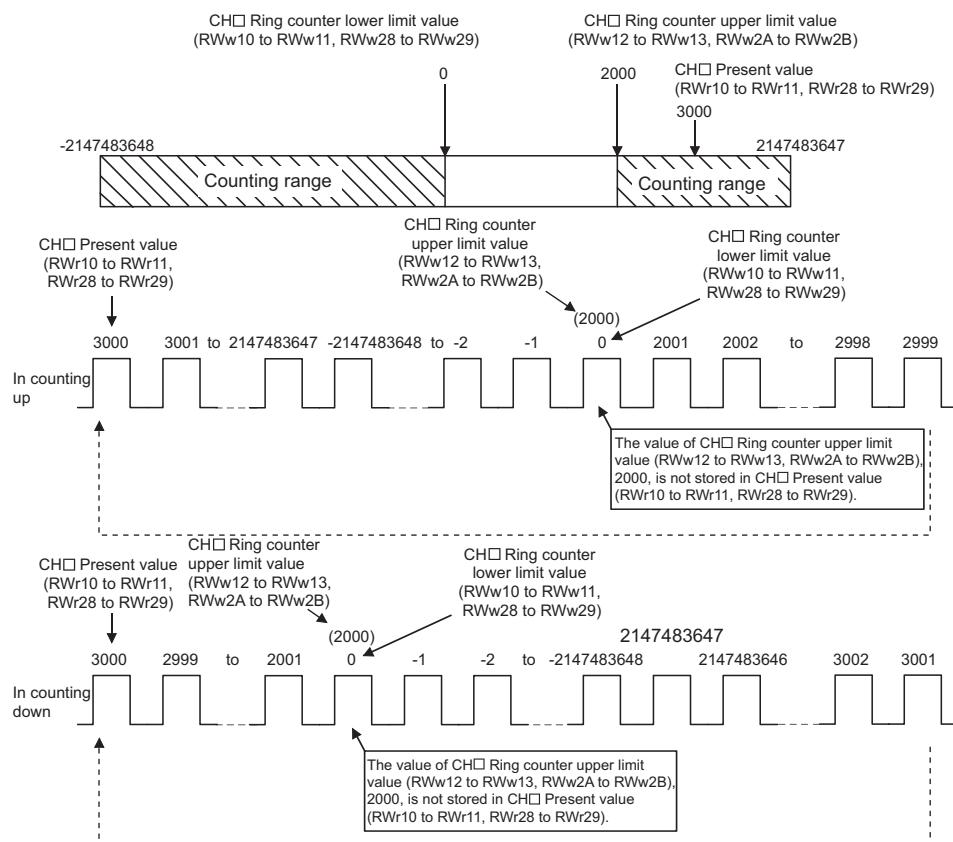
When the value in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) reaches CH□ Ring counter lower limit value (RW_w10 to RW_w11, RW_w28 to RW_w29), the value in CH□ Ring counter lower limit value (RW_w10 to RW_w11, RW_w28 to RW_w29) is held as the present value. The value "ring counter upper limit value + 1" is stored in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) at the next count-up pulse input.

- For counting down

When the value in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) reaches CH□ Ring counter upper limit value (RW_w12 to RW_w13, RW_w2A to RW_w2B), the value in CH□ Ring counter lower limit value (RW_w10 to RW_w11, RW_w28 to RW_w29) is automatically stored in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29).

Both for counting up and down, the value in CH□ Ring counter upper limit value (RW_w12 to RW_w13, RW_w2A to RW_w2B) is not stored in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29).

For example, if CH□ Count enable command (RY24, RY3C) is turned on when CH□ Ring counter lower limit value (RW_w10 to RW_w11, RW_w28 to RW_w29) is 0, CH□ Ring counter upper limit value (RW_w12 to RW_w13, RW_w2A to RW_w2B) is 2000, and CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) is 3000, the counting range and the CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) change as follows.



(c) Ring counter lower limit value = Ring counter upper limit value

When the ring counter lower limit value equals to the ring counter upper limit value, the counting range is from -2147483648 to 2147483647 regardless of CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29).

Point

- The setting values of CH□ Ring counter upper limit value (RWw12 to RWw13, RWw2A to RWw2B) and CH□ Ring counter lower limit value (RWw10 to RWw11, RWw28 to RWw29) can be reflected by turning off then on Initial data processing completion flag (RY8) or by turning off then on Initial data setting request flag (RY9). In that case, however, monitoring data such as CH□ Present value (RWw10 to RWw11, RWw28 to RWw29) is cleared. For ordinary use, reflect the setting values by turning off then on CH□ Count enable command (RY24, RY3C).
- When CH□ Count enable command (RY24, RY3C) is on, the stored value does not change even if a value is written to CH□ Ring counter lower limit value (RWw10 to RWw11, RWw28 to RWw29) and CH□ Ring counter upper limit value (RWw12 to RWw13, RWw2A to RWw2B).
Turn off CH□ Count enable command (RY24, RY3C) before changing CH□ Ring counter upper limit value (RWw12 to RWw13, RWw2A to RWw2B) and CH□ Ring counter lower limit value (RWw10 to RWw11, RWw28 to RWw29). The OFF time must be longer than ΔT_1 .
For ΔT_1 , refer to Page 283, Appendix 4.
- Always turn off CH□ Count enable command (RY24, RY3C) before changing the counting range by the preset/replace function to prevent a miscount.

8.3 Comparison Output Function

The comparison output function outputs ON/OFF signals comparing the count value with any point or range set by the user.

The coincidence output function or the cam switch function can be selected depending on the processing method.

Set the comparison output function in the parameter setting window or Comparison output setting (address: 0100_H).

8.3.1 Operation overview of the coincidence output function and the cam switch function

The following table shows the operation overview of the coincidence output function and the cam switch function.

Item	Coincidence output function	Cam switch function
Comparison target	CH□ Present value (RWr10 to RWr11, RWr28 to RWr29)	CH□ Present value (RWr10 to RWr11, RWr28 to RWr29)
Number of output points per channel	0 to 4 points	0 to 16 points
Comparison start timing	When Initial data processing request flag (RX8) is off and Initial data setting completion flag (RX9) is off	When CH□ Cam switch execute (RX26, RX3E) is turned off then on
Setting item for comparison point/range	<ul style="list-style-type: none">Point setting (Coincidence output 1 to 4)/Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD)Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF)	<ul style="list-style-type: none">Cam switch function parameter data (address: 1500_H to 1FFF_H)
Change method of comparison point/range	<ul style="list-style-type: none">Turning off then on Setting change request (Coincidence output 1 to 4) (RY14 to RY17)Turning off then on Initial data processing completion flag (RY8)Turning off then on Initial data setting request flag (RY9)^{*1}	Turning off then on CH□ Cam switch execute (RX26, RX3E)
Comparison result	Internal output	<ul style="list-style-type: none">Coincidence output 1 to 4 (RX10 to RX13)Counter value greater/smaller signal (RWr0) (only for coincidence output)
	External output	Coincidence output 1 to 4 terminals (EQU1 to EQU4)
Preset/replace (at coincidence output) function	Provided	Not provided
Output reset timing	<ul style="list-style-type: none">When Reset command (Coincidence output 1 to 4) (RY10 to RY13) is turned off then on (for coincidence output)When values are counted outside the detection area (for within-range output or out-of-range output)	Automatically reset depending on Cam switch function, step No.1 to No.16 setting (Output 1 to 16) of remote buffer memory
External output enable timing	When CH□ Coincidence output enable command (RY20, RY38) is turned off then on	When CH□ Cam switch execute (RX26, RX3E) is turned off then on after CH□ Cam switch execute command (RY26, RY3E) is turned off then on

*1 When Initial data processing request flag (RX8) is on, the setting data is not checked.

8.3.2 Coincidence output function

The coincidence output function compares CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) with a coincidence detection point or with an area divided by the coincidence output upper/lower limit value, and outputs the comparison result from Coincidence output 1 to 4 terminals (EQU1 to EQU4). At coincidence output, Coincidence output 1 to 4 (RX10 to RX13) turns on.

The unit to output the comparison result is called coincidence output.

Four points are assigned to coincidence output. The present value is compared with each point and the comparison result is output from the point.

(1) Setting method of the coincidence output function

1. Set "Parameter write" for "Method selection".

 "CC IE Field Configuration" window \Rightarrow Select a high-speed counter module in "List of stations"
 \Rightarrow [CC IE Field Configuration] \Rightarrow [Parameter Processing of Slave Station]

2. Set "0: Coincidence Output Function" for "Comparison output setting".

<input checked="" type="checkbox"/>	Comparison output function			
	Comparison output setting	0: Coincide...		
	Coincidence output 1 channel assignme...	0: CH1		
	Coincidence output 2 channel assignme...	0: CH1	0: Coincidence Output Function	
	Coincidence output 3 channel assignme...	0: CH1	1: Cam Switch Function	

3. Set a channel to be compared for "Coincidence output 1 to 4 channel assignment setting".

.....	Coincidence output 1 channel assignment setting	0: CH1		
.....	Coincidence output 2 channel assignment setting	0: CH1		
.....	Coincidence output 3 channel assignment setting	0: CH1	0: CH1	
.....	Coincidence output 4 channel assignment setting	0: CH1	1: CH2	

4. Set the comparison condition for "Coincidence output 1 to 4 comparison condition setting".

.....	Coincidence output 1 comparison condition setting	0: Coincide...		
.....	Coincidence output 2 comparison condition setting	0: Coincide...		
.....	Coincidence output 3 comparison condition setting	0: Coincide...	0: Coincidence Output	
.....	Coincidence output 4 comparison condition setting	0: Coincide...	1: Within-range Output	
.....	Preset/replace setting at coincidence output (Coinci...	0: Present ...	2: Out-of-range Output	

Point

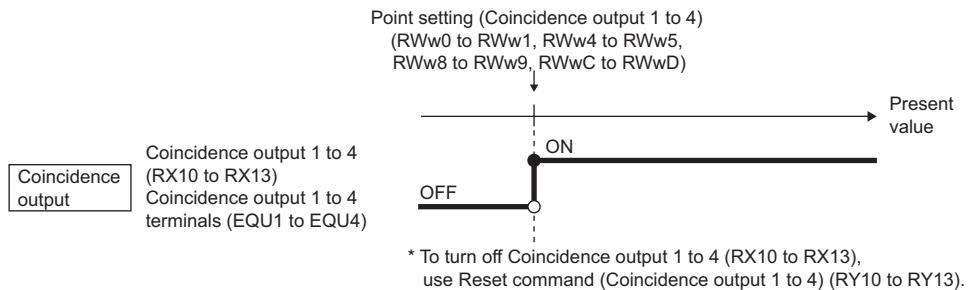
When "Operation mode setting" is set to a mode other than "0: Normal Mode", the setting of "Coincidence output 1 to 4 comparison condition setting" is ignored.

(2) Comparison condition types and setting

Depending on the selected comparison condition, the range to be compared with the present value differs.

(a) Coincidence output

Coincidence output 1 to 4 turn on when CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) matches with a point set in Point setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD).



(b) Within-range output

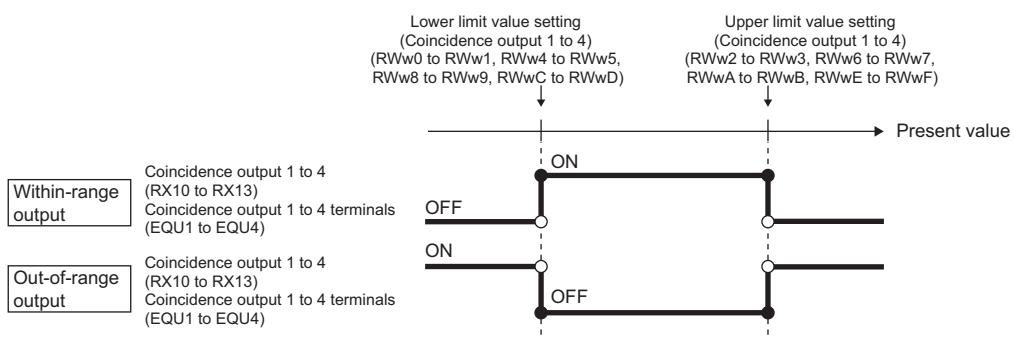
Coincidence output 1 to 4 turn on when both the following conditions are satisfied.

- When CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD) or more
- When CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF) or less

(c) Out-of-range output

Coincidence output 1 to 4 turn on when either of the following conditions is satisfied.

- When CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is less than Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD)
- When CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) exceeds Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF)



(3) Comparison start timing of the coincidence output function

The coincidence output function starts comparison when "CH□ Operation mode setting" is set to "0: Normal Mode", and when Initial data processing request flag (RX8) turns off then on.

The following table lists the timing of when the settings related to the coincidence output function are enabled.

○: Enable —: Disable

Setting item	Timing of when settings are enabled			Reference
	When Initial data processing completion flag (RY8) is turned off then on	When Initial data setting request flag (RY9) is turned off then on	When Setting change request (Coincidence output 1 to 4) (RY14 to RY17) is turned off then on	
"Coincidence output 1 to 4 channel assignment setting"	—	○	—	—
"Coincidence output 1 to 4 comparison condition setting"	—	○	—	—
"Preset/replace setting at coincidence output (Coincidence output 1 to 2)"*3	—	○	—	—
Point setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD)	○*1	○*2	○	Page 261, Appendix 2 (7), Page 262, Appendix 2 (8)
Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD)	○*1	○*2	○	Page 261, Appendix 2 (7), Page 262, Appendix 2 (8)
Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF)	○*1	○*2	○	Page 261, Appendix 2 (7), Page 262, Appendix 2 (8)

*1 When Initial data processing request flag (RX8) is on, the setting data is checked.

*2 When Initial data processing request flag (RX8) is on, the setting data is not checked.

*3 For details on the preset/replace (at coincidence output) function, refer to the following.

 Page 114, Section 8.3.3

(4) Output destination of comparison result for the coincidence output function

The following table lists the output destination of the comparison result for each comparison condition.

○: Enable —: Disable

Setting item	Comparison condition			Output overview>
	Coincidence output	Within-range output	Out-of-range output	
Coincidence output 1 to 4 (RX10 to RX13)	○	○	○	Outputs the result whether the specified comparison condition was satisfied or not.
Coincidence output 1 to 4 terminals (EQU1 to EQU4)	○	○	○	
Counter value greater/smaller signal (RWr0)	○	—	—	Outputs a relationship (greater or smaller) between the present value and the point setting (coincidence output 1 to 4).

The following table lists the details on Counter value greater/smaller signal (RWr0).

Details	Bit name	Point setting (Coincidence output 1 to 4)		
		(Present value) >	(Present value) =	(Present value) <
b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0	Counter value smaller (Coincidence output 1 to 4)	0	0	1
0 0 0 0 0 0 0 0 0 Counter value greater Counter value smaller	Counter value greater (Coincidence output 1 to 4)	1	0	0

(5) Output setting on Coincidence output 1 to 4 terminals (EQU1 to EQU4)

To output signals from Coincidence output 1 to 4 terminals (EQU1 to EQU4) to outside, enable output by turning on CH□ Coincidence output enable command (RY20, RY38).

Doing so enables all coincidence outputs assigned to the target channel in "Coincidence output 1 to 4 channel assignment setting".

Comparison condition	Comparison setting item	Setting details	Reference
Coincidence output	Point setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD)	Set the point to be compared with the present value.	Page 261, Appendix 2 (7), Page 262, Appendix 2 (8)
Within-range output or out-of-range output	<ul style="list-style-type: none"> • Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF) • Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD) 	Set the upper and lower limit values for the area to be compared with the present value. When the upper limit value is less than the lower limit value, Upper limit value setting error (Coincidence output 1 to 4) (error code: □311 _H to □314 _H) occurs.	Page 261, Appendix 2 (7), Page 262, Appendix 2 (8)

Point

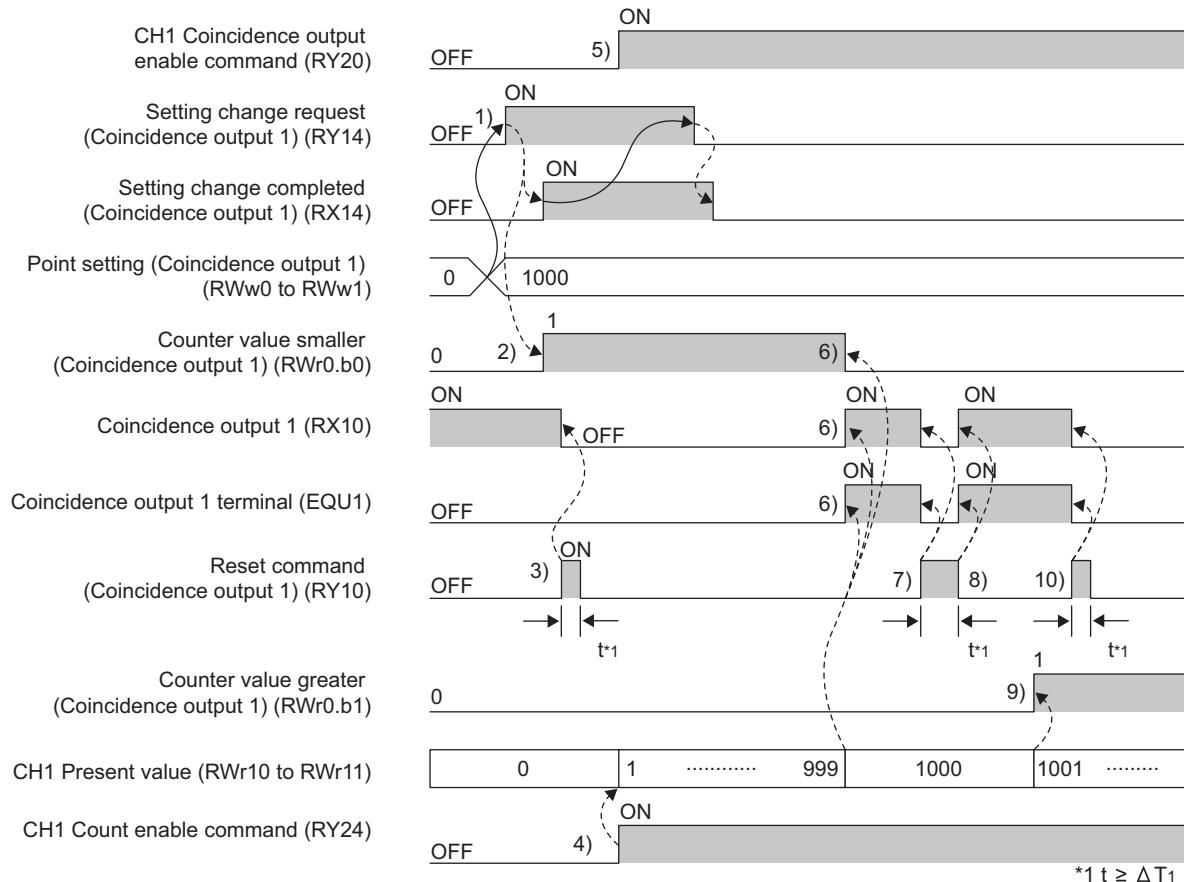
Turning off then on Initial data processing completion flag (RY8) when the comparison condition is coincidence output or when the comparison setting item for within-range output (Point setting (Coincidence output 1)/Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) to Upper limit value setting (Coincidence output 4) (RWwE to RWwF)) is 0 (default) turns on Coincidence output 1 to 4 (RX10 to RX13) because CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) of when Initial data processing request flag (RX8) is turned off is 0 (default). To turn off Coincidence output 1 to 4 (RX10 to RX13), set the comparison setting item to other than 0 or to a range that does not include 0 before turning off then on Initial data processing completion flag (RY8).

(6) Operation example of each comparison condition

(a) Operation example of coincidence output

The following figure shows the timing to enable Point setting (Coincidence output 1) and an operation example of when the present value matches Point setting (Coincidence output 1) (1000) for the case where coincidence output is set as the comparison condition. Note that Coincidence output 1 is assigned to CH1.

----> Controlled by the high-speed counter module
 -----> Controlled by the program



*1 $t \geq \Delta T_1$

No.	Description
1)	Start comparison of the present value and a value set to Point setting (Coincidence output 1) (RWw0 to RWw1) in the following order. (1) Write 1000 into Point setting (Coincidence output 1) (RWw0 to RWw1). (2) Turn off then on Setting change request (Coincidence output 1) (RY14). (3) The values set in Point setting (Coincidence output 1) (RWw0 to RWw1) are enabled when Setting change completed (Coincidence output 1) (RX14) turns on. After confirming that Setting change completed (Coincidence output 1) (RX14) turns on, turn off Setting change request (Coincidence output 1) (RY14).
2)	When CH1 Present value (RW _r 10 to RW _r 11) is less than Point setting (Coincidence output 1) (RWw0 to RWw1), the value in Counter value smaller (Coincidence output 1) (RW _r 0.b0) is 1.
3)	When Reset command (Coincidence output 1) (RY10) is turned on, Coincidence output 1 (RX10) and the coincidence output 1 terminal (EQU1) turn off.
4)	Turn off then on CH1 Count enable command (RY24) to start counting.
5)	If performing coincidence output from the coincidence output 1 terminal (EQU1), turn on CH1 Coincidence output enable command (RY20).
6)	When CH1 Present value (RW _r 10 to RW _r 11) equals to Point setting (Coincidence output 1) (RWw0 to RWw1), Coincidence output 1 (RX10) and the coincidence output 1 terminal (EQU1) turn on. Also, Counter value smaller (Coincidence output 1) (RW _r 0.b0) becomes 0.
7)	If Reset command (Coincidence output 1) (RY10) is turned on while CH1 Present value (RW _r 10 to RW _r 11) and Point setting (Coincidence output 1) (RWw0 to RWw1) match, Coincidence output 1 (RX10) and the coincidence output 1 terminal (EQU1) turn off.
8)	If Reset command (Coincidence output 1) (RY10) is turned off while CH1 Present value (RW _r 10 to RW _r 11) and Point setting (Coincidence output 1) (RWw0 to RWw1) match, Coincidence output 1 (RX10) and the coincidence output 1 terminal (EQU1) turn on again.
9)	When CH1 Present value (RW _r 10 to RW _r 11) is more than Point setting (Coincidence output 1) (RWw0 to RWw1), the value in Counter value greater (Coincidence output 1) (RW _r 0.b1) is 1.
10)	Turn on Reset command (Coincidence output 1) (RY10) to reset Coincidence output 1 (RX10) and the coincidence output 1 terminal (EQU1). If Coincidence output 1 (RX10) and the coincidence output 1 terminal (EQU1) remain on, the next coincidence output cannot be detected.

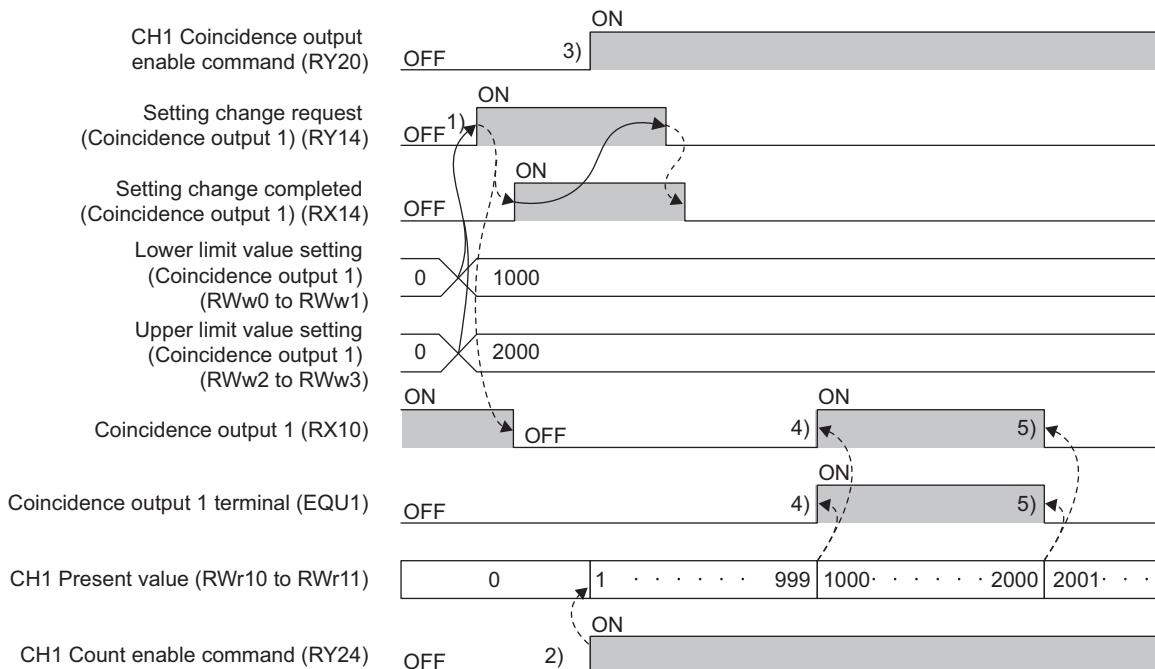
Point

- Coincidence output 1 to 4 (RX10 to RX13) turn on regardless of CH□ Coincidence output enable command (RY20, RY38).
- Set the ON time of Reset command (Coincidence output 1 to 4) (RY10 to RY13) to ΔT_1 or longer.
For ΔT_1 , refer to Page 283, Appendix 4.
- Due to coincidence detection processing inside the high-speed counter module, the counter value greater or smaller corresponding to Counter value greater/smaller signal (RW_r0) is not updated at the same time when Coincidence output 1 to 4 (RX10 to RX13) turns off then on. Therefore, the counter value greater or smaller may be 1 even though it is not the correct value.
- Even if Point setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD) is changed, the present value is not compared with the changed value unless Setting change request (Coincidence output 1 to 4) (RY14 to RY17) is turned off then on.

(b) Operation example of within-range output

The following figure shows the timing to enable Lower limit value setting (Coincidence output 1) (1000) and Upper limit value setting (Coincidence output 1) (2000) and an operation example of when the present value reaches the setting range (1000 to 2000) for the case where within-range output is set as the comparison condition. Note that Coincidence output 1 is assigned to CH1.

----> : Controlled by the high-speed counter module
 -----> : Controlled by the program



No.	Description
1)	Start comparison of the present value and values set to Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) and Upper limit value setting (Coincidence output 1) (RWw2 to RWw3) in the following order. (1) Write 1000 into Lower limit value setting (Coincidence output 1) (RWw0 to RWw1). (2) Write 2000 into Upper limit value setting (Coincidence output 1) (RWw2 to RWw3). (3) Turn off then on Setting change request (Coincidence output 1) (RY14). (4) The values set for Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) and Upper limit value setting (Coincidence output 1) (RWw2 to RWw3) are enabled when Setting change completed (Coincidence output 1) (RX14) turns on. After confirming that Setting change completed (Coincidence output 1) (RX14) turns on, turn off Setting change request (Coincidence output 1) (RY14).
2)	Turn off then on CH1 Count enable command (RY24) to start counting.
3)	If performing coincidence output from the coincidence output 1 terminal (EQU1), turn on CH1 Coincidence output enable command (RY20).
4)	When CH1 Present value (RWr10 to RWr11) is Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) or more and the present value is within the specified range, Coincidence output 1 (RX10) and the coincidence output 1 terminal (EQU1) turn on.
5)	When CH1 Present value (RWr10 to RWr11) is more than Upper limit value setting (Coincidence output 1) (RWw2 to RWw3) and the present value is outside the specified range, Coincidence output 1 (RX10) and the coincidence output 1 terminal (EQU1) turn off.

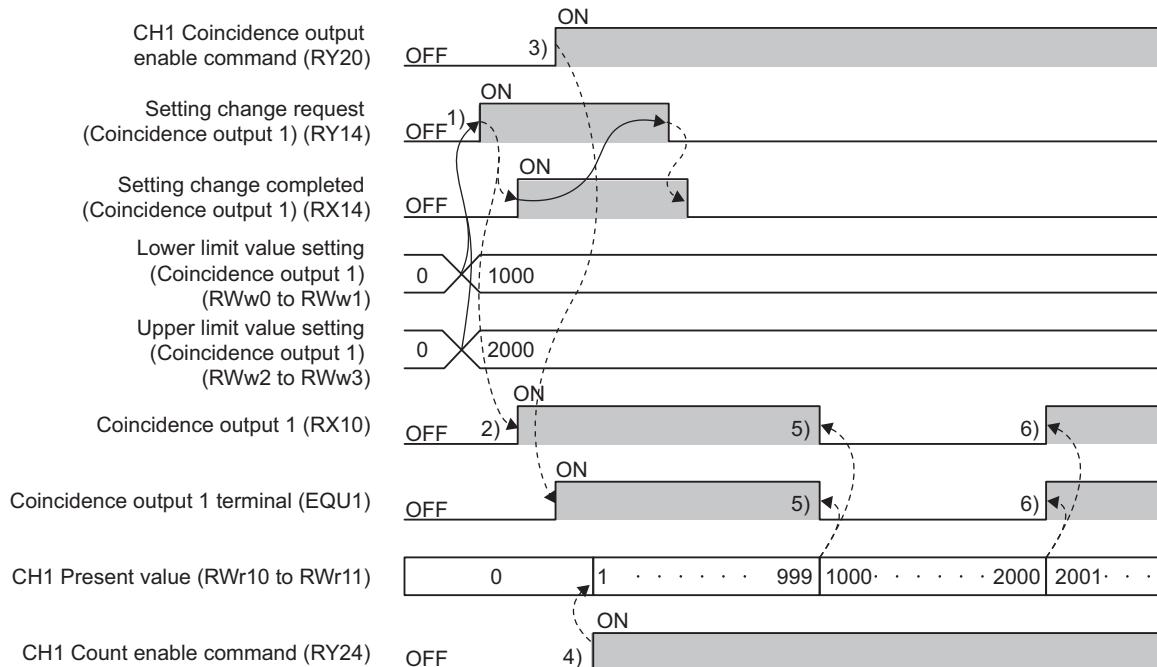
Point 

- Coincidence output 1 to 4 (RX10 to RX13) turn on regardless of CH□ Coincidence output enable command (RY20, RY38).
- Even if Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD) and Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF) are changed, the present value is not compared with the changed value unless Setting change request (Coincidence output 1 to 4) (RY14 to RY17) is turned off then on.

(c) Operation example of out-of-range output

The following figure shows the timing to enable Lower limit value setting (Coincidence output 1) (1000) and Upper limit value setting (Coincidence output 1) (2000) and an operation example of when the present value reaches out of the setting range (1000 to 2000) for the case where out-of-range output is set as the comparison condition. Note that Coincidence output 1 is assigned to CH1.

----> Controlled by the high-speed counter module
 -----> Controlled by the program



No.	Description
1)	Start comparison of the present value and values set to Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) and Upper limit value setting (Coincidence output 1) (RWw2 to RWw3) in the following order. (1) Write 1000 into Lower limit value setting (Coincidence output 1) (RWw0 to RWw1). (2) Write 2000 into Upper limit value setting (Coincidence output 1) (RWw2 to RWw3). (3) Turn off then on Setting change request (Coincidence output 1) (RY14). (4) The values set for Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) and Upper limit value setting (Coincidence output 1) (RWw2 to RWw3) are enabled when Setting change completed (Coincidence output 1) (RX14) turns on. After confirming that Setting change completed (Coincidence output 1) (RX14) turns on, turn off Setting change request (Coincidence output 1) (RY14).
2)	CH1 Present value (RWrl0 to RWrl1) becomes less than Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) and Coincidence output 1 (RX10) turns on since the present value is outside the specified range.
3)	If performing coincidence output from the coincidence output 1 terminal (EQU1), turn on CH1 Coincidence output enable command (RY20). In this case, the coincidence output 1 terminal (EQU1) turns on immediately since Coincidence output 1 (RX10) is already on.
4)	Turn off then on CH1 Count enable command (RY24) to start counting.
5)	When CH1 Present value (RWrl0 to RWrl1) is Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) or more and the present value is within the specified range, Coincidence output 1 (RX10) and the coincidence output 1 terminal (EQU1) turn off.
6)	When CH1 Present value (RWrl0 to RWrl1) is more than Upper limit value setting (Coincidence output 1) (RWw2 to RWw3) and the present value is outside the specified range, Coincidence output 1 (RX10) and the coincidence output 1 terminal (EQU1) turn on.

Point 

- Coincidence output 1 to 4 (RX10 to RX13) turn on regardless of CH□ Coincidence output enable command (RY20, RY38).
- Even if Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD) and Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF) are changed, the present value is not compared with the changed value unless Setting change request (Coincidence output 1 to 4) (RY14 to RY17) is turned off then on.

8.3.3 Preset/replace (at coincidence output) function

The preset/replace (at coincidence output) function performs the preset/replace function (replaces the present value with a value preset by the user) at the rising state (off to on) of Coincidence output 1 and 2.

The preset/replace by this function is performed to the channel assigned to Coincidence output 1 and 2.

This function is not available for Coincidence output 3 and 4.

(1) Setting method of the preset/replace (at coincidence output) function

1. Set "Parameter write" for "Method selection".

☞ "CC IE Field Configuration" window ⇨ Select a high-speed counter module in "List of stations"
⇨ [CC IE Field Configuration] ⇨ [Parameter Processing of Slave Station]

2. Set "0: Coincidence Output Function" for "Comparison output setting".

<input checked="" type="checkbox"/>	Comparison output function				
	Comparison output setting	0: Coincide...			
	Coincidence output 1 channel assignme...	0: CH1			
	Coincidence output 2 channel assignme...	0: CH1			0: Coincidence Output Function
	Coincidence output 3 channel assignme...	0: CH1			1: Cam Switch Function

3. Set a channel to be compared for "Coincidence output 1 to 4 channel assignment setting".

	Coincidence output 1 channel assignment setting	0: CH1		
	Coincidence output 2 channel assignment setting	0: CH1		
	Coincidence output 3 channel assignment setting	0: CH1		0: CH1
	Coincidence output 4 channel assignment setting	0: CH1		1: CH2

4. Set the comparison condition for "Coincidence output 1 to 4 comparison condition setting".

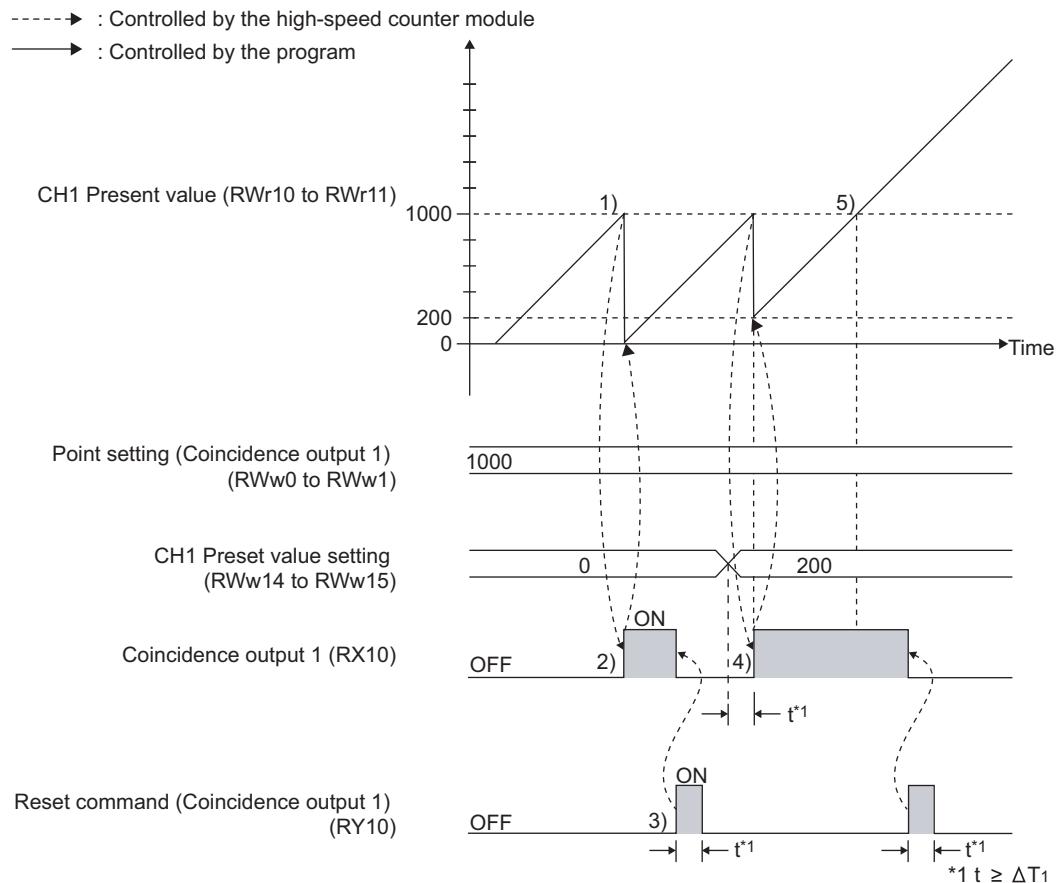
	Coincidence output 1 comparison condition setting	0: Coincide...		
	Coincidence output 2 comparison condition setting	0: Coincide...		
	Coincidence output 3 comparison condition setting	0: Coincide...		0: Coincidence Output
	Coincidence output 4 comparison condition setting	0: Coincide...		1: Within-range Output
	Preset/replace setting at coincidence output (Coinci...	0: Present...		2: Out-of-range Output

5. Set "1: Present value replaced" for "Preset/replace setting at coincidence output (Coincidence output 1 to 2)".

	Coincidence output 4 comparison condition setting	0: Coincide...		
	Preset/replace setting at coincidence output (Coincidence output 1)	0: Present...		
	Preset/replace setting at coincidence output (Coincidence output 2)	0: Present...		0: Present value not replaced
	Cam switch output unit assignment setting	0: No Assi...		1: Present value replaced
	Cam switch output 1 channel assignment setting	0: CH1		

(2) Operation example of the preset/replace (at coincidence output) function

The following figure shows an operation example in which the preset value (0 or 200) is stored to the present value when the present value reaches Point setting (Coincidence output 1) (1000). Note that the comparison condition of Coincidence output 1 is set to coincidence output, and it is assigned to CH1.



No.	Description
1)	When CH1 Present value (RWr10 to RWr11) equals to Point setting (Coincidence output 1) (RWw0 to RWw1), Coincidence output 1 (RX10) turns on.
2)	The preset/replace function is performed at the rising state (off to on) of Coincidence output 1 (RX10).
3)	Turn on Reset command (Coincidence output 1) (RY10) and turn off Coincidence output 1 (RX10) so that Coincidence output 1 (RX10) rises (off to on) when the next CH1 Present value (RWr10 to RWr11) = Point setting (coincidence output 1) (RWw0 to RWw1) is made.
4)	If CH1 Preset value setting (RWw14 to RWw15) was changed in advance, the preset/replace function is performed with the changed value.
5)	If Coincidence output 1 (RX10) was not reset, Coincidence output 1 (RX10) remains on without rising when CH1 Present value (RWr10 to RWr11) = Point setting (Coincidence output 1) (RWw0 to RWw1) is made. Therefore, the preset/replace function does not operate.

Point

- While CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) is on, values cannot be replaced by this function as well as by CH□ Preset/replace command (RY21, RY39). Turn off then on CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B) to turn off CH□ External preset/replace (Z Phase) request detection (RX23, RX3B).
- Have a ΔT_1 or longer interval after changing CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) until the value is replaced because there are maximum of ΔT_1 delay until change in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) is reflected.*1
- To perform the preset/replace function continuously using the same coincidence output, have a ΔT_1 or longer interval. The preset/replace function may not operate if there is not a ΔT_1 or longer interval.*1
The following is the rough standard of an interval for performing the preset/replace function continuously using the same coincidence output.
 $(|Point setting (Coincidence output 1 to 4)|^2 - Preset value setting) > (Input pulse speed (pps)/1000)$
- When the preset/replace (at coincidence output) function is used under the condition where pulses are input in a counting speed of 2Mpps or faster, a pulse count difference (plus one or minus one pulse) occurs. Use the function after checking that the difference does not cause a problem for the system.

*1 For ΔT_1 , refer to Page 283, Appendix 4.

*2 Change this into Upper limit value setting (Coincidence output 1 to 4) or Lower limit value setting (Coincidence output 1 to 4) according to the comparison condition and the setting in which Coincidence output 1 to 4 turns on.

8.3.4 Cam switch function

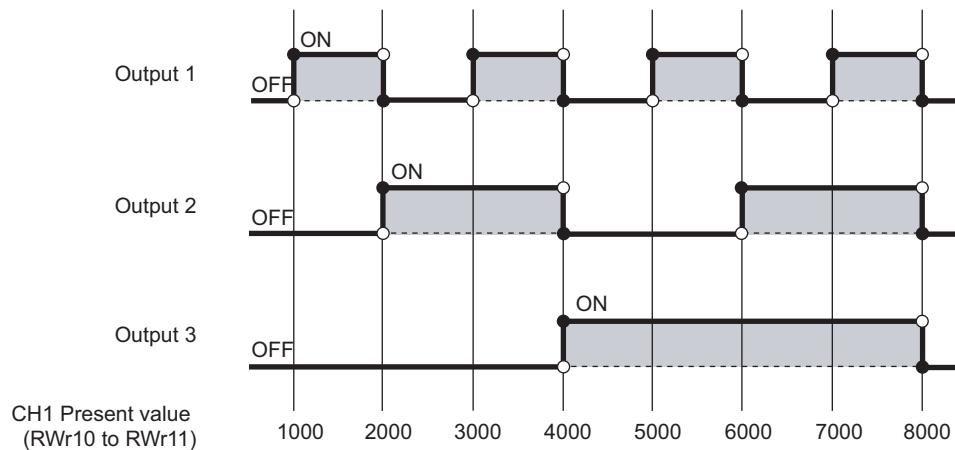
The cam switch function allows users to output the ON/OFF status of any of the output terminals on the extension output module (Y0 to YF) according to the value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29).

The maximum of 16 steps of ON/OFF switching can be set per output point.

Up to 16 output points can be set.

Ex. The following figure and table show an operation example of output control according to CH1 Present value (RWr10 to RWr11) with CH1 being assigned to "Cam switch output 1 channel assignment setting", "Cam switch output 2 channel assignment setting", and "Cam switch output 3 channel assignment setting".

CH1 Present value (RWr10 to RWr11)	Output 3	Output 2	Output 1
-2147483648 to 999	OFF	OFF	OFF
1000 to 1999	OFF	OFF	ON
2000 to 2999	OFF	ON	OFF
3000 to 3999	OFF	ON	ON
4000 to 4999	ON	OFF	OFF
5000 to 5999	ON	OFF	ON
6000 to 6999	ON	ON	OFF
7000 to 7999	ON	ON	ON
8000 to 2147483647	OFF	OFF	OFF



(1) Setting method of the cam switch function

1. Set "Parameter write" for "Method selection".

☞ "CC IE Field Configuration" window ⇒ Select a high-speed counter module in "List of stations"
⇒ [CC IE Field Configuration] ⇒ [Parameter Processing of Slave Station]

2. Set "1: Cam Switch Function" for "Comparison output setting".

<input checked="" type="checkbox"/>	Comparison output function			
	Comparison output setting	0: Coincide...		
	Coincidence output 1 channel assignment setting	0: CH1		
	Coincidence output 2 channel assignment setting	0: CH1		0: Coincidence Output Function 1: Cam Switch Function
	Coincidence output 3 channel assignment setting	0: CH1		

3. Set "1: Stage 1" for "Cam switch output unit assignment setting".

	Cam switch output unit assignment setting	0: No Assi...		
	Cam switch output 1 channel assignment setting	0: CH1		
	Cam switch output 2 channel assignment setting	0: CH1		0: No Assignment 1: Stage 1
	Cam switch output 3 channel assignment setting	0: CH1		

4. Set a channel to be compared for "Cam switch output 1 to 16 channel assignment setting".

	Cam switch output 1 channel assignment setting	0: CH1		
	Cam switch output 2 channel assignment setting	0: CH1		
	Cam switch output 3 channel assignment setting	0: CH1		0: CH1 1: CH2
	Cam switch output 4 channel assignment setting	0: CH1		

5. Set Cam switch function parameter data (address: 1500_H to 1FFF_H) in a program.

For details, refer to the following.

☞ Page 119, Section 8.3.4 (2)

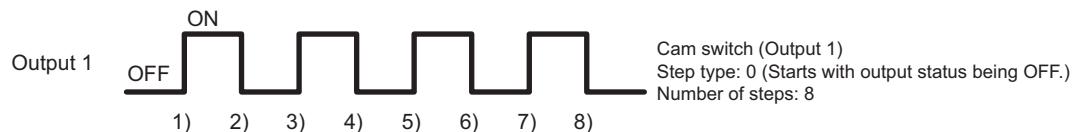


The cam switch function and the number of ON times integration function cannot be used together.

(2) Output range setting

With the cam switch function, the maximum of 16 steps of ON/OFF switching can be set per output point.

The part where the ON/OFF signal status is switched is referred to as a step.



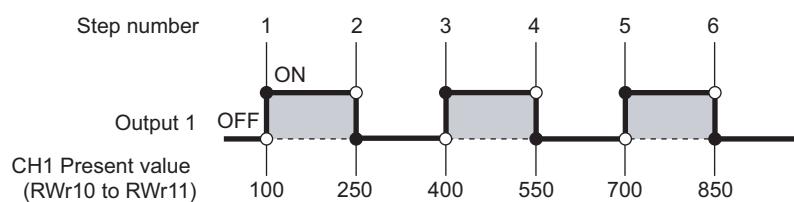
* 1) to 8) indicate the step number.

Setting item	Setting details
Cam switch function, step type (Output 1 to 16)	Set the ON/OFF status of the output of the extension output module (Y0 to YF) at the time when the pulse counting starts.
Cam switch function, number of steps (Output 1 to 16)	Set the number of steps for the cam of Output 1 to 16. Setting range is 0 to 16. In the case where the number of steps is 0, output is always off when set to be started from off in the step type setting and on when set to be started from on in the setting.
Cam switch function, step No.1 to No.16 setting (Output 1 to 16)	Set the count value where the ON/OFF status of the output of the extension output module (Y0 to YF) is switched.

Ex. Cam switch function, step type (Output 1) (address: 1500_H) is set to "Starts with output status being OFF (0_H)", and Cam switch function, number of steps (Output 1) (address: 1501_H) is set to 6.

Note that Output 1 is assigned to CH1.

Setting item	Setting value
Cam switch function, step type (Output 1) (address: 1500 _H)	0
Cam switch function, number of steps (Output 1) (address: 1501 _H)	6
Cam switch function, step No.1 setting (Output 1) (address: 1502 _H to 1503 _H)	100
Cam switch function, step No.2 setting (Output 1) (address: 1504 _H to 1505 _H)	250
Cam switch function, step No.3 setting (Output 1) (address: 1506 _H to 1507 _H)	400
Cam switch function, step No.4 setting (Output 1) (address: 1508 _H to 1509 _H)	550
Cam switch function, step No.5 setting (Output 1) (address: 150A _H to 150B _H)	700
Cam switch function, step No.6 setting (Output 1) (address: 150C _H to 150D _H)	850
Cam switch function, step No.7 setting (Output 1) (address: 150E _H to 150F _H)	Setting not necessary
Cam switch function, step No.16 setting (Output 1) (address: 1520 _H to 1521 _H)	



(3) Minimum setting width of the ON/OFF status

To output the ON/OFF signal according to the setting, set the value of each step No. so that the following formula is satisfied.

$$(\text{Input pulse speed [pps]} \times \text{Allowed time [s]}) \leq \left(\text{Cam switch function, step No.}i + 1 \text{ setting (Output } \blacklozenge \text{)} \right) - \left(\text{Cam switch function, step No.}i \text{ setting (Output } \blacklozenge \text{)} \right)$$

- Allowable time: $(\Delta T_2 \times 2) + (\text{output response time of the extension output module}^{\ast 1})$
- \blacklozenge : Cam switch output No. (1 to 16)
- i : Step No. (1 to 15)

For ΔT_2 , refer to Page 283, Appendix 4.

$\ast 1$ Either of the output response time for switching on from off or that for switching off from on, whichever is longer

Ex. When the input pulse speed is 10kpps and the output response time of the extension output module is 1.5ms

$$\text{Allowable time: } (0.5\text{ms} \times 2) + 1.5\text{ms} = 2.5\text{ms}$$

$$\text{Setting width of the ON/OFF status: } (10 \times 10^3) \times (2.5 \times 10^{-3}) = 25$$

Therefore, set the difference between the values of Cam switch function, step No. i setting (Output \blacklozenge) and Cam switch function, step No. $i + 1$ setting (Output \blacklozenge) to 25 or more.

(4) Timing of when the cam switch function setting is enabled

The following table shows the timing of when the cam switch function is enabled.

CH□ Cam switch execute command (RY26, RY3E) is enabled while Initial data processing request flag (RX8) is off or Initial data setting completion flag (RX9) is off.

○: Enable —: Disable

Setting item	Timing of when settings are enabled	
	When Initial data setting completion flag (RX9) is turned off then on	When CH□ Cam switch execute command (RY26, RY3E) is off then on
"Cam switch output unit assignment setting"	○	—
"Cam switch output 1 to 16 channel assignment setting"	○	—
Cam switch function, step type (Output \blacklozenge) (address: $1500_H + 80_H \times (\blacklozenge - 1)$)	—	○
Cam switch function, number of steps (Output \blacklozenge) (address: $1501_H + 80_H \times (\blacklozenge - 1)$)	—	○
Cam switch function, step No. i setting (Output \blacklozenge) (address: $1502_H + 80_H \times (\blacklozenge - 1)$ to $1521_H + 80_H \times (\blacklozenge - 1)$)	—	○

\blacklozenge : Cam switch output No. (1 to 16)

i : Step No. (1 to 16)



For all of Cam switch function, step type (Output \blacklozenge), Cam switch function, number of steps (Output \blacklozenge), and Cam switch function, step No. i setting (Output \blacklozenge) of cam switch output \blacklozenge that is not used, set the default (0). When a value other than the default is set, output may be turned on when the cam switch function is performed.

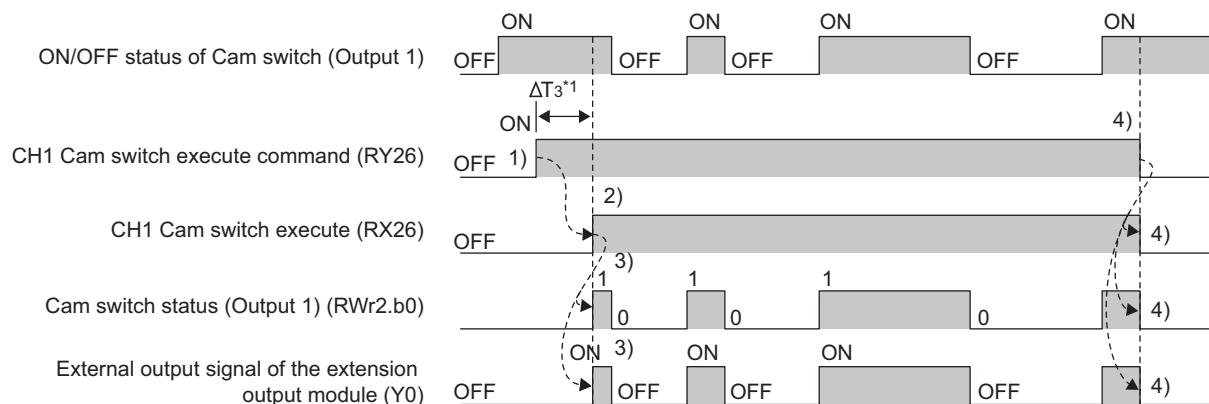
In addition, when a value other than the default value is backed up to the nonvolatile memory by turning off then on Initial data setting request flag (RY9), the setting in the nonvolatile memory also must be set to the default. If the setting in the nonvolatile memory is not the default, the above setting item becomes the backed up value when the module power supply is turned off then on or the module returns from the remote reset.

(5) Signal timing of the cam switch function

The following figure shows the signal timing of the cam switch function.

- Only Cam switch (Output 1) is used.
- Coincidence output 1 is assigned to CH1.
- "1: Stage 1" is assigned to "Cam switch output unit assignment setting".
- "0: CH1" is assigned to "Cam switch output 1 channel assignment setting".

-----> Controlled by the high-speed counter module
—> Controlled by the program



No.	Description
1)	When CH1 Cam switch execute command (RY26) is turned off then on, the step setting of Cam switch (Output 1) is acquired and CH1 Cam switch execute (RX26) turns on. (If the value is changed while the cam switch function is in operation, the change is ignored.)
2)	The cam switch function operates when CH1 Cam switch execute (RX26) turns on.
3)	CH1 Present value (RW2r10 to RW2r11) and the step setting of Cam switch (Output 1) are compared and the result is output from Y0 of the extension output module. The output status can be checked by Cam switch status (Output 1) (RW2r.b0) of Cam switch output signal (RW2r).
4)	When CH1 Cam switch execute command (RY26) is turned off, the operation is as follows: <ul style="list-style-type: none"> CH1 Cam switch execute (RX26) turns off. Cam switch status (Output 1) (RW2r.b0) becomes 0. Y0 of the extension output module is turned off.

*1 For ΔT_3 , refer to Page 283, Appendix 4.



Cam switch output signal (RW2r) turns on regardless of CH□ Count enable command (RY24, RY3C).

8.4 Preset/replace Function

The preset/replace function replaces the count value with any value preset by the user. This value is called a preset value.

This function can be used to start counting pulses from the preset value.

Perform this function by one of the following methods. This section describes No.1 and 2.

No.	Method	Reference
1	Performing the preset/replace function by a program	Page 123, Section 8.4 (1)
2	Performing the preset/replace function by CH□ Phase Z input terminal (Z1, Z2)	Page 124, Section 8.4 (2)
3	Performing the preset/replace function by the preset/replace (at coincidence output) function	Page 114, Section 8.3.3
4	Performing the preset/replace function by the count disable/preset/replace function	Page 142, Section 8.11
5	Performing the preset/replace function by the latch counter/preset/replace function	Page 145, Section 8.12

Point

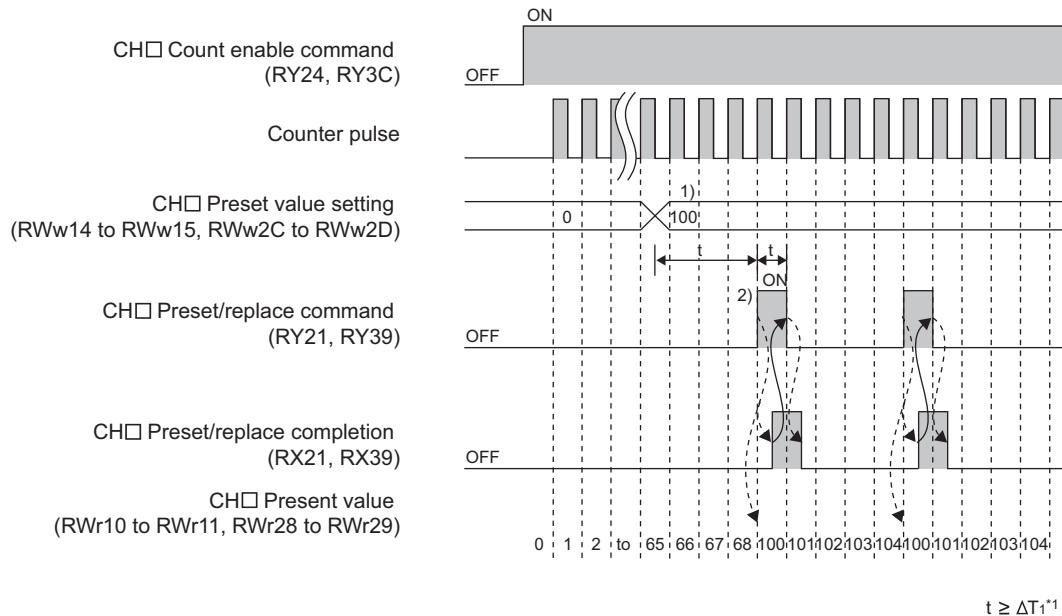
All the above preset/replace functions cannot be performed while CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) is on.

(1) Performing the preset/replace function by a program

The following figure shows an operation example of changing the present value to the preset value (100) at any timing.

Turning on CH□ Preset/replace command (RY21, RY39) by a program performs the preset/replace function.

----→ Controlled by the high-speed counter module
→ Controlled by the program



No.	Description
1)	Write any value to CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) in 32-bit binary. (Setting range: -2147483648 to 2147483647)
2)	The value in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) at the rising edge (off to on) of CH□ Preset/replace command (RY21, RY39). Also, CH□ Preset/replace completion (RX21, RX39) turns on. When turning off CH□ Preset/replace command (RY21, RY39) after checking CH□ Preset/replace completion (RX21, RX39) turns on, CH□ Preset/replace completion (RX21, RX39) turns off. The value can be replaced regardless of the ON/OFF status of CH□ Count enable command (RY24, RY3C).

*1 For ΔT_1 , refer to Page 283, Appendix 4.

(2) Performing the preset/replace function by CH□ Phase Z input terminal (Z1, Z2)

The preset/replace function by CH□ Phase Z input terminal (Z1, Z2) can be performed when the set trigger condition is met.

(a) Setting method of the condition for the preset/replace function by CH□ Phase Z input terminal (Z1, Z2)

1. Set "Parameter write" for "Method selection".

 "CC IE Field Configuration" window \Rightarrow Select a high-speed counter module in "List of stations"
 \Rightarrow [CC IE Field Configuration] \Rightarrow [Parameter Processing of Slave Station]

2. Set "CH□ Z phase (Preset) trigger setting".

CH1 Z phase (Preset) trigger setting	0: Rising	<input type="button" value="▼"/>
CH1 External preset/replace (Z Phase) request detection setting	0: ON at de...	
CH1 Counter function selection	0: Count Di...	
CH1 Function input logic setting	0: Positive ...	
CH1 Latch counter input logic setting	0: Positive ...	
CH1 Z phase input response time setting	0: OFF > 0	

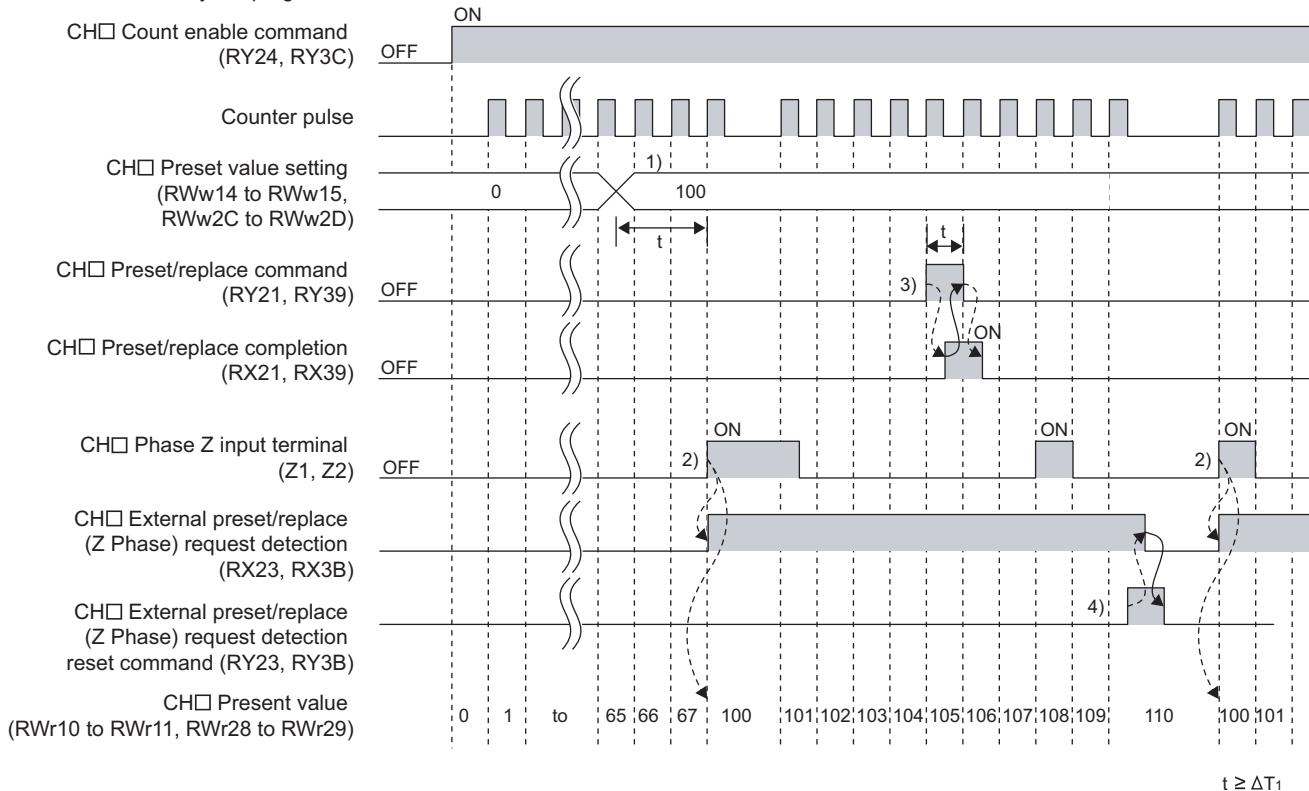
3. Set "CH□ External preset/replace (Z Phase) request detection setting".

CH1 External preset/replace (Z Phase) request detection setting	0: ON at de...	<input type="button" value="▼"/>
CH1 Counter function selection	0: Count Di...	
CH1 Function input logic setting	0: Positive ...	
CH1 Latch counter input logic setting	0: Positive ...	

(b) Operation example of the preset/replace function by CH□ Phase Z input terminal (Z1, Z2)

The following figure shows an operation example of turning on CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) and changing the present value to the preset value (100) at the rising edge of CH□ Phase Z input terminal (Z1, Z2).

- Controlled by the high-speed counter module
- Controlled by the program



No.	Description
1)	Write any value to CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) in 32-bit binary. (Setting range: -2147483648 to 2147483647)
2)	The value in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) at the rising edge (off to on) of CH□ Phase Z input terminal (Z1, Z2). Also, CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) turns on. The value can be replaced regardless of the ON/OFF status of CH□ Count enable command (RY24, RY3C).
3)	While CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) is on, the value cannot be replaced by either CH□ Preset/replace command (RY21, RY39) or CH□ Phase Z input terminal (Z1, Z2). Also, when CH□ Preset/replace command (RY21, RY39) is turned off then on, CH□ Preset/replace completion (RX21, RX39) turns on. However, the value is not replaced. Turn off CH□ Preset/replace completion (RX21, RX39) by turning off CH□ Preset/replace command (RY21, RY39).
4)	When CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) turns off by turning on CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B), the value can be replaced.

Point

- While CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) is on, the value cannot be replaced by any methods. Replace the value after turning off CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) by turning on CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B).
- Have a ΔT_1 or longer interval after changing CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) until CH□ Phase Z input terminal (Z1, Z2) is turned on because there are maximum of ΔT_1 delay until change in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) is reflected. An interval is not necessary when the preset/replace function is performed by the preset/replace command since there is a delay of when the preset/replace command is used.*1
- When the preset/replace function is performed by CH□ Phase Z input terminal (Z1, Z2), the operation response time follows CH□ Z phase input response time setting (address: 0129_H.b0 to b1, 0149_H.b0 to b1). Since CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is updated synchronizing with the internal control cycle, a maximum of delay time shown below occurs until the preset value is stored.
 - ΔT_1 *1 + Setting time of CH□ Z phase input response time setting (address: 0129_H.b0 to b1, 0149_H.b0 to b1)

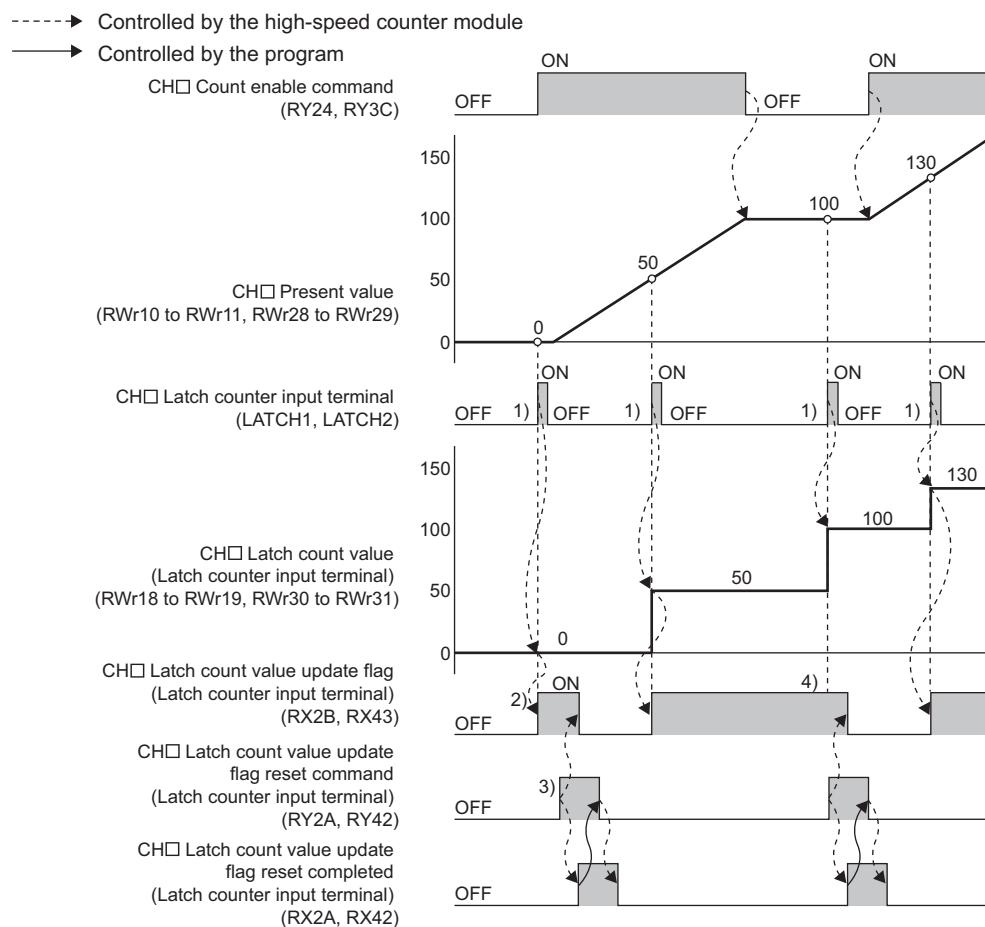
*1 For ΔT_1 , refer to Page 283, Appendix 4.

8.5 Latch Counter Function by Latch Counter Input Terminal

(1) Latching the present value by the latch counter input terminal

The latch counter function by latch counter input terminal acquires the value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) of the counter and stores it in the remote register when CH□ Latch counter input terminal (LATCH1, LATCH2) is input.

The following figure shows an operation example of acquiring the value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) as CH□ Latch count value (Latch counter input terminal) (RWr18 to RWr19, RWr30 to RWr31) at the rising edge of CH□ Latch counter input terminal (LATCH1, LATCH2).



No.	Description
1)	The value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is stored in CH□ Latch count value (Latch counter input terminal) (RWr18 to RWr19, RWr30 to RWr31) at the rising edge of CH□ Latch counter input terminal (LATCH1, LATCH2).
2)	After CH□ Latch count value (Latch counter input terminal) (RWr18 to RWr19, RWr30 to RWr31) is updated, CH□ Latch count value update flag (Latch counter input terminal) (RX2B, RX43) turns on.
3)	When CH□ Latch count value update flag reset command (Latch counter input terminal) (RY2A, RY42) is turned off then on, the high-speed counter module turns off CH□ Latch count value update flag (Latch counter input terminal) (RX2B, RX43) and turns on CH□ Latch count value update flag reset completed (Latch counter input terminal) (RX2A, RX42). After that, CH□ Latch count value update flag reset completed (Latch counter input terminal) (RX2A, RX42) turns off when CH□ Latch count value update flag reset command (Latch counter input terminal) (RY2A, RY42) is turned off.
4)	CH□ Latch count value (Latch counter input terminal) (RWr18 to RWr19, RWr30 to RWr31) is updated even if CH□ Latch count value update flag (Latch counter input terminal) (RX2B, RX43) is on. (The latch counter function operates regardless of the ON/OFF status of CH□ Count enable command (RY24, RY3C).)

Point

When the latch counter function is performed by CH□ Latch counter input terminal (LATCH1, LATCH2), the operation response time follows CH□ Latch counter input response time setting (address: 0129_H.b4 to b5, 0149_H.b4 to b5). Since CH□ Latch count value (Latch counter input terminal) (RWr18 to RWr19, RWr30 to RWr31) is updated synchronizing with the internal control cycle, a maximum of delay time shown below occurs until the acquired value is stored.

- ΔT_1 ^{*1} + Setting time of CH□ Latch counter input response time setting (address: 0129_H.b4 to b5, 0149_H.b4 to b5)

*1 For ΔT_1 , refer to Page 283, Appendix 4.

8.6 Counter Function Selection

When CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2) is input, one of the functions shown below can be used.

The function can be selected for each channel.

(1) Counter function selection list

○ : Enable — : Disable

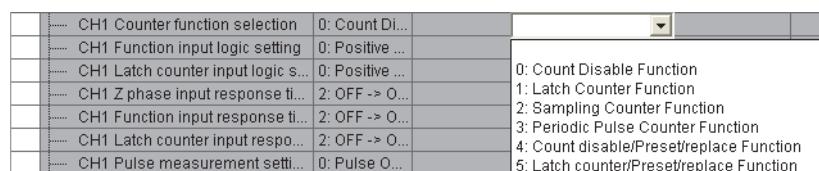
Function name	Remote buffer memory setting				Method	
	CH□ Operation mode setting (address: 0120 _H , 0140 _H)	CH□ Counter function selection (address: 0126 _H , 0146 _H)	CH□ Function input logic setting (address: 0127 _H , 0147 _H)	CH□ Function input response time setting (address: 0129 _H .b2 to b3, 0149 _H .b2 to b3)	CH□ Selected counter function start command (RY25, RY3D)	CH□ Function input terminal (FUNC1, FUNC2)
Count disable function	0	0	0/1	00/01/10	○	○
Latch counter function	0	1	0/1	00/01/10	○	○
Sampling counter function	0	2	0/1	00/01/10	○	○
Periodic pulse counter function	0	3	0/1	00/01/10	○	○
Count disable/preset/replace function	0	4	0/1	00/01/10	—	○
Latch counter/preset/replace function	0	5	0/1	00/01/10	—	○

(2) Setting method of the counter function selection

1. Set "Parameter write" for "Method selection".

 "CC IE Field Configuration" window \Rightarrow Select a high-speed counter module in "List of stations"
 \Rightarrow [CC IE Field Configuration] \Rightarrow [Parameter Processing of Slave Station]

2. For "CH□ Counter function selection", select a counter function to be used.



Point

In the counter function selection, a delay occurs before the start of the selected function due to any of the following factors:

- Input response time of CH□ Function input terminal (FUNC1, FUNC2)
- Scan time of the program (for CH□ Selected counter function start command (RY25, RY3D))
- Link scan time of the network (for CH□ Selected counter function start command (RY25, RY3D))
- Internal control cycle in the high-speed counter module ($\Delta T_2 = 0.5\text{ms}$) (for CH□ Selected counter function start command (RY25, RY3D))^{*3}

The count errors by these delays are as follows:

- Count error (maximum) which occurs when a function is performed by CH□ Function input terminal (FUNC1, FUNC2)

$$\frac{\text{Function input response time setting (max.) [ms]}}{1000} \text{ (s)} \times \text{Pulse input speed [pps]}^{\ast 1}$$

- Count error (maximum) which occurs when a function is performed by CH□ Selected counter function start command (RY25, RY3D)
(When the master module is the QJ71GF11-T2 with Block Data Assurance per Station set and in the asynchronous mode)

$$\left(\frac{(SM \times n2) [\text{ms}] + (LS \times 2) [\text{ms}] + \Delta T_1 [\text{ms}]}{1000} \right) \text{ (s)} \times \text{Pulse input speed [pps]}^{\ast 1}$$

SM: Scan time of the program in the master station

LS: Link scan time

n2: Value obtained from $(LS \div SM)$

(The value after the decimal point shall be rounded up.)

For the sampling counter function and the periodic pulse counter function, a sampling/periodic time error due to a component error ($\pm 100\text{ppm}$) occurs. The count error is as follows:

$$\text{Sampling/periodic time [s]}^{\ast 2} \times \frac{100 [\text{ppm}]}{1000000} \times \text{Pulse input speed [pps]}^{\ast 1}$$

^{*1} Pulse input speed [pps] = pulse input frequency [Hz] \times number of multiples [count]

^{*2} Sampling/periodic time [s] = Sampling/periodic time setting value \times Sampling/periodic time unit [s]

(When the sampling/periodic time unit setting is 1 [ms], the sampling/periodic time is 0.001 [s]. When the unit setting is 10 [ms], the time is 0.01 [s].)

^{*3} For ΔT_1 and ΔT_2 , refer to Page 283, Appendix 4.

8.7 Count Disable Function

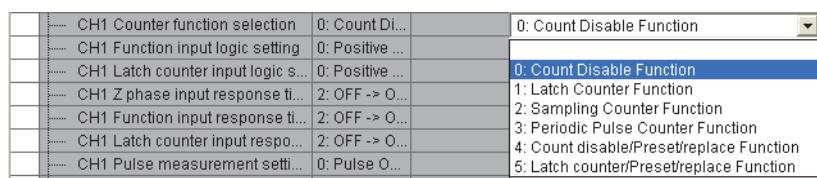
The count disable function stops the counting when CH□ Function input terminal (FUNC1, FUNC2) or CH□ Selected counter function start command (RY25, RY3D) is input during the counting.

(1) Setting method of the count disable function

1. Set "Parameter write" for "Method selection".

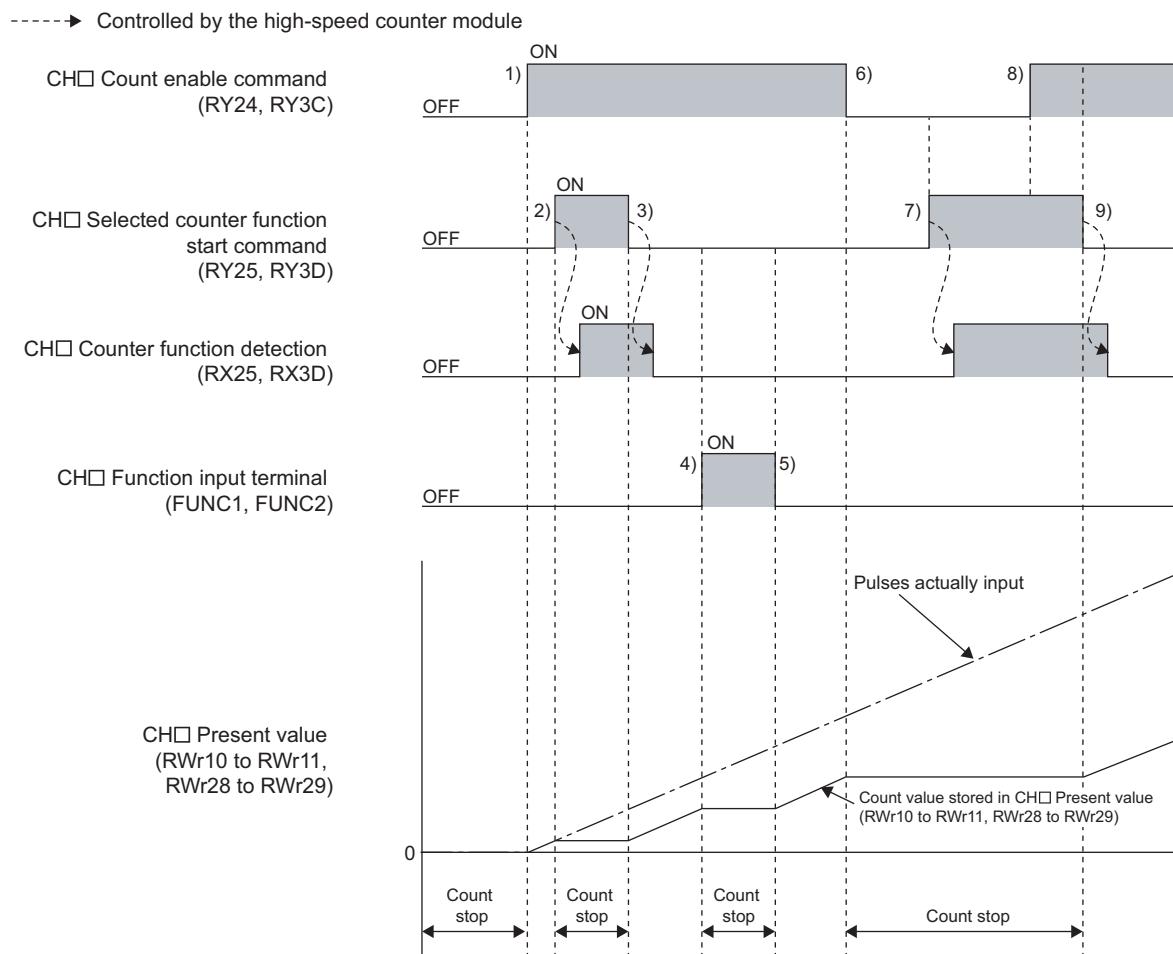
→ "CC IE Field Configuration" window ⇒ Select a high-speed counter module in "List of stations"
⇒ [CC IE Field Configuration] ⇒ [Parameter Processing of Slave Station]

2. Select "0: Count Disable Function" in "CH□ Counter function selection".



(2) Operation example of the count disable function

The following figure shows an operation example of stopping the counting while CH□ Selected counter function start command (RY25, RY3D) and CH□ Function input terminal (FUNC1, FUNC2) are on.



No.	Description
1)	Counting starts by turning on CH□ Count enable command (RY24, RY3C).
2)	Counting stops by turning on CH□ Selected counter function start command (RY25, RY3D). Also, CH□ Counter function detection (RX25, RX3D) turns on by turning on CH□ Selected counter function start command (RY25, RY3D).
3)	Counting resumes by turning off CH□ Selected counter function start command (RY25, RY3D). Also, CH□ Counter function detection (RX25, RX3D) turns off by turning off CH□ Selected counter function start command (RY25, RY3D).
4)	Counting stops by turning on CH□ Function input terminal (FUNC1, FUNC2).
5)	Counting resumes by turning off CH□ Function input terminal (FUNC1, FUNC2).
6)	Counting stops by turning off CH□ Count enable command (RY24, RY3C).
7)	Counting stops regardless of CH□ Selected counter function start command (RY25, RY3D) since CH□ Count enable command (RY24, RY3C) is off.
8)	Counting remains stopped even if CH□ Count enable command (RY24, RY3C) is turned on since CH□ Selected counter function start command (RY25, RY3D) is on.
9)	Counting resumes by turning off CH□ Selected counter function start command (RY25, RY3D).

8.8 Latch Counter Function (Counter Function Selection)

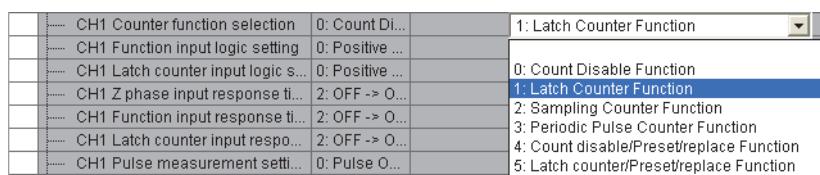
The latch counter function by counter function selection acquires CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) of the counter and stores it in the remote register when CH□ Function input terminal (FUNC1, FUNC2) or CH□ Selected counter function start command (RY25, RY3D) is input.

(1) Setting method of the latch counter function (counter function selection)

1. Set "Parameter write" for "Method selection".

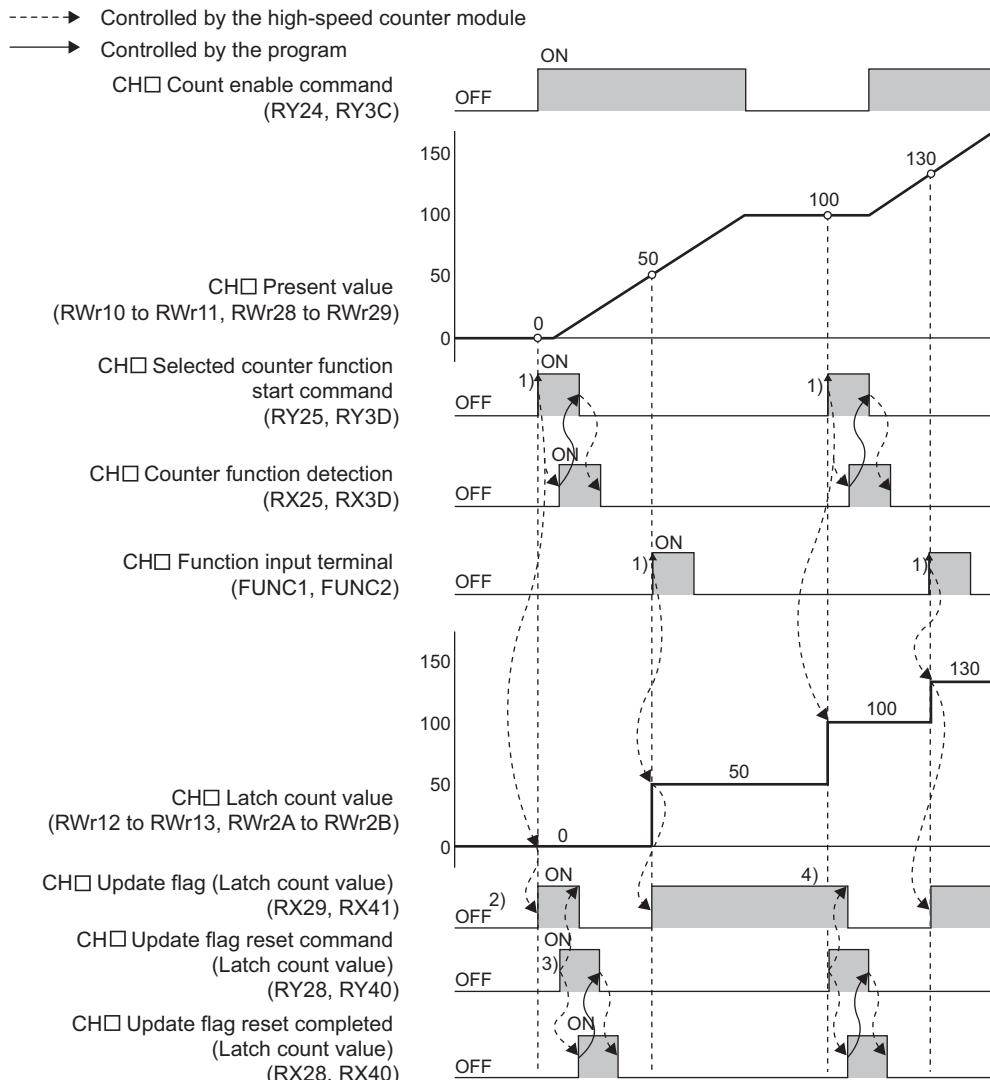
☞ "CC IE Field Configuration" window ⇒ Select a high-speed counter module in "List of stations"
⇒ [CC IE Field Configuration] ⇒ [Parameter Processing of Slave Station]

2. Select "1: Latch Counter Function" in "CH□ Counter function selection".



(2) Operation example of the latch counter function (counter function selection)

The following figure shows an operation example of acquiring the value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) as CH□ Latch count value (RWr12 to RWr13, RWr2A to RWr2B) at the rising edge of CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2).



No.	Description
1)	The value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is stored in CH□ Latch count value (RWr12 to RWr13, RWr2A to RWr2B) at the rising edge of CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2). For CH□ Selected counter function start command (RY25, RY3D), CH□ Counter function detection (RX25, RX3D) turns on or off by turning on or off CH□ Selected counter function start command (RY25, RY3D).
2)	After CH□ Latch count value (RWr12 to RWr13, RWr2A to RWr2B) is updated, CH□ Update flag (Latch count value) (RX29, RX41) turns on.
3)	When CH□ Update flag reset command (Latch count value) (RY28, RY40) is turned off then on, the high-speed counter module turns off CH□ Update flag (Latch count value) (RX29, RX41) and turns on CH□ Update flag reset completed (Latch count value) (RX28, RX40). After that, CH□ Update flag reset completed (Latch count value) (RX28, RX40) turns off when CH□ Update flag reset command (Latch count value) (RY28, RY40) is turned off.
4)	CH□ Latch count value (RWr12 to RWr13, RWr2A to RWr2B) is updated even if CH□ Update flag (Latch count value) (RX29, RX41) is on. (The latch counter function operates regardless of the ON/OFF status of CH□ Count enable command (RY24, RY3C).)

Point

- When the latch counter function is performed by CH□ Function input terminal (FUNC1, FUNC2), the operation response time follows CH□ Function input response time setting (address: 0129_H.b2 to b3, 0149_H.b2 to b3). Since CH□ Latch count value (RWr12 to RWr13, RWr2A to RWr2B) is updated synchronizing with the internal control cycle, a maximum of delay time shown below occurs until the acquired value is stored.
 - $\Delta T_1^{*1} + \text{Setting time of CH□ Function input response time setting (address: 0129}_H.b2 \text{ to b3, 0149}_H.b2 \text{ to b3)}$
- *1 For ΔT_1 , refer to Page 283, Appendix 4.
- The latch counter function cannot be performed while CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2) is on even if the other is turned on.

8.9 Sampling Counter Function

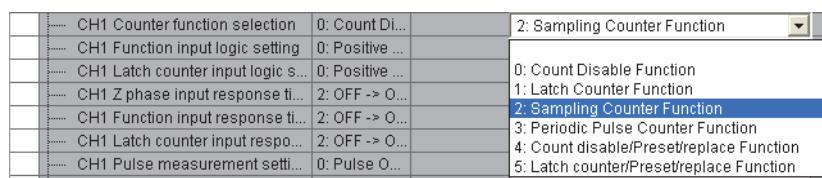
The sampling counter function counts pulses that are input during the specified sampling period (T) and stores it as CH□ Sampling count value (RWr12 to RWr13, RWr2A to RWr2B) in the remote register.

(1) Setting method of the sampling counter function

1. Set "Parameter write" for "Method selection".

 "CC IE Field Configuration" window \Rightarrow Select a high-speed counter module in "List of stations" \Rightarrow [CC IE Field Configuration] \Rightarrow [Parameter Processing of Slave Station]

2. Select "2: Sampling Counter Function" in "CH□ Counter function selection".



(2) Setting of the sampling period

Set the sampling period (T) by setting values to CH□ Cycle setting (Sampling counter/Periodic pulse counter) (RWw17, RWw2F) and CH□ Time unit setting (Sampling counter/Periodic pulse counter) (RWw16, RWw2E).

When CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned off then on, the setting values are enabled.

However, the setting values are enabled from the next operation of sampling counter function if the settings are changed while the sampling counter function is being performed.

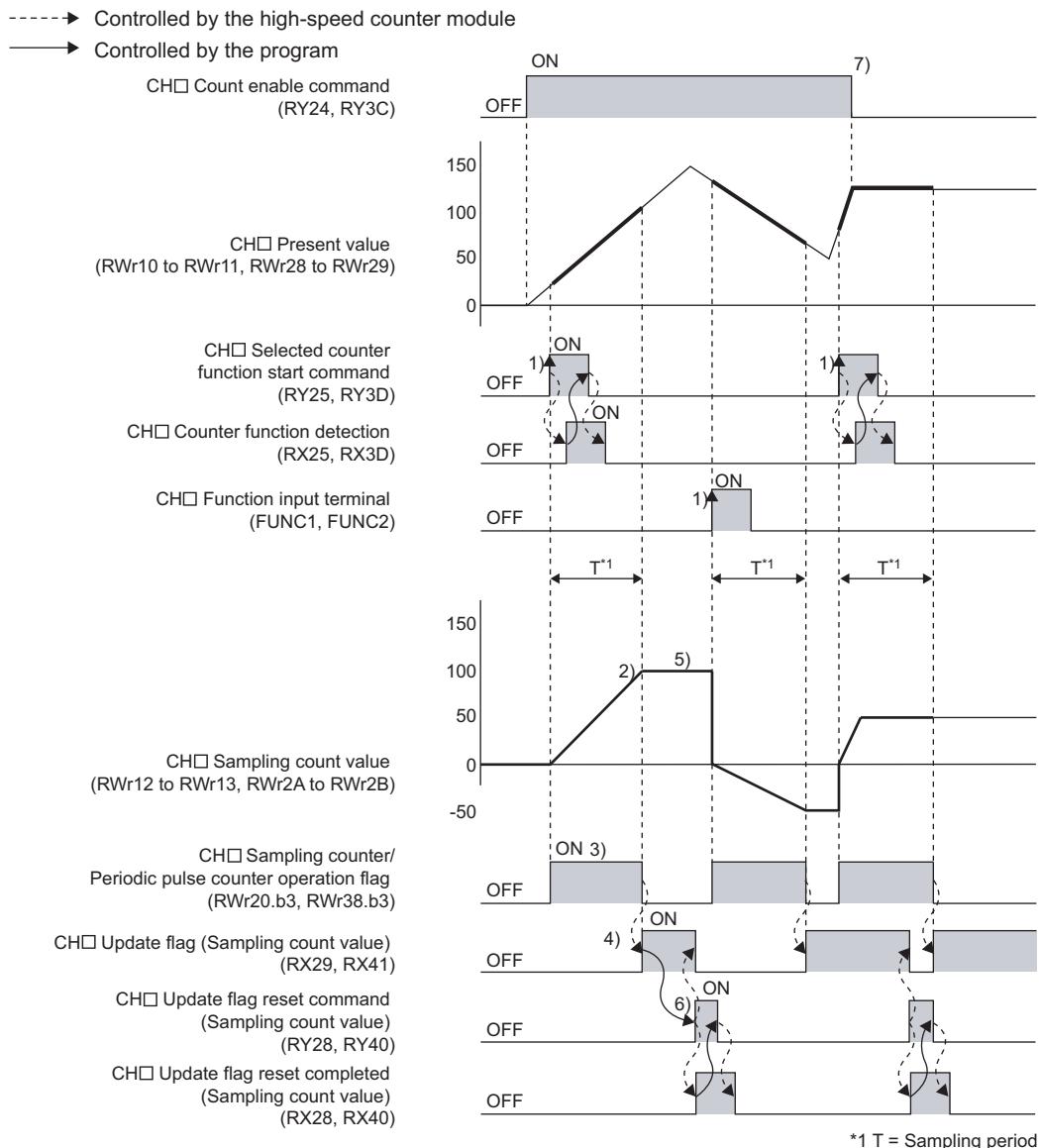
Setting item	Setting range	Reference
CH□ Time unit setting (Sampling counter/Periodic pulse counter) (RWw16, RWw2E)	0: 1ms 1: 10ms	Page 264, Appendix 2 (11)
CH□ Cycle setting (Sampling counter/Periodic pulse counter) (RWw17, RWw2F)	1 to 65535	

Point

- Change the sampling period by CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F). When the period is changed by Initial data processing completion flag (RY8) or Initial data setting request flag (RY9), the items of the monitor value such as CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) are cleared.
- When changing the sampling period by using CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F), note the following:
Do not execute the sampling counter function by CH□ Function input terminal (FUNC1, FUNC2) from when CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned on until CH□ Setting change completed (Sampling counter/Periodic pulse counter) (RX27, RX3F) turns on. Doing so may perform counting with the previous setting.

(3) Operation example of the sampling counter function

The following figure shows an operation example of acquiring the number of the pulses input in the set sampling period (1ms) as CH0 Sampling count value (RWr12 to RWr13, RWr2A to RWr2B).



No.	Description
1)	Counting the input pulses starts from 0 at the rising edge of CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2). For CH□ Selected counter function start command (RY25, RY3D), CH□ Counter function detection (RX25, RX3D) turns on or off by turning on or off CH□ Selected counter function start command (RY25, RY3D).
2)	Counting stops at the end of the preset sampling period.
3)	While the sampling counter function is being performed, set CH□ Sampling counter/Periodic pulse counter operation flag (RW _r 20.b3, RW _r 38.b3) to Operating (1).
4)	At the end of each sampling period, CH□ Update flag (Sampling count value) (RX29, RX41) turns on.
5)	Even after the counting is completed, the values stored in CH□ Sampling count value (RW _r 12 to RW _r 13, RW _r 2A to RW _r 2B) remain the same until CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2) is turned on again. When CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2) is turned on again, 0 is stored in CH□ Sampling count value (RW _r 12 to RW _r 13, RW _r 2A to RW _r 2B) and the counting resumes.
6)	When CH□ Update flag reset command (Sampling count value) (RY28, RY40) is turned on, the high-speed counter module turns off CH□ Update flag (Sampling count value) (RX29, RX41) and turns on CH□ Update flag reset completed (Sampling count value) (RX28, RX40). After that, CH□ Update flag reset completed (Sampling count value) (RX28, RX40) turns off when CH□ Update flag reset command (Sampling count value) (RY28, RY40) is turned off.
7)	Although the sampling counter function operates regardless of the ON/OFF status of CH□ Count enable command (RY24, RY3C), CH□ Sampling count value (RW _r 12 to RW _r 13, RW _r 2A to RW _r 2B) is not counted while CH□ Count enable command (RY24, RY3C) is off. At the end of the sampling period after CH□ Count enable command (RY24, RY3C) is turned off, CH□ Sampling counter/Periodic pulse counter operation flag (RW _r 20.b3, RW _r 38.b3) is set to Not operating (0) and CH□ Update flag (Sampling count value) (RX29, RX41) turns on.

Point

- The sampling counter function cannot be performed while CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2) is on even if the other is turned on.
- By turning off both CH□ Selected counter function start command (RY25, RY3D) and CH□ Function input terminal (FUNC1, FUNC2) and then turning on one of them during the operation of the sampling counter function, the pulses are counted from 0 again though the sampling period is continually measured.
- Depending on the pulse input speed and sampling period, the values stored in CH□ Sampling count value (RW_r12 to RW_r13, RW_r2A to RW_r2B) may be over the upper limit value (2147483647) or below the lower limit value (-2147483648). In that case, the value stored in CH□ Sampling count value (RW_r12 to RW_r13, RW_r2A to RW_r2B) remains the upper limit value (2147483647) or the lower limit value (-2147483648), and CH□ Overflow/underflow error (Sampling count value/Periodic pulse count, difference value) (error code: □050_H) occurs. Despite this minor error, the sampling counter function keeps working till the end of the sampling period.
- To perform the sampling counter function again, reset CH□ Update flag (Sampling count value) (RX29, RX41) before turning on again CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2). If it is not reset, whether its value was updated after the re-execution cannot be checked.

8.10 Periodic Pulse Counter Function

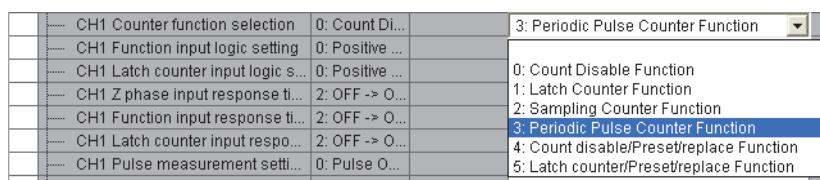
The periodic pulse counter function stores the values which are stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) and CH□ Periodic pulse count, difference value (RWr12 to RWr13, RWr2A to RWr2B) in the remote register every specified cycle time (T).

(1) Setting method of the periodic pulse counter function

1. Set "Parameter write" for "Method selection".

 "CC IE Field Configuration" window \Rightarrow Select a high-speed counter module in "List of stations"
 \Rightarrow [CC IE Field Configuration] \Rightarrow [Parameter Processing of Slave Station]

2. Select "3: Periodic Pulse Counter Function" in "CH□ Counter function selection".



(2) Setting of the cycle time

Set the cycle time (T) by setting values to CH□ Cycle setting (Sampling counter/Periodic pulse counter) (RWw17, RWw2F) and CH□ Time unit setting (Sampling counter/Periodic pulse counter) (RWw16, RWw2E).

When CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned off then on, the setting values are enabled.

However, the setting values are enabled from the next operation of periodic pulse counter function if the setting is changed while the periodic pulse counter function is being performed.

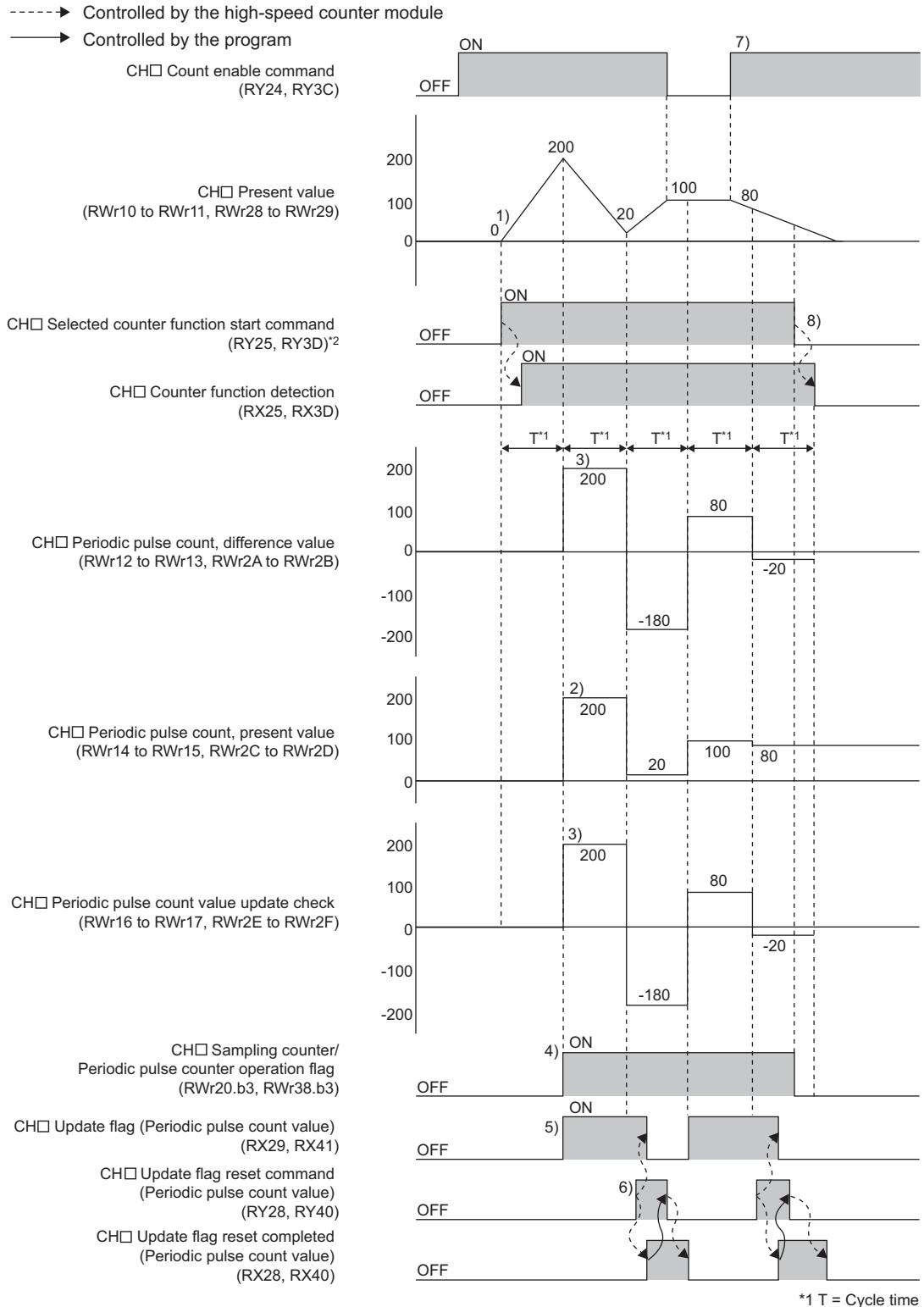
Setting item	Setting range	Reference
CH□ Time unit setting (Sampling counter/Periodic pulse counter) (RWw16, RWw2E)	0: 1ms 1: 10ms	Page 264, Appendix 2 (11)
CH□ Cycle setting (Sampling counter/Periodic pulse counter) (RWw17, RWw2F)	1 to 65535	

Point

- Change the cycle time by CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F). When the cycle time is changed by Initial data processing completion flag (RY8) or Initial data setting request flag (RY9), the items of the monitor value such as CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) are cleared.
- When changing the cycle time by using CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F), note the following:
 Do not execute the periodic pulse counter function by CH□ Function input terminal (FUNC1, FUNC2) from when CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned on until CH□ Setting change completed (Sampling counter/Periodic pulse counter) (RX27, RX3F) turns on. Doing so may perform counting with the previous setting.

(3) Operation example of the periodic pulse counter function

The following figure shows an operation example of storing each calculated value in CH□ Periodic pulse count, difference value (RW_r12 to RW_r13, RW_r2A to RW_r2B), CH□ Periodic pulse count, present value (RW_r14 to RW_r15, RW_r2C to RW_r2D), and CH□ Periodic pulse count value update check (RW_r16 to RW_r17, RW_r2E to RW_r2F) based on the value in CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29) counted within the preset cycle time (1ms).



*2 Though the periodic pulse counter function can also be performed by CH□ Function input terminal (FUNC1, FUNC2), the status of CH□ Counter function detection (RX25, RX3D) does not change.

No.	Description
1)	Counting the input pulses starts from 0 at the rising edge of CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2). For CH□ Selected counter function start command (RY25, RY3D), CH□ Counter function detection (RX25, RX3D) turns on or off by turning on or off CH□ Selected counter function start command (RY25, RY3D).
2)	Every preset cycle time, the value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is stored in CH□ Periodic pulse count, present value (RWr14 to RWr15, RWr2C to RWr2D).
3)	Every preset cycle time, the difference of the count values between the previous one and the present one is stored in CH□ Periodic pulse count, difference value (RWr12 to RWr13, RWr2A to RWr2B) and CH□ Periodic pulse count value update check (RWr16 to RWr17, RWr2E to RWr2F).
4)	While the periodic pulse counter function is being performed, set CH□ Sampling counter/Periodic pulse counter operation flag (RWr20.b3, RWr38.b3) to Operating (1).
5)	CH□ Update flag (Periodic pulse count value) (RX29, RX41) turns on when CH□ Periodic pulse count, difference value (RWr12 to RWr13, RWr2A to RWr2B), CH□ Periodic pulse count, present value (RWr14 to RWr15, RWr2C to RWr2D), and CH□ Periodic pulse count value update check (RWr16 to RWr17, RWr2E to RWr2F) are updated.
6)	When CH□ Update flag reset command (Periodic pulse count value) (RY28, RY40) is turned on, the high-speed counter module turns off CH□ Update flag (Periodic pulse count value) (RX29, RX41) and turns on CH□ Update flag reset completed (Periodic pulse count value) (RX28, RX40). After that, CH□ Update flag reset completed (Periodic pulse count value) (RX28, RX40) turns off when CH□ Update flag reset command (Periodic pulse count value) (RY28, RY40) is turned off.
7)	The periodic pulse counter function operates regardless of the ON/OFF status of CH□ Count enable command (RY24, RY3C).
8)	The periodic pulse counter function is stopped by turning off both CH□ Selected counter function start command (RY25, RY3D) and CH□ Function input terminal (FUNC1, FUNC2).

Point

- Use the periodic pulse count value after checking the values in CH□ Periodic pulse count, difference value (RWr12 to RWr13, RWr2A to RWr2B) and CH□ Periodic pulse count value update check (RWr16 to RWr17, RWr2E to RWr2F) are equal. When they are different, the periodic pulse count value includes values before and after the end of the cycle time and there is a value discrepancy. Read again CH□ Periodic pulse count, difference value (RWr12 to RWr13, RWr2A to RWr2B), CH□ Periodic pulse count, present value (RWr14 to RWr15, RWr2C to RWr2D), and CH□ Periodic pulse count value update check (RWr16 to RWr17, RWr2E to RWr2F).
- Depending on the pulse input speed and cycle time, the value in CH□ Periodic pulse count, difference value (RWr12 to RWr13, RWr2A to RWr2B) and CH□ Periodic pulse count value update check (RWr16 to RWr17, RWr2E to RWr2F) may be over the upper limit value (2147483647) or below the lower limit value (-2147483648). (The value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is stored in CH□ Periodic pulse count, present value (RWr14 to RWr15, RWr2C to RWr2D).) In that case, the values in CH□ Periodic pulse count, difference value (RWr12 to RWr13, RWr2A to RWr2B) and CH□ Periodic pulse count value update check (RWr16 to RWr17, RWr2E to RWr2F) remain the upper limit value (2147483647) or the lower limit value (-2147483648), and CH□ Overflow/underflow error (Sampling count value/Periodic pulse count, difference value) (error code: □050) occurs. Despite this minor error, the periodic pulse counter function keeps working.
- To perform the periodic pulse counter function again, reset CH□ Update flag (Periodic pulse count value) (RX29, RX41) before turning on again CH□ Selected counter function start command (RY25, RY3D) or CH□ Function input terminal (FUNC1, FUNC2). If it is not reset, whether its value was updated after the re-execution cannot be checked.

8.11 Count Disable/preset/replace Function

The count disable/preset/replace function executes the count disable function and the preset/replace function according to the status change of CH□ Function input terminal (FUNC1, FUNC2) without switching the functions by the counter function selection.

(1) Setting method of the count disable/preset/replace function

1. Set "Parameter write" for "Method selection".

☛ "CC IE Field Configuration" window ⇒ Select a high-speed counter module in "List of stations"
⇒ [CC IE Field Configuration] ⇒ [Parameter Processing of Slave Station]

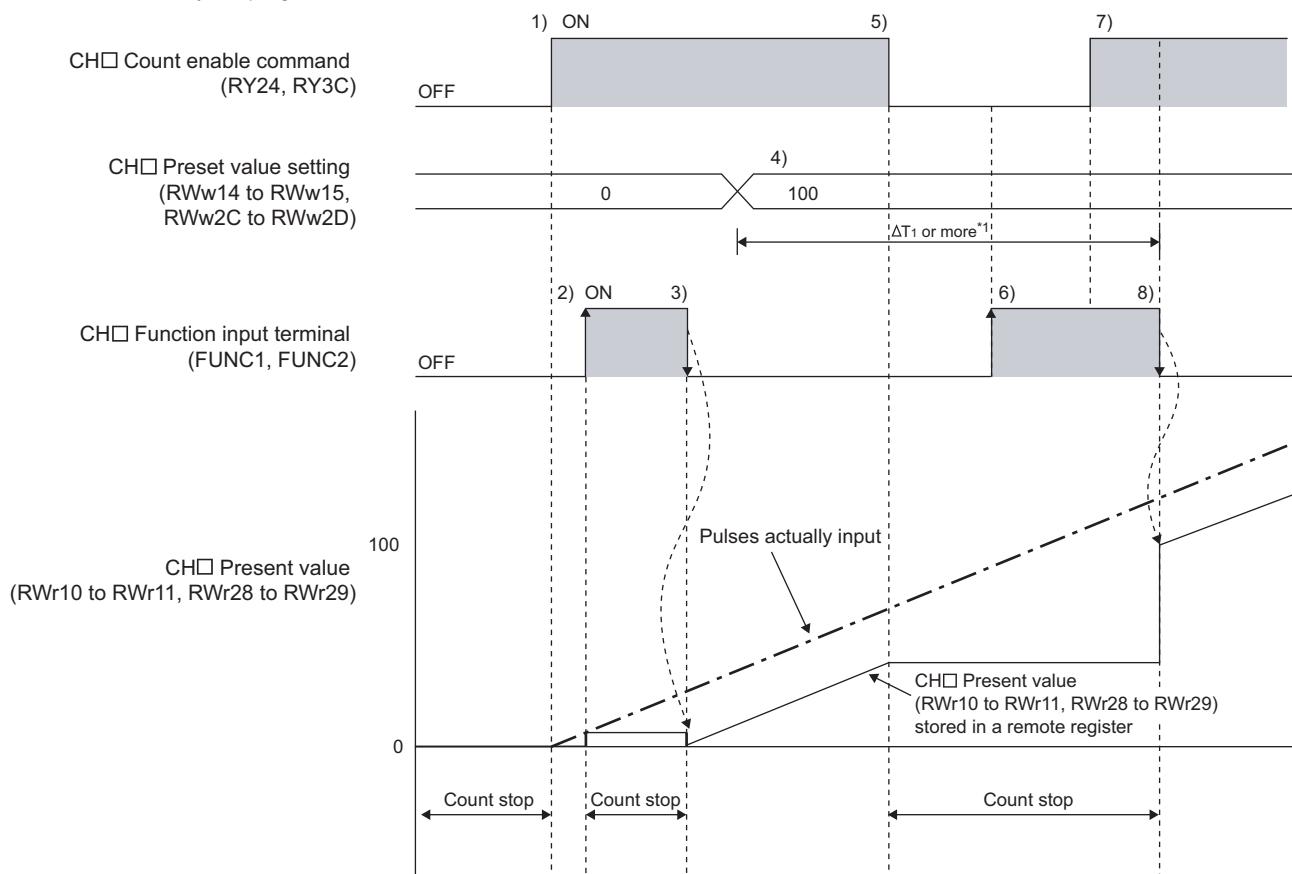
2. Select "4: Count disable/Preset/replace Function" in "CH□ Counter function selection".

CH1 Counter function selection	0: Count Di...	4: Count disable/Preset/replace Function
CH1 Function input logic setting	0: Positive ...	0: Count Disable Function
CH1 Latch counter input logic s...	0: Positive ...	1: Latch Counter Function
CH1 Z phase input response ti...	2: OFF -> O...	2: Sampling Counter Function
CH1 Function input response ti...	2: OFF -> O...	3: Periodic Pulse Counter Function
CH1 Latch counter input respo...	2: OFF -> O...	4: Count disable/Preset/replace Function
CH1 Pulse measurement setti...	0: Pulse O...	5: Latch counter/Preset/replace Function

(2) Operation example of the count disable/preset/replace function

The following figure shows an operation example of stopping counting while CH□ Function input terminal (FUNC1, FUNC2) is on and storing the preset value (0 or 100) in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) at the falling edge of CH□ Function input terminal (FUNC1, FUNC2).

-----→ Controlled by the high-speed counter module
→ Controlled by the program



*1 For ΔT_1 , refer to Page 283, Appendix 4.

No.	Description
1)	Counting starts by turning on CH□ Count enable command (RY24, RY3C).
2)	Counting stops at the rising edge of CH□ Function input terminal (FUNC1, FUNC2).
3)	The value in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) at the falling edge of CH□ Function input terminal (FUNC1, FUNC2), and the counting resumes.
4)	Set any values to CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D).
5)	Counting stops by turning off CH□ Count enable command (RY24, RY3C).
6)	Counting stops regardless of CH□ Function input terminal (FUNC1, FUNC2) since CH□ Count enable command (RY24, RY3C) is off.
7)	Counting remains stopped even if CH□ Count enable command (RY24, RY3C) is turned on since CH□ Function input terminal (FUNC1, FUNC2) is on.
8)	The value in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) at the falling edge of CH□ Function input terminal (FUNC1, FUNC2), and the counting resumes.

Point

- The count value cannot be replaced with the preset value while CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) is on.
Replace the value after CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) turns off by turning on CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B).
- Have a ΔT_1 or longer interval after changing CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) until the value is replaced since there are maximum of ΔT_1 delay until change in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) is reflected. For ΔT_1 , refer to Page 283, Appendix 4.

8.12 Latch Counter/preset/replace Function

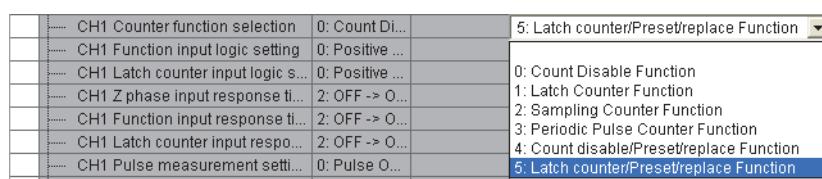
The latch counter/preset/replace function executes the latch counter function and the preset/replace function according to the status change of CH□ Function input terminal (FUNC1, FUNC2) without switching the functions by the counter function selection.

(1) Setting method of the latch counter/preset/replace function

1. Set "Parameter write" for "Method selection".

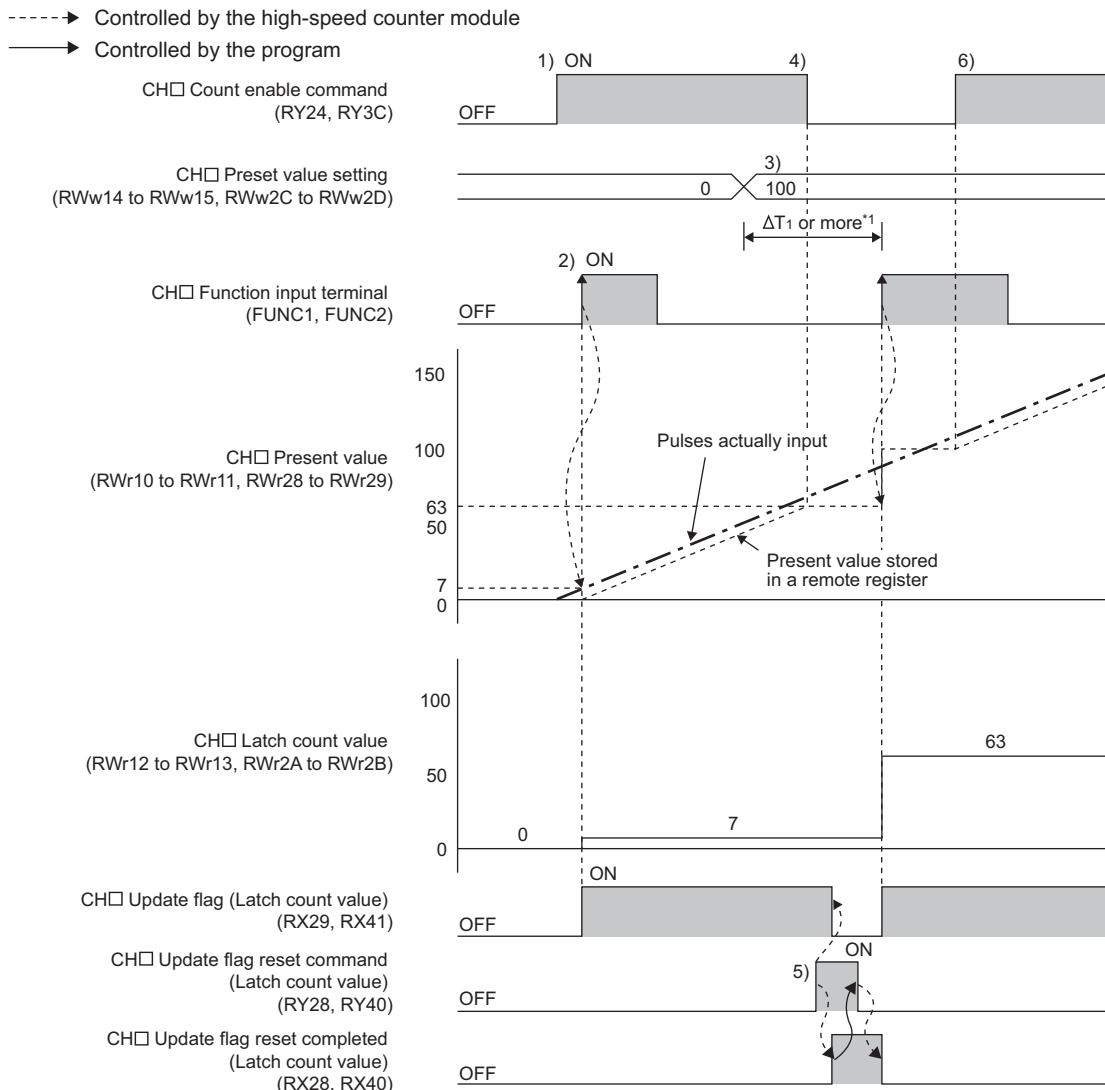
☞ "CC IE Field Configuration" window ⇒ Select a high-speed counter module in "List of stations"
⇒ [CC IE Field Configuration] ⇒ [Parameter Processing of Slave Station]

2. Select "5: Latch counter/Preset/replace Function" in "CH□ Counter function selection".



(2) Operation example of the latch counter/preset/replace function

The following figure shows an operation example of storing the preset value (0 or 100) in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) after storing the value which are stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) in CH□ Latch count value (RWr12 to RWr13, RWr2A to RWr2B) at the rising edge of CH□ Function input terminal (FUNC1, FUNC2).



*1 For ΔT_1 , refer to Page 283, Appendix 4.

No.	Description
1)	Counting starts by turning on CH□ Count enable command (RY24, RY3C).
2)	The value in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) is stored in CH□ Latch count value (RWr12 to RWr13, RWr2A to RWr2B), and the value in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) at the rising edge of CH□ Function input terminal (FUNC1, FUNC2). After CH□ Latch count value (RWr12 to RWr13, RWr2A to RWr2B) is updated, CH□ Update flag (Latch count value) (RX29, RX41) turns on.
3)	Set any values to CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D).
4)	Counting stops by turning off CH□ Count enable command (RY24, RY3C).
5)	When CH□ Update flag reset command (Latch count value) (RY28, RY40) is turned off then on, the high-speed counter module turns off CH□ Update flag (Latch count value) (RX29, RX41) and turns on CH□ Update flag reset completed (Latch count value) (RX28, RX40). After that, CH□ Update flag reset completed (Latch count value) (RX28, RX40) turns off when CH□ Update flag reset command (Latch count value) (RY28, RY40) is turned off.
6)	Counting resumes by turning on CH□ Count enable command (RY24, RY3C).

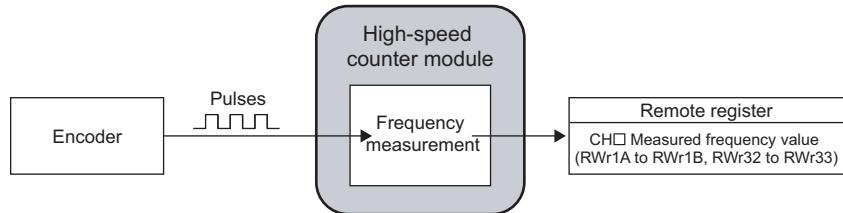
Point

- The count value cannot be replaced with the preset value while CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) is on.
Replace the value after CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) turns off by turning on CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B).
- Have a ΔT_1 or longer interval after changing CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) until the value is replaced since there are maximum of ΔT_1 delay until change in the preset value is reflected.*1
 - ΔT_1 *1 + Setting time of CH□ Function input response time setting (address: 0129_H.b2 to b3, 0149_H.b2 to b3)
- When the latch counter function is performed by CH□ Function input terminal (FUNC1, FUNC2), the operation response time follows CH□ Function input response time setting (address: 0129_H.b2 to b3, 0149_H.b2 to b3). Since CH□ Latch count value (RWr12 to RWr13, RWr2A to RWr2B) is updated synchronizing with the internal control cycle, a maximum of delay time shown below occurs until the acquired value is stored.

*1 For ΔT_1 , refer to Page 283, Appendix 4.

8.13 Frequency Measurement Function

The frequency measurement function counts the pulses of the pulse input terminals in phase A and B, and automatically calculates the frequency.



(1) Setting method of the frequency measurement function

1. Set "Parameter write" for "Method selection".

☞ "CC IE Field Configuration" window ⇒ Select a high-speed counter module in "List of stations"
⇒ [CC IE Field Configuration] ⇒ [Parameter Processing of Slave Station]

2. Set "CH□ Operation mode setting" to "1: Frequency Measurement Mode".

CH1 Operation mode setting	0: Normal ...	1: Frequency Measurement Mode
CH1 Count source selection	0: A Phase/...	
CH1 Pulse input mode	0: 1-Phase...	0: Normal Mode
CH1 Counting speed setting	0: 10kpps	1: Frequency Measurement Mode
CH1 Counter format	0: Linear C...	2: Rotation Speed Measurement Mode
CH1 Z phase (Preset) trigger s...	0: Rising	3: Pulse Measurement Mode
		4: PWM Output Mode

(2) Calculation of the frequency

The frequency measurement function calculates the frequency from the following formula.

- Frequency (Hz) = Count value per unit of time ÷ Unit of time^{*1}

*1 Select a unit of time from 0.01s, 0.1s, or 1s.

Therefore, when the count value per unit of time is 0, the frequency is 0(Hz).

At subtraction count, the value of the frequency is negative.

(3) Setting of the unit of time for frequency measurement

Set a unit of time by setting a value to CH□ Time unit setting (Frequency measurement) (RWw18, RWw30).

Setting item	Setting range	Reference
CH□ Time unit setting (Frequency measurement) (RWw18, RWw30)	0: 0.01s 1: 0.1s 2: 1s	—

Point

- Whichever mode ("1: 1-Phase Multiple of 2", "4: 2-Phase Multiple of 2", or "5: 2-Phase Multiple of 4") is set in "CH□ Pulse input mode" (Page 92, Section 8.1.1), the frequency (Hz) is calculated based on the count value per unit of time.
- When "1: 1-Phase Multiple of 2" is set in "CH□ Pulse input mode" (Page 92, Section 8.1.1) and the input frequency in phase A is 10kHz (10000 per second), the measured frequency value becomes 20kHz since the pulse count is regarded as 20000 based on the calculation below.
Pulse count = 10000 (pulse) × 2 = 20000 (pulse/s)
- Measurable frequency (minimum)
The frequency is calculated from the count value per unit of time. However, the frequency smaller than the one in the following table cannot be measured correctly as the count value is in an integer number.

Unit of time	Measurable frequency (minimum)
1s	1Hz
0.1s	10Hz
0.01s	100Hz

When a unit of time is 0.01s and the input frequency is 1234Hz, the measured frequency value is 1200Hz or 1300Hz. By doing the moving average count, the fluctuation of the measured values can be lowered.

(4) Moving average count

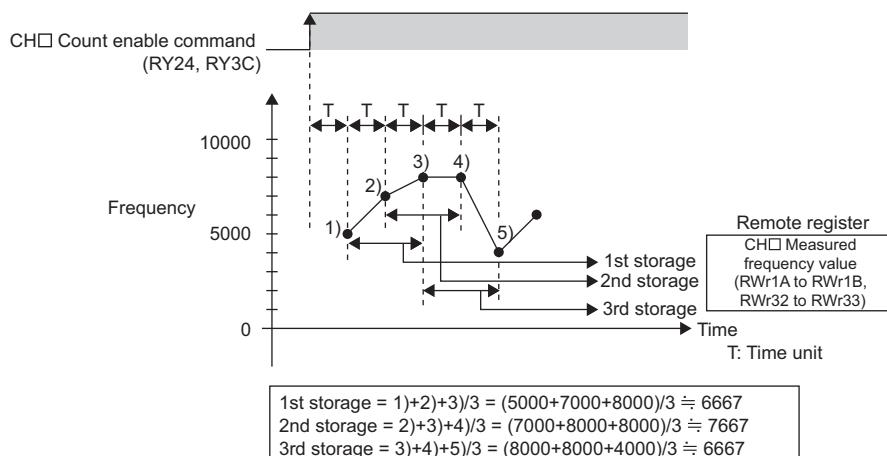
When the frequency measurement function is used, the fluctuation of the measured frequency values can be lowered by doing the moving average count.

Set the number of the moving average count to CH□ Moving average count (Frequency measurement) (RWw19, RWw31).

Setting item	Setting range	Reference
CH□ Moving average count (Frequency measurement) (RWw19, RWw31)	1 to 100 (When 1 is set, the operation is performed with the moving average count regarded as not being done.)	Page 265, Appendix 2 (12)

After the specified number of counts are done, the average of the measured frequency values is stored in CH□ Measured frequency value (RWr1A to RWr1B, RWr32 to RWr33) as shown below.

Ex. When the number for CH□ Moving average count (Frequency measurement) (RWw19, RWw31) is set to 3



Point

After the start of the frequency measurement, CH□ Update flag (Measured frequency value) (RX2D, RX45) turns on every time the measured value is stored in the remote register.

The value previously stored in the remote register is held while CH□ Update flag (Measured frequency value) (RX2D, RX45) is off. (Except at the start of the measurement)

(5) Operation example of the frequency measurement function

The following figure shows an operation example of when CH□ Time unit setting (Frequency measurement) (RWw18, RWw30) is set to 0.01s and CH□ Moving average count (Frequency measurement) (RWw19, RWw31) is set to 3.

-----> Controlled by the high-speed counter module
—> Controlled by the program

CH□ Count enable command (RY24, RY3C)

CH□ Time unit setting (Frequency measurement) (RWw18, RWw30)

CH□ Moving average count (Frequency measurement) (RWw19, RWw31)

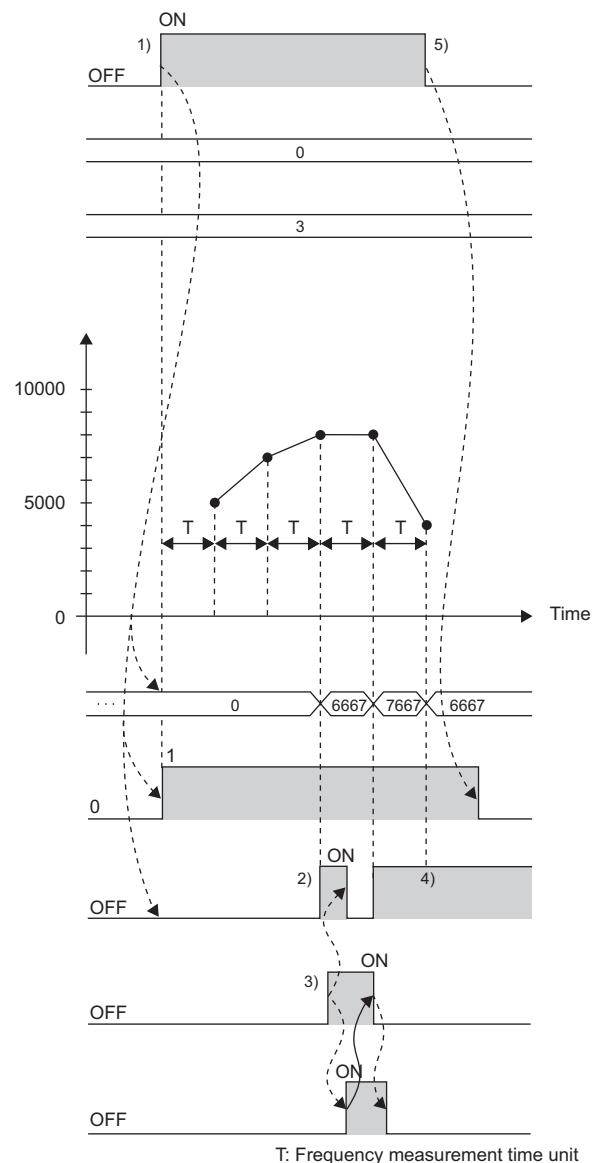
CH□ Measured frequency value (RWr1A to RWr1B, RWr32 to RWr33)

CH□ Frequency measurement flag (RWr20.b4, RWr38.b4)

CH□ Update flag (Measured frequency value) (RX2D, RX45)

CH□ Update flag reset command (Measured frequency value) (RY2C, RY44)

CH□ Update flag reset completed (Measured frequency value) (RX2C, RX44)



No.	Description
1)	<p>The following processing is performed when CH□ Count enable command (RY24, RY3C) is turned on to turn CH□ Frequency measurement flag (RWr20.b4, RWr38.b4) to Operating (1).</p> <ul style="list-style-type: none"> • The values in CH□ Time unit setting (Frequency measurement) (RWw18, RWw30) and CH□ Moving average count (Frequency measurement) (RWw19, RWw31) are acquired. (If the value is changed during the frequency measurement, the change is ignored.) • CH□ Update flag (Measured frequency value) (RX2D, RX45) turns off. • The value in CH□ Measured frequency value (RWr1A to RWr1B, RWr32 to RWr33) is cleared to 0.
2)	CH□ Update flag (Measured frequency value) (RX2D, RX45) turns on when a value is stored in CH□ Measured frequency value (RWr1A to RWr1B, RWr32 to RWr33).
3)	<p>When CH□ Update flag reset command (Measured frequency value) (RY2C, RY44) is turned off then on, the high-speed counter module turns off CH□ Update flag (Measured frequency value) (RX2D, RX45) and turns on CH□ Update flag reset completed (Measured frequency value) (RX2C, RX44).</p> <p>After that, CH□ Update flag reset completed (Measured frequency value) (RX2C, RX44) turns off when CH□ Update flag reset command (Measured frequency value) (RY2C, RY44) is turned off.</p>
4)	CH□ Measured frequency value (RWr1A to RWr1B, RWr32 to RWr33) is updated even when CH□ Update flag (Measured frequency value) (RX2D, RX45) is on.
5)	CH□ Frequency measurement flag (RWr20.b4, RWr38.b4) changes to Not operating (0) when CH□ Count enable command (RY24, RY3C) is turned off.

Point

- The margin of error (maximum) of the frequency measurement function is calculated from the following formula.

$$\text{Real frequency (Hz)} \times \frac{100 \text{ (ppm)}}{1000000} + \frac{1}{\text{Time unit (Frequency measurement) (s)} \times \text{Moving average count (Frequency measurement)}}$$

Ex. The following table shows each value to be put into the formula.

Item	Value
Real frequency (Hz)	1234Hz
Time unit (Frequency measurement) (s)	0.01s
Moving average count (Frequency measurement)	2 times

The margin of error (maximum) is calculated as shown below.

$$1234 \text{ (Hz)} \times \frac{100 \text{ (ppm)}}{1000000} + \frac{1}{0.01 \text{ (s)} \times 2}$$

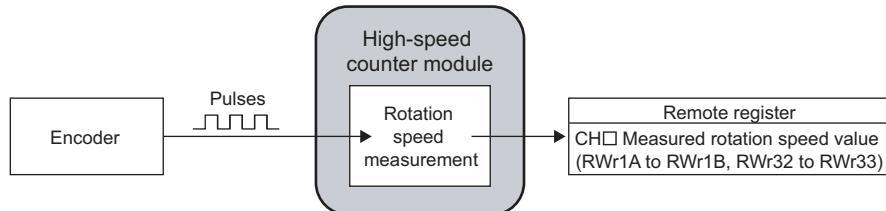
$$= 0.1234 \text{ (Hz)} + 50 \text{ (Hz)}$$

$$= 50.1234 \text{ (Hz)}$$

- CH□ Measured frequency value (RWr1A to RWr1B, RWr32 to RWr33) is updated without resetting CH□ Update flag (Measured frequency value) (RX2D, RX45).
- CH□ Update flag reset command (Measured frequency value) (RY2C, RY44) responds within ΔT_1 after the action. For ΔT_1 , refer to the following.
 - Internal Control Cycle and Response Delay Time (Page 283, Appendix 4)

8.14 Rotation Speed Measurement Function

The rotation speed measurement function counts the pulses of the pulse input terminals in phase A and B, and automatically calculates the rotation speed.



(1) Setting method of the rotation speed measurement function

1. Set "Parameter write" for "Method selection".

→ "CC IE Field Configuration" window → Select a high-speed counter module in "List of stations"
→ [CC IE Field Configuration] → [Parameter Processing of Slave Station]

2. Set "CH□ Operation mode setting" to "2: Rotation Speed Measurement Mode".

CH1 Operation mode setting	0: Normal ...	2: Rotation Speed Measurement Mode
CH1 Count source selection	0: A Phase/...	
CH1 Pulse input mode	0: 1-Phase...	0: Normal Mode
CH1 Counting speed setting	0: 10kpps	1: Frequency Measurement Mode
CH1 Counter format	0: Linear C...	2: Rotation Speed Measurement Mode
CH1 Z phase (Preset) trigger s...	0: Rising	3: Pulse Measurement Mode
		4: PWM Output Mode

(2) Calculation of the rotation speed

The rotation speed measurement function calculates the rotation speed from the following formula.

- Rotation speed (r/min) = $(60 \times \text{Count value per unit of time}) \div (\text{Unit of time}^{\ast 1} \times \text{Number of pulses per rotation}^{\ast 2})$

^{∗1} Select a unit of time from 0.01s, 0.1s, or 1s.

^{∗2} Set the number of pulses per rotation in the range of 1 to 8000000.

Therefore, when the count value per unit of time is 0, the rotation speed is 0(r/min).

At subtraction count, the value of the rotation speed is negative.

(3) Setting of the unit of time for rotation speed measurement and the number of pulses per rotation

Set a unit of time to CH□ Time unit setting (Rotation speed measurement) (RWw18, RWw30).

Set the number of pulses per rotation to CH□ Number of pulses per rotation (RWw1A to RWw1B, RWw32 to RWw33).

Setting item	Setting range	Reference
CH□ Time unit setting (Rotation speed measurement) (RWw18, RWw30)	0: 0.01s 1: 0.1s 2: 1s	—
CH□ Number of pulses per rotation (RWw1A to RWw1B, RWw32 to RWw33)	1 to 8000000	—

Point

- Whichever mode ("1: 1-Phase Multiple of 2", "4: 2-Phase Multiple of 2", or "5: 2-Phase Multiple of 4") is set in "CH□ Pulse input mode" (Page 92, Section 8.1.1), the rotation speed (r/min) is calculated based on the count value per unit of time.
- Required pulse speed (minimum)
The rotation speed is calculated from the count value per unit of time. However, the pulse speed lower than the one in the following table, the rotation speed cannot be measured correctly as the count value is in an integer number. Input the pulses with the speed shown below or higher.

Unit of time	Required pulse speed (minimum)
1s	1pps
0.1s	10pps
0.01s	100pps

When a unit of time is 0.01[s], the number of pulses per rotation is 60, and when the pulse input speed is 1234[pps], the value of the calculated rotation speed is 1200(r/min) or 1300(r/min). By doing the moving average count, the fluctuation of the measured values can be lowered.

(4) Moving average count

When the rotation speed measurement function is used, the fluctuation of the measured rotation speed can be lowered by doing the moving average count.

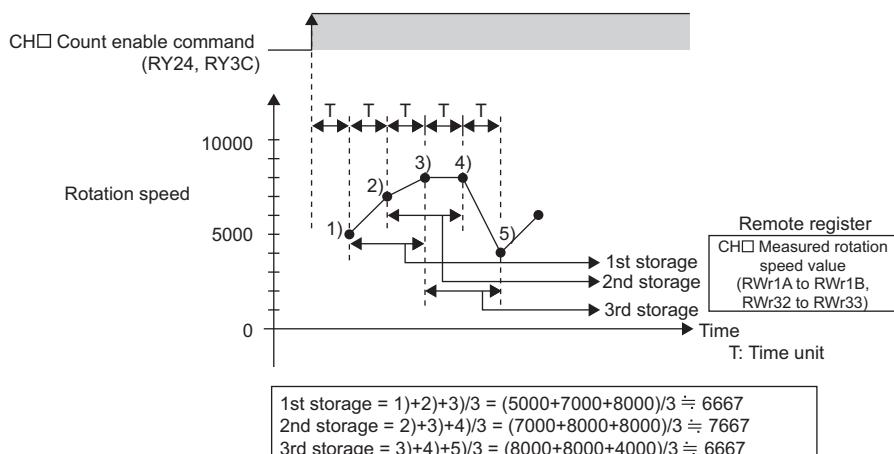
Set the number of the moving average count is set to CH□ Moving average count (Rotation speed measurement) (RWw19, RWw31).

8

Setting item	Setting range	Reference
CH□ Moving average count (Rotation speed measurement) (RWw19, RWw31)	1 to 100 (When 1 is set, the operation is performed with the moving average count regarded as not being done.)	Page 265, Appendix 2 (12)

After the specified number of counts are done, the average of the measured values of the rotation speed is stored in CH□ Measured rotation speed value (RWr1A to RWr1B, RWr32 to RWr33) as shown below.

Ex. When the number for CH□ Moving average count (Rotation speed measurement) (RWw19, RWw31) is set to 3



(5) Operation example of the rotation speed measurement function

The following figure shows an operation example with the following settings.

- CH□ Time unit setting (Rotation speed measurement) (RWw18, RWw30): 0.01s
- CH□ Moving average count (Rotation speed measurement) (RWw19, RWw31): 3
- CH□ Number of pulses per rotation (RWw1A to RWw1B, RWw32 to RWw33): 1000

- Controlled by the high-speed counter module
- Controlled by the program

CH□ Count enable command
(RY24, RY3C)

CH□ Time unit setting
(Rotation speed measurement)
(RWw18, RWw30)

CH□ Moving average count
(Rotation speed measurement)
(RWw19, RWw31)

CH□ Number of pulses per rotation
(RWw1A to RWw1B, RWw32 to RWw33)

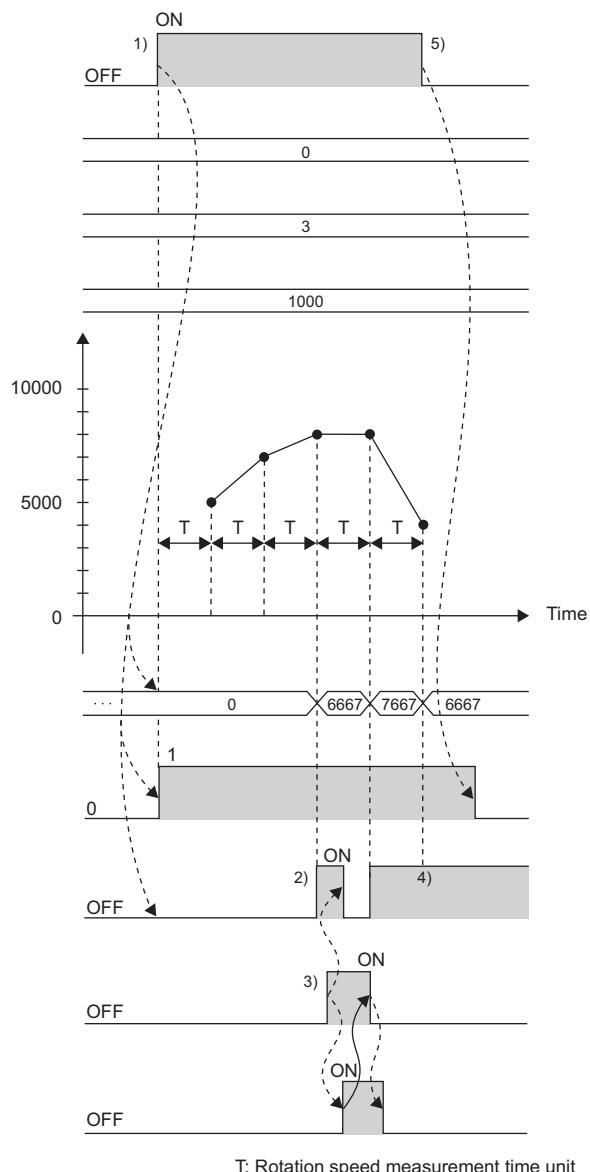
CH□ Measured rotation speed value
(RW_r1A to RW_r1B, RW_r32 to RW_r33)

CH□ Rotation speed measurement flag
(RW_r20.b5, RW_r38.b5)

CH□ Update flag
(Measured rotation speed value)
(RX2D, RX45)

CH□ Update flag reset command
(Measured rotation speed value)
(RY2C, RY44)

CH□ Update flag reset completed
(Measured rotation speed value)
(RX2C, RX44)



No.	Description
1)	The following processing is performed when CH□ Count enable command (RY24, RY3C) is turned on to turn CH□ Rotation speed measurement flag (RW _r 20.b5, RW _r 38.b5) to Operating (1). <ul style="list-style-type: none"> • The values of CH□ Time unit setting (Rotation speed measurement) (RW_w18, RW_w30), CH□ Moving average count (Rotation speed measurement) (RW_w19, RW_w31), and CH□ Number of pulses per rotation (RW_w1A to RW_w1B, RW_w32 to RW_w33) are acquired. (If the value is changed during the rotation speed measurement, the change is ignored.) • CH□ Update flag (Measured rotation speed value) (RX2D, RX45) turns off. • The value in CH□ Measured rotation speed value (RW_r1A to RW_r1B, RW_r32 to RW_r33) is cleared to 0.
2)	CH□ Update flag (Measured rotation speed value) (RX2D, RX45) turns on when a value is stored in CH□ Measured rotation speed value (RW _r 1A to RW _r 1B, RW _r 32 to RW _r 33).
3)	When CH□ Update flag reset command (Measured rotation speed value) (RY2C, RY44) is turned off then on, the high-speed counter module turns off CH□ Update flag (Measured rotation speed value) (RX2D, RX45) and turns on CH□ Update flag reset completed (Measured rotation speed value) (RX2C, RX44). After that, CH□ Update flag reset completed (Measured rotation speed value) (RX2C, RX44) turns off when CH□ Update flag reset command (Measured rotation speed value) (RY2C, RY44) is turned off.
4)	CH□ Measured rotation speed value (RW _r 1A to RW _r 1B, RW _r 32 to RW _r 33) is updated even when CH□ Update flag (Measured rotation speed value) (RX2D, RX45) is on.
5)	CH□ Rotation speed measurement flag (RW _r 20.b5, RW _r 38.b5) changes to Not operating (0) when CH□ Count enable command (RY24, RY3C) is turned off.

Point

- After the start of the rotation speed measurement, CH□ Update flag (Measured rotation speed value) (RX2D, RX45) turns on every time the measured value is stored in CH□ Measured rotation speed value (RW_r1A to RW_r1B, RW_r32 to RW_r33). The value previously stored in the remote register is held while CH□ Update flag (Measured rotation speed value) (RX2D, RX45) is off. (Except at the start of the measurement)
- The margin of error (maximum) of the rotation speed measurement function is calculated from the following formula.

$$\text{Actual rotation speed (r/min)} \times \frac{100 \text{ (ppm)}}{1000000} + \frac{60}{\text{Time unit (Rotation speed measurement) (s)} \times \text{Moving average count (Rotation speed measurement)} \times \text{Number of pulses per rotation}}$$

Ex. The following table shows each value to be put into the formula.

Item	Value
Actual rotation speed (r/min)	1234r/min
Time unit (Rotation speed measurement) (s)	0.01s
Moving average count (Rotation speed measurement)	4 times
Number of pulses per rotation	60

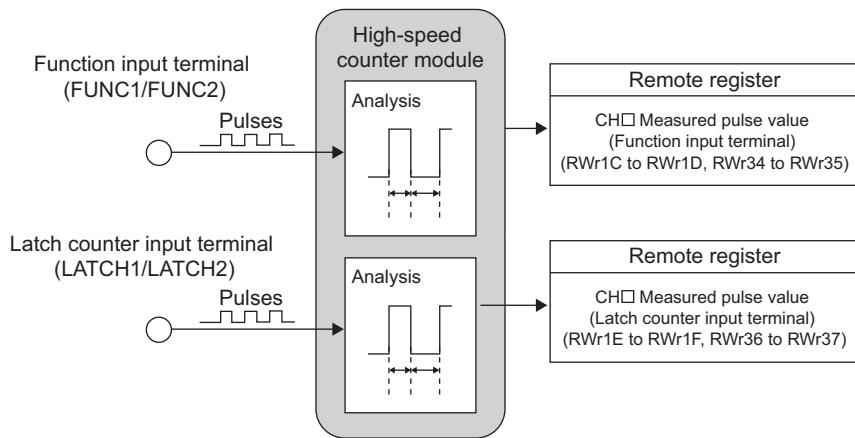
The margin of error (maximum) is calculated as shown below.

$$\begin{aligned}
 & 1234 \text{ (r/min)} \times \frac{100 \text{ (ppm)}}{1000000} + \frac{60}{0.01 \text{ (s)} \times 4 \times 60} \\
 & = 0.1234 \text{ (r/min)} + 25 \text{ (r/min)} \\
 & = 25.1234 \text{ (r/min)}
 \end{aligned}$$

- CH□ Measured rotation speed value (RW_r1A to RW_r1B, RW_r32 to RW_r33) is updated without resetting CH□ Update flag (Measured rotation speed value) (RX2D, RX45).
- CH□ Update flag reset command (Measured rotation speed value) (RY2C, RY44) responds within ΔT_1 after the action. For ΔT_1 , refer to the following.
 - Internal Control Cycle and Response Delay Time (Page 283, Appendix 4)

8.15 Pulse Measurement Function

The pulse measurement function measures the ON width or OFF width of pulses that are input to the external input terminals, CH□ Function input terminal (FUNC1, FUNC2) or CH□ Latch counter input terminal (LATCH1, LATCH2). When the next pulse is measured, the measured value is written over the previous value.



(1) Setting method of the pulse measurement function

1. Set "Parameter write" for "Method selection".

🔗 "CC IE Field Configuration" window ➔ Select a high-speed counter module in "List of stations"
➔ [CC IE Field Configuration] ➔ [Parameter Processing of Slave Station]

2. Set "CH□ Operation mode setting" to "3: Pulse Measurement Mode".

CH1 Operation mode setting	0: Normal ...	3: Pulse Measurement Mode
CH1 Count source selection	0: A Phase/...	
CH1 Pulse input mode	0: 1-Phase...	
CH1 Counting speed setting	0: 10kpps	
CH1 Counter format	0: Linear C...	
CH1 Z phase (Preset) trigger s...	0: Rising	

3. Set the pulse width to be measured in "CH□ Pulse measurement setting (Function input terminal)".

CH1 Pulse measurement setting (Function input terminal)	0: Pulse O...	0: Pulse ON Width
CH1 Pulse measurement setting (Latch counter input terminal)	0: Pulse O...	
<input checked="" type="checkbox"/> CH2 Setting		0: Pulse ON Width 1: Pulse OFF Width
CH2 Operation mode setting	0: Normal ...	

4. Set the pulse width to be measured in "CH□ Pulse measurement setting (Latch counter input terminal)".

CH1 Pulse measurement setting (Function input terminal)	0: Pulse O...	0: Pulse ON Width
CH1 Pulse measurement setting (Latch counter input terminal)	0: Pulse O...	
<input checked="" type="checkbox"/> CH2 Setting		0: Pulse ON Width 1: Pulse OFF Width
CH2 Operation mode setting	0: Normal ...	
CH2 Count source selection	0: A Phase/...	

(2) Terminals for the pulse measurement

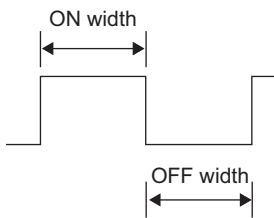
The following table lists the terminals that are used for the pulse measurement for each channel.

Channel	Terminals for the pulse measurement
CH1	Function input terminal 1 (FUNC1)
	Latch counter input terminal 1 (LATCH1)
CH2	Function input terminal 2 (FUNC2)
	Latch counter input terminal 2 (LATCH2)

(3) Pulse width to be measured

Set which pulse width (ON or OFF) is to be measured by using "CH□ Pulse measurement setting (Function input terminal)" and "CH□ Pulse measurement setting (Latch counter input terminal)".

The measured value is stored in CH□ Measured pulse value (Function input terminal) (RWr1C to RWr1D, RWr34 to RWr35) or CH□ Measured pulse value (Latch counter input terminal) (RWr1E to RWr1F, RWr36 to RWr37).



Pulse width to be measured	Setting value of pulse width to be measured	Description
Pulse ON width	0	The ON time of the input pulse is measured.
Pulse OFF width	1	The OFF time of the input pulse is measured.

(4) Measurable range of the pulses

The measurable range of the pulses is between 2000 and 2147483647 (0.2ms to approx. 214s). When the input pulses are beyond the measurable range, the error code (□660_H or □662_H) is stored in CH□ Latest error code (RWr22, RWr3A) and Error status flag (RXA) and the ERR. LED turns on.

To resume the measurement, input the pulses once again, or perform the operation as shown below.

Measurement to be resumed	Operation	Remarks
Measurement with the function input terminal	Turn off then on the F start command.*1	The pulse measurement is not resumed until the F measurement flag or the L measurement flag changes to Not operating (OFF) after the F start command or L start command is turned off.*1
Measurement with the latch counter input terminal	Turn off then on the L start command.*1	

*1 The abbreviations mean as the follows.

- F start command: CH□ Pulse measurement start command (Function input terminal) (RY30, RY48)
- L start command: CH□ Pulse measurement start command (Latch counter input terminal) (RY32, RY4A)
- F measurement flag: CH□ Pulse measurement flag (Function input terminal) (RWr20.b6, RWr38.b6)
- L measurement flag: CH□ Pulse measurement flag (Latch counter input terminal) (RWr20.b7, RWr38.b7)

(5) Update timing of the measured values of pulses

The measured pulse value is updated in the remote register every ΔT_2 cycle. So when the measurement is done twice or more within ΔT_2 , only the latest measured value is stored in the remote registers. For details on ΔT_2 , refer to the following.

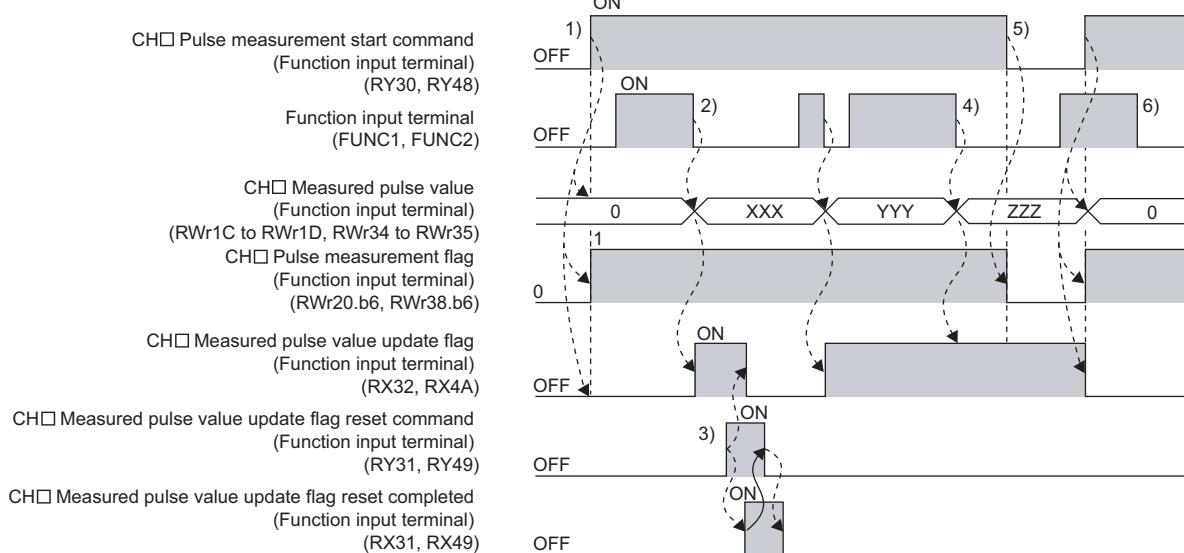
- Internal Control Cycle and Response Delay Time (☞ Page 283, Appendix 4)

(6) Operation example of the pulse measurement function

The following figure shows an operation example of the pulse measurement for the ON width with CH□ Function input terminal (FUNC1, FUNC2).

The explanations in the following table are for the measurement with CH□ Function input terminal (FUNC1, FUNC2). The same can be applied to the measurement with CH□ Latch counter input terminal (LATCH1, LATCH2) except the difference of the terminals for the pulse measurement and the setting items. For details on the difference, refer to Page 159, Section 8.15 (7).

-----→ Controlled by the high-speed counter module
→ Controlled by the program



No.	Description
1)	When CH□ Pulse measurement start command (Function input terminal) (RY30, RY48) is turned on, CH□ Pulse measurement flag (Function input terminal) (RWRI20.b6, RWRI38.b6) changes to Operating (1). The following processing are performed. The remote input signal and remote register remain the same before the measured pulse value is stored. <ul style="list-style-type: none"> CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A) turns off. The value in CH□ Measured pulse value (Function input terminal) (RWRI1C to RWRI1D, RWRI34 to RWRI35) changes to 0.
2)	The following processing is performed when the measured pulse value is stored. <ul style="list-style-type: none"> CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A) turns on.
3)	When CH□ Measured pulse value update flag reset command (Function input terminal) (RY31, RY49) is turned off then on, the high-speed counter module turns off CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A) and turns on CH□ Measured pulse value update flag reset completed (Function input terminal) (RX31, RX49). After that, CH□ Measured pulse value update flag reset completed (Function input terminal) (RX31, RX49) turns off when CH□ Measured pulse value update flag reset command (Function input terminal) (RY31, RY49) is turned off.
4)	CH□ Measured pulse value (Function input terminal) (RWRI1C to RWRI1D, RWRI34 to RWRI35) is updated even if CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A) is on.
5)	CH□ Pulse measurement flag (Function input terminal) (RWRI20.b6, RWRI38.b6) changes to Not operating (0) and the pulse measurement stops by turning off CH□ Pulse measurement start command (Function input terminal) (RY30, RY48).
6)	If the pulse (pulse ON width in this case) is input before CH□ Pulse measurement flag (Function input terminal) (RWRI20.b6, RWRI38.b6) changes to Operating (1), CH□ Measured pulse value (Function input terminal) (RWRI1C to RWRI1D, RWRI34 to RWRI35) is not updated even when CH□ Function input terminal (FUNC1, FUNC2) is turned off. Note that the pulse that is input after the setting in CH□ Pulse measurement flag (Function input terminal) (RWRI20.b6, RWRI38.b6) changes to Operating (1) is to be measured.

Point

When the pulse measurement function is executed with CH□ Function input terminal (FUNC1, FUNC2), the time to be taken to update CH□ Measured pulse value (Function input terminal) (RW_r1C to RW_r1D, RW_r34 to RW_r35) varies according to the time set in "CH□ Function input response time setting". (The same can be applied to the measurement with CH□ Latch counter input terminal (LATCH1, LATCH2) except the differences such as the setting items.)

(7) Pulse measurement difference between CH□ Function input terminal (FUNC1, FUNC2) and CH□ Latch counter input terminal (LATCH1, LATCH2)

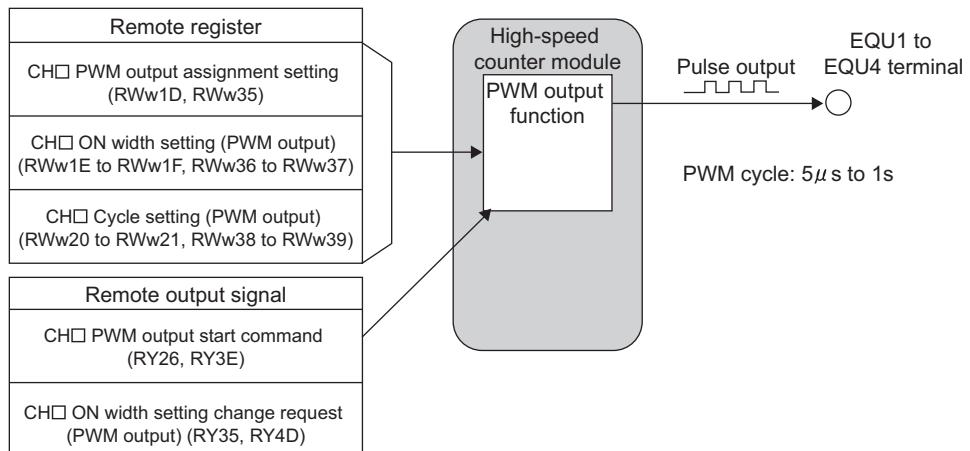
The pulse measurement same as CH□ Function input terminal (FUNC1, FUNC2) can be applied to the measurement with CH□ Latch counter input terminal (LATCH1, LATCH2) except the difference of the terminals for the pulse measurement and the setting items.

The following table lists the differences of the setting items between both terminals.

Input terminal, setting item	Pulse measurement (with function input terminal)	Pulse measurement (with latch counter input terminal)
Terminals for the pulse measurement	CH□ Function input terminal (FUNC1, FUNC2)	CH□ Latch counter input terminal (LATCH1, LATCH2)
Setting for pulse width to be measured	CH□ Pulse measurement setting (Function input terminal) (address: 012A _H , 014A _H)	CH□ Pulse measurement setting (Latch counter input terminal) (address: 012B _H , 014B _H)
Measured pulse value	CH□ Measured pulse value (Function input terminal) (RW _r 1C to RW _r 1D, RW _r 34 to RW _r 35)	CH□ Measured pulse value (Latch counter input terminal) (RW _r 1E to RW _r 1F, RW _r 36 to RW _r 37)
Pulse measurement start command	CH□ Pulse measurement start command (Function input terminal) (RY30, RY48)	CH□ Pulse measurement start command (Latch counter input terminal) (RY32, RY4A)
Pulse measurement flag	CH□ Pulse measurement flag (Function input terminal) (RW _r 20.b6, RW _r 38.b6)	CH□ Pulse measurement flag (Latch counter input terminal) (RW _r 20.b7, RW _r 38.b7)
Measured pulse value update flag	CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A)	CH□ Measured pulse value update flag (Latch counter input terminal) (RX34, RX4C)
Measured pulse value update flag reset command	CH□ Measured pulse value update flag reset command (Function input terminal) (RY31, RY49)	CH□ Measured pulse value update flag reset command (Latch counter input terminal) (RY33, RY4B)
Measured pulse value update flag reset completed	CH□ Measured pulse value update flag reset completed (Function input terminal) (RX31, RX49)	CH□ Measured pulse value update flag reset completed (Latch counter input terminal) (RX33, RX4B)

8.16 PWM Output Function

The PWM output function outputs the PWM waveform (up to 200kHz) from one of the coincidence output 1 to 4 terminals (EQU1 to EQU4). Up to four points can be assigned for one channel. The same waveform is to be output to the assigned terminals. The ON width setting (PWM output) can be changed during PWM output.

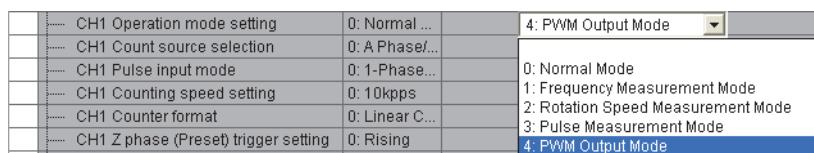


(1) Setting method of the PWM output function

1. Set "Parameter write" for "Method selection".

☞ "CC IE Field Configuration" window ⇒ Select a high-speed counter module in "List of stations"
⇒ [CC IE Field Configuration] ⇒ [Parameter Processing of Slave Station]

2. Set "CH□ Operation mode setting" to "4: PWM Output Mode".



(2) Assignment of the PWM output terminals

To output the PWM waveform, assign Coincidence output 1 to 4 to the corresponding channel in "Coincidence output 1 to 4 channel assignment setting". Then, by using CH□ PWM output assignment setting (RWw1D, RWw35) of the remote register, assign which Coincidence output is used for the PWM waveform output. The following table shows the setting examples of the assignment.

Ex. Assignment example of the PWM output terminals (CH1)

Ex.	Setting item	Setting detail	Operation
1	Coincidence output 1 channel assignment setting	0: CH1	The error code ($\square 670_H$) is stored in CH□ Latest error code (RWw22, RWw3A) since no Coincidence output is assigned as the PWM output terminal. At this time, Error status flag (RXA) and the ERR. LED turns on.
	Coincidence output 2 channel assignment setting	0: CH1	
	Coincidence output 3 channel assignment setting	1: CH2	
	Coincidence output 4 channel assignment setting	1: CH2	
	CH1 PWM output assignment setting (RWw1D)	0000 _H	No PWM output terminals
2	Coincidence output 1 channel assignment setting	0: CH1	Coincidence output 2 is assigned to the PWM output terminal and the operation is performed.
	Coincidence output 2 channel assignment setting	0: CH1	
	Coincidence output 3 channel assignment setting	1: CH2	
	Coincidence output 4 channel assignment setting	1: CH2	
	CH1 PWM output assignment setting (RWw1D)	0002 _H	Coincidence output 2 is assigned to the PWM output terminal.
3	Coincidence output 1 channel assignment setting	0: CH1	Coincidence output 1 and Coincidence output 2 are assigned to the PWM output terminal and the operation is performed. (The same PWM waveform is output.)
	Coincidence output 2 channel assignment setting	0: CH1	
	Coincidence output 3 channel assignment setting	1: CH2	
	Coincidence output 4 channel assignment setting	1: CH2	
	CH1 PWM output assignment setting (RWw1D)	0003 _H	Coincidence output 1 and Coincidence output 2 are assigned to the PWM output terminal.

Ex.	Setting item	Setting detail	Operation
4	Coincidence output 1 channel assignment setting	0: CH1	The error code ($\square 670_H$) is stored in CH□. Latest error code (RWr22, RWr3A) since the Coincidence output is assigned to Coincidence output 3 that is used by CH2. At this time, Error status flag (RXA) and the ERR. LED turns on.
	Coincidence output 2 channel assignment setting	0: CH1	
	Coincidence output 3 channel assignment setting	1: CH2	
	Coincidence output 4 channel assignment setting	1: CH2	
	CH1 PWM output assignment setting (RWw1D)	0004_H	
5	Coincidence output 1 channel assignment setting	0: CH1	Coincidence output 1 to 4 are assigned to the PWM output terminal and the operation is performed. (The same PWM waveform is output from all the Coincidence output terminals.)
	Coincidence output 2 channel assignment setting	0: CH1	
	Coincidence output 3 channel assignment setting	0: CH1	
	Coincidence output 4 channel assignment setting	0: CH1	
	CH1 PWM output assignment setting (RWw1D)	$000F_H$	

Point

For Coincidence output that is assigned as the PWM output terminal in CH□ PWM output assignment setting (RWw1D, RWw35), the setting in "Coincidence output 1 to 4 comparison condition setting" is disabled.

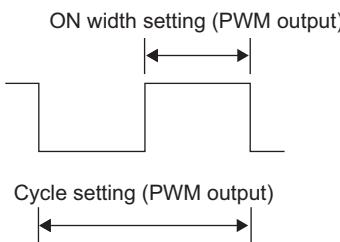
(3) Setting method of the output waveform

Set the output waveform by using CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37) and CH□ Cycle setting (PWM output) (RWw20 to RWw21, RWw38 to RWw39).

The following table lists the setting items.

Setting item	Setting range	Description	Remarks
CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37)	0, 10 to 10000000 ^{*1}	Set the ON time of the output pulse.	0.1μs per unit
CH□ Cycle setting (PWM output) (RWw20 to RWw21, RWw38 to RWw39)	50 to 1000000	Set the cycle of the output pulse.	0.1μs per unit

*1 Set the value that is equal to or smaller than the one set to the cycle setting (PWM output).



Point

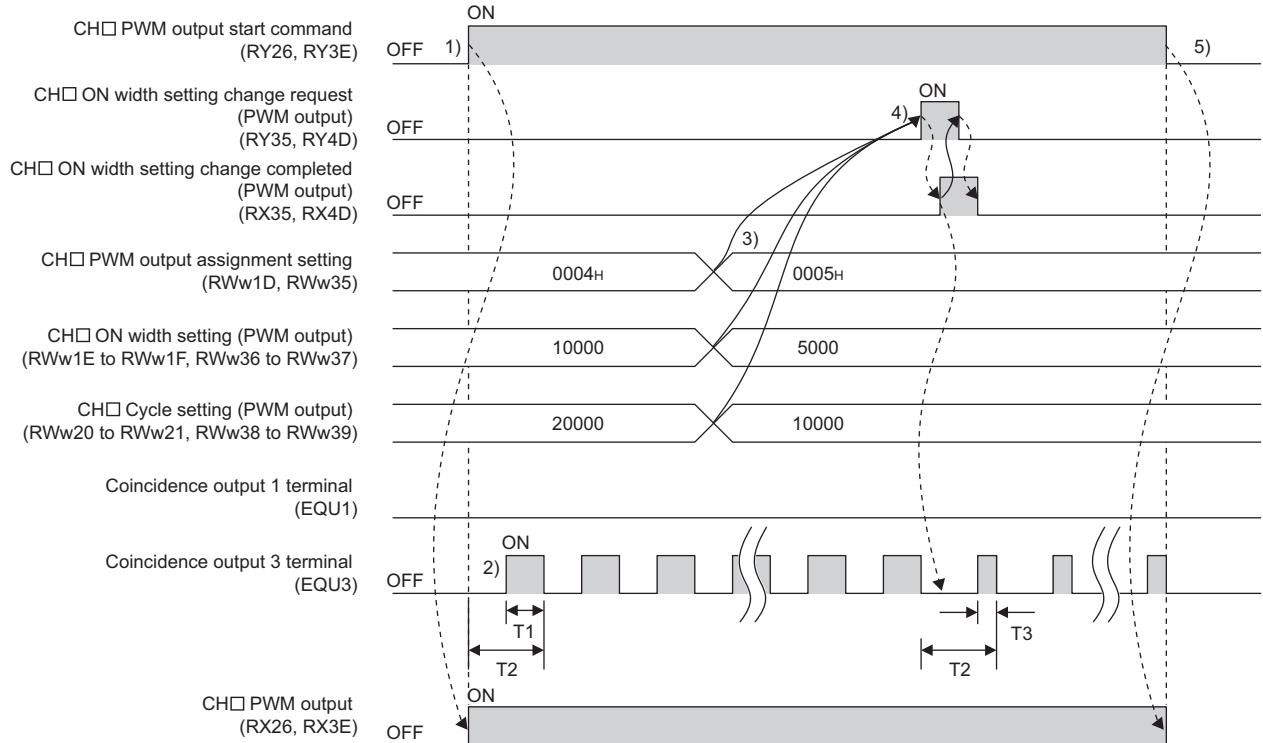
- The ON width of the PWM output is calculated from the following formula according to the duty ratio to be specified.
ON width of the PWM output = Cycle of the PWM output × Duty ratio [%] ÷ 100
- Given that output circuits or connected devices of the high-speed counter module do not affect the value, the margin of error (maximum) of each setting value is calculated as shown below.
 - ON width setting (PWM output) [μs] × 100 [ppm] ÷ 1000000 + 0.1 [μs]
 - Cycle setting (PWM output) [μs] × 100 [ppm] ÷ 1000000 + 0.1 [μs]

(4) Operation example of the PWM output function

The following figure shows an operation example of outputting the PWM waveform whose cycle time is 2ms and ON time is 1ms to change the ON time to 0.5ms during PWM output.

Coincidence output is assigned to the corresponding channel in the "Coincidence output 3 channel assignment setting".

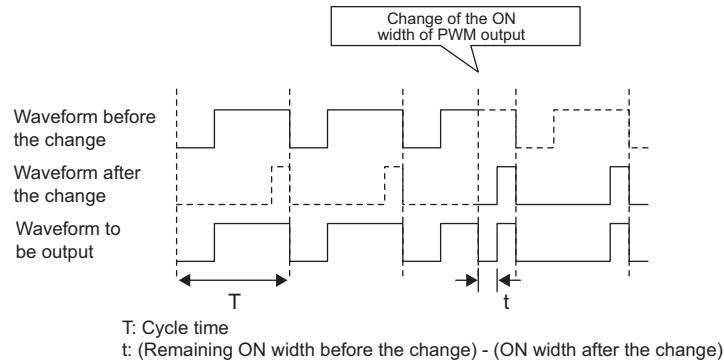
→ Controlled by the high-speed counter module
 → Controlled by the program



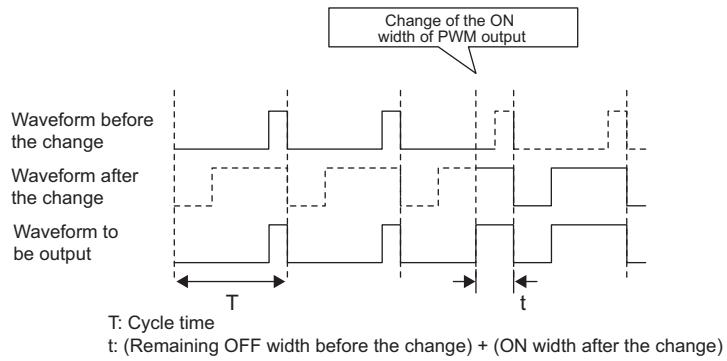
No.	Description
1)	<p>The following processing is performed when CH□ PWM output start command (RY26, RY3E) is turned on to turn on CH□ PWM output (RX26, RX3E).</p> <ul style="list-style-type: none"> • The values in CH□ PWM output assignment setting (RWw1D, RWw35), CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37), and CH□ Cycle setting (PWM output) (RWw20 to RWw21, RWw38 to RWw39) are acquired. • The PWM waveform is output from one of the coincidence output 1 to 4 terminals (EQU1 to EQU4) based on the settings. (The PWM waveform is output starting with OFF.)
2)	<p>The PWM waveform continues to be output based on the acquired settings until CH□ PWM output start command (RY26, RY3E) is turned off or CH□ ON width setting change request (PWM output) (RY35, RY4D) is turned on.</p>
3)	<p>When the values in CH□ PWM output assignment setting (RWw1D, RWw35), CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37), and CH□ Cycle setting (PWM output) (RWw20 to RWw21, RWw38 to RWw39) are changed, the PWM waveform is not changed. Only the value in CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37) can be changed by CH□ ON width setting change request (PWM output) (RY35, RY4D).</p>
4)	<p>The following processing is performed when CH□ ON width setting change request (PWM output) (RY35, RY4D) is turned off then on to turn on CH□ ON width setting change completed (PWM output) (RX35, RX4D).</p> <ul style="list-style-type: none"> • The value in CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37) is acquired. • The PWM waveform is output from one of the coincidence output 1 to 4 terminals (EQU1 to EQU4) based on the settings. The change is reflected immediately. <p>Turn off CH□ ON width setting change request (PWM output) (RY35, RY4D) when CH□ ON width setting change completed (PWM output) (RX35, RX4D) turns on. CH□ ON width setting change completed (PWM output) (RX35, RX4D) turns off when CH□ ON width setting change request (PWM output) (RY35, RY4D) is turned off.</p>
5)	<p>The following processing is performed when CH□ PWM output start command (RY26, RY3E) is turned off to turn off CH□ PWM output (RX26, RX3E).</p> <ul style="list-style-type: none"> • Turn off the coincidence output 1 to 4 terminals (EQU1 to EQU4) immediately.

Point

- The waveform that is output from the coincidence output 1 to 4 terminals (EQU1 to EQU4), the external output terminals, can be affected by output circuits or connected devices of the high-speed counter module and change its form. Therefore, check the waveform by using, for example, a synchroscope, and set the output waveform.
- When changing the cycle time of the PWM waveform, turn off CH□ PWM output start command (RY26, RY3E) to turn off CH□ PWM output (RX26, RX3E). After checking that CH□ PWM output (RX26, RX3E) is off, change the setting of CH□ Cycle setting (PWM output) (RWw20 to RWw21, RWw38 to RWw39), and turn on CH□ PWM output start command (RY26, RY3E) again.
- When the ON time is changed during PWM output, the change is reflected immediately, therefore, the ON time before the change may be interrupted at the cycle in which the ON time is changed. When the ON time after the change is shorter than the ON time before the change, unnecessary OFF waveform may be output depending on the changing timing.



When the ON time after the change is longer than the ON time before the change, the ON waveform may be output at the time of the change depending on the changing timing.



8.17 Output HOLD/CLEAR Setting Function

When the high-speed counter module is disconnected from data link, or the CPU module operating status is STOP, whether to hold or clear the last Coincidence output (EQU1 to EQU4) and the output status of the extension output module can be set. Set whether to hold or clear the values for all the output points of the module in a batch from the module parameter setting window of GX Works2 or the program.

(1) Output HOLD/CLEAR setting and its operation

The following table lists the ON/OFF status of when HOLD or CLEAR is set for an output.

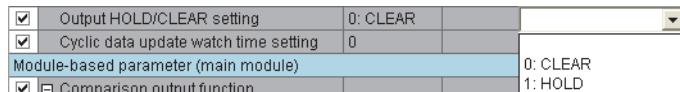
Operating status	"Output HOLD/CLEAR setting" "0: CLEAR" (default)		"Output HOLD/CLEAR setting" "1: HOLD"	
	Last output status OFF	Last output status ON	Last output status OFF	Last output status ON
Data link in operation	CPU module in RUN	OFF	ON	OFF
	CPU module in STOP	OFF	OFF	OFF
	CPU module in PAUSE	OFF	ON	OFF
	CPU module in RESET	OFF	OFF	OFF
During disconnection/cyclic stop	OFF	OFF	OFF	ON

(2) Setting method

1. Set "Parameter write" for "Method selection".

 "CC IE Field Configuration" window \Rightarrow Select a high-speed counter module in "List of stations" \Rightarrow [CC IE Field Configuration] \Rightarrow [Parameter Processing of Slave Station]

2. For "Output HOLD/CLEAR setting", select "0: CLEAR" or "1: HOLD".



Item	Setting range
Output HOLD/CLEAR setting	<ul style="list-style-type: none"> • 0: CLEAR • 1: HOLD

Point

When the output status changes according to the change in the comparison result after the output is set to HOLD, the output of the following functions changes.

- Coincidence output (EQU1 to EQU4) of the coincidence output function
- Coincidence output (EQU1 to EQU4) of the PWM output function
- Output of the extension output module that is used as the output of the cam switch function (Y0 to YF)

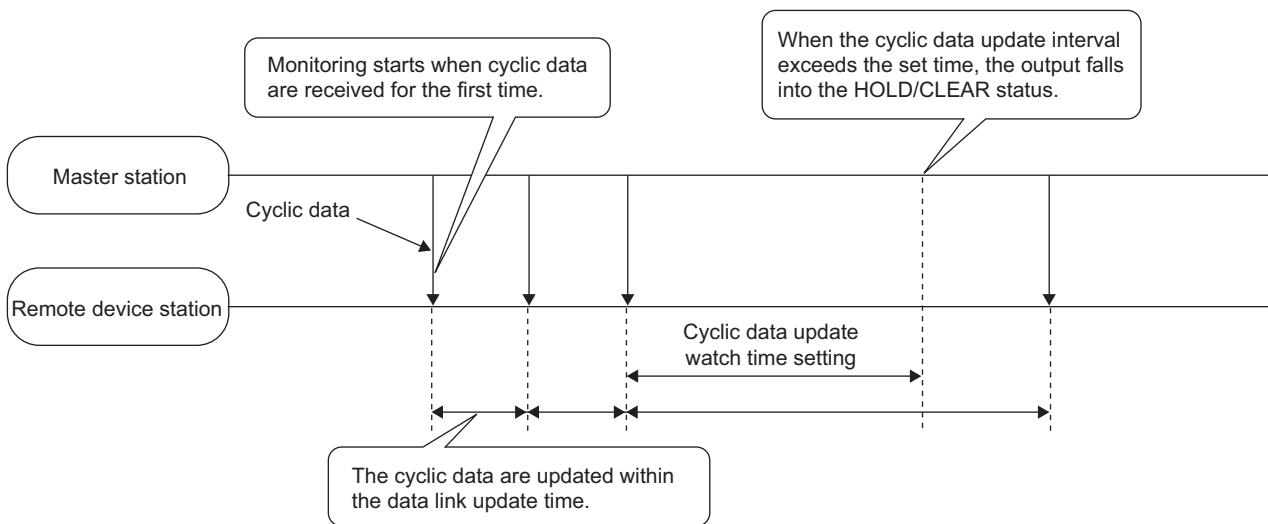
8.18 Cyclic Data Update Watch Function

This function monitors the cyclic data update interval. When the cyclic transmission remains to be stopped over the set watch time, this function holds or clears the value which is output just before.

In the cyclic transmission stop status, the D LINK LED is flashing (Data link in operation (cyclic transmission stopped)) or off (Data link not performed (disconnected)).

Set whether to hold or clear the output value using the output HOLD/CLEAR setting function. For the output HOLD/CLEAR setting function, refer to the following.

- Output HOLD/CLEAR Setting Function (☞ Page 167, Section 8.17)



(1) Setting method

1. Set "Parameter write" for "Method selection".

☞ "CC IE Field Configuration" window ⇒ Select a high-speed counter module in "List of stations" ⇒ [CC IE Field Configuration] ⇒ [Parameter Processing of Slave Station]

2. For "Cyclic data update watch time setting", set the monitoring time.

<input checked="" type="checkbox"/>	Cyclic data update watch time setting	0	20
-------------------------------------	---------------------------------------	---	----

Item	Setting range
Cyclic data update watch time setting	<ul style="list-style-type: none">• 0 (Not monitor)• 1 to 20 (0.1 to 2 seconds, in increments of 100ms)

Point

Set the greater value for the cyclic data update watch time setting than that of the link scan time.

8.19 Error Notification Function

When an error or warning occurs, the high-speed counter module notifies the master station of it using remote input signals and remote registers.

Remark

The notification of the error or warning can be checked on the LED on the front of the module.
For details, refer to the following.

- PART NAMES (☞ Page 21, CHAPTER 2)

(1) Notification of an error

The high-speed counter module notifies the master station of an error in the following method.

Item	Description	Reference
Error status flag (RXA)	Turns on when a moderate error or major error occurs.	
CH□ Error status (RX36, RX4E)	Turns on when a moderate error or major error occurs for each channel.	Page 236, Appendix 1.1
CH□ Latest error code (RWr22, RWr3A)*1	An error code is stored when a moderate error or major error occurs for each channel.	Page 260, Appendix 2 (6)

*1 Errors independent from channels are station errors stored in CH1 Latest error code (RWr22).

(a) Method for clearing an error

The method for clearing an error depends on the error type.

Error type	Clearing an error
Major error	The error cannot be cleared.
Moderate error	Turn off then on CH□ Error reset command (RY36, RY4E) or Initial data setting request flag (RY9) after removing the error cause.

(2) Notification of a warning

The high-speed counter module notifies the master station of a warning in the following method.

Name	Description	Reference
Warning status flag (RX7)	Turns on when a minor error occurs.	
CH□ Warning status (RX37, RX4F)	Turns on when a minor error occurs for each channel.	Page 236, Appendix 1.1
CH□ Latest warning code (RWr23, RWr3B)*1	The error code is stored when a minor error occurs for each channel.	Page 260, Appendix 2 (6)

*1 Errors independent from channels are station errors stored in CH1 Latest warning code (RWr23).

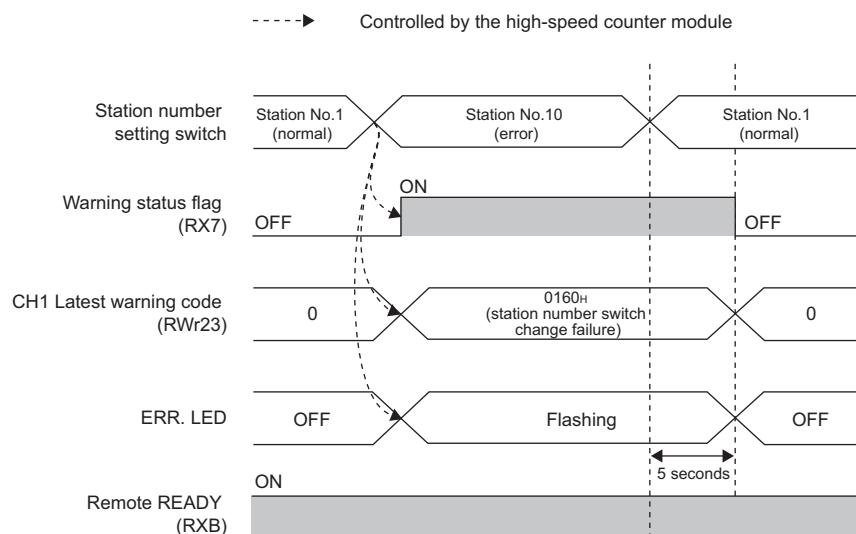
(a) Method for clearing a warning

Error type		Clearing an error	
Minor error	Warning	Error code: Other than □050H	A warning is cleared five seconds after the error cause is removed.*1
		Error code: □050H	Turning off then on CH□ Error reset command (RY36, RY4E) resets the warning status of each channel.*1

*1 A warning results in the following state five seconds after the error cause is removed or CH□ Error reset command (RY36, RY4E) is turned off then on.

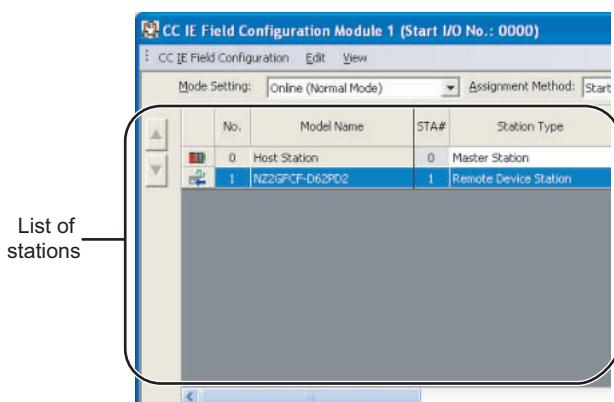
- Warning status flag (RX7) turns off.
- CH□ Warning status (RX37, RX4F) of a channel where the error cause is removed turns off.
- CH□ Latest warning code (RW_r23, RW_r3B) of a channel where the error cause is removed is cleared.
- The ERR. LED turns off.

Ex. Operation to clear Station number switch change failure (error code: 0160H)

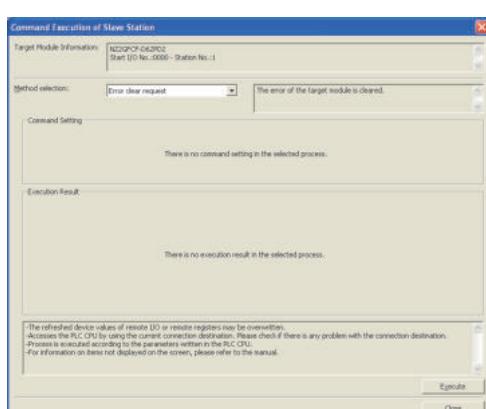


(3) Method for clearing an error by executing the command of the slave station

The following shows how to clear an error by executing the command of the slave station.



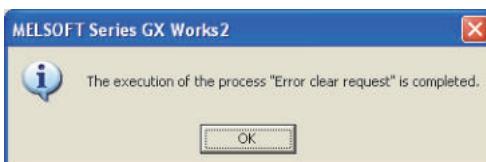
1. Select the high-speed counter module in "List of stations" on the "CC IE Field Configuration" window.



2. Open the "Command Execution of Slave Station" window.

→ [CC IE Field Configuration] ⇔ [Command Execution of Slave Station]

3. Set "Method selection" to "Error clear request" and click the button.



4. When the window shown on the left is displayed, click the button.

5. The error for the high-speed counter module is cleared.

8.20 Function at the Extension Module Installation

One extension I/O module can be connected to one high-speed counter module.

In addition, functions unique to the extension I/O module can be used.

Point

- Turn off the high-speed counter module before replacing the extension I/O module. If the extension module is removed when the module power supply is on, the error code (1F00_H) is stored to CH1 Latest error code (RW_{r22}), Error status flag (RXA) turns on, and the ERR. LED turns on. The main module stops its operation.
- After replacing the extension I/O module, write the parameters again.

(1) Functions available with an extension I/O module connected

Function	Reference
Cam switch function	Page 117, Section 8.3.4
External power supply monitoring function	Page 173, Section 8.20 (2)
Output HOLD/CLEAR setting function	Page 167, Section 8.17
Cyclic data update watch function	Page 168, Section 8.18
Input response time setting function	Page 174, Section 8.20 (3)
Number of ON times integration function*1	CC-Link IE Field Network Remote I/O Module User's Manual

*1 The function cannot be used with the cam switch function.

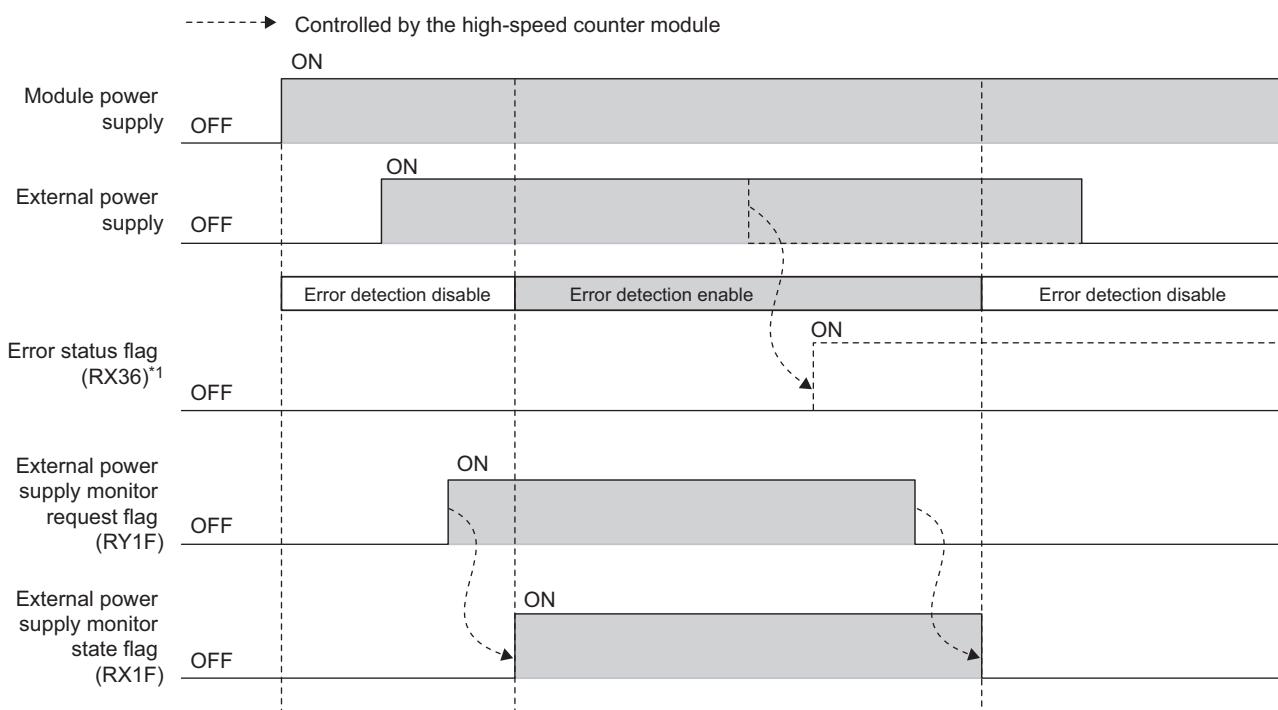
(2) External power supply monitoring function

Using this function, the high-speed counter module monitors the ON/OFF status of the external power supply and indicates it with the I/O PW LED on the extension output module.

By using External power supply monitor request flag (RY1F), a moderate error is generated when the external power supply is off. Thus, the ON/OFF status of the external power supply is notified and the extension output module can be stopped.

(a) External power supply monitoring function

When the external power supply is turned off with External power supply monitor request flag (RY1F) on, a moderate error occurs. When using this function, check that the external power supply stabilizes before turning on External power supply monitor request flag (RY1F). When turning off the external power supply, turn off External power supply monitor request flag (RY1F) in advance.



*1 Errors which occur in the extension I/O module are displayed in the error area of CH1 of the high-speed counter module.

(b) Setting and checking the external power supply monitoring function

Item	Description	Reference
External power supply monitor request flag (RY1F)	Set whether to enable or disable the external power supply monitoring function.	Page 249, Appendix 1.2
External power supply monitor state flag (RX1F)	Indicates whether the external power supply monitoring function is enabled or disabled.	Page 236, Appendix 1.1

(3) Input response time setting function

This function prevents an incorrect input due to noise by setting the response time until the extension input module recognizes an actual input as the X signal.

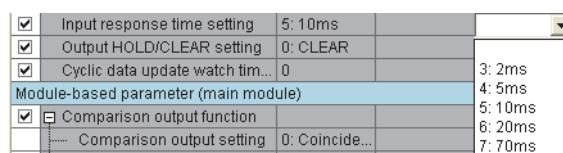
The input response time can be set from the module parameter setting window of GX Works2 or the program.

(a) Setting method

1. Set "Parameter write" for "Method selection".

 "CC IE Field Configuration" window \Rightarrow Select a high-speed counter module in "List of stations" \Rightarrow [CC IE Field Configuration] \Rightarrow [Parameter Processing of Slave Station]

2. For "Input response time setting", select the appropriate input response time.



Item	Setting range
Input response time setting	<ul style="list-style-type: none">• 3: 2ms• 4: 5ms• 5: 10ms• 6: 20ms• 7: 70ms

Point

The extension input module may take in noise as an input depending on the input response time setting. The pulse width which is taken in as an input varies depending on the response time set in parameters.

To set the input response time, consider fully the operating environment.

The following table shows the minimum values of the pulse widths which may be taken in as an input. The pulse widths lower than the values shown below can be filtered as noise.

Value of input response time setting	2ms	5ms	10ms	20ms	70ms
Minimum values of the pulse widths which may be taken in as an input (the maximum pulse widths which can be filtered as noise)	0.15ms	2ms	4ms	9ms	36ms

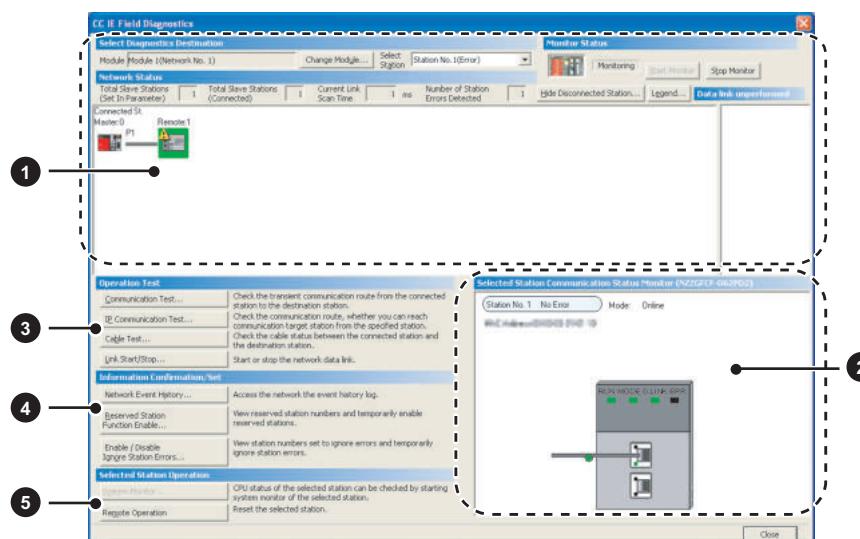
8.21 CC-Link IE Field Network Diagnostic Function

With this function, whether any network error occurs or not can be checked through GX Works2 connected to the CPU module.

(1) How to use

1. Connect GX Works2 to the CPU module.
2. Start CC-Link IE Field Network diagnostics from the menu of GX Works2.

→ [Diagnostics] ⇒ [CC IE Field Diagnostics]



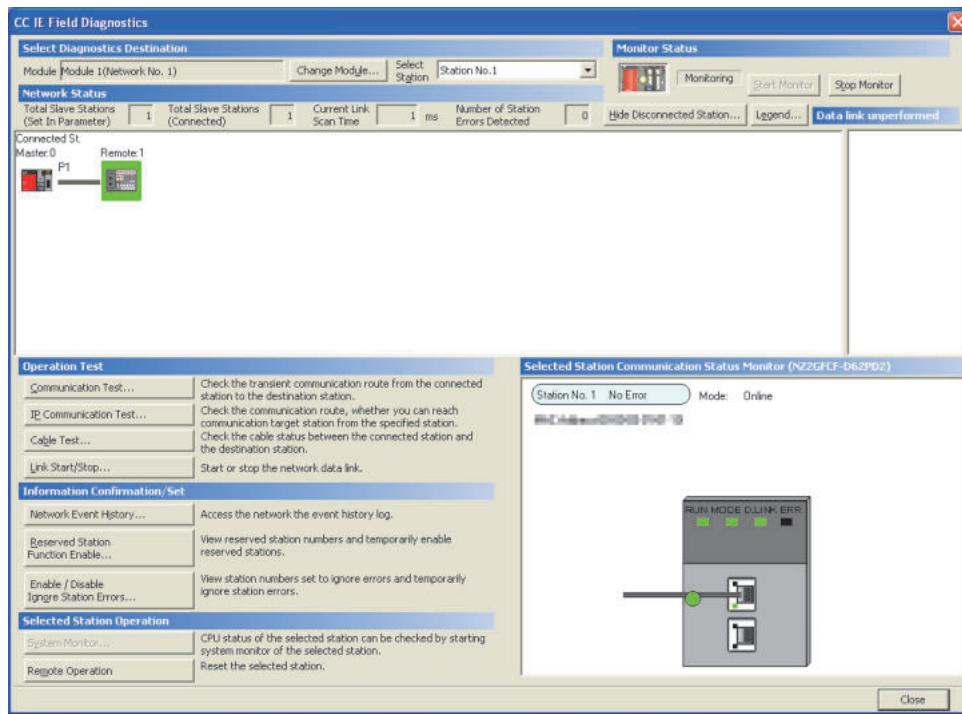
Item to be diagnosed	Description	Reference
① Display of network configuration diagram and error status	The status of the CC-Link IE Field Network can be checked. When an error or warning for the high-speed counter module occurs, an icon appears.	
② Display of selected-station status and error details	The communication status of the station selected in "Networks Status" can be checked.*1	
③ Communication Test IP Communication Test Cable Test Link Start/Stop	Communication Test The transient communication route and whether the communication is established from the connected station to the destination station can be checked.	User's manual for the master/local module used
	IP Communication Test The reaching time and the route of the IP communication from the connected station to the target station can be checked. This function is unavailable for the high-speed counter module.	
	Cable Test The cable status between the connected station and the destination station can be checked.	
	Link Start/Stop The network data link can be started and stopped.	
④ Network Event History Reserved Station Function Enable Enable/Disable Ignore Station Errors	Network Event History The history of various events that occurred in the network can be checked.	
	Reserved Station Function Enable A reservation for a station can be temporarily cancelled, and the cancellation can be disabled. Also, the station numbers for the modules set as reserved stations can be checked on a list.	
	Enable/Disable Ignore Station Errors A station not set as an error invalid station can be temporarily set as an error invalid station, and the error invalid station setting can be disabled. Also, the station numbers for the modules set as (temporarily) error ignore stations can be checked on a list.	
⑤ System Monitor Remote Operation	System Monitor The system monitor on the selected station is activated and the status of the module can be checked. This function is unavailable for the high-speed counter module.	Page 177, Section 8.21 (1) (a)
	Remote Operation The selected station can be reset through the remote operation.	

*1 "Selected Station Communication Status Monitor", which appears at the bottom right in the window, indicates the communication status of the high-speed counter module. For the error and warning for the high-speed counter module, refer to the following.

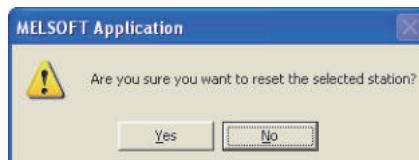
- Checking for The Error Codes and the Warning Codes (☞ Page 205, Section 11.1)

(a) Remote operation

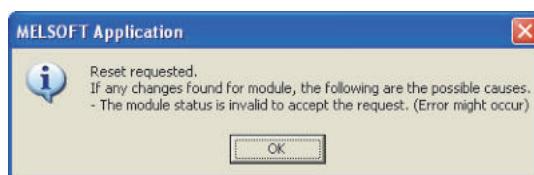
1. Select a slave station to be reset and click the **Remote Operation** button.



2. Clicking the **Yes** button on the following window starts the remote reset.



3. Click the **OK** button on the following window.



CHAPTER 9 PROGRAMMING

This chapter describes the basic programs of the high-speed counter module.

9.1 Precautions for Programming

This section describes precautions to create CC-Link IE Field Network programs.

(1) Cyclic transmission program

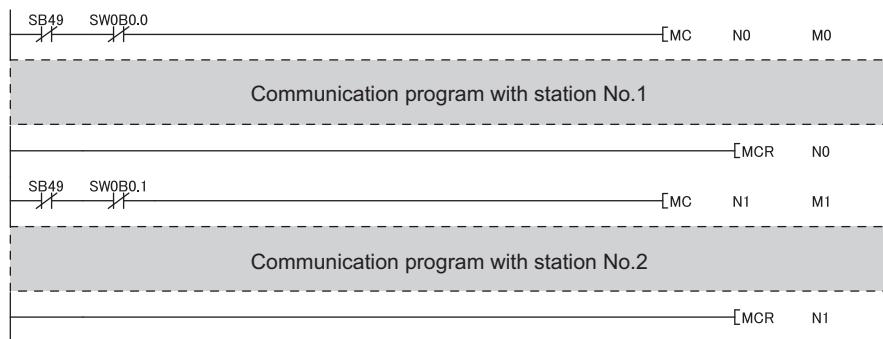
For a cyclic transmission program, interlock with the following link special relay (SB) and link special register (SW).

- Own station data link status (master station) (SB0049)
- Data link status (each station) (SW00B0 to SW00B7)

For the link special relay (SB) and link special register (SW), refer to the following.

 User's manual for the master/local module used

Ex. Interlock example



(2) Transient transmission program

For a transient transmission program, interlock with the following link special relay (SB) and link special register (SW).

- Own station baton pass status (master station) (SB0047)
- Baton pass status (each station) (SW00A0 to SW00A7)

For the link special relay (SB) and link special register (SW), refer to the following.

 User's manual for the master/local module used

Ex. Interlock example



(3) Initial data processing request flag (RX8) program

To operate the high-speed counter module, the initial processing is required.

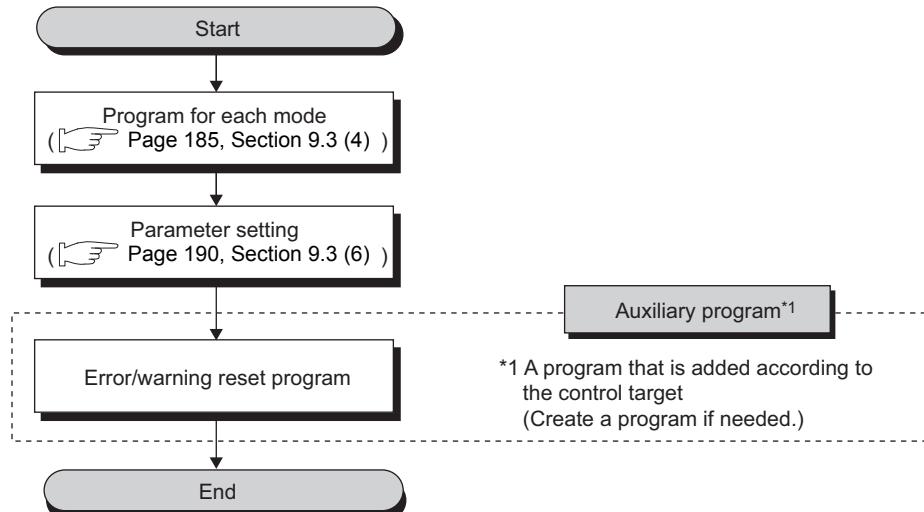
Since the high-speed counter module does not operate until the initial processing is completed after the module is powered on, always check that Remote READY (RXB) is on after the initial processing is performed.

For Initial data processing request flag (RX8) program, refer to the following.

 Page 181, Section 9.3

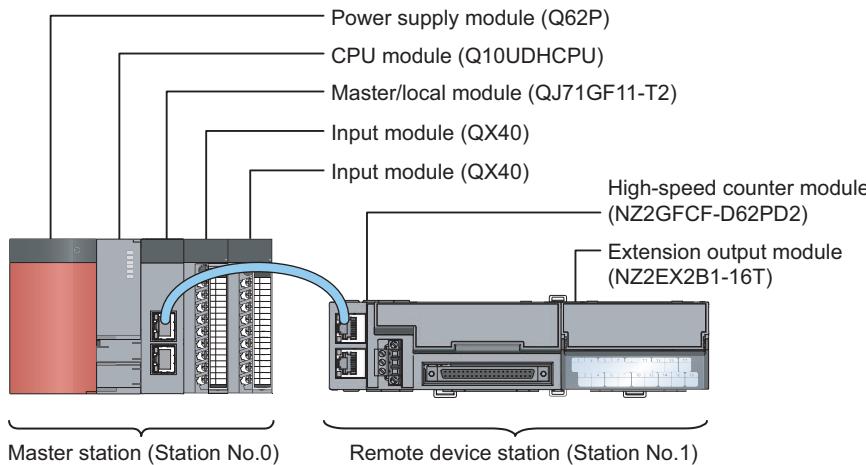
9.2 Procedure for Programming

Create a program to count the pulses, according to the following procedure.

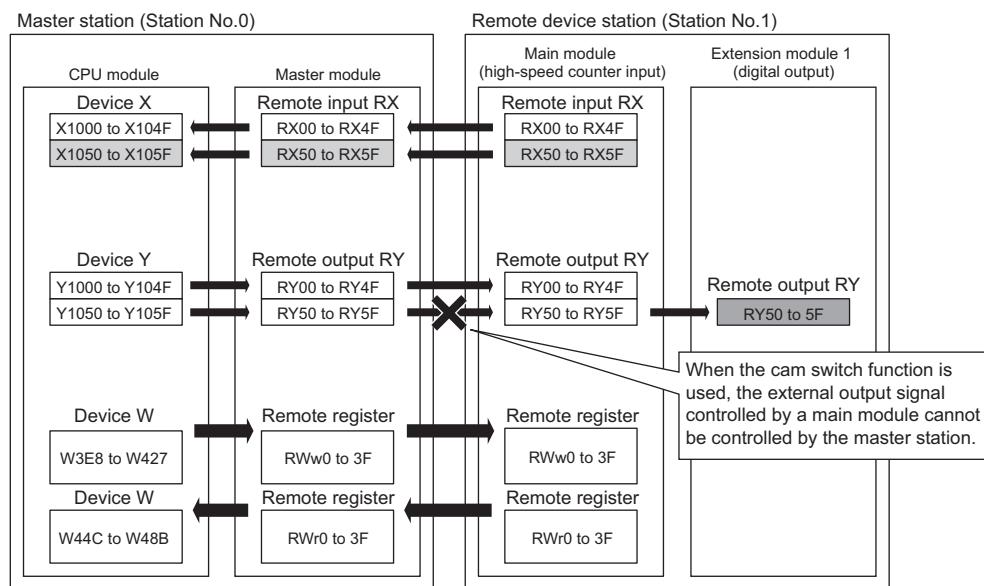


9.3 Program Example

(1) System configuration



(a) Link device assignment



(2) Program condition

This program uses Coincidence output 1 and Coincidence output 2 of CH1 in the high-speed counter module.

The extension output module is used for outputting digital output signals and cam switch output signals.

(3) Initial setting description

(a) Remote buffer memory (parameter area) setting

Setting item	Setting value
Input response time setting	5: 10ms (Initial value)
Output HOLD/CLEAR setting	1: HOLD
Cyclic data update watch time setting	10 (× 100ms)
Comparison output setting	Set a value according to the comparison output function to be used.
Coincidence output 1 channel assignment setting	0: CH1 (Initial value)
Coincidence output 2 channel assignment setting	0: CH1 (Initial value)
Coincidence output 3 channel assignment setting	1: CH2
Coincidence output 4 channel assignment setting	1: CH2
Coincidence output 1 comparison condition setting	0: Coincidence Output (Initial value)
Coincidence output 2 comparison condition setting	1: Within-range Output
Coincidence output 3 comparison condition setting	0: Coincidence Output (Initial value)
Coincidence output 4 comparison condition setting	0: Coincidence Output (Initial value)
Preset/replace setting at coincidence output (Coincidence output 1)	0: Present value not replaced (Initial value)
Preset/replace setting at coincidence output (Coincidence output 2)	0: Present value not replaced (Initial value)
Cam switch output unit assignment setting	1: Stage 1
Cam switch output 1 channel assignment setting	0: CH1 (Initial value)
Cam switch output 2 channel assignment setting	0: CH1 (Initial value)
Cam switch output 3 channel assignment setting	0: CH1 (Initial value)
Cam switch output 4 channel assignment setting	0: CH1 (Initial value)
Cam switch output 5 channel assignment setting	0: CH1 (Initial value)
Cam switch output 6 channel assignment setting	0: CH1 (Initial value)
Cam switch output 7 channel assignment setting	0: CH1 (Initial value)
Cam switch output 8 channel assignment setting	0: CH1 (Initial value)
Cam switch output 9 channel assignment setting	1: CH2
Cam switch output 10 channel assignment setting	1: CH2
Cam switch output 11 channel assignment setting	1: CH2
Cam switch output 12 channel assignment setting	1: CH2
Cam switch output 13 channel assignment setting	1: CH2
Cam switch output 14 channel assignment setting	1: CH2
Cam switch output 15 channel assignment setting	1: CH2
Cam switch output 16 channel assignment setting	1: CH2
CH1 Operation mode setting	Set a value according to the operation mode to be used.
CH1 Count source selection	0: A Phase/B Phase (Initial value)
CH1 Pulse input mode	3: 2-Phase Multiple of 1
CH1 Counting speed setting	2: 200kpps
CH1 Counter format	Set a value according to the counter format to be used.
CH1 Z phase (Preset) trigger setting	0: Rising (Initial value)

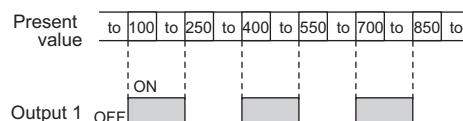
Setting item	Setting value
CH1 External preset/replace (Z Phase) request detection setting	0: ON at detection (Initial value)
CH1 Counter function selection	Set a value according to the counter function to be used.
CH1 Function input logic setting	0: Positive Logic (Initial value)
CH1 Latch counter input logic setting	0: Positive Logic (Initial value)
CH1 Z phase input response time setting	Set any response time.
CH1 Function input response time setting	Set any response time.
CH1 Latch counter input response time setting	Set any response time.
CH1 Pulse measurement setting (Function input terminal)	0: Pulse ON Width (Initial value)
CH1 Pulse measurement setting (Latch counter input terminal)	1: Pulse OFF Width

Set the initial values for the parameters in CH2 and the extension output module.

(b) Extended parameter (remote buffer memory) setting

Set the extended parameter (remote buffer memory) only when using the cam switch function.

Set it to operate Cam switch output 1 for CH1 Present value as shown below.



Setting item	Setting details
Cam switch function, step type (Output 1)	0: Starts with output status being OFF
Cam switch function, number of steps (Output 1)	6
Cam switch function, step No.1 setting (Output 1)	100
Cam switch function, step No.2 setting (Output 1)	250
Cam switch function, step No.3 setting (Output 1)	400
Cam switch function, step No.4 setting (Output 1)	550
Cam switch function, step No.5 setting (Output 1)	700
Cam switch function, step No.6 setting (Output 1)	850

Point

- The setting value in the item related to the cam switch function is enabled when CH□ Cam switch execute command (RY26, RY3E) is turned off then on. However, the extended parameter is set before turning on then off Initial data setting request flag (RY9) to save the extended parameter to the nonvolatile memory in this program.
- The extended parameters can be read/written only by the REMFR/REMTO instruction unlike the parameters.

(c) Remote register setting

Setting item	Setting details (setting value)
Point setting (Coincidence output 1) (RWw0 to RWw1)*1	1000
Lower limit value setting (Coincidence output 2) (RWw4 to RWw5)*1	1000
Upper limit value setting (Coincidence output 2) (RWw6 to RWw7)*1	2000
CH1 Ring counter lower limit value (RWw10 to RWw11)*2	-5000
CH1 Ring counter upper limit value (RWw12 to RWw13)*2	5000
CH1 Preset value setting (RWw14 to RWw15)	100
CH1 Time unit setting (Sampling counter/Periodic pulse counter) (RWw16)*3	1ms(0)
CH1 Cycle setting (Sampling counter/Periodic pulse counter) (RWw17)*3	2000ms(2000)
CH1 Frequency measurement*4	—
CH1 Time unit setting (Frequency measurement) (RWw18)	0.01s(0)
CH1 Moving average count (Frequency measurement) (RWw19)	3
CH1 Rotation speed measurement*5	—
CH1 Time unit setting (Rotation speed measurement) (RWw18)	0.01s(0)
CH1 Moving average count (Rotation speed measurement) (RWw19)	3
CH1 Number of pulses per rotation (RWw1A to RWw1B)	1000
CH1 PWM output*6	—
CH1 PWM output assignment setting (RWw1D)	Output to Coincidence output 1 (0001 _H)
CH1 ON width setting (PWM output) (RWw1E to RWw1F)	100.0us(1000)
CH1 Cycle setting (PWM output) (RWw20 to RWw21)	200.0us(2000)

*1 Set only when using the coincidence output function.

*2 Set only when using the ring counter function.

*3 Set only when using the sampling counter function or the periodic pulse counter function.

*4 Set only under the frequency measurement mode.

*5 Set only under the rotation speed measurement mode.

*6 Set only under the PWM output mode.

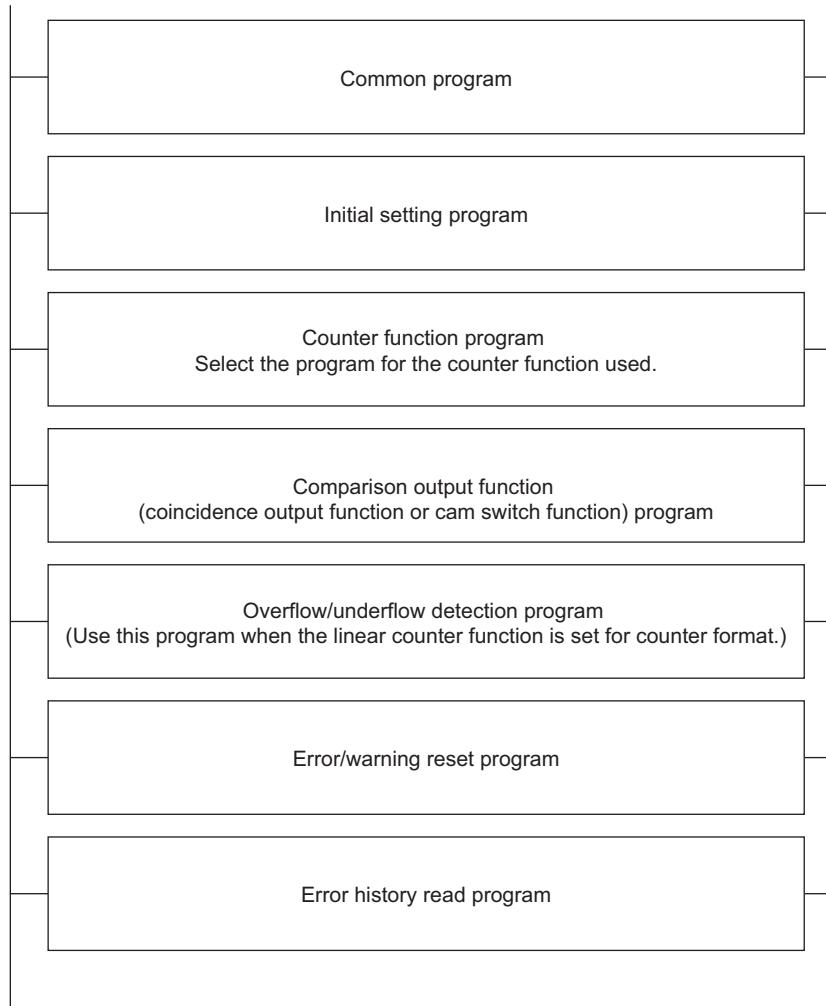
Point

If Initial data processing request flag (RX8) turns on when the module is powered on, always set the remote register.

(4) Configuration of program examples

The following figure shows a configuration of a program example.

(a) Program configuration under the normal mode



(b) Program configuration under a mode other than the normal mode

Program examples under a mode other than the normal mode operate in a single-program example.

(c) Error/warning reset program and error history read program

If an error or warning processing is required for a program example under a mode other than the normal mode, add the error/warning reset program and error history read program of the normal mode before the MCR instruction of each program.

(5) Device for user

Device	Description	
X20	Count start signal	QX40 (X20 to X2F)
X21	Present value read signal	
X22	Coincidence output data setting signal	
X23	Preset/replace command signal	
X24	Count stop signal	
X25	Coincidence output clear signal	
X26	Counter function start signal	
X27	Counter function stop signal	
X28	Latch count data read signal	
X29	Latch counter start signal	
X2A	Sampling count data read signal	
X2B	Sampling count start signal	
X2C	Periodic pulse count data read signal	
X2D	Periodic pulse count start signal	
X30	Latch count value (Latch counter input terminal) read signal	
X31	Cam switch start signal	
X32	Frequency measurement start signal	
X33	Frequency measurement stop signal	
X34	Rotation speed measurement start signal	QX40 (X30 to X3F)
X35	Rotation speed measurement stop signal	
X36	Pulse measurement (Function input terminal) start signal	
X37	Pulse measurement (Latch counter input terminal) start signal	
X38	Pulse measurement (Function input terminal) stop signal	
X39	Pulse measurement (Latch counter input terminal) stop signal	
X3A	PWM output start signal	
X3B	PWM output stop signal	
X3C	Error/warning reset start signal	
X3D	Error history read start signal	

Device	Description
X1007	Warning status flag
X1008	Initial data processing request flag
X1009	Initial data setting completion flag
X100A	Error status flag
X100B	Remote READY
X1010	Coincidence output 1
X1011	Coincidence output 2
X1012	Coincidence output 3
X1013	Coincidence output 4
X1014	Setting change completed (Coincidence output 1)
X1015	Setting change completed (Coincidence output 2)
X1016	Setting change completed (Coincidence output 3)
X1017	Setting change completed (Coincidence output 4)
X101F	External power supply monitor state flag (for extension output module)
X1021	CH1 Preset/replace completion
X1023	CH1 External preset/replace (Z Phase) request detection
X1025	CH1 Counter function detection
X1026	CH1 Cam switch execute/PWM output
X1027	CH1 Setting change completed (Sampling counter/Periodic pulse counter)
X1028	CH1 Update flag reset completed (Latch count value/Sampling count value/Periodic pulse count value)
X1029	CH1 Update flag (Latch count value/Sampling count value/Periodic pulse count value)
X102A	CH1 Latch count value update flag reset completed (Latch counter input terminal)
X102B	CH1 Latch count value update flag (Latch counter input terminal)
X102C	CH1 Update flag reset completed (Measured frequency value/Measured rotation speed value)
X102D	CH1 Update flag (Measured frequency value/Measured rotation speed value)
X1031	CH1 Measured pulse value update flag reset completed (Function input terminal)
X1032	CH1 Measured pulse value update flag (Function input terminal)
X1033	CH1 Measured pulse value update flag reset completed (Latch counter input terminal)
X1034	CH1 Measured pulse value update flag (Latch counter input terminal)
X1035	CH1 ON width setting change completed (PWM output)
X1036	CH1 Error status
X1037	CH1 Warning status

Device	Description	
Y1008	Initial data processing completion flag	NZ2GFCF-D62PD2 (Y1000 to Y104F)
Y1009	Initial data setting request flag	
Y1010	Reset command (Coincidence output 1)	
Y1011	Reset command (Coincidence output 2)	
Y1012	Reset command (Coincidence output 3)	
Y1013	Reset command (Coincidence output 4)	
Y1014	Setting change request (Coincidence output 1)	
Y1015	Setting change request (Coincidence output 2)	
Y1016	Setting change request (Coincidence output 3)	
Y1017	Setting change request (Coincidence output 4)	
Y101F	External power supply monitor request flag (for extension output module)	
Y1020	CH1 Coincidence output enable command	
Y1021	CH1 Preset/replace command	
Y1022	CH1 Count down command	
Y1023	CH1 External preset/replace (Z Phase) request detection reset command	
Y1024	CH1 Count enable command	
Y1025	CH1 Selected counter function start command	
Y1026	CH1 Cam switch execute command/PWM output start command	
Y1027	CH1 Setting change request (Sampling counter/Periodic pulse counter)	
Y1028	CH1 Update flag reset command (Latch count value/Sampling count value/Periodic pulse count value)	
Y102A	CH1 Latch count value update flag reset command (Latch counter input terminal)	
Y102C	CH1 Update flag reset command (Measured frequency value/Measured rotation speed value)	
Y1030	CH1 Pulse measurement start command (Function input terminal)	
Y1031	CH1 Measured pulse value update flag reset command (Function input terminal)	
Y1032	CH1 Pulse measurement start command (Latch counter input terminal)	
Y1033	CH1 Measured pulse value update flag reset command (Latch counter input terminal)	
Y1035	CH1 ON width setting change request (PWM output)	
Y1036	CH1 Error reset command	
Y1050	LED signal for checking the coincidence output 1	NZ2EX2B1-16T (Y1050 to Y105F)
Y1051	LED signal for checking the coincidence output 2	
Y1052	LED signal for checking underflow occurrence	
Y1053	LED signal for checking overflow occurrence	
Y1054	LED signal for checking that PWM output is in process	
D1100	Counter value greater/smaller signal	
D1116 to D1117	CH1 Present value	
D1118 to D1119	CH1 Latch count value/Sampling count value/Periodic pulse count, difference value	
D1120 to D1121	CH1 Periodic pulse count, present value	
D1122 to D1123	CH1 Periodic pulse count value update check	
D1124 to D1125	CH1 Latch count value (Latch counter input terminal)	
D1126 to D1127	CH1 Measured frequency value/Measured rotation speed value	

Device	Description
D1128 to D1129	CH1 Measured pulse value (Function input terminal)
D1130 to D1131	CH1 Measured pulse value (Latch counter input terminal)
D1132	CH1 Status
D1134*1	CH1 Latest error code
D1135*2	CH1 Latest warning code
D3000 to D3239	Error history 1 to 15
D3300	Cam switch function, step type (Output 1)
D3301	Cam switch function, number of steps (Output 1)
D3302 to D3303	Cam switch function, step No.1 setting (Output 1)
D3304 to D3305	Cam switch function, step No.2 setting (Output 1)
D3306 to D3307	Cam switch function, step No.3 setting (Output 1)
D3308 to D3309	Cam switch function, step No.4 setting (Output 1)
D3310 to D3311	Cam switch function, step No.5 setting (Output 1)
D3312 to D3313	Cam switch function, step No.6 setting (Output 1)
M0	Communication ready flag (station No.1)
M10	Initial setting completion
M100	Parameter initial setting start
M101	Parameter initial setting completion
M102	Remote register initial setting start
M110	REMTO instruction completion flag
M111	REMTO instruction error completion flag
M112	Parameter setting normal completion flag
M200	REMFR instruction completion flag
M201	REMFR instruction error completion flag
M202	Error history read normal completion flag
SB0047	Own station baton pass status (master station)
SB0049	Own station data link status (master station)
SW00A0.0	Baton pass status (each station) (station No.1)
SW00B0.0	Data link status (each station) (station No.1)
N0	Nesting (station No.1)

*1 Stores the latest error (major error or moderate error), and holds it also after an error reset.

*2 Stores the latest warning (minor error), and holds it also after an error reset.

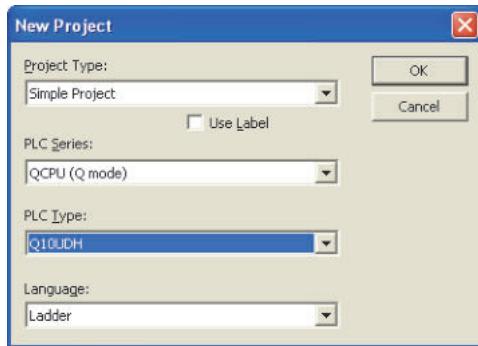
(6) Setting procedure

Connect GX Works2 to the master station to configure the setting.

1. Create a project on GX Works2.

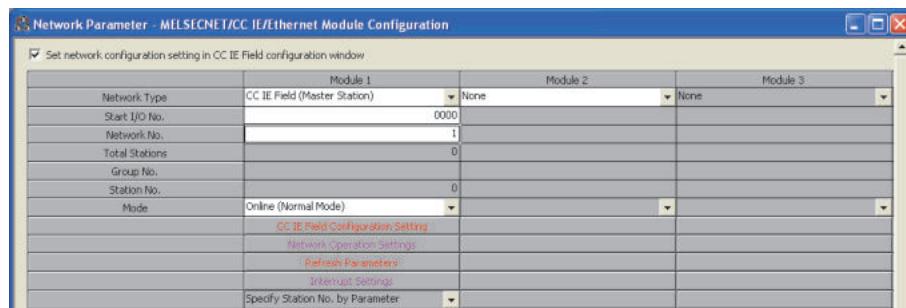
Select "QCPU (Q mode)" for "PLC Series" and select "Q10UDH" for "PLC Type".

☛ [Project] ⇒ [New]



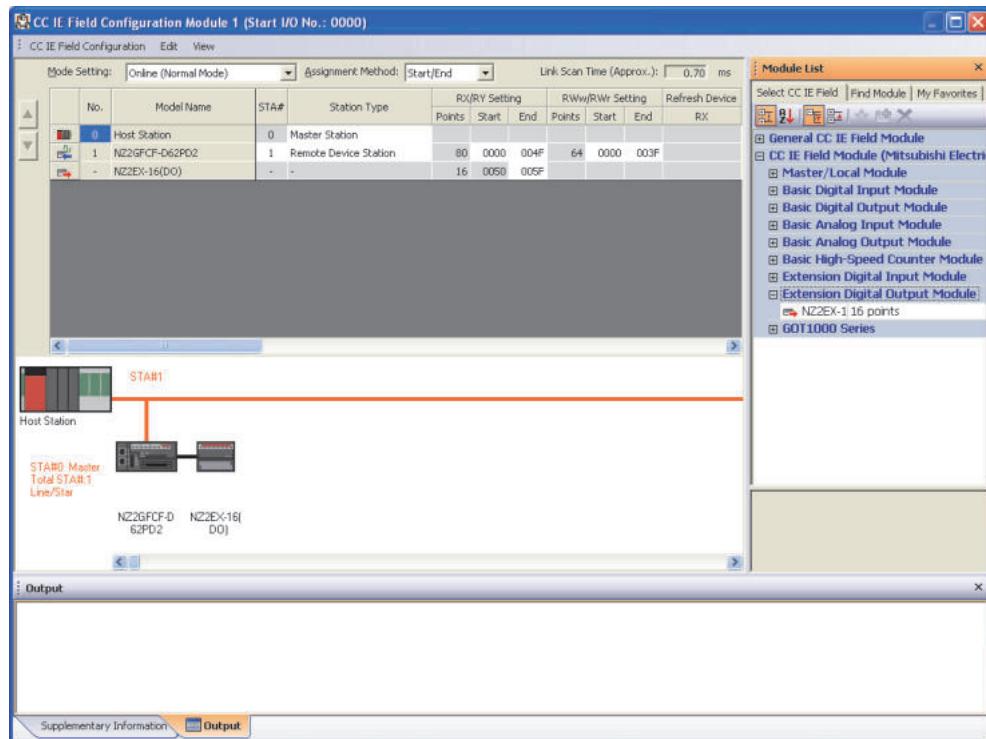
2. Display the network parameter setting window and configure the setting as follows.

☛ Project window ⇒ [Parameter] ⇒ [Network Parameter] ⇒ [Ethernet/CC IE/MELSECNET]



3. Display the "CC IE Field Configuration" window and configure the configuration and station number of the slave station as follows.

→ [CC IE Field Configuration Setting] button

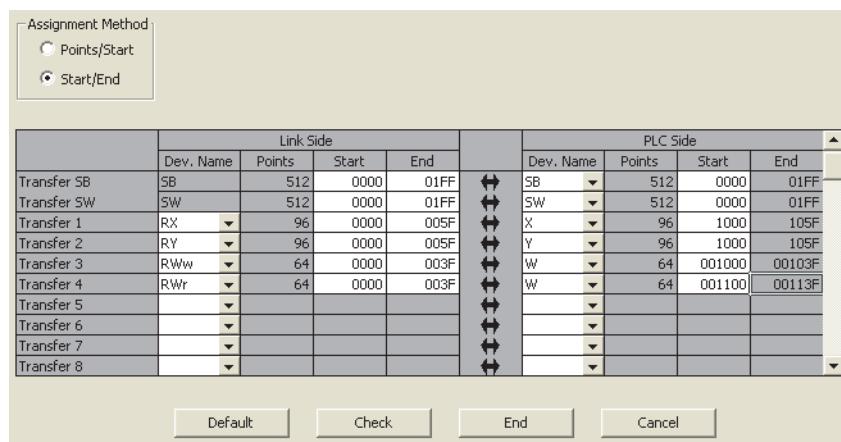


4. Close the "CC IE Field Configuration" window.

→ [CC IE Field Configuration] → [Close with Reflecting the Setting]

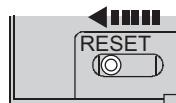
5. Display the refresh parameter setting window and configure the setting as follows.

→ [Refresh Parameters] button



6. Write the set parameter to the CPU module of the master station and reset the CPU module, or turn off then on the power supply.

→ [Online] → [Write to PLC...]

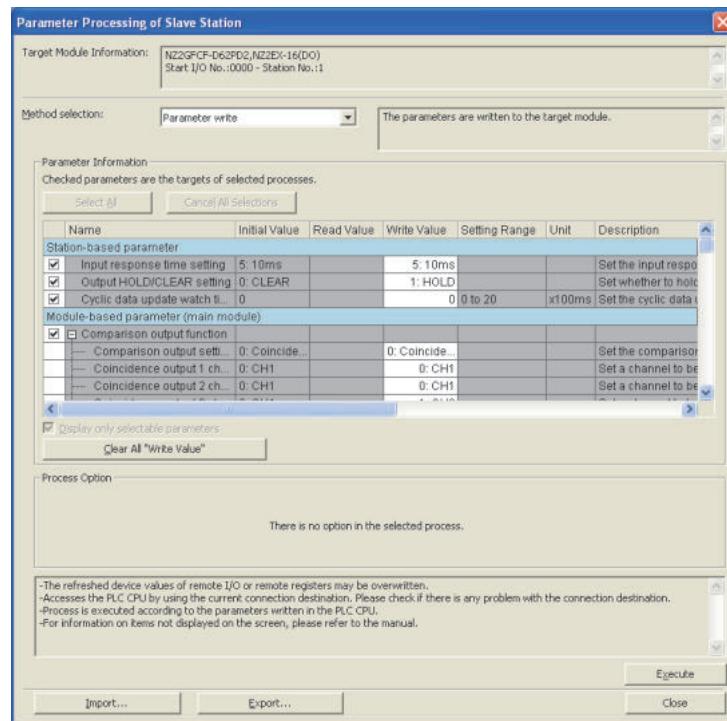


or Power OFF → ON

7. Display the "Parameter Processing of Slave Station" window and change "Method selection" to "Parameter write" to set the following.

☞ [Ethernet/CC IE/MELSECNET] ⇒ [CC IE Field Configuration Setting] button ⇒

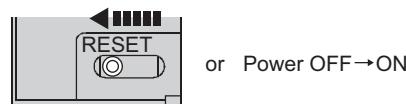
Select a high-speed counter module in "List of stations" ⇒ [CC IE Field Configuration] ⇒ [Parameter Processing of Slave Station]



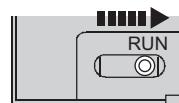
8. Click the button to write the parameter to the high-speed counter module.

(7) Setting method of the program

1. Create a program in Page 193, Section 9.3 (8) to Page 202, Section 9.3 (13) on GX Works2 according to the mode or function to use.
2. Write the program to the CPU module of the master station and reset the CPU module, or turn off then on the power supply.



3. Change the status of the CPU module of the master station to RUN.



(8) Program example under the normal mode (when the coincidence output is set with the comparison output function)

(a) Common program



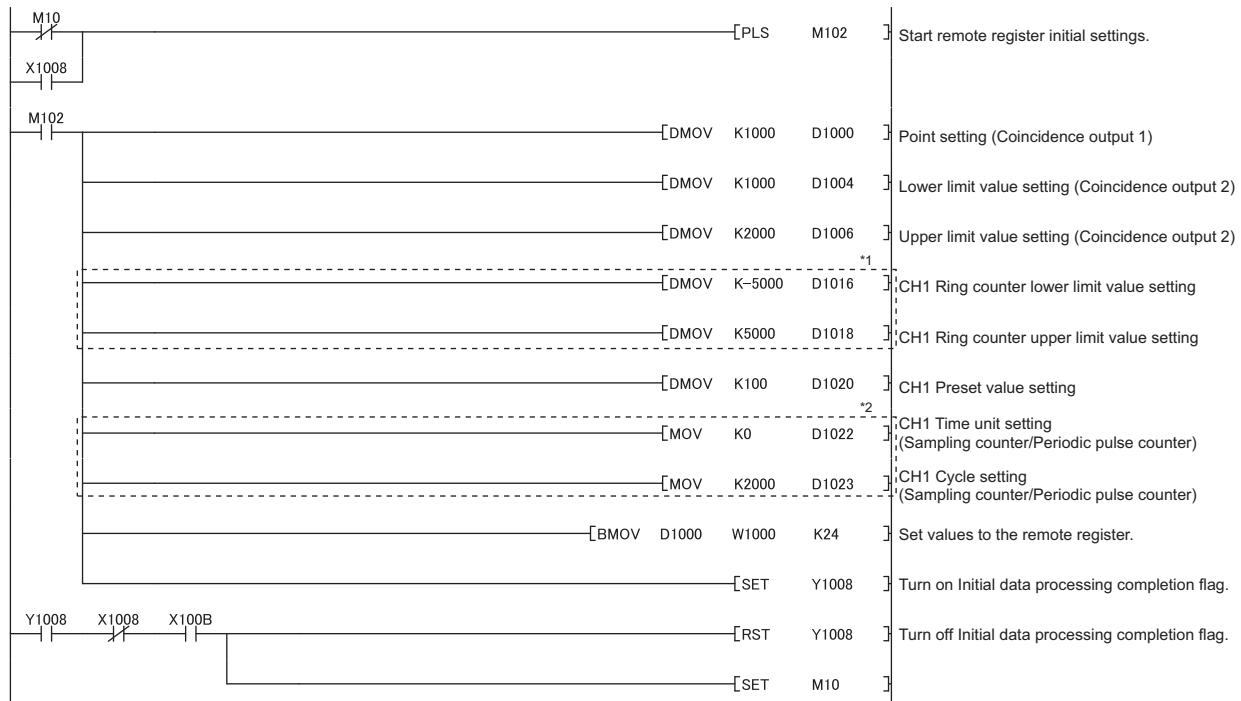
*1 Add the following MCR instruction at the end of the program.



Point

If the master station does not receive a response for several link scans from the high-speed counter module, the high-speed counter module is determined as a cyclic transmission faulty station and the corresponding bit of the data link status (each station) (SW00B0 to SW00B7) turns on.

(b) Initial setting program

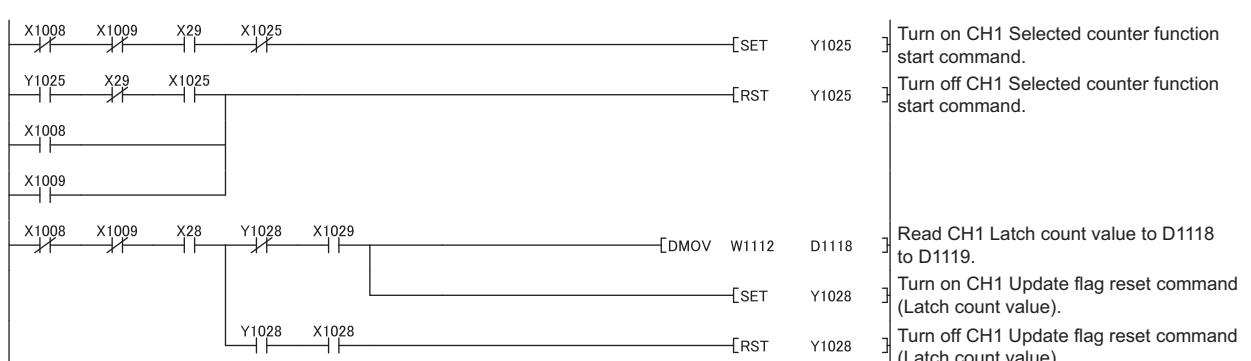
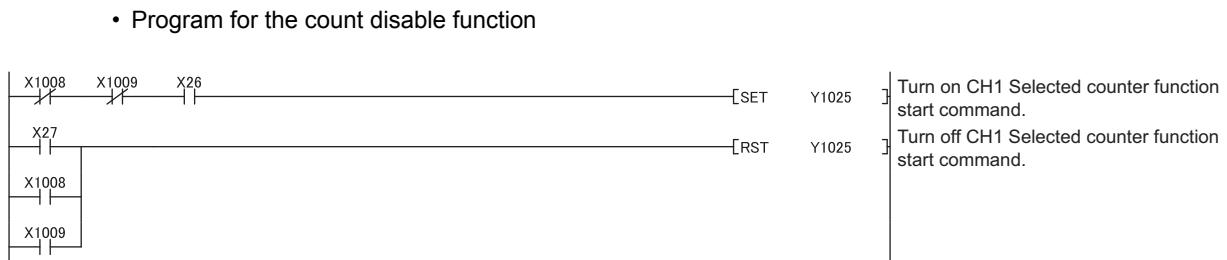
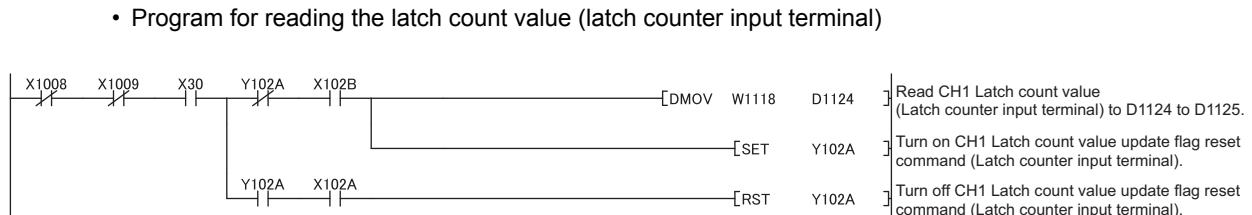
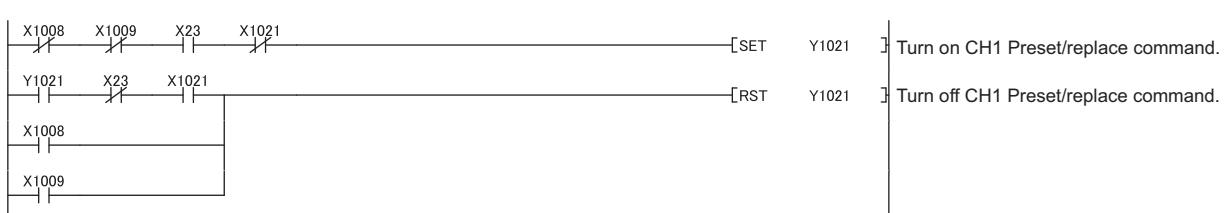
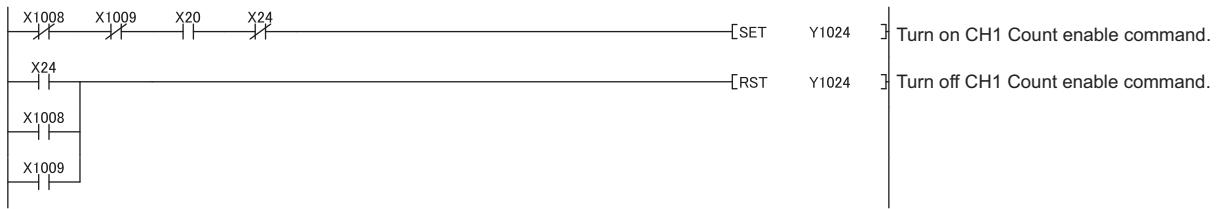


*1 Set only when using the ring counter function.

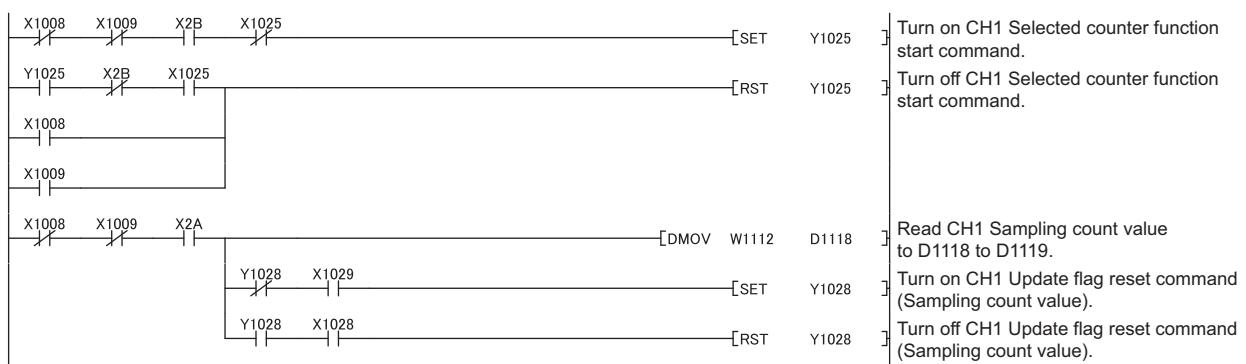
*2 Set only when using the sampling counter function or periodic pulse counter function.

(c) Counter function programs

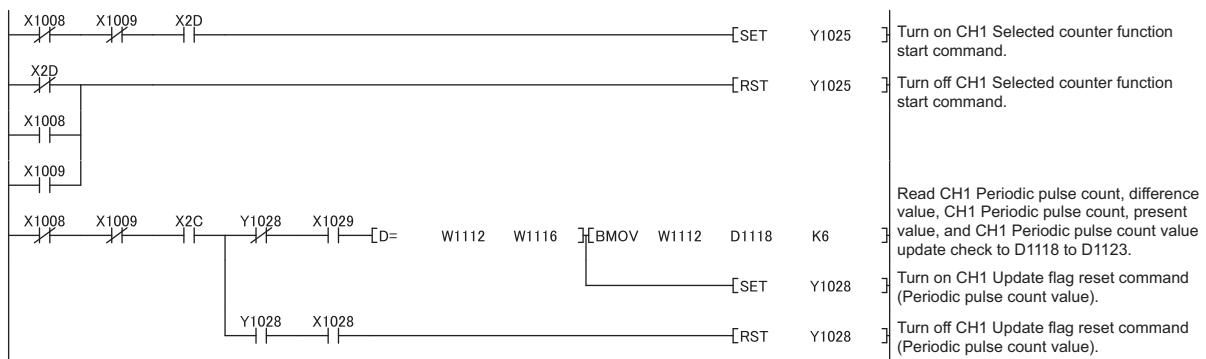
- Program for starting/stopping the counter



- Program for the sampling counter function

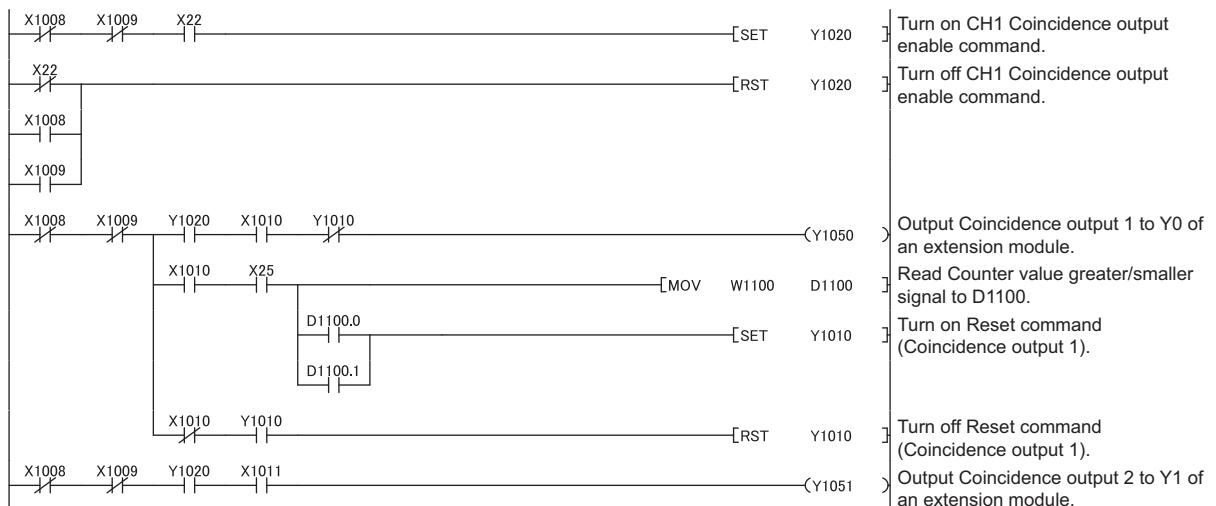


- Program for the periodic pulse counter function

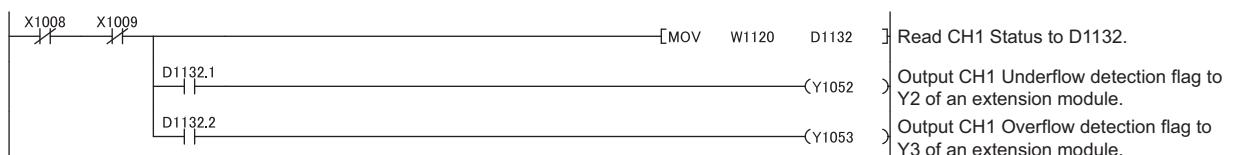


(d) Program for the comparison output function

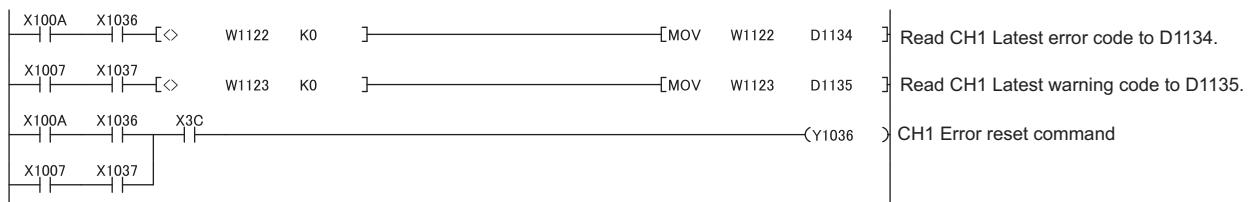
- Program for the coincidence output function



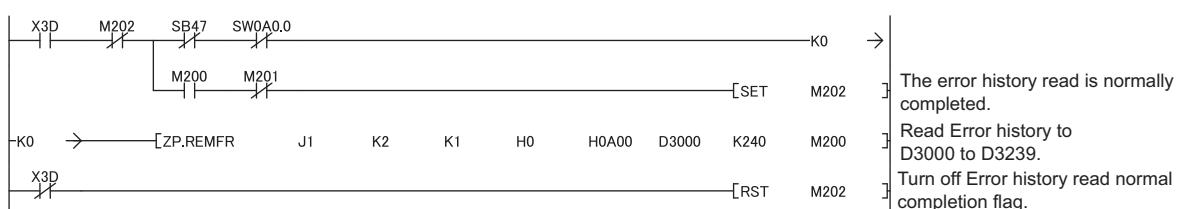
(e) Program for overflow/underflow detection processing



(f) Program for an error/warning reset



(g) Program for reading the error history

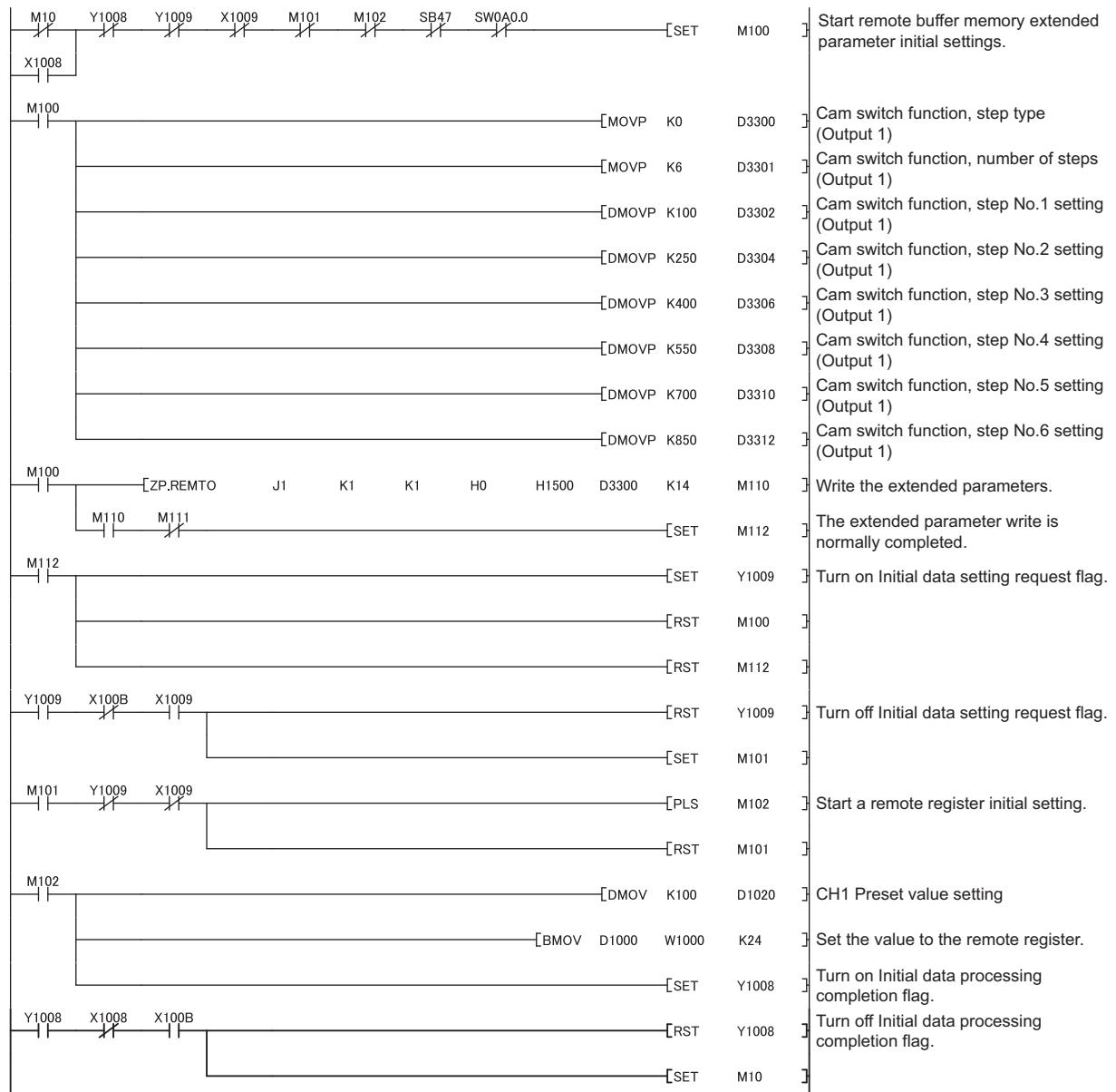


(9) Program example under the normal mode (when the cam switch function is set with the comparison output function)

(a) Common program

The program is the same as the program example of the normal mode. (☞ Page 193, Section 9.3 (8) (a))

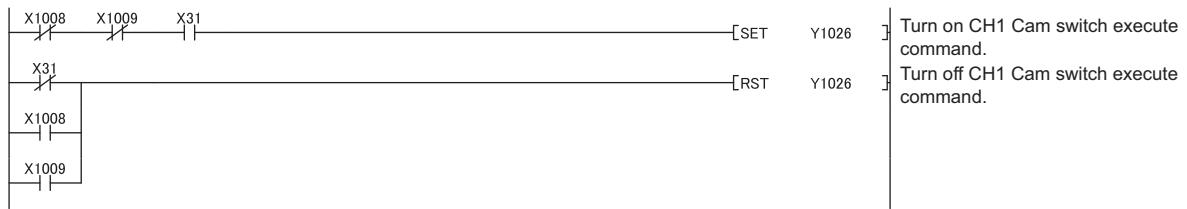
(b) Initial setting program



(c) Counter function programs

The program is the same as the program example of the normal mode. (☞ Page 194, Section 9.3 (8) (c))

(d) Program for the cam switch function



(e) Program for overflow/underflow detection processing

The program is the same as the program example of the normal mode. (☞ Page 196, Section 9.3 (8) (e))

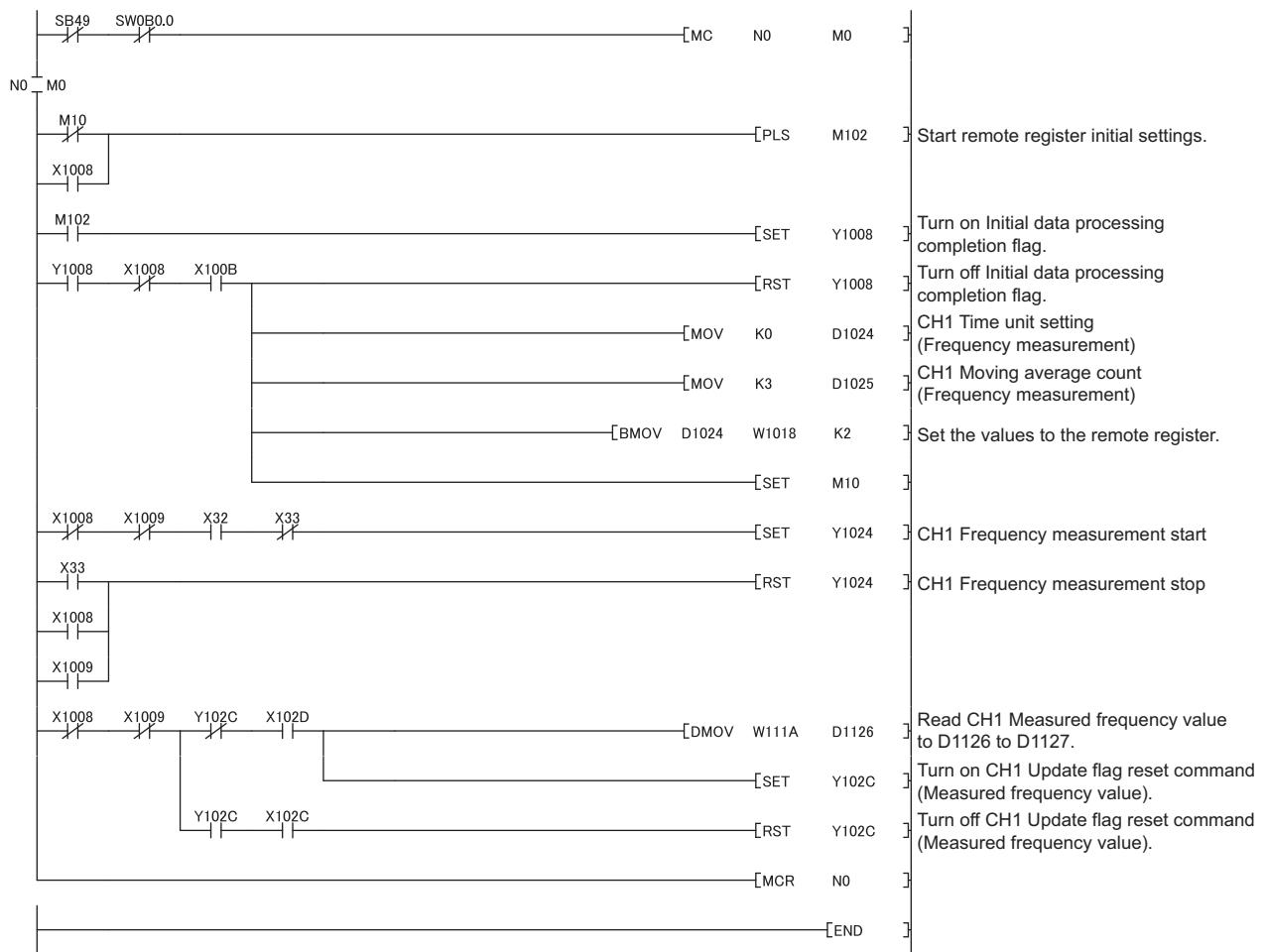
(f) Program for an error/warning reset

The program is the same as the program example of the normal mode. (☞ Page 196, Section 9.3 (8) (f))

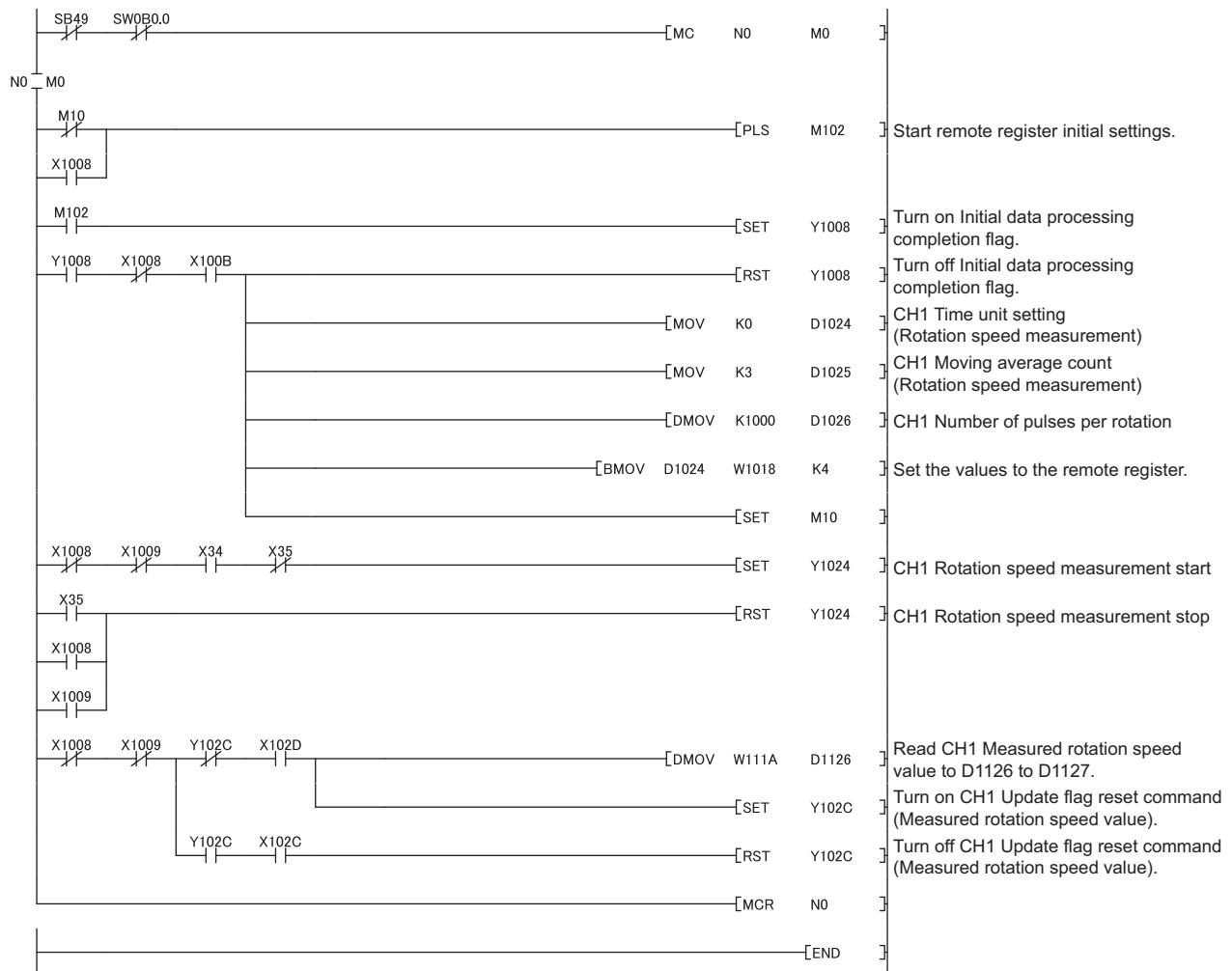
(g) Program for reading the error history

The program is the same as the program example of the normal mode. (☞ Page 196, Section 9.3 (8) (g))

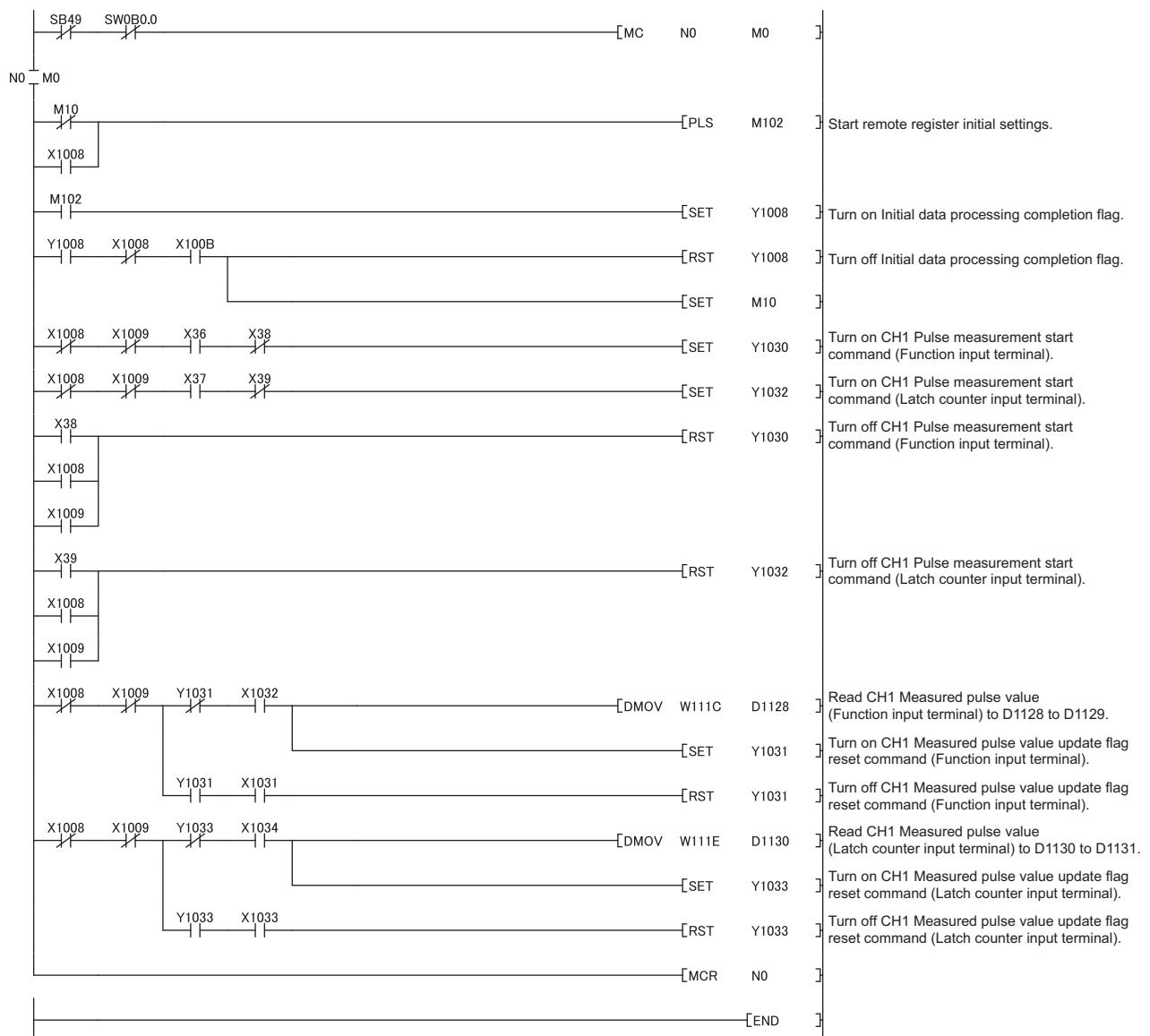
(10) Program example of the frequency measurement mode



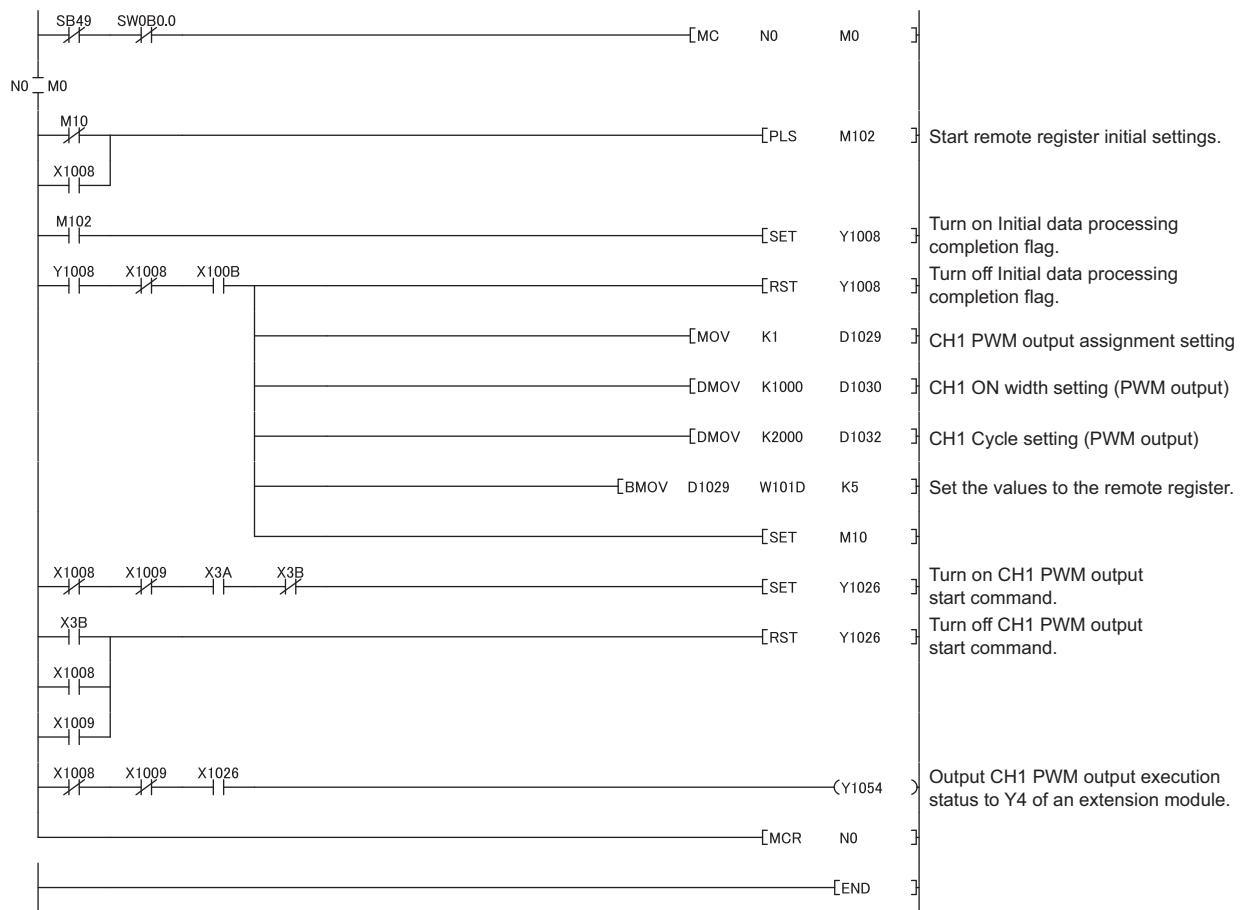
(11) Program example of the rotation speed measurement mode



(12)Program example of the pulse measurement mode



(13)Program example of the PWM output mode



CHAPTER 10 MAINTENANCE AND INSPECTION

The high-speed counter module has no special item to be inspected. However, to maintain the best condition of the system, perform the inspection in accordance with the items described in the user's manual of the CPU module used.

Memo

CHAPTER 11 TROUBLESHOOTING

This chapter describes errors that may occur while the high-speed counter module is used, and those troubleshooting.

11.1 Checking for the Error Codes and the Warning Codes

Error codes can be checked by any of the following methods:

- Checking by executing a command of the slave station (☞ Page 205, Section 11.1 (1))
- Checking by CH□ Latest error code (RW_r22, RW_r3A) (☞ Page 207, Section 11.1 (2))

Warning codes can be checked by any of the following methods:

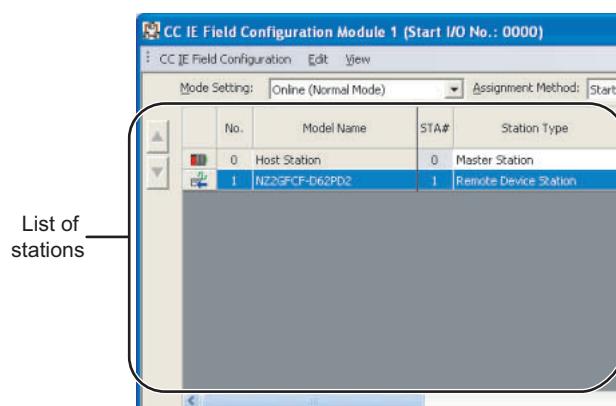
- Checking by executing a command of the slave station (☞ Page 205, Section 11.1 (1))
- Checking by CH□ Latest warning code (RW_r23, RW_r3B) (☞ Page 207, Section 11.1 (3))

Point

- Errors of the high-speed counter module are detected at not only every station, but also every channel.
- Errors detected at a channel are stored in the remote register for the channel.
- Errors independent from channels are station errors stored in CH1 Latest error code (RW_r22) or CH1 Latest warning code (RW_r23).

(1) Checking by executing a command of the slave station

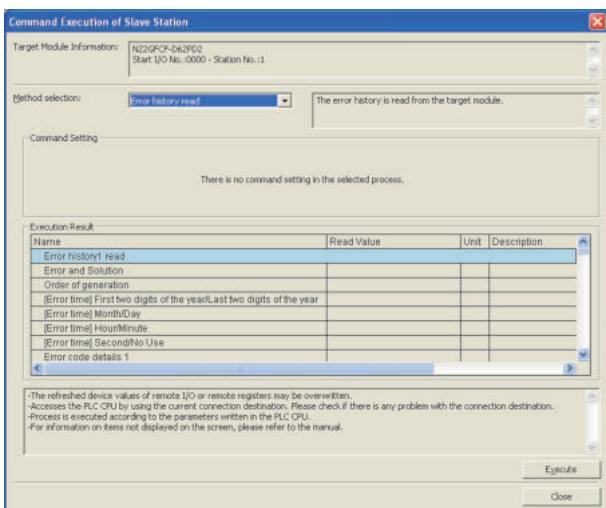
This section describes how to check the errors by executing a command of the slave station.



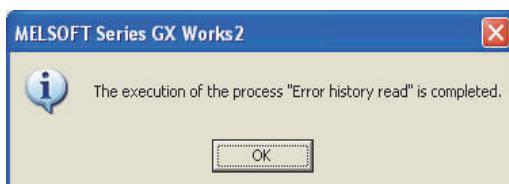
1. Select the high-speed counter module in "List of stations" on the "CC IE Field Configuration" window.

2. Open the "Command Execution of Slave Station" window.

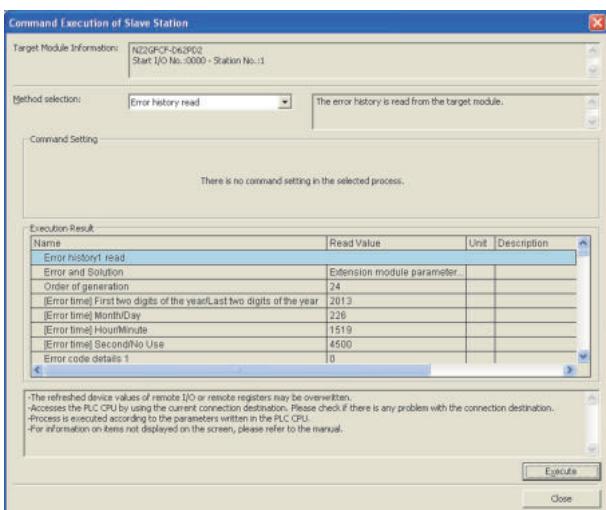
☞ [CC IE Field Configuration] ⇨ [Command Execution of Slave Station]



3. Set "Method selection" to "Error history read" and click the  button.



4. When the window shown on the left is displayed, click the  button.

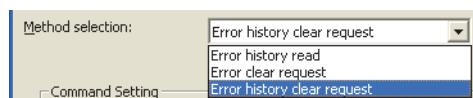


5. The error history of the high-speed counter module is displayed in "Execution Result".

Item	Contents
Error and Solution	The action for the error is displayed.
Order of generation	The order of error occurrence is displayed.
[Error time] First two digits of the year/Last two digits of the year	The date and time of error occurrence is displayed. (When the tens place of Month, Hour and Second is "0", the date and time are displayed without "0".)
[Error time] Month/Day	(When the tens place of Month, Hour and Second is "0", the date and time are displayed without "0".)
[Error time] Hour/Minute	(When the tens place of Month, Hour and Second is "0", the date and time are displayed without "0".)
[Error time] Second/No Use	
Error code details 1 to Error code details 10	The value in the remote register Error code details 1 to 10 of when an error occurs is stored.

Point

- The error history registers 15 errors at a maximum. If 16 or more errors occur, errors are deleted from the oldest.
- If the same error occurs continuously, only the error that occurred first is stored to the error history.
- Even after the power of the module is turned off then on, the error history remains.
- To initialize the error history, set "Method selection" to "Error history clear request" on the "Command Execution of Slave Station" window and click the  button.

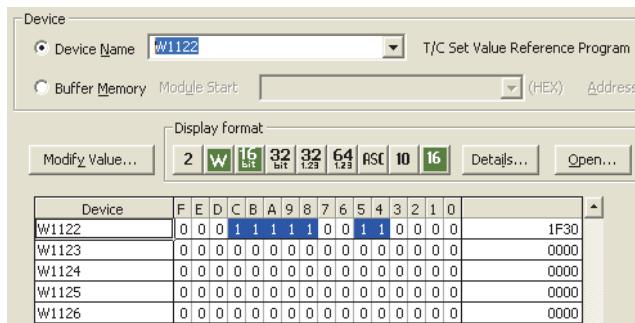


(2) Checking by CH□ Latest error code (RWr22, RWr3A)

Check the latest error code with the remote register of the master/local module.

🔗 [Online] ➔ [Monitor] ➔ [Device/Buffer Memory Batch]

Ex. When the refresh target device for CH1 Latest error code (RWr22) is W1122



The screenshot shows a software interface for monitoring device memory. The 'Device Name' is set to 'W1122'. The 'Display format' is set to '16 bit'. The table below shows the memory map for device W1122, with the 16-bit value at address 0 being 1F30.

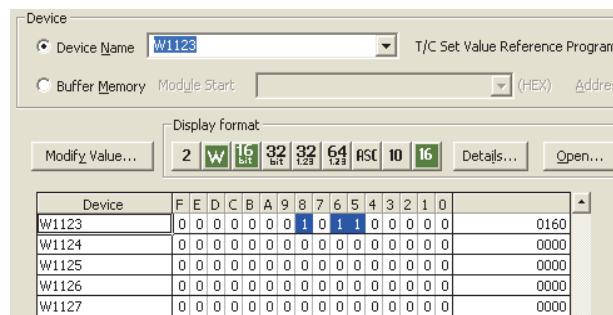
Device	F	E	D	C	B	A	9	8	7	6	5	4	3	2	1	0
W1122	0	0	0	1	1	1	1	0	0	1	1	0	0	0	0	1F30
W1123	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000
W1124	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000
W1125	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000
W1126	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000

(3) Checking by CH□ Latest warning code (RWr23, RWr3B)

Check the latest warning code with the remote register of the master/local module.

🔗 [Online] ➔ [Monitor] ➔ [Device/Buffer Memory Batch]

Ex. When the refresh target device for CH1 Latest warning code (RWr23) is W1123



The screenshot shows a software interface for monitoring device memory. The 'Device Name' is set to 'W1123'. The 'Display format' is set to '16 bit'. The table below shows the memory map for device W1123, with the 16-bit value at address 0 being 0160.

Device	F	E	D	C	B	A	9	8	7	6	5	4	3	2	1	0
W1123	0	0	0	0	0	0	1	0	1	1	0	0	0	0	0	0160
W1124	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000
W1125	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000
W1126	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000
W1127	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0000

11.2 Error Code List

This section describes error codes.

Error codes are classified by error number as follows.

Error code	Classification	Reference
0000 _H to 3FFF _H D529 _H , D52B _H	High-speed counter module error	Page 208, Section 11.2 (1)
D000 _H to DFFF _H (D529 _H and D52B _H excluded)	CC-Link IE Field Network error	Page 223, Section 11.2 (2)

(1) Error code list (0000_H to 3FFF_H, D529_H, D52B_H)

The errors are classified into the following three types.

Classification	Description	
Major error	An error that cannot be recovered. The RUN LED turns off.	
Moderate error	An error where the module cannot continue to operate. The ERR. LED turns on.	
Minor error	An error where the module can continue to operate. The ERR. LED flashes.	

If an error occurs, check that the D LINK LED is on. Then take corrective actions as listed below.

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
000B _H	Major error	Network number change error	The network number has been changed via the network.	*13		Take measures against noise and reset the module. If the same error occurs again, a module hardware failure may be the cause. Please consult your local Mitsubishi representative.
000C _H	Major error	Station number change error	The station number has been changed via the network.	*13		Take measures against noise and reset the module. If the same error occurs again, a module hardware failure may be the cause. Please consult your local Mitsubishi representative.
0010 _H	Major error	Hardware error	Module hardware failure	*13		Power off then on the module. If the same error occurs again, a module failure may be the cause. Please consult your local Mitsubishi representative.
0105 _H	Moderate error	Clock data out- of-range error	The clock data acquired from the CPU module are abnormal.	*3		Noise effect or a hardware failure may be the cause. If the same error occurs again after the measures against noise are taken, please consult your local Mitsubishi representative.

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
0110 _H	Moderate error	Non-volatile memory data error (module operation information)	The module operation information stored in the nonvolatile memory is abnormal.	*16		<ul style="list-style-type: none"> Initialize the module operation information in the nonvolatile memory by setting Module operation information initialization command (address: 1004_H) to Not commanded (0) → Commanded (1) → Not commanded (0). Note that the number of ON times integration value is initialized to 0. Take measures against noise, such as using a shielded cable for connection. If the same error occurs again, a module failure may be the cause. Please consult your local Mitsubishi representative.
0120 _H	Moderate error	Non-volatile memory data error (parameter)	The parameter data stored in the nonvolatile memory are abnormal.	*13		<ul style="list-style-type: none"> Set the parameters in the nonvolatile memory to the default values by setting Parameter area initialization command (address: 1002_H) to Not commanded (0) → Commanded (1) → Not commanded (0). Set the parameters again. Take measures against noise, such as using a shielded cable for connection. If the same error occurs again, a module failure may be the cause. Please consult your local Mitsubishi representative.
0130 _H	Moderate error	Non-volatile memory data error (Extended parameter)	The extended parameter data stored in the nonvolatile memory are abnormal.	*13		<ul style="list-style-type: none"> Set the parameters in the nonvolatile memory to the default values by setting Parameter area initialization command (address: 1002_H) to Not commanded (0) → Commanded (1) → Not commanded (0). Set the parameters again. Take measures against noise, such as using a shielded cable for connection. If the same error occurs again, a module failure may be the cause. Please consult your local Mitsubishi representative.

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
0140 _H	Minor error	Non-volatile memory data error (error history)	The error history data stored in the nonvolatile memory are abnormal.	*1		<ul style="list-style-type: none"> The module recovers automatically soon after this error occurred. However, the preceding error history data are erased. Take measures against noise, such as using a shielded cable for connection. If the same error occurs again, a module failure may be the cause. Please consult your local Mitsubishi representative.
0150 _H	Minor error	Remote buffer memory access error	The REMFR/REMTO instruction has accessed the range outside the remote buffer memory range.	*1		Correct the REMFR/REMTO instruction setting so that the instruction accesses the range within the remote buffer memory range.
0160 _H	Minor error	Station number switch change failure	The setting on the station number setting switch has been changed while the module power supply is on.	*1		Set the switch back to the station number which was set when the module was powered on.
0330 _H	Moderate error	Number of ON times integration function setting error	The number of ON times integration function is enabled when the cam switch function is selected.	*13		Set Number of ON times integration function enable (address: 0202 _H) to 0000 _H , and turn off then on Initial data setting request flag (RY9).
0340 _H	Moderate error	Cam switch output unit assignment setting error	A value other than 0 and 1 is set in Cam switch output unit assignment setting (address: 0104 _H).	*13		Set Cam switch output unit assignment setting (address: 0104 _H) to 0 or 1, and turn off then on Initial data setting request flag (RY9).
0800 _H	Moderate error	Comparison output setting error	The setting in Comparison output setting (address: 0100 _H) is in one of the following cases. <ul style="list-style-type: none"> A value other than 0 and 1 is set. If 1 is set, the value in CH□ Operation mode setting (address: 0120_H, 0140_H) is other than 0. 	*13		Take the following actions, and turn off then on Initial data setting request flag (RY9). <ul style="list-style-type: none"> Set Comparison output setting (address: 0100_H) to 0 or 1. Set CH□ Operation mode setting (address: 0120_H, 0140_H) to 0.
0850 _H	Moderate error	Cyclic data update watch time setting error	A value other than 0 to 20 is set in Cyclic data update watch time setting (address: 0003 _H).	*13		Set Cyclic data update watch time setting (address: 0003 _H) to a value between 0 and 20, and turn off then on Initial data setting request flag (RY9).
0F40 _H	Moderate error	Input response time setting error	The lower 3 bits of Input response time setting (address: 0001 _H) is set to 000b, 001b, or 010b.	*13		Set the lower 3 bits of Input response time setting (address: 0001 _H) to a value other than 000b, 001b, and 010b, then turn on Initial data setting request flag (RY9).
1341 _H	Moderate error	Cam switch output unit assignment error	An extension output module does not exist where Cam switch output unit assignment setting (address: 0104 _H) assigns the module.	*13		Power off the module, and connect an extension output module where Cam switch output unit assignment setting (address: 0104 _H) assigns the module. Then power on the module.

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
1F00 _H	Major error	Extension module 1 connection error	The extension module is improperly connected or an extension module not allowed to be connected has been connected.	*13		Check the contact points on the extension module, and if the module is allowed to be connected. If the same error occurs again, a module failure may be the cause. Please consult your local Mitsubishi representative.
1F20 _H	Moderate error	External power supply OFF error	The external power supply for the extension output module is off while the external power supply monitoring function is enabled.	*14		<ul style="list-style-type: none"> Check the external power supply status for the external output module. If this error occurs when the system starts or stops, change the timing of when the external power supply monitoring function is enabled.
1F30 _H	Moderate error	Extension module parameter failure	The parameter for specifying the extension module type has specified a type different from the connected one.	*13		Correct the setting in Extension module identification code (address: 0200 _H) so that the setting matches the connected extension module and the module points.
□050 _H *15	Minor error	CH□ Overflow/ underflow error (Sampling count value/Periodic pulse count, difference value)	CH□ Sampling count value (RW _r 12 to RW _r 13, RW _r 2A to RW _r 2B), CH□ Periodic pulse count, difference value (RW _r 12 to RW _r 13, RW _r 2A to RW _r 2B), or CH□ Periodic pulse count value update check (RW _r 16 to RW _r 17, RW _r 2E to RW _r 2F) is outside the range of -2147483648 to 2147483647. □ indicates the channel where settings are incorrect.	*2	*3	Adjust the values so that the product of Input pulse speed [pps] × Sampling/Periodic time [s] is within the range.
□200 _H	Moderate error	CH□ Overflow/underf low error	The value in CH□ Present value (RW _r 10 to RW _r 11, RW _r 28 to RW _r 29) is outside the range of -2147483648 to 2147483647 in the linear counter function operation. □ indicates the channel where settings are incorrect.	*5	*3	Replace the present value with the preset value.

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
□210 _H	Moderate error	CH□ Ring counter upper/lower limit value setting error	The value in CH□ Ring counter upper limit value (RWw12 to RWw13, RWw2A to RWw2B) is smaller than the value in CH□ Ring counter lower limit value (RWw10 to RWw11, RWw28 to RWw29) in the ring counter function operation. □ indicates the channel where settings are incorrect.	If the parameters are written with the parameter processing of the slave station, or Initial data processing completion flag (RY8) or Initial data setting request flag (RY9) is turned off then on: * ¹³ If CH□ Count enable command (RY24, RY3C) is turned off then on: * ⁴	If the parameters are written with the parameter processing of the slave station, or Initial data processing completion flag (RY8) or Initial data setting request flag (RY9) is turned off then on: * ¹³ If CH□ Count enable command (RY24, RY3C) is turned off then on: * ³	Set the values that satisfy the condition "CH□ Ring counter lower limit value (RWw10 to RWw11, RWw28 to RWw29) ≤ CH□ Ring counter upper limit value (RWw12 to RWw13, RWw2A to RWw2B)", and perform one of the following operations. <ul style="list-style-type: none">• If Initial data processing request flag (RX8) is on, turn off then on Initial data processing completion flag (RY8).• If the parameters are written with the parameter processing of the slave station, or Initial data setting completion flag (RX9) is on, turn off then on Initial data setting request flag (RY9).• If Initial data processing request flag (RX8) and Initial data setting completion flag (RX9) are off, turn off then on CH□ Count enable command (RY24, RY3C).
□30◊ _H	Moderate error	Comparison condition setting error (Coincidence output◊)	A value other than 00b to 10b is set in Coincidence output◊ of Coincidence output comparison condition setting (address: 0102 _H). □ indicates the channel where settings are incorrect. ◊ indicates the number of Coincidence output on which this error occurred.	* ¹³		Set coincidence output◊ of Coincidence output comparison condition setting (address: 0102 _H) to a value between 00b and 10b, and turn off then on Initial data setting request flag (RY9).

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
□31◇ _H	Moderate error	Upper limit value setting error (Coincidence output◇)	The value in Upper limit value setting (Coincidence output◇) is smaller than the value in Lower limit value setting (Coincidence output◇). □ indicates the channel where settings are incorrect. ◇ indicates the number of Coincidence output on which this error occurred.	If the parameters are written with the parameter processing of the slave station, or Initial data processing completion flag (RY8) or Initial data setting request flag (RY9) is turned off then on: * ¹³ If Setting change request (Coincidence output◇)(RY14 to RY17) is turned off then on: * ⁶	If the parameters are written with the parameter processing of the slave station, or Initial data processing completion flag (RY8) or Initial data setting request flag (RY9) is turned off then on: * ¹³ If Setting change request (Coincidence output◇)(RY14 to RY17) is turned off then on: * ³	Set the values that satisfy the condition "Lower limit value setting (Coincidence output◇) ≤ Upper limit value setting (Coincidence output◇)", and perform one of the following operations. • If Initial data processing request flag (RX8) is on, turn off then on Initial data processing completion flag (RY8). • If the parameters are written with the parameter processing of the slave station, or Initial data setting completion flag (RY9) is on, turn off then on Initial data setting request flag (RY9). • If Initial data processing request flag (RX8) and Initial data setting completion flag (RX9) are off, turn off then on Setting change request (Coincidence output◇) (RY14 to RY17).
□351 _H	Moderate error	Cam switch function, number of steps setting error (Output 1)	A value other than 0 to 16 is set in Cam switch function, number of steps (Output 1) (address: 1501 _H). □ indicates the channel where settings are incorrect.	* ⁷	* ³	Set Cam switch function, number of steps (Output 1) (address: 1501 _H) to a value between 0 and 16, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
⋮	⋮	⋮	⋮	⋮	⋮	⋮
□359 _H	Moderate error	Cam switch function, number of steps setting error (Output 9)	A value other than 0 to 16 is set in Cam switch function, number of steps (Output 9) (address: 1901 _H). □ indicates the channel where settings are incorrect.	* ⁷	* ³	Set Cam switch function, number of steps (Output 9) (address: 1901 _H) to a value between 0 and 16, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
□360 _H	Moderate error	Cam switch function, number of steps setting error (Output 10)	A value other than 0 to 16 is set in Cam switch function, number of steps (Output 10) (address: 1981 _H). □ indicates the channel where settings are incorrect.	* ⁷	* ³	Set Cam switch function, number of steps (Output 10) (address: 1981 _H) to a value between 0 and 16, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
⋮	⋮	⋮	⋮	⋮	⋮	⋮
□366 _H	Moderate error	Cam switch function, number of steps setting error (Output 16)	A value other than 0 to 16 is set in Cam switch function, number of steps (Output 16) (address: 1C81 _H). □ indicates the channel where settings are incorrect.	* ⁷	* ³	Set Cam switch function, number of steps (Output 16) (address: 1C81 _H) to a value between 0 and 16, and turn off then on CH□ Cam switch execute command (RY26, RY3E).

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
□391 _H	Moderate error	Cam switch function, step type setting error (Output 1)	A value other than 0 and 1 is set in Cam switch function, step type (Output 1) (address: 1500 _H). □ indicates the channel where settings are incorrect.	*7	*3	Set Cam switch function, step type (Output 1) (address: 1500 _H) to 0 or 1, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
⋮	⋮	⋮	⋮	⋮	⋮	⋮
□399 _H	Moderate error	Cam switch function, step type setting error (Output 9)	A value other than 0 and 1 is set in Cam switch function, step type (Output 9) (address: 1900 _H). □ indicates the channel where settings are incorrect.	*7	*3	Set Cam switch function, step type (Output 9) (address: 1900 _H) to 0 or 1, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
⋮	⋮	⋮	⋮	⋮	⋮	⋮
□3A0 _H	Moderate error	Cam switch function, step type setting error (Output 10)	A value other than 0 and 1 is set in Cam switch function, step type (Output 10) (address: 1980 _H). □ indicates the channel where settings are incorrect.	*7	*3	Set Cam switch function, step type (Output 10) (address: 1980 _H) to 0 or 1, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
⋮	⋮	⋮	⋮	⋮	⋮	⋮
□3A6 _H	Moderate error	Cam switch function, step type setting error (Output 16)	A value other than 0 and 1 is set in Cam switch function, step type (Output 16) (address: 1C80 _H). □ indicates the channel where settings are incorrect.	*7	*3	Set Cam switch function, step type (Output 16) (address: 1C80 _H) to 0 or 1, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
⋮	⋮	⋮	⋮	⋮	⋮	⋮
□401 _H	Moderate error	Cam switch function, step No. setting error (Output 1)	The values set in Cam switch function, step No.1 to No.16 setting (Output 1) (address: 1502 _H to 1521 _H) are not in the ascending order. □ indicates the channel where settings are incorrect.	*7	*3	Set Cam switch function, step No.1 to No.16 setting (Output 1) (address: 1502 _H to 1521 _H) to values in the ascending order, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
⋮	⋮	⋮	⋮	⋮	⋮	⋮
□409 _H	Moderate error	Cam switch function, step No. setting error (Output 9)	The values set in Cam switch function, step No.1 to No.16 setting (Output 9) (address: 1902 _H to 1921 _H) are not in the ascending order. □ indicates the channel where settings are incorrect.	*7	*3	Set Cam switch function, step No.1 to No.16 setting (Output 9) (address: 1902 _H to 1921 _H) to values in the ascending order, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
⋮	⋮	⋮	⋮	⋮	⋮	⋮
□410 _H	Moderate error	Cam switch function, step No. setting error (Output 10)	The values set in Cam switch function, step No.1 to No.16 setting (Output 10) (address: 1982 _H to 19A1 _H) are not in the ascending order. □ indicates the channel where settings are incorrect.	*7	*3	Set Cam switch function, step No.1 to No.16 setting (Output 10) (address: 1982 _H to 19A1 _H) to values in the ascending order, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
⋮	⋮	⋮	⋮	⋮	⋮	⋮

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
□416 _H	Moderate error	Cam switch function, step No. setting error (Output 16)	The values set in Cam switch function, step No.1 to No.16 setting (Output 16) (address: 1C82 _H to 1CA1 _H) are not in the ascending order. □ indicates the channel where settings are incorrect.	*7	*3	Set Cam switch function, step No.1 to No.16 setting (Output 16) (address: 1C82 _H to 1CA1 _H) to values in the ascending order, and turn off then on CH□ Cam switch execute command (RY26, RY3E).
□501 _H	Moderate error	CH□ Time unit setting error (Sampling counter/ Periodic pulse counter)	A value other than 0 and 1 is set in CH□ Time unit setting (Sampling counter/Periodic pulse counter) (RWw16, RWw2E). □ indicates the channel where settings are incorrect.	If the parameters are written with the parameter processing of the slave station, or Initial data processing completion flag (RY8) or Initial data setting request flag (RY9) is turned off then on: *13 If CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned off then on: *8	If the parameters are written with the parameter processing of the slave station, or Initial data processing completion flag (RY8) or Initial data setting request flag (RY9) is turned off then on: *13 If CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned off then on: *3	Set CH□ Time unit setting (Sampling counter/Periodic pulse counter) (RWw16, RWw2E) to 0 or 1, and perform one of the following operations. • If Initial data processing request flag (RX8) is on, turn off then on Initial data processing completion flag (RY8). • If the parameters are written with the parameter processing of the slave station, or Initial data setting completion flag (RX9) is on, turn off then on Initial data setting request flag (RY9). • If Initial data processing request flag (RX8) and Initial data setting completion flag (RX9) are off, turn off then on CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F).
□502 _H	Moderate error	CH□ Cycle setting error (Sampling counter/ Periodic pulse counter)	CH□ Cycle setting (Sampling counter/Periodic pulse counter) (RWw17, RWw2F) is set to 0. □ indicates the channel where settings are incorrect.	If the parameters are written with the parameter processing of the slave station, or Initial data processing completion flag (RY8) or Initial data setting request flag (RY9) is turned off then on: *13 If CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned off then on: *8	If the parameters are written with the parameter processing of the slave station, or Initial data processing completion flag (RY8) or Initial data setting request flag (RY9) is turned off then on: *13 If CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned off then on: *3	Set CH□ Cycle setting (Sampling counter/Periodic pulse counter) (RWw17, RWw2F) to a value between 1 and 65535, and perform one of the following operations. • If Initial data processing request flag (RX8) is on, turn off then on Initial data processing completion flag (RY8). • If the parameters are written with the parameter processing of the slave station, or Initial data setting completion flag (RX9) is on, turn off then on Initial data setting request flag (RY9). • If Initial data processing request flag (RX8) and Initial data setting completion flag (RX9) are off, turn off then on CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F).

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
□601 _H	Moderate error	CH□ Moving average count setting error (Frequency measurement)	A value other than 1 to 100 is set in CH□ Moving average count (Frequency measurement) (RWw19, RWw31). □ indicates the channel where settings are incorrect.	*9	*3	Set CH□ Moving average count (Frequency measurement) (RWw19, RWw31) to a value between 1 and 100, and turn off then on CH□ Count enable command (RY24, RY3C).
□602 _H	Moderate error	CH□ Time unit setting error (Frequency measurement)	A value other than 0 to 2 is set in CH□ Time unit setting (Frequency measurement) (RWw18, RWw30). □ indicates the channel where settings are incorrect.	*9	*3	Set CH□ Time unit setting (Frequency measurement) (RWw18, RWw30) to a value between 0 and 2, and turn off then on CH□ Count enable command (RY24, RY3C).
□621 _H	Moderate error	CH□ Moving average count setting error (Rotation speed measurement)	A value other than 1 to 100 is set in CH□ Moving average count (Rotation speed measurement) (RWw19, RWw31). □ indicates the channel where settings are incorrect.	*10	*3	Set CH□ Moving average count (Rotation speed measurement) (RWw19, RWw31) to a value between 1 and 100, and turn off then on CH□ Count enable command (RY24, RY3C).
□622 _H	Moderate error	CH□ Time unit setting error (Rotation speed measurement)	A value other than 0 to 2 is set in CH□ Time unit setting (Rotation speed measurement) (RWw18, RWw30). □ indicates the channel where settings are incorrect.	*10	*3	Set CH□ Time unit setting (Rotation speed measurement) (RWw18, RWw30) to a value between 0 and 2, and turn off then on CH□ Count enable command (RY24, RY3C).
□623 _H	Moderate error	CH□ Number of pulses per rotation setting error	A value other than 1 to 8000000 is set in CH□ Number of pulses per rotation (RWw1A to RWw1B, RWw32 to RWw33). □ indicates the channel where settings are incorrect.	*10	*3	Set CH□ Number of pulses per rotation (RWw1A to RWw1B, RWw32 to RWw33) to a value between 1 and 8000000, and turn off then on CH□ Count enable command (RY24, RY3C).
□660 _H	Moderate error	CH□ Pulse measurement range overflow error (Function input terminal)	A pulse from CH□ Function input terminal (FUNC1 or FUNC2) is beyond the measurable range (approx. 214s). □ indicates the channel where settings are incorrect.	*11	*3	Measure pulses within the measurable range. To resume the measurement, take either of the following actions. <ul style="list-style-type: none">• Input the target pulses again.• Turn off then on CH□ Pulse measurement start command (Function input terminal) (RY30, RY48).
□661 _H	Moderate error	CH□ Pulse measurement setting error (Function input terminal)	A value other than 0 and 1 is set in CH□ Pulse measurement setting (Function input terminal) (address: 012A _H , 014A _H). □ indicates the channel where settings are incorrect.	*13		Set CH□ Pulse measurement setting (Function input terminal) (address: 012A _H , 014A _H) to 0 or 1, and turn off then on Initial data setting request flag (RY9).

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
□662 _H	Moderate error	CH□ Pulse measurement range overflow error (Latch counter input terminal)	A pulse from CH□ Latch counter input terminal (LATCH1 or LATCH2) is beyond the measurable range (approx. 214s). □ indicates the channel where settings are incorrect.	*11	*3	Measure pulses within the measurable range. To resume the measurement, take either of the following actions. <ul style="list-style-type: none">• Input the target pulses again.• Turn off then on CH□ Pulse measurement start command (Latch counter input terminal) (RY32, RY4A).
□663 _H	Moderate error	CH□ Pulse measurement setting error (Latch counter input terminal)	A value other than 0 and 1 is set in CH□ Pulse measurement setting (Latch counter input terminal) (address: 012B _H , 014B _H). □ indicates the channel where settings are incorrect.	*13		Set CH□ Pulse measurement setting (Latch counter input terminal) (address: 012B _H , 014B _H) to 0 or 1, and turn off then on Initial data setting request flag (RY9).
□670 _H	Moderate error	CH□ PWM output assignment setting error	The setting in CH□ PWM output assignment setting (RWw1D, RWw35) is in either of the following cases. <ul style="list-style-type: none">• All the bits from b0 to b3 are not on.• Coincidence output△ bit which is assigned to the other channel is on. □ indicates the channel where settings are incorrect.	*12	*3	Take the following actions, and turn off then on CH□ PWM output start command (RY26, RY3E). <ul style="list-style-type: none">• Turn on one or more bits from b0 to b3.• Turn on Coincidence output△ bit which is assigned to the target channel.
□671 _H	Moderate error	CH□ ON width setting error (PWM output)	A value other than 0 and 10 to 10000000 is set in CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37). □ indicates the channel where settings are incorrect.	If CH□ PWM output start command (RY26, RY3E) is turned off then on: *12 If CH□ ON width setting change request (PWM output) (RY35, RY4D) is turned off then on: *1	*3	Set CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37) to 0 or a value between 10 and 10000000, and perform either of the following operations. <ul style="list-style-type: none">• If CH□ PWM output (RX26, RX3E) is off, turn off then on CH□ PWM output start command (RY26, RY3E).• If CH□ PWM output (RX26, RX3E) is on, turn off then on CH□ ON width setting change request (PWM output) (RY35, RY4D).
□672 _H	Moderate error	CH□ Cycle setting error (PWM output)	A value other than 50 to 10000000 is set in CH□ Cycle setting (PWM output) (RWw20 to RWw21, RWw38 to RWw39). □ indicates the channel where settings are incorrect.	*12	*3	Set CH□ Cycle setting (PWM output) (RWw20 to RWw21, RWw38 to RWw39) to a value between 50 and 10000000, and turn off then on CH□ PWM output start command (RY26, RY3E).

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
□673 _H	Moderate error	CH□ ON width/Cycle setting error (PWM output)	The value in CH□ Cycle setting (PWM output) (RWw20 to RWw21, RWw38 to RWw39) is smaller than the value in CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37). □ indicates the channel where settings are incorrect.	If CH□ PWM output start command (RY26, RY3E) is turned off then on: *12 If CH□ ON width setting change request (PWM output) (RY35, RY4D) is turned off then on: *1	*3	Set the values that satisfy the condition "CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37) ≤ CH□ Cycle setting (PWM output) (RWw20 to RWw21, RWw38 to RWw39)", and perform either of the following operations. <ul style="list-style-type: none">• If CH□ PWM output (RX26, RX3E) is off, turn off then on CH□ PWM output start command (RY26, RY3E).• If CH□ PWM output (RX26, RX3E) is on, turn off then on CH□ ON width setting change request (PWM output) (RY35, RY4D).
□810 _H	Moderate error	CH□ Operation mode setting error	A value other than 0 to 4 is set in CH□ Operation mode setting (address: 0120 _H , 0140 _H). □ indicates the channel where settings are incorrect.	*13		Set CH□ Operation mode setting (address: 0120 _H , 0140 _H) to a value between 0 and 4, and turn off then on Initial data setting request flag (RY9).
□811 _H	Moderate error	CH□ Count source selection setting error	The setting in CH□ Count source selection (address: 0121 _H , 0141 _H) is in either of the following cases. <ul style="list-style-type: none">• If the value in CH□ Operation mode setting (address: 0120_H, 0140_H) is 0, a value other than 0 to 2 is set.• If the value in CH□ Operation mode setting (address: 0120_H, 0140_H) is 1 or 2, a value other than 0 is set. □ indicates the channel where settings are incorrect.	*13		Take either of the following actions on CH□ Count source selection (address: 0121 _H , 0141 _H), and turn off then on Initial data setting request flag (RY9). <ul style="list-style-type: none">• If the value in CH□ Operation mode setting (address: 0120_H, 0140_H) is 0, set a value between 0 and 2.• If the value in CH□ Operation mode setting (address: 0120_H, 0140_H) is 1 or 2, set 0.

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
□812H	Moderate error	CH□ Count source coincidence output setting error	<p>Either of the following cases is the cause if the value in CH□ Operation mode setting (address: 0120_H, 0140_H) is 0, and the value in CH□ Count source selection (address: 0121_H, 0141_H) is 1 or 2.</p> <ul style="list-style-type: none"> • A value other than 0 and 4 is set in CH□ Operation mode setting (address: 0120_H, 0140_H) of the other channel. • A channel where CH□ Count source selection (address: 0121_H, 0141_H) is set is the same as the channel assigned to the corresponding bit of Coincidence output channel assignment setting (address: 0101_H). <p>□ indicates the channel where settings are incorrect.</p>	*13		<p>Take the following actions, and turn off then on Initial data setting request flag (RY9).</p> <ul style="list-style-type: none"> • Set CH□ Operation mode setting (address: 0120_H, 0140_H) for the other channel to 0 or 4. • Set the corresponding bit of Coincidence output channel assignment setting (address: 0101_H) to the channel where CH□ Count source selection (address: 0121_H, 0141_H) is not set.
□813H	Moderate error	CH□ Pulse input mode setting error	<p>A value other than 0 to 5 is set in CH□ Pulse input mode (address: 0122_H, 0142_H).</p> <p>□ indicates the channel where settings are incorrect.</p>	*13		<p>Set CH□ Pulse input mode (address: 0122_H, 0142_H) to a value between 0 and 5, and turn off then on Initial data setting request flag (RY9).</p>
□814H	Moderate error	CH□ Counting speed setting error	<p>The setting in CH□ Counting speed setting (address: 0123_H, 0143_H) is in one of the following cases.</p> <ul style="list-style-type: none"> • If the value in CH□ Pulse input mode (address: 0122_H, 0142_H) is 0, 2, or 3, a value other than 0 to 5 is set. • If the value in CH□ Pulse input mode (address: 0122_H, 0142_H) is 1 or 4, a value other than 0 to 6 is set. • If the value in CH□ Pulse input mode (address: 0122_H, 0142_H) is 5, a value other than 0 to 7 is set. <p>□ indicates the channel where settings are incorrect.</p>	*13		<p>Take one of the following actions on CH□ Counting speed setting (address: 0123_H, 0143_H), and turn off then on Initial data setting request flag (RY9).</p> <ul style="list-style-type: none"> • If the value in CH□ Pulse input mode (address: 0122_H, 0142_H) is 0, 2, or 3, set a value between 0 and 5. • If the value in CH□ Pulse input mode (address: 0122_H, 0142_H) is 1 or 4, set a value between 0 and 6. • If the value in CH□ Pulse input mode (address: 0122_H, 0142_H) is 5, set a value between 0 and 7.

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
□815 _H	Moderate error	Coincidence output channel assignment setting error	The channel where the PWM output mode is selected is not assigned to the setting in Coincidence output channel assignment setting (address: 0101 _H). □ indicates the channel where settings are incorrect.	*13		Assign the channel where the PWM output mode is selected on Coincidence output channel assignment setting (address: 0101 _H), and turn off then on Initial data setting request flag (RY9).
□820 _H	Moderate error	CH□ Counter format setting error	A value other than 0 and 1 is set in CH□ Counter format (address: 0124 _H , 0144 _H). □ indicates the channel where settings are incorrect.	*13		Set CH□ Counter format (address: 0124 _H , 0144 _H) to 0 or 1, and turn off then on Initial data setting request flag (RY9).
□821 _H	Moderate error	CH□ Counter function selection setting error	A value other than 0 to 5 is set in CH□ Counter function selection (address: 0126 _H , 0146 _H). □ indicates the channel where settings are incorrect.	*13		Set CH□ Counter function selection (address: 0126 _H , 0146 _H) to a value between 0 and 5, and turn off then on Initial data setting request flag (RY9).
□822 _H	Moderate error	CH□ Function input logic setting error	A value other than 0 and 1 is set in CH□ Function input logic setting (address: 0127 _H , 0147 _H). □ indicates the channel where settings are incorrect.	*13		Set CH□ Function input logic setting (address: 0127 _H , 0147 _H) to 0 or 1, and turn off then on Initial data setting request flag (RY9).
□823 _H	Moderate error	CH□ Latch counter input logic setting error	A value other than 0 and 1 is set in CH□ Latch counter input logic setting (address: 0128 _H , 0148 _H). □ indicates the channel where settings are incorrect.	*13		Set CH□ Latch counter input logic setting (address: 0128 _H , 0148 _H) to 0 or 1, and turn off then on Initial data setting request flag (RY9).
□824 _H	Moderate error	CH□ Z phase input response time setting error	A value other than 00b to 10b is set in CH□ Z phase input response time setting (address: 0129 _H .b0 to b1, 0149 _H .b0 to b1). □ indicates the channel where settings are incorrect.	*13		Set CH□ Z phase input response time setting (address: 0129 _H .b0 to b1, 0149 _H .b0 to b1) to a value between 00b and 10b, and turn off then on Initial data setting request flag (RY9).
□825 _H	Moderate error	CH□ Function input response time setting error	A value other than 00b to 10b is set in CH□ Function input response time setting (address: 0129 _H .b2 to b3, 0149 _H .b2 to b3). □ indicates the channel where settings are incorrect.	*13		Set CH□ Function input response time setting (address: 0129 _H .b2 to b3, 0149 _H .b2 to b3) to a value between 00b and 10b, and turn off then on Initial data setting request flag (RY9).

Error code (hexadecimal)	Classification	Error name	Description and cause	Operation of when an error occurs		Action
				Error CH	The other CHs	
□826 _H	Moderate error	CH□ Latch counter input response time setting error	A value other than 00b to 10b is set in CH□ Latch counter input response time setting (address: 0129 _H .b4 to b5, 0149 _H .b4 to b5). □ indicates the channel where settings are incorrect.	*13		Set CH□ Latch counter input response time setting (address: 0129 _H .b4 to b5, 0149 _H .b4 to b5) to a value between 00b and 10b, and turn off then on Initial data setting request flag (RY9).
D529 _H	Major error	Communication error 1		*13		
D52B _H	Major error	Communication error 2	The communication LSI is in failure.	*13		<ul style="list-style-type: none"> Malfunction due to noise may be the cause. Check the cable distance or grounding condition of each device. Then take measures against noise. Conduct the unit test. If the same error occurs again, a hardware failure of the module may be the cause. Please consult your local Mitsubishi representative.

- *1 Keeps its operation with the normal setting value just before the error.
- *2 Stores -2147483648 or 2147483647 in CH□ Sampling count value (RW_r12 to RW_r13, RW_r2A to RW_r2B), CH□ Periodic pulse count, difference value (RW_r12 to RW_r13, RW_r2A to RW_r2B), or CH□ Periodic pulse count value update check (RW_r16 to RW_r17, RW_r2E to RW_r2F), and continues to count.
- *3 Keeps its normal operation unless an error occurs.
- *4 The ring counter function does not start counting.
- *5 The linear counter function stops counting.
- *6 Compares the count value with the normal setting value just before the error. The error does not affect Coincidence output△ assigned to the error CH and the other functions.
- *7 Does not execute the cam switch function. The error does not affect the other functions.
- *8 Executes the sampling counter function or periodic pulse counter function with the normal setting value just before the error.
- *9 Does not start to measure the frequency.
- *10 Does not start to measure the rotation speed.
- *11 Stops measuring pulses.
- *12 Does not output the PWM waveform.
- *13 Stops operations except the one on the error and updating EQU1 to EQU4 terminal status (RW_r1), Cam switch output signal (RW_r2), Cam switch output terminal status (RW_r3), CH□ Status (RW_r20, RW_r38), and CH□ External input status (RW_r21, RW_r39).
- *14 Continues its operation although the external output terminals of the extension output module are forced off. (Y0 LED to YF LED on the extension output module turn on or off depending on the output status.)
- *15 A minor error which can be reset by turning off then on CH□ Error reset command (RY36, RY4E)
- *16 Stores 0 in all the monitor data and keeps 0 until the module operation information is initialized. The number of ON times integration does not start.

Point

- When multiple errors occur, only the latest error code is stored in CH□ Latest error code (RWr22, RWr3A) or CH□ Latest warning code (RWr23, RWr3B). (Error codes which do not have □ on their names are stored in CH1.)
Old errors can be checked with the error history of GX Works2.
For the error history, refer to the following.
 - Checking by executing a command of the slave station (☞ Page 205, Section 11.1 (1))
 - Error history 1 to 15 (address: 0A00_H to 0AEF_H) (☞ Page 276, Appendix 3 (14))
- Turning on CH□ Error reset command (RY36, RY4E) resets errors. However, the error causes are detected again and thus the error codes are stored again unless the error causes are removed.

(a) Detailed error information list

Detailed information about errors is stored in Error code details 1 in Error history 1 to 15 (address: 0A00_H to 0AEF_H). The following table lists the error codes with the detailed information.

Error code (hexadecimal)	Classification	Error name	Error code details 1	Error code details 2 to 10
□050 _H	Minor error	CH□ Overflow/underflow error (Sampling count value/Periodic pulse count, difference value)	0: Underflow 1: Overflow	0 (fixed)
□200 _H	Moderate error	CH□ Overflow/underflow error	0: Underflow 1: Overflow	0 (fixed)
Error codes other than □ 050 _H and □ 200 _H	—	—	0 (fixed)	0 (fixed)

(2) Error code list (D000_H to DFFF_H (D529_H and D52B_H excluded))

When an error occurs, the ERR. LED does not turn on. The D LINK LED flashes or turns off.

Troubleshoot the problem with the CC-Link IE Field Network diagnostics. (☞ Page 175, Section 8.21)

Error code (hexadecimal)	Error name	Description and cause	Action
D0E0 _H	Station type mismatch	The network parameter is incorrect or outside the range.	In the network configuration settings of the master station, change the station type to the remote device station.
D0E1 _H	Own station reserved	The network parameter is incorrect or outside the range.	<ul style="list-style-type: none"> In the network configuration settings of the master station, cancel the reserved station setting. Change the station number of the module to a station number that is not reserved.
D0E2 _H	Station No. already in use (own station)	The network parameter is incorrect or outside the range.	<ul style="list-style-type: none"> Set a unique station number. After taking the above action, turn off then on or reset all the stations where this error has been detected.
D0E3 _H	Own station No. out of range	The network parameter is incorrect or outside the range.	Add the station information of the module in the network configuration settings of the master station.
D217 _H	Transient data command error	The transient data request command is incorrect.	Correct the request command at the request source, and retry the operation.
D2A0 _H	Receive buffer full	The target station is overloaded and cannot receive transient data.	<ul style="list-style-type: none"> Check the network status using the CC-Link IE Field Network diagnostics of GX Works2. When the target station is overloaded and cannot receive transient data, send the data to the target station after a while.
D2A3 _H	Transient data length error	The received transient data is incorrect.	Correct the number of data (frame length) at the request source, and retry the operation.
D72A _H	Station number switch out of range (a value other than 1 to 120)	A station number out of range has been set.	Set the station number within the allowable range.
DF01 _H	Transient data divided error	The divided transient data have been received.	Set the transient data size within the range that can be handled by the module. Then send the transient data that is not divided.

Point

When multiple errors occur, only the latest error code is stored in CH□ Latest error code (RWr22, RWr3A) or CH□ Latest warning code (RWr23, RWr3B).

Old errors can be checked with the error history of GX Works2.

For the error history, refer to the following.

- Checking by executing a command of the slave station (☞ Page 205, Section 11.1 (1))
- Error history 1 to 15 (address: 0A00_H to 0AFF_H) (☞ Page 276, Appendix 3 (14))

11.3 Checking the LEDs

This section describes how to troubleshoot the system by the LEDs.

Point

For troubleshooting with the LEDs of the extension I/O module, refer to the following.

 CC-Link IE Field Network Remote I/O Module User's Manual

(1) When the PW LED does not turn on

Check item	Action
Is any LED other than the PW LED turned on?	When any LED other than the PW LED turns on, a hardware failure may be the cause. Please consult your local Mitsubishi representative.
Is the module power supply (24VDC) wired?	Wire the module power supply (24VDC).
Is the module power supply (24VDC) turned on?	Turn on the module power supply (24VDC).
Is the voltage of the module power supply (24VDC) within the specified range?	Set the voltage value within the range of performance specifications.

(2) When the RUN LED does not turn on

Check item	Action
Does the voltage of the module power supplied externally reach to the voltage of the performance specifications?	Check that module power supply voltage is within the range of performance specifications. ( Page 27, Section 3.2) After the check, power off then on the module.
Does any hardware error occur?	If the RUN LED does not turn on even after the module power supply is turned off then on, a module failure may be the cause. Please consult your local Mitsubishi representative.

(3) When the MODE LED flashes

Check item	Action
Is the high-speed counter module in execution of the unit test?	When the high-speed counter module is in execution of the unit test, the D LINK LED turns on after the unit test is completed. Take corrective action according to the result of the unit test. ( Page 227, Section 11.4)

(4) When the D LINK LED turns off

Check item	Action
Does the own station in network operate normally?	Connect GX Works2 to the master station, and check that the own station is performing data link by CC-Link IE Field Network diagnostics. ( User's manual for the master/local module used)
Are 1000BASE-T-compliant Ethernet cables used?	Replace the cable with a 1000BASE-T-compliant Ethernet cable. ( User's manual for the master/local module used)
Is the station-to-station distance 100m or less?	Change the station-to-station distance to 100m or less.
Does the cabling condition (bend radius) meet the specifications?	Refer to the manual for the Ethernet cable used, and correct the bend radius.
Is any Ethernet cable disconnected?	Replace the Ethernet cable.
Do other stations connected to the high-speed counter module normally operate?	Check that the power supplies of the other stations are turned on.
Does the switching hub normally operate?	<ul style="list-style-type: none"> Check that a 1000BASE-T-compliant switching hub is used. ( User's manual for the master/local module used) Check that the power supply of the switching hub is turned on.
Is the station number of the high-speed counter module duplicated with any of other stations?	<p>Two or more duplicated stations exist. Change the setting so that all the station numbers differ.</p>

(5) When the D LINK LED flashes

Check item	Action
Does the station number setting of the high-speed counter module match the station number of the high-speed counter module set in the network configuration settings of the master station or in the CC IE Field configuration?	Match the station number of the high-speed counter module with the station number set in the network configuration settings of the master station or in the CC IE Field configuration.
Is the station type remote device station?	Change the station type of the module to the remote device station in the network configuration settings of the master station.
Is the high-speed counter module a reserved station?	Change the setting of reserved/ignored error station to other than the reserved station in the network configuration settings of the master station.
Is stop of the data link checked through CC-Link IE Field Network diagnostics?	Check the link status through CC-Link IE Field Network diagnostics and start the link when the data link is stopped.
Is the station number setting switch set to other than 1 to 120?	The setting range for the station number setting switch is 1 to 120. Set the number between 1 and 120.

(6) When the L ER LED turns on

Check item	Action
Are Ethernet cables normal?	<ul style="list-style-type: none"> Check that 1000BASE-T-compliant Ethernet cables are used. ( User's manual for the master/local module used) Check that the station-to-station distance is 100m or less. Check that the Ethernet cables are not disconnected.
Does the switching hub in the system normally operate?	<ul style="list-style-type: none"> Check that a 1000BASE-T-compliant switching hub is used. ( User's manual for the master/local module used) Check that the power supply of the switching hub is turned on.
Do other stations connected to the high-speed counter module normally operate?	Check that the power supplies of the other stations are turned on.
Is the mode of the module on the master station set to other than Online?	Change the mode of the module to Online.
Is there any noise affecting the system?	Check the wiring condition of the Ethernet cables.
Is the loopback function enabled for the master station?	When the loopback function is enabled, check that the ring topology is correctly configured for the port where the L ER LED is on. ( User's manual for the master/local module used)

(7) When the LINK LED turns off

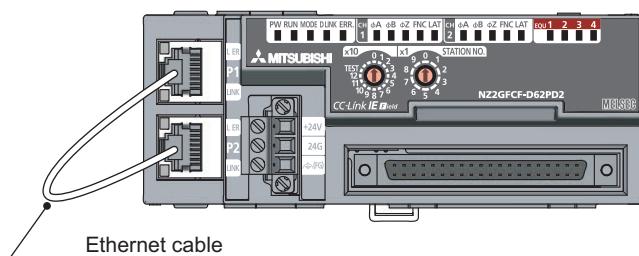
Check item	Action
Are Ethernet cables normal?	<ul style="list-style-type: none"> Check that 1000BASE-T-compliant Ethernet cables are used. ( User's manual for the master/local module used) Check that the station-to-station distance is 100m or less. Check that the Ethernet cables are not disconnected.
Do the switching hub and other stations in the system normally operate?	<ul style="list-style-type: none"> Check that a 1000BASE-T-compliant switching hub is used. ( User's manual for the master/local module used) Check that the power supplies of the switching hub and other stations are turned on.

(8) When the ERR. LED flashes/turns on

Check item	Action
Does any error occur?	Identify the error cause of the high-speed counter module and take corrective action with GX Works2.

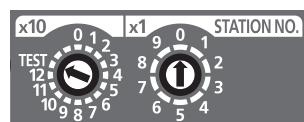
11.4 Unit Test

Run a unit test to check if there is any abnormality in the high-speed counter module.



1. Power off the module.
2. Connect the PORT1 and PORT2 of the high-speed counter module with an Ethernet cable.

Ethernet cable



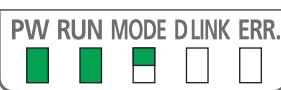
3. Set the station number setting switch as follows.

- x10: TEST
- x1: 0

4. Power on the module.

5. Unit test begins.

The MODE LED flashes while the unit test is being executed.

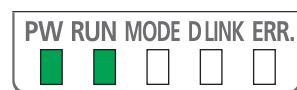


■ : ON

■ : Flashing

□ : OFF

When completed

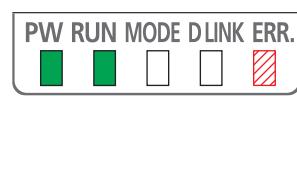


■ : ON

■ : Flashing

□ : OFF

When failed



■ : ON

■ : Flashing

□ : OFF

6. The MODE LED turns off when the unit test is completed.

- When completed

The ERR. LED does not turn on, but remains off.

- When failed

The ERR. LED turns on.

If the test fails, replace the Ethernet cable and run the test again. If the test fails again, it may be due to a hardware failure in the high-speed counter module. Please consult your local Mitsubishi representative.

Remark

When unit test fails, the error details can be checked in the error history.

To check the error history, set the station number of the high-speed counter module and connect the module to the master station with an Ethernet cable.

For the error history, refer to the following.

- Checking by executing a command of the slave station (☞ Page 205, Section 11.1 (1))
- Error history 1 to 15 (address: 0A00_H to 0AFF_H) (☞ Page 276, Appendix 3 (14))

11.5 Troubleshooting for Each Phenomenon

This section describes troubleshooting for each phenomenon.

Perform troubleshooting for each phenomenon when the high-speed counter module does not operate properly with no error. When an error occurs in the high-speed counter module, identify the error cause with GX Works2.

11.5.1 When the setting on the operation mode setting is the normal mode

(1) When the module does not count or perform normal count

(a) When the module does not count

Check item	Action
Is CH□ Count enable command (RY24, RY3C) on?	Turn on CH□ Count enable command (RY24, RY3C) in a program.
Is CH□ Function input terminal (FUNC1, FUNC2) off?	If the count disable function is selected for the counter function selection setting, pulses are not counted while CH□ Function input terminal (FUNC1, FUNC2) is on. Turn off CH□ Function input terminal (FUNC1, FUNC2).
Is the pulse input method the same as what has been selected in CH□ Pulse input mode (address: 0122 _H , 0142 _H)?	Change the pulse input method or the setting in CH□ Pulse input mode (address: 0122 _H , 0142 _H) so that they match.
Does the CPU module indicate any error?	If an error is indicated with the CPU module, refer to troubleshooting on the user's manual for the CPU module used.
Is the external wiring to φA and φB correct?	Check the external wiring and correct errors.
Do the LEDs of φA and φB turn on by applying a voltage to the pulse input terminals in φA and φB using devices such as a voltage stabilizer?	If the LEDs of φA and φB turn on, check the external wiring and wiring on the encoder side. If the LEDs of φA and φB do not turn on, a module failure may be the cause. Please consult your local Mitsubishi representative.

(b) When the module does not count normally

Check item	Action
Does a program used read out the present value in unit of 2 words (32 bits)?	Read out it in unit of 2 words (32 bits).
Is the preset value within the count range of the ring counter when the counter format is the ring counter?	Set the preset value so that the value is within the count range of the ring counter.
Measures against noise	Are the shielded twisted pair cables used for pulse input wiring?
	Use the shielded twisted pair cables for pulse input wiring.
	Are measures against noise taken for the adjacent devices and inside the control panel?
	Take noise reduction measures such as attaching a CR surge suppressor to the magnet switch.
	Is the distance between the high voltage equipment and pulse input line kept enough?
	Bundle up the pulse input lines in a single tube, and keep a distance of 150mm or more between the pulse input lines and the power line even inside the control panel.
	Does any noise come from the grounded part of the high-speed counter module?
	Separate the grounding cable of the high-speed counter module from the grounded part. If the case of the high-speed counter module touches the grounded part, separate it.

Check item	Action
Does the input pulse waveform meet the performance specifications?	Check the pulse waveform with a synchronoscope. If the input pulse does not meet the performance specifications, input pulses which meet the performance specifications.
Does the other channel show the same count result when the same input is applied to the other channel?	If a different count value appears, a module failure may be the cause. Please consult your local Mitsubishi representative.

Point

● How to fix pulse form

This portion describes how to fix pulse waveform by dummy resistance that can be used against noises from outside or distortion of pulse waveform.

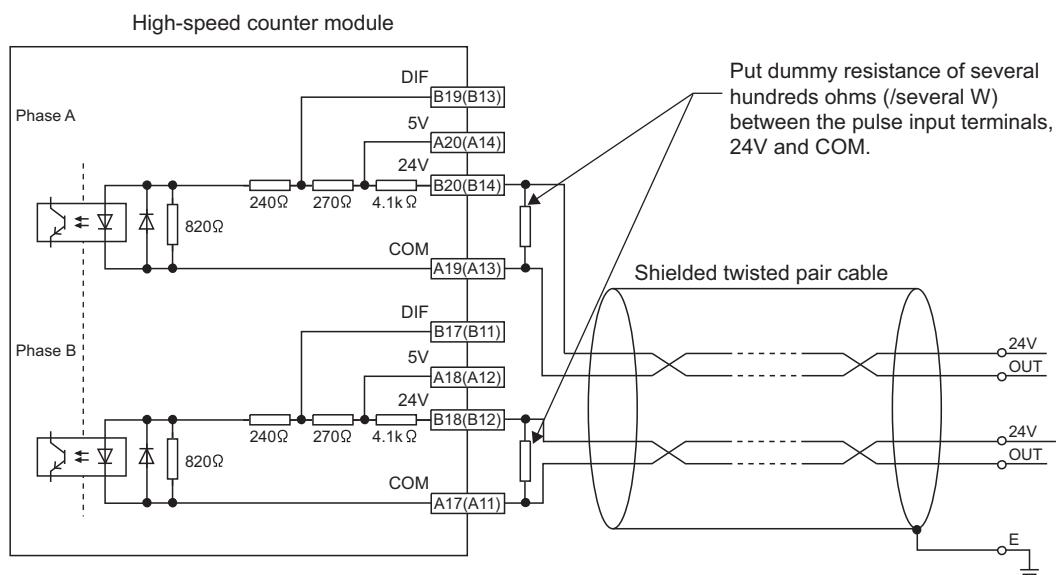
To fix pulse waveform effectively, increase load current inside cables by applying dummy resistance of several hundreds ohms (/several W) between the pulse input terminals connected to the encoder. The greater the load current, the more effective this method is.

● Effect

- When the distance between the encoder and the high-speed counter module is long
Distortion of waveform is fixed and the pulse waveform becomes stable.

- When the pulse waveform is distorted due to noises from outside
Taking the method above stabilizes pulse waveform; distortion of pulse waveform by noise can be reduced.

● Example of dummy resistance at 24VDC



● How to choose dummy resistance

The following example describes how to choose the required resistance amount and rated-standard electricity of dummy resistance.

<Example>

- How to calculate the dummy resistance amount (at 24VDC)

Calculation: $R = V \div I = 24V \div 35mA = 680 \Omega$

- How to calculate rated-standard electricity (at 24VDC)

Calculation: $P_1 = V \times I = 24V \times 35mA = 0.84W$ (approximately 1W)

Calculation including a margin: $P_2 = P_1 \times 2 = 0.84 \times 2 = 1.68W$ (approximately 2W)

Result: Install dummy resistance of 680Ω (/2W) in between the pulse input terminals.

(2) When the coincidence output function does not perform normal operation

(a) When Coincidence output 1 to 4 (RX10 to RX13) do not turn on

Check item	Action
Are Coincidence output 1 to 4 assigned properly?	Review the setting in Coincidence output channel assignment setting (address: 0101 _H).
Are the comparison conditions for Coincidence output 1 to 4 proper?	Review the setting in Coincidence output comparison condition setting (address: 0102 _H).
Is Initial data setting request flag (RY9) or Setting change request (Coincidence output 1 to 4) (RY14 to RY17) turned on after changing Point setting (Coincidence output 1)/Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) to Upper limit value setting (Coincidence output 4) (RWwE to RWwF)?	Turn on Initial data setting request flag (RY9) or Setting change request (Coincidence output 1 to 4) (RY14 to RY17) after changing Point setting (Coincidence output 1)/Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) to Upper limit value setting (Coincidence output 4) (RWwE to RWwF).
Is Reset command (Coincidence output 1 to 4) (RY10 to RY13) off? (Only when Coincidence output is selected as the comparison condition)	Turn off Reset command (Coincidence output 1 to 4) (RY10 to RY13).
Are the settings in Point setting (Coincidence output 1)/Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) to Upper limit value setting (Coincidence output 4) (RWwE to RWwF) within the count range of the ring counter when the counter format is the ring counter?	Set Point setting (Coincidence output 1)/Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) to Upper limit value setting (Coincidence output 4) (RWwE to RWwF) within the count range of the ring counter.

(b) When Coincidence output 1 to 4 (RX10 to RX13) does not turn off

Check item	Action
Is the ON time of Reset command (Coincidence output 1 to 4) (RY10 to RY13) ΔT_1 ^{*1} or longer? (Only when Coincidence output is selected as the comparison condition)	Set the ON time of Reset command (Coincidence output 1 to 4) (RY10 to RY13) to ΔT_1 ^{*1} or longer. (☞ Page 249, Appendix 1.2)

*1 For ΔT_1 , refer to the following.

☞ Page 283, Appendix 4

(c) When only Coincidence output 1 to 4 terminals (EQU1 to EQU4) do not turn on

Check item	Action
Is CH□ Coincidence output enable command (RY20, RY38) on?	Turn on CH□ Coincidence output enable command (RY20, RY38).
Is the external wiring to Coincidence output 1 to 4 terminals (EQU1 to EQU4) correct?	Check the external wiring and correct errors.

(d) When the count value cannot be replaced with a preset value by the preset/replace (at coincidence output) function

Check item	Action
Is CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) off?	Turn off CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) by turning on CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B). Note that the ON/OFF time of CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B) must be ΔT_1^{*1} or longer. (☞ Page 249, Appendix 1.2)
Is Preset/replace setting at coincidence output (address: 0103 _H) set to "Present value replaced (1)"?	Set Preset/replace setting at coincidence output (address: 0103 _H) to Present value replaced (1).
Is Coincidence output 1 to 4 (RX10 to RX13) off?	This function replaces the count value with the preset value at the rising edge (OFF to ON) of Coincidence output 1 to 4 (RX10 to RX13). Turn off Coincidence output 1 to 4 (RX10 to RX13) before replacing the value.
Is the interval between every execution of this function ΔT_1^{*1} or longer?	Set the interval of ΔT_1^{*1} or longer between every execution of this function referring to the following. ☞ Page 114, Section 8.3.3
Is the interval of ΔT_1^{*1} or longer taken between change in the setting in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) and the execution of preset?	Set the interval of ΔT_1^{*1} or longer between change in the setting in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) and the execution of preset.

*1 For ΔT_1 , refer to the following.

☞ Page 283, Appendix 4

(3) When the cam switch function does not perform normal operation

(a) When Cam switch output signal (RWr2) does not turn on or off

Check item	Action
Is the cam switch output assigned properly?	Review the settings in Cam switch output unit assignment setting (address: 0104 _H) and Cam switch output channel assignment setting (address: 0105 _H).
For the step setting, is the minimum setting width of the ON/OFF status proper?	Review the minimum setting width of the ON/OFF status referring to the following. ☞ Page 117, Section 8.3.4
Is the step setting within the count range of the ring counter when the counter format is the ring counter?	Review the step setting and set steps within the count range of the ring counter.

(b) When only the output (Y0 to YF) of the extension output module does not turn on

Check item	Action
Is the external power supply for the extension output module on?	Turn on the external power supply for the extension output module.
Is the external wiring at the output terminal of the extension output module correct?	Check the external wiring and correct errors.

(4) When the count value cannot be replaced with a value preset by the user

(a) When the preset/replace function by CH□ Preset/replace command (RY21, RY39) cannot be performed

Check item	Action
Is CH□ Preset/replace completion (RX21, RX39) used as an interlock?	Turn on or off CH□ Preset/replace command (RY21, RY39) using CH□ Preset/replace completion (RX21, RX39) as an interlock.
Is CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) off?	Turn off CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) by turning on CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B). Note that the ON/OFF time of CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B) must be ΔT_1 ^{*1} or longer. (☞ Page 249, Appendix 1.2)

*1 For ΔT_1 , refer to the following.

☞ Page 283, Appendix 4

(b) When the preset/replace function by CH□ Phase Z input terminal (Z1, Z2) cannot be performed

Check item	Action
Is the external wiring to CH□ Phase Z input terminal (Z1, Z2) correct?	Check the external wiring and correct errors.
Is the interval of ΔT_1 ^{*1} or longer taken between change in the setting in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) and the execution of preset?	Set the interval of ΔT_1 ^{*1} or longer between change in the setting in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) and the execution of preset.
Is CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) off?	Turn off CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) by turning on CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B). Note that the ON/OFF time of CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B) must be ΔT_1 ^{*1} or longer. (☞ Page 249, Appendix 1.2)

*1 For ΔT_1 , refer to the following.

☞ Page 283, Appendix 4

(c) When the preset/replace function by CH□ Function input terminal (FUNC1, FUNC2) cannot be performed

Check item	Action
Is the external wiring to CH□ Function input terminal (FUNC1, FUNC2) correct?	Check the external wiring and correct errors.
Is the interval of ΔT_1 ^{*1} or longer taken between change in the setting in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) and the execution of preset?	Set the interval of ΔT_1 ^{*1} or longer between change in the setting in CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) and the execution of preset.
Is CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) off?	Turn off CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) by turning on CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B). Note that the ON/OFF time of CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B) must be ΔT_1 ^{*1} or longer. (☞ Page 249, Appendix 1.2)

*1 For ΔT_1 , refer to the following.

☞ Page 283, Appendix 4

(5) When the counter function selection cannot be performed

(a) When turning on CH□ Selected counter function start command (RY25, RY3D) does not perform the counter function selection

Check item	Action
Does the selected function apply to CH□ Selected counter function start command (RY25, RY3D)?	Check referring to the following. Page 129, Section 8.6
If the selected function is one that starts to work at the rising edge (OFF to ON) of CH□ Selected counter function start command (RY25, RY3D), is CH□ Counter function detection (RX25, RX3D) used as an interlock?	Turn on or off CH□ Selected counter function start command (RY25, RY3D) using CH□ Counter function detection (RX25, RX3D) as an interlock.
Is CH□ Function input terminal (FUNC1, FUNC2) off?	Turn off CH□ Function input terminal (FUNC1, FUNC2).

(b) When the input from CH□ Function input terminal (FUNC1, FUNC2) does not perform the counter function selection

Check item	Action
Is the external wiring to CH□ Function input terminal (FUNC1, FUNC2) correct?	Check the external wiring and correct errors.
Is CH□ Selected counter function start command (RY25, RY3D) off?	Turn off CH□ Selected counter function start command (RY25, RY3D).

11.5.2 When the setting on the operation mode setting is the frequency measurement mode

(1) When the module does not measure or perform normal measurement

 Page 228, Section 11.5.1 (1)

11.5.3 When the setting on the operation mode setting is the rotation speed measurement mode

(1) When the module does not measure or perform normal measurement

 Page 228, Section 11.5.1 (1)

11.5.4 When the setting on the operation mode setting is the pulse measurement mode

(1) When the module does not measure or perform normal measurement

(a) When the module does not measure

Check item	Action
Does the CPU module indicate any error?	If an error is indicated with the CPU module, refer to troubleshooting on the user's manual for the CPU module used.
Is CH□ Pulse measurement start command (Function input terminal) (RY30, RY48) or CH□ Pulse measurement start command (Latch counter input terminal) (RY32, RY4A), the signal corresponding to the terminal to be measured, turned on?	Turn on the signal corresponding to the terminal to be measured, CH□ Pulse measurement start command (Function input terminal) (RY30, RY48) or CH□ Pulse measurement start command (Latch counter input terminal) (RY32, RY4A).
Are the external wirings to CH□ Function input terminal (FUNC1, FUNC2) and CH□ Latch counter input terminal (LATCH1, LATCH2) correct?	Check the external wiring and correct errors.

(b) When the module does not measure normally

Check item	Action
Measures against noise	Are the shielded twisted pair cables used for pulse input wiring?
	Are measures against noise taken for the adjacent devices and inside the control panel?
	Is the distance between the high voltage equipment and pulse input line kept enough?
	Does any noise come from the grounded part of the high-speed counter module?
Does a program used read out the 2-word data such as a measured pulse value in unit of 2 words (32 bits)?	Read out it in unit of 2 words (32 bits).

11.5.5 When the setting on the operation mode setting is the PWM output mode

(1) When the module does not perform normally

Check item	Action	
Does the CPU module indicate any error?	If an error is indicated with the CPU module, refer to troubleshooting on the user's manual for the CPU module used.	
Are Coincidence output 1 to 4 assigned properly?	Review the setting in Coincidence output channel assignment setting (address: 0101 _H) and CH□ PWM output assignment setting (RWw1D, RWw35).	
Is the external wiring to Coincidence output 1 to 4 terminals (EQU1 to EQU4) correct?	Check the external wiring and correct errors.	
Is a resistive load connected to the coincidence output 1 to 4 terminals (EQU1 to EQU4)?	Connect a resistive load since the output waveform is highly distorted by connecting a load other than a resistive load.	
Measures against noise	Are the shielded twisted pair cables used for PWM output wiring?	Use the shielded twisted pair cables for PWM output wiring.
	Are measures against noise taken for the adjacent devices and inside the control panel?	Take noise reduction measures such as attaching a CR surge suppressor to the magnet switch.
	Is the distance between the high voltage equipment and PWM output line kept enough?	Bundle up the PWM output lines in a single tube, and keep a distance of 150mm or more between the PWM output lines and the power line even inside the control panel.
	Does any noise come from the grounded part of the high-speed counter module?	Separate the grounding cable of the high-speed counter module from the grounded part. If the case of the high-speed counter module touches the grounded part, separate it.

APPENDICES

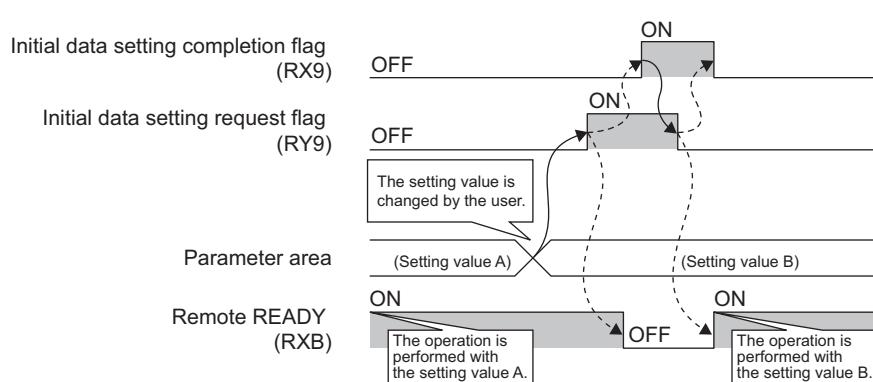
Appendix 1 Details of Remote I/O Signals

Appendix 1.1 Details of remote input signals

The following shows details of remote input signals.

Remote input (RX) No.	Signal name	Description
RX7	Warning status flag	<p>• This signal turns on when CH□ Warning status (RX37, RX4F) turns on. • This signal turns off when CH□ Warning status (RX37, RX4F) turns off.</p> <p>-----> Controlled by the high-speed counter module -----> Controlled by the program</p> <p>CH1 Error reset command (RY36) OFF ON</p> <p>Remote READY (RXB) ON</p> <p>CH1 Latest warning code (RW23) 0 1050H 0</p> <p>CH1 Warning status (RX37) ON OFF ON OFF</p> <p>CH2 Warning status (RX4F) ON OFF</p> <p>Warning status flag (RX7) OFF ON</p> <p>*1 This signal cannot be reset arbitrarily by output signals such as CH□ Error reset command (RY36, RY4E) depending on warning codes (error codes of minor errors). For details, refer to Page 208, Section 11.2.</p>

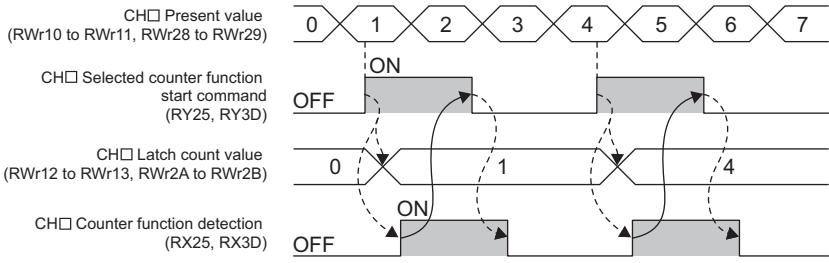
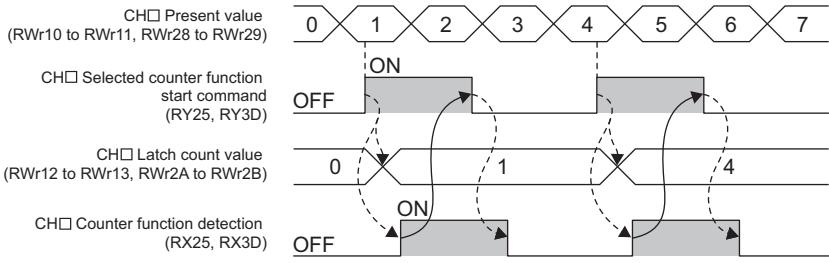
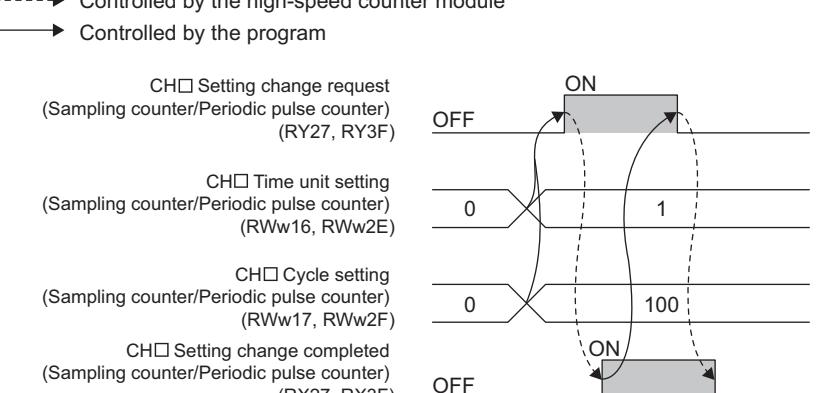
Remote input (RX) No.	Signal name	Description
RX8	Initial data processing request flag	<ul style="list-style-type: none"> After the module is powered on or the remote reset is performed, this signal turns on to let the high-speed counter module request the initial setting. When this signal is on, set initial data to the remote register (RWw) and turn on Initial data processing completion flag (RY8). To change the setting in the parameter area of the remote buffer memory as well, change the setting in the parameter area, enable the setting values by turning on Initial data setting request flag (RY9), then turn on Initial data processing completion flag (RY8). While this signal is on, the high-speed counter module does not count pulses. <p>This signal turns off in the following case.</p> <ul style="list-style-type: none"> Initial data processing completion flag (RY8) is turned on when all setting values of the remote register (RWw) and the remote buffer memory are normal. <p>This signal turns on in the following case.</p> <ul style="list-style-type: none"> After the module is powered on or the remote reset is performed <p>-----→ Controlled by the high-speed counter module → Controlled by the program</p> <p>Module power supply ON OFF</p> <p>Initial data processing request flag (RX8) OFF ON OFF</p> <p>Initial data processing completion flag (RY8) OFF ON OFF</p> <p>Initial data setting completion flag (RX9) OFF ON OFF</p> <p>Initial data setting request flag (RY9) OFF ON OFF</p> <p>Parameter area (Setting value A) (Setting value B) Parameter settings are read from the internal nonvolatile memory. The setting value is changed by the user.</p> <p>Remote READY (RXB) OFF ON OFF</p> <p>The operation is set with the setting value B. The operation is set with the setting value A.</p> <ul style="list-style-type: none"> After checking that the initial data processing is completed (this signal turns off) and Initial data setting completion flag (RX9) turns off, turn on CH\square Count enable command (RY24, RY3C) to start pulse counting. Remote output signals other than CH\square Error reset command (RY36, RY4E) that are already turned on when this signal turns off are recognized as they are turned on right after this signal turns off. At the rising state of either of Coincidence output 1 or Coincidence output 2 for which the preset/replace (at coincidence output) function is enabled from the comparison result at when this signal turns off, the count value is replaced with the preset value. (However, this operation is performed only when Comparison output setting (address: 0100_H) is set to Coincidence Output Function (0) and CH\square Operation mode setting (address: 0120_H, 0140_H) is set to Normal Mode (0).) If an error occurs, such as when a value out of the setting range of the remote register (RWw) or the remote buffer memory is detected, this signal does not turn off even if Initial data processing completion flag (RY8) is turned off. (This signal remains on.) In this case, remove the error cause and turn on then off Initial data processing completion flag (RY8). In addition, the OFF time must be longer than ΔT_1.^{*1} <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>

Remote input (RX) No.	Signal name	Description
RX9	Initial data setting completion flag	<p>This signal is used as an interlock for turning on/off Initial data setting request flag (RY9) when the setting values in the parameter area of the remote buffer memory are changed or the setting values of the extended parameter area are saved into the nonvolatile memory.</p> <ul style="list-style-type: none"> While this signal is on, the high-speed counter module does not count pulses. <p>This signal turns off in the following cases.</p> <ul style="list-style-type: none"> Until Initial data setting request flag (RY9) is turned on after the module is powered on Initial data setting request flag (RY9) is turned off when the setting values in the parameter area of the remote buffer memory are normal. <p>This signal turns on in the following case.</p> <ul style="list-style-type: none"> When Initial data setting request flag (RY9) is turned on <p>Controlled by the high-speed counter module Controlled by the program</p>  <ul style="list-style-type: none"> Initial data setting completion flag (RX9): ON during initial data setting, OFF when completed. Initial data setting request flag (RY9): ON when RX9 is ON. Parameter area: Shows two setting values, A and B, which are swapped during the process. Remote READY (RXB): ON during initial data setting, OFF when completed. <p>After checking that the initial data setting processing is completed (this signal turns off) and Initial data processing request flag (RX8) turns off, turn on CH□ Count enable command (RY24, RY3C) to start pulse counting.</p> <ul style="list-style-type: none"> Remote output signals other than CH□ Error reset command (RY36, RY4E) that are already turned on when this signal turns off are recognized as they are turned on right after this signal turns off. When Initial data processing request flag (RX8) is off and at the rising state of either of Coincidence output 1 or Coincidence output 2 for which the preset/replace (at coincidence output) function is enabled from the comparison result at when this signal turns off, the count value is replaced with the preset value. (However, this operation is performed only when Comparison output setting (address: 0100_H) is set to Coincidence Output Function (0) and CH□ Operation mode setting (address: 0120_H, 0140_H) is set to Normal Mode (0).) If an error occurs, such as when a value out of the setting range of the remote register (RWw) or the remote buffer memory is detected, this signal does not turn off even if Initial data setting request flag (RY9) is turned off. (This signal remains on.) In this case, remove the error cause and turn on then off Initial data setting request flag (RY9). In addition, the OFF time must be longer than ΔT_1.¹ <p>¹ For ΔT_1, refer to Page 283, Appendix 4.</p>

Remote input (RX) No.	Signal name	Description
RXA	Error status flag	<ul style="list-style-type: none"> This signal turns on when CH□ Error status (RX36, RX4E) turns on. This signal turns off when CH□ Error status (RX36, RX4E) turns off. <p>→ Controlled by the high-speed counter module → Controlled by the program</p> <p>CH1 Error reset command (RY36) → ON → OFF → ON</p> <p>Remote READY (RXB) → ON → OFF → ON</p> <p>CH1 Latest error code (RW22) → 0 → 1200H → 0</p> <p>CH1 Error status (RX36) → OFF → ON → OFF → ON</p> <p>CH2 Error status (RX4E) → ON → OFF</p> <p>Error status flag (RXA) → OFF → ON → OFF → ON</p>
RXB	Remote READY	<ul style="list-style-type: none"> This signal turns on when the initial data setting processing is completed after the module is powered on or the remote reset is performed. This signal turns on after Initial data processing request flag (RX8) turns off. This signal turns on when Initial data processing request flag (RX8) is off and Initial data setting completion flag (RX9) is turned off. This signal turns off when Error status flag (RXA) turns on. This signal can be used as an interlock of programs. <p>(For the overview of the operation, refer to the descriptions of Initial data processing request flag (RX8), Initial data setting completion flag (RX9), and Error status flag (RXA).)</p>
RX10	Coincidence output 1	<ul style="list-style-type: none"> This signal turns on when the comparison condition of CH□ Present value (RW10 to RW11, RW28 to RW29) is satisfied in the coincidence output function. (For details of the ON/OFF conditions of this signal, refer to Page 103, Section 8.3.2.) The ON condition can be changed with Coincidence output comparison condition setting (address: 0102H).
RX11	Coincidence output 2	<p>Ex. For within-range output operation</p> <p>→ Controlled by the high-speed counter module</p> <p>Point setting (Coincidence output 1 to 4)/ Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD)</p> <p>Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF)</p> <p>Coincidence output 1 to 4 (RX10 to RX13)</p> <p>CH□ Present value (RW10 to RW11, RW28 to RW29)</p> <p>1000</p> <p>2000</p> <p>ON → OFF → ON</p> <p>0 → 1 → 999 → 1000 → 2000 → 2001 → ...</p>
RX12	Coincidence output 3	
RX13	Coincidence output 4	<ul style="list-style-type: none"> Up to ΔT_1^{*1} delay occurs until this signal turns on after the comparison conditions of CH□ Present value (RW10 to RW11, RW28 to RW29) are satisfied in the coincidence output function. <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>

Remote input (RX) No.	Signal name	Description
RX14	Setting change completed (Coincidence output 1)	<ul style="list-style-type: none"> This signal turns on when the changes of the following remote registers (RWw) are reflected to the high-speed counter module in the coincidence output function. Point setting (Coincidence output 1 to 4)/Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD) Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF) <p>For Coincidence output 1, Setting change completed (Coincidence output 1) (RX14) turns on after the changes of Point setting (Coincidence output 1)/Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) and Upper limit value setting (Coincidence output 1) (RWw2 to RWw3) are reflected to the high-speed counter module by Setting change request (Coincidence output 1) (RY14).</p> <p>For Coincidence output 1, Setting change completed (Coincidence output 1) (RX14) turns off when Setting change request (Coincidence output 1) (RY14) is turned off.</p> <p>For Coincidence output 2 to 4, each corresponding remote I/O signals and remote register (RWw) are used.</p>
RX15	Setting change completed (Coincidence output 2)	
RX16	Setting change completed (Coincidence output 3)	<p>-----→ Controlled by the high-speed counter module → Controlled by the program</p> <p>Setting change request (Coincidence output 1 to 4) (RY14 to RY17)</p> <p>Point setting (Coincidence output 1 to 4)/Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD)</p> <p>Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF)</p> <p>Setting change completed (Coincidence output 1 to 4) (RX14 to RX17)</p>
RX17	Setting change completed (Coincidence output 4)	
RX1F	External power supply monitor state flag	<ul style="list-style-type: none"> This signal turns on when the external power supply monitoring function is enabled by turning on External power supply monitor request flag (RY1F). This signal turns off when the external power supply monitoring function is disabled by turning off External power supply monitor request flag (RY1F). <p>-----→ Controlled by the high-speed counter module</p> <p>External power supply monitor request flag (RY1F)</p> <p>External power supply monitoring function</p> <p>External power supply monitor state flag (RX1F)</p>

Remote input (RX) No.	Signal name	Description
RX21	CH1	<ul style="list-style-type: none"> This signal turns on when the preset is completed by turning on CH□ Preset/replace command (RY21, RY39). This signal turns off when CH□ Preset/replace command (RY21, RY39) is turned off. <p>-----> Controlled by the high-speed counter module —> Controlled by the program</p> <p>CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) </p> <p>CH□ Preset/replace command (RY21, RY39) </p> <p>CH□ Preset/replace completion (RX21, RX39) </p> <p>CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) </p> <ul style="list-style-type: none"> Up to ΔT_1^{*1} delay occurs until this signal turns on after the preset is completed. <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>
RX39	CH2	
RX23	CH1	<ul style="list-style-type: none"> This signal turns on when a count value is replaced with the preset value by CH□ Phase Z input terminal (Z1, Z2). Note that this signal does not turn on when Z phase (Preset) trigger setting (address: 0125_H.b0 to b1, 0145_H.b0 to b1) in CH□ Phase Z setting (address: 0125_H, 0145_H) is set to During ON (11). This signal turns off when CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B) is turned on. The value is not replaced while this signal is on. Note that this signal does not turn on when External preset/replace (Z Phase) request detection setting (address: 0125_H.b4, 0145_H.b4) in CH□ Phase Z setting (address: 0125_H, 0145_H) is set to Not ON at detection (1). This signal turns on only when External preset/replace (Z Phase) request detection setting (address: 0125_H.b4, 0145_H.b4) is set to ON at detection (0). The following figure shows the case when Z phase (Preset) trigger setting (address: 0125_H.b0 to b1, 0145_H.b0 to b1) in CH□ Phase Z setting (address: 0125_H, 0145_H) is set to Rising (00). <p>-----> Controlled by the high-speed counter module —> Controlled by the program</p> <p>CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) </p> <p>CH□ Phase Z input terminal (Z1, Z2) </p> <p>CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) </p> <p>CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B) </p> <p>CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) </p> <ul style="list-style-type: none"> Up to ΔT_1^{*1} delay occurs until this signal turns on after the preset is completed. <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>
RX3B	CH2	<p>CH□ Preset value setting (RWw14 to RWw15, RWw2C to RWw2D) </p> <p>CH□ Phase Z input terminal (Z1, Z2) </p> <p>CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) </p> <p>CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B) </p> <p>CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) </p> <p>$t \geq \Delta T_1$</p> <ul style="list-style-type: none"> Up to ΔT_1^{*1} delay occurs until this signal turns on after the preset is completed. <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>

Remote input (RX) No.	Signal name	Description
RX25	CH1	<ul style="list-style-type: none"> This signal turns on when the counter function starts by turning on CH□ Selected counter function start command (RY25, RY3D). This signal turns off when CH□ Selected counter function start command (RY25, RY3D) is turned off. The following figure shows an operation example of when the latch counter function is performed. <p>-----→ Controlled by the high-speed counter module → Controlled by the program</p> 
RX3D	CH2	<p>CH□ Present value (RWr10 to RWr11, RWr28 to RWr29)</p> <p>CH□ Selected counter function start command (RY25, RY3D)</p> <p>CH□ Latch count value (RWr12 to RWr13, RWr2A to RWr2B)</p> <p>CH□ Counter function detection (RX25, RX3D)</p> 
RX26	CH1	<ul style="list-style-type: none"> This signal turns on when the cam switch function is started by turning on CH□ Cam switch execute command/PWM output start command (RY26, RY3E). This signal turns on when the PWM output is started by turning on CH□ Cam switch execute command/PWM output start command (RY26, RY3E). This signal turns off when CH□ Cam switch execute command/PWM output start command (RY26, RY3E) is turned off.
RX3E	CH2	
RX27	CH1	<ul style="list-style-type: none"> This signal turns on after the changes of CH□ Time unit setting (Sampling counter/Periodic pulse counter) (RWw16, RWw2E) and CH□ Cycle setting (Sampling counter/Periodic pulse counter) (RWw17, RWw2F) by CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) are reflected to the high-speed counter module. This signal turns off when CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned off. <p>-----→ Controlled by the high-speed counter module → Controlled by the program</p> 
RX3F	CH2	

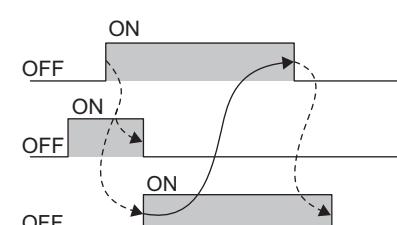
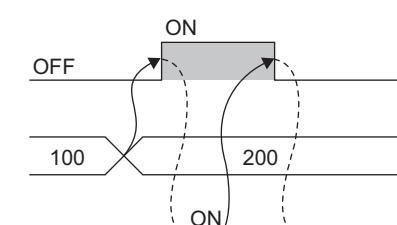
Remote input (RX) No.	Signal name	Description
RX28	CH1 Update flag reset completed (Latch count value)	<ul style="list-style-type: none"> This signal turns on when resetting CH□ Update flag (Latch count value) (RX29, RX41) by CH□ Update flag reset command (Latch count value) (RY28, RY40) is completed. This signal turns off when CH□ Update flag reset command (Latch count value) (RY28, RY40) is turned off. <p>-----→ Controlled by the high-speed counter module → Controlled by the program</p> <p>CH□ Update flag reset command (Latch count value) (RY28, RY40)</p> <p>CH□ Update flag (Latch count value) (RX29, RX41)</p> <p>CH□ Update flag reset completed (Latch count value) (RX28, RX40)</p>
RX40	CH2 Update flag reset completed (Sampling count value)	<ul style="list-style-type: none"> This signal turns on when resetting CH□ Update flag (Sampling count value) (RX29, RX41) by CH□ Update flag reset command (Sampling count value) (RY28, RY40) is completed. This signal turns off when CH□ Update flag reset command (Sampling count value) (RY28, RY40) is turned off. <p>(The operation is the same as that of CH□ Update flag reset completed (Latch count value) (RX28, RX40) except the signal name.)</p>
	CH2 Update flag reset completed (Periodic pulse count value)	<ul style="list-style-type: none"> This signal turns on when resetting CH□ Update flag (Periodic pulse count value) (RX29, RX41) by CH□ Update flag reset command (Periodic pulse count value) (RY28, RY40) is completed. This signal turns off when CH□ Update flag reset command (Periodic pulse count value) (RY28, RY40) is turned off. <p>(The operation is the same as that of CH□ Update flag reset completed (Latch count value) (RX28, RX40) except the signal name.)</p>

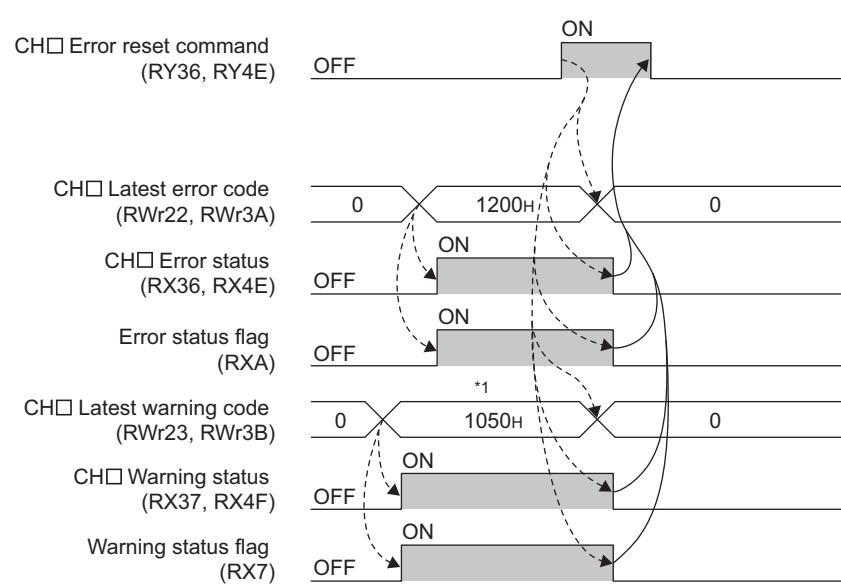
Remote input (RX) No.	Signal name		Description
RX29	CH1	Update flag (Latch count value)	<ul style="list-style-type: none"> This signal turns on when CH□ Latch count value (RW_r12 to RW_r13, RW_r2A to RW_r2B) is updated. ( Page 133, Section 8.8,  Page 145, Section 8.12) CH□ Latch count value (RW_r12 to RW_r13, RW_r2A to RW_r2B) is updated without resetting this flag. This signal turns off when CH□ Update flag reset command (Latch count value) (RY28, RY40) is turned on. Up to ΔT_1^{*1} delay occurs until this signal turns on after CH□ Latch count value (RW_r12 to RW_r13, RW_r2A to RW_r2B) is updated. (For the overview of the operation, refer to the description of CH□ Update flag reset completed (Latch count value) (RX28, RX40).) <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>
		Update flag (Sampling count value)	<ul style="list-style-type: none"> This signal turns on when CH□ Sampling count value (RW_r12 to RW_r13, RW_r2A to RW_r2B) is updated. ( Page 136, Section 8.9) CH□ Sampling count value (RW_r12 to RW_r13, RW_r2A to RW_r2B) is updated without resetting this flag. This signal turns off when CH□ Update flag reset command (Sampling count value) (RY28, RY40) is turned on. Up to ΔT_1^{*1} delay occurs until this signal turns on after CH□ Sampling count value (RW_r12 to RW_r13, RW_r2A to RW_r2B) is updated. (For the overview of the operation, refer to the description of CH□ Update flag reset completed (Sampling count value) (RX28, RX40).) <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>
RX41	CH2	Update flag (Periodic pulse count value)	<ul style="list-style-type: none"> This signal turns on when CH□ Periodic pulse count, difference value (RW_r12 to RW_r13, RW_r2A to RW_r2B), CH□ Periodic pulse count, present value (RW_r14 to RW_r15, RW_r2C to RW_r2D), and CH□ Periodic pulse count value update check (RW_r16 to RW_r17, RW_r2E to RW_r2F) are updated. ( Page 139, Section 8.10) CH□ Periodic pulse count, difference value (RW_r12 to RW_r13, RW_r2A to RW_r2B), CH□ Periodic pulse count, present value (RW_r14 to RW_r15, RW_r2C to RW_r2D), and CH□ Periodic pulse count value update check (RW_r16 to RW_r17, RW_r2E to RW_r2F) are updated without resetting this flag. This signal turns off when CH□ Update flag reset command (Periodic pulse count value) (RY28, RY40) is turned on. Up to ΔT_1^{*1} delay occurs until this signal turns on after CH□ Periodic pulse count, difference value (RW_r12 to RW_r13, RW_r2A to RW_r2B), CH□ Periodic pulse count, present value (RW_r14 to RW_r15, RW_r2C to RW_r2D), and CH□ Periodic pulse count value update check (RW_r16 to RW_r17, RW_r2E to RW_r2F) are updated. (For the overview of the operation, refer to the description of CH□ Update flag reset completed (Periodic pulse count value) (RX28, RX40).) <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>

Remote input (RX) No.	Signal name	Description
RX2A	CH1 Latch count value update flag reset completed (Latch counter input terminal)	<ul style="list-style-type: none"> This signal turns on when resetting CH\square Latch count value update flag (Latch counter input terminal) (RX2B, RX43) by CH\square Latch count value update flag reset command (Latch counter input terminal) (RY2A, RY42) is completed. This signal turns off when CH\square Latch count value update flag reset command (Latch counter input terminal) (RY2A, RY42) is turned off. <p>-----> Controlled by the high-speed counter module ————> Controlled by the program</p> <p>CH\square Latch count value update flag reset command (Latch counter input terminal) (RY2A, RY42)</p> <p>CH\square Latch count value update flag (Latch counter input terminal) (RX2B, RX43)</p> <p>CH\square Latch count value update flag reset completed (Latch counter input terminal) (RX2A, RX42)</p>
RX42	CH2	
RX2B	CH1 Latch count value update flag (Latch counter input terminal)	<ul style="list-style-type: none"> This signal turns on when CH\square Latch count value (Latch counter input terminal) (RWr18 to RWr19, RWr30 to RWr31) is updated. Refer to Page 127, Section 8.5 CH\square Latch count value (Latch counter input terminal) (RWr18 to RWr19, RWr30 to RWr31) is updated without resetting this flag. This signal turns off when CH\square Latch count value update flag reset command (Latch counter input terminal) (RY2A, RY42) is turned on. Up to ΔT_1^{*1} delay occurs until this signal turns on after CH\square Latch count value (Latch counter input terminal) (RWr18 to RWr19, RWr30 to RWr31) is updated. <p>(For the overview of the operation, refer to the description of CH\square Latch count value update flag reset completed (Latch counter input terminal) (RX2A, RX42).)</p> <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>
RX43	CH2	
RX2C	CH1	<ul style="list-style-type: none"> This signal turns on when resetting CH\square Update flag (Measured frequency value) (RX2D, RX45) by CH\square Update flag reset command (Measured frequency value) (RY2C, RY44) is completed. This signal turns off when CH\square Update flag reset command (Measured frequency value) (RY2C, RY44) is turned off.
RX44	CH2 Update flag reset completed (Measured frequency value)	<p>-----> Controlled by the high-speed counter module ————> Controlled by the program</p> <p>CH\square Update flag reset command (Measured frequency value) (RY2C, RY44)</p> <p>CH\square Update flag (Measured frequency value) (RX2D, RX45)</p> <p>CH\square Update flag reset completed (Measured frequency value) (RX2C, RX44)</p>
	CH2 Update flag reset completed (Measured rotation speed value)	<ul style="list-style-type: none"> This signal turns on when resetting CH\square Update flag (Measured rotation speed value) (RX2D, RX45) by CH\square Update flag reset command (Measured rotation speed value) (RY2C, RY44) is completed. This signal turns off when CH\square Update flag reset command (Measured rotation speed value) (RY2C, RY44) is turned off. <p>(The operation is the same as that of CH\square Update flag reset completed (Measured frequency value) (RX2C, RX44) except the signal name.)</p>

Remote input (RX) No.	Signal name		Description
RX2D	CH1	Update flag (Measured frequency value)	<ul style="list-style-type: none"> This signal turns on when CH□ Measured frequency value (RWr1A to RWr1B, RWr32 to RWr33) is updated. (☞ Page 148, Section 8.13) CH□ Measured frequency value (RWr1A to RWr1B, RWr32 to RWr33) is updated without resetting this flag. This signal turns off when CH□ Update flag reset command (Measured frequency value) (RY2C, RY44) is turned on. Up to ΔT_1^{*1} delay occurs until this signal turns on after CH□ Measured frequency value (RWr1A to RWr1B, RWr32 to RWr33) is updated. (For the overview of the operation, refer to the description of CH□ Update flag reset completed (Measured frequency value) (RX2C, RX44).)
		Update flag (Measured rotation speed value)	<ul style="list-style-type: none"> This signal turns on when CH□ Measured rotation speed value (RWr1A to RWr1B, RWr32 to RWr33) is updated. (☞ Page 152, Section 8.14) CH□ Measured rotation speed value (RWr1A to RWr1B, RWr32 to RWr33) is updated without resetting this flag. This signal turns off when CH□ Update flag reset command (Measured rotation speed value) (RY2C, RY44) is turned on. Up to ΔT_1^{*1} delay occurs until this signal turns on after CH□ Measured rotation speed value (RWr1A to RWr1B, RWr32 to RWr33) is updated. (For the overview of the operation, refer to the description of CH□ Update flag reset completed (Measured rotation speed value) (RX2C, RX44).)
RX45	CH2	Measured pulse value update flag reset completed (Function input terminal)	<ul style="list-style-type: none"> This signal turns on when resetting CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A) by CH□ Measured pulse value update flag reset command (Function input terminal) (RY31, RY49) is completed. This signal turns off when CH□ Measured pulse value update flag reset command (Function input terminal) (RY31, RY49) is turned off. <p>-----→ Controlled by the high-speed counter module → Controlled by the program</p>
		CH2	<p>CH□ Measured pulse value update flag reset command (Function input terminal) (RY31, RY49)</p> <p>CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A)</p> <p>CH□ Measured pulse value update flag reset completed (Function input terminal) (RX31, RX49)</p>
RX32	CH1	Measured pulse value update flag (Function input terminal)	<ul style="list-style-type: none"> This signal turns on when CH□ Measured pulse value (Function input terminal) (RWr1C to RWr1D, RWr34 to RWr35) is updated. CH□ Measured pulse value (Function input terminal) (RWr1C to RWr1D, RWr34 to RWr35) is updated without resetting this flag. This signal turns off when CH□ Measured pulse value update flag reset command (Function input terminal) (RY31, RY49) is turned on.
		CH2	<ul style="list-style-type: none"> Up to ΔT_1^{*1} delay occurs until this signal turns on after CH□ Measured pulse value (Function input terminal) (RWr1C to RWr1D, RWr34 to RWr35) is updated. (For the overview of the operation, refer to the description of CH□ Measured pulse value update flag reset completed (Function input terminal) (RX31, RX49).)

*1 For ΔT_1 , refer to Page 283, Appendix 4.

Remote input (RX) No.	Signal name	Description
RX33	CH1 Measured pulse value update flag reset completed (Latch counter input terminal)	<ul style="list-style-type: none"> This signal turns on when resetting CH□ Measured pulse value update flag (Latch counter input terminal) (RX34, RX4C) by CH□ Measured pulse value update flag reset command (Latch counter input terminal) (RY33, RY4B) is completed. This signal turns off when CH□ Measured pulse value update flag reset command (Latch counter input terminal) (RY33, RY4B) is turned off. <p>----→ Controlled by the high-speed counter module → Controlled by the program</p>
RX4B	CH2	<p>CH□ Measured pulse value update flag reset command (Latch counter input terminal) (RY33, RY4B)</p> <p>CH□ Measured pulse value update flag (Latch counter input terminal) (RX34, RX4C)</p> <p>CH□ Measured pulse value update flag reset completed (Latch counter input terminal) (RX33, RX4B)</p> 
RX34	CH1 Measured pulse value update flag (Latch counter input terminal)	<ul style="list-style-type: none"> This signal turns on when CH□ Measured pulse value (Latch counter input terminal) (RWr1E to RWr1F, RWr36 to RWr37) is updated. CH□ Measured pulse value (Latch counter input terminal) (RWr1E to RWr1F, RWr36 to RWr37) is updated without resetting this flag. This signal turns off when CH□ Measured pulse value update flag reset command (Latch counter input terminal) (RY33, RY4B) is turned on. Up to ΔT_1^{*1} delay occurs until this signal turns on after CH□ Measured pulse value (Latch counter input terminal) (RWr1E to RWr1F, RWr36 to RWr37) is updated. (For the overview of the operation, refer to the description of CH□ Measured pulse value update flag reset completed (Latch counter input terminal) (RX33, RX4B).) <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>
RX4C	CH2	
RX35	CH1 ON width setting change completed (PWM output)	<ul style="list-style-type: none"> This signal turns on when the changes of CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37) are reflected to the high-speed counter module by CH□ ON width setting change request (PWM output) (RY35, RY4D). This signal turns off when CH□ ON width setting change request (PWM output) (RY35, RY4D) is turned off. <p>----→ Controlled by the high-speed counter module → Controlled by the program</p>
RX4D	CH2	<p>CH□ ON width setting change request (PWM output) (RY35, RY4D)</p> <p>CH□ ON width setting (PWM output) (RWw1E to RWw1F, RWw36 to RWw37)</p> <p>CH□ ON width setting change completed (PWM output) (RX35, RX4D)</p> 

Remote input (RX) No.	Signal name	Description
RX36	CH1	<ul style="list-style-type: none"> This signal turns on when a moderate error or major error occurs on a channel corresponding to this signal. This signal turns off when CH□ Error reset command (RY36, RY4E) is turned on and no moderate error or major error newly occurs. <p>-----→ Controlled by the high-speed counter module → Controlled by the program</p>  <p>CH□ Error reset command (RY36, RY4E) OFF ON</p> <p>CH□ Error status (RX36, RX4E) 0 1200H 0</p> <p>Error status flag (RXA) OFF ON OFF</p> <p>CH□ Latest warning code (RW_r23, RW_r3B) 0 1050H 0</p> <p>CH□ Warning status (RX37, RX4F) OFF ON OFF</p> <p>Warning status flag (RX7) OFF ON OFF</p> <p>*1 This signal cannot be reset arbitrarily by output signals such as CH□ Error reset command (RY36, RY4E) depending on warning codes (error codes of minor errors). For details, refer to Page 208, Section 11.2.</p>
RX4E	CH2	<p>CH□ Latest error code (RW_r22, RW_r3A)</p> <p>CH□ Error status (RX36, RX4E)</p> <p>Error status flag (RXA)</p> <p>CH□ Latest warning code (RW_r23, RW_r3B)</p> <p>CH□ Warning status (RX37, RX4F)</p> <p>Warning status flag (RX7)</p>
RX37	CH1	<ul style="list-style-type: none"> This signal turns on when a minor error occurs on a channel corresponding to this signal. This signal turns off when CH□ Error reset command (RY36, RY4E) is turned on and no minor error newly occurs. Some warning codes (error codes of minor errors) cannot be reset by turning on CH□ Error reset command (RY36, RY4E). For details, refer to Page 208, Section 11.2.
RX4F	CH2	<ul style="list-style-type: none"> This signal turns off when no minor error newly occurs five seconds after a minor error occurred. (For the overview of the operation, refer to the description of CH□ Error status (RX36, RX4E).) However, this signal may not turn off even after five seconds depending on warning codes (error codes of minor errors). For details, refer to Page 208, Section 11.2.

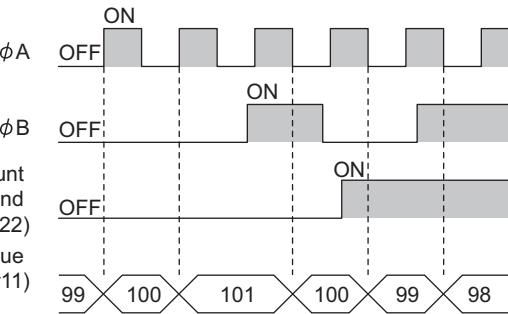
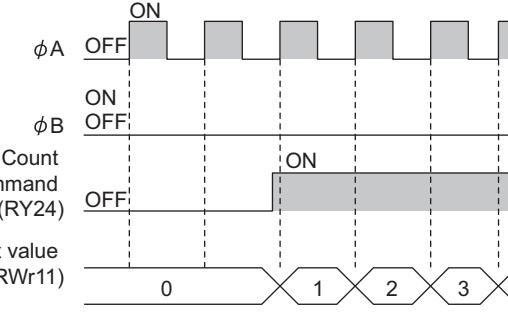
Appendix 1.2 Details of remote output signals

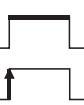
The following shows details of remote output signals.

Remote output (RY) No.	Signal name	Operation timing	Description
RY8	Initial data processing completion flag		<ul style="list-style-type: none"> This signal is turned on when initial data processing has been completed after the module is powered on, the remote reset is performed, or parameters are initialized. When this signal is turned on, the high-speed counter module starts counting regarding the content of the remote register (RWw) as the initial value. (For the overview of the operation, refer to Page 236, Appendix 1.1.)
RY9	Initial data setting request flag		<ul style="list-style-type: none"> Turn on this signal to activate the setting data in the parameter area of the remote buffer memory. Turn on this signal to save the setting values of the extended parameter area into the nonvolatile memory. When this signal is turned on, the setting values in the parameter area of the remote buffer memory are reflected to the inside of the module. In addition, the setting values of the extended parameter area are saved into the nonvolatile memory. When this signal is turned on, all the following remote input signals turn off. <div style="border: 1px solid black; padding: 5px;"> <ul style="list-style-type: none"> • Warning status flag (RX7) • Error status flag (RXA) • Remote READY (RXB) • Coincidence output 1 to 4 (RX10 to RX13) • Setting change completed (Coincidence output 1 to 4) (RX14 to RX17) • CH□ Preset/replace completion (RX21, RX39) • CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) • CH□ Counter function detection (RX25, RX3D) • CH□ Cam switch execute/PWM output (RX26, RX3E) • CH□ Setting change completed (Sampling counter/Periodic pulse counter) (RX27, RX3F) • CH□ Update flag reset completed (Latch count value/Sampling count value/Periodic pulse count value) (RX28, RX40) • CH□ Update flag (Latch count value/Sampling count value/Periodic pulse count value) (RX29, RX41) • CH□ Latch count value update flag reset completed (Latch counter input terminal) (RX2A, RX42) • CH□ Latch count value update flag (Latch counter input terminal) (RX2B, RX43) • CH□ Update flag reset completed (Measured frequency value/Measured rotation speed value) (RX2C, RX44) • CH□ Update flag (Measured frequency value/Measured rotation speed value) (RX2D, RX45) • CH□ Measured pulse value update flag reset completed (Function input terminal) (RX31, RX49) • CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A) • CH□ Measured pulse value update flag reset completed (Latch counter input terminal) (RX33, RX4B) • CH□ Measured pulse value update flag (Latch counter input terminal) (RX34, RX4C) • CH□ ON width setting change completed (PWM output) (RX35, RX4D) • CH□ Error status (RX36, RX4E) • CH□ Warning status (RX37, RX4F) • External input signals of the extension input module (RX50 to RX5F) </div>

Remote output (RY) No.	Signal name	Operation timing	Description
RY9	Initial data setting request flag		<ul style="list-style-type: none"> When this signal is turned on, all the remote registers (RW_r) of the high-speed counter module are cleared to 0. When this signal is turned on, all the following remote buffer memory areas are cleared to 0. <ul style="list-style-type: none"> Channel assignment (Coincidence output 1 to 4) (address: 0600_H) CH□ Operation mode (address: 0620_H, 0640_H) CH□ Selected counter function (address: 0621_H, 0641_H) <p>For details of the ON/OFF timing of this signal, refer to Page 236, Appendix 1.1.</p>
RY10	Reset command (Coincidence output 1)		<ul style="list-style-type: none"> Turn on this signal to turn off Coincidence output 1 to 4 (RX10 to RX13) and coincidence output 1 to 4 terminals (EQU1 to EQU4). This signal is valid only when Coincidence Output Function (0) is selected in Comparison output setting (address: 0100_H) and Coincidence Output (00) is selected in Coincidence output comparison condition setting (address: 0102_H).
RY11	Reset command (Coincidence output 2)		<p>-----> Controlled by the high-speed counter module —> Controlled by the program</p>
RY12	Reset command (Coincidence output 3)		<p>Point setting (Coincidence output 1 to 4) (RW_w0 to RW_w1, RW_w4 to RW_w5, RW_w8 to RW_w9, RW_wC to RW_wD)</p> <p>Coincidence output 1 to 4 (RX10 to RX13)</p> <p>Reset command (Coincidence output 1 to 4) (RY10 to RY13)</p> <p>CH□ Present value (RW_r10 to RW_r11, RW_r28 to RW_r29)</p>
RY13	Reset command (Coincidence output 4)		<p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p>
RY14	Setting change request (Coincidence output 1)		<ul style="list-style-type: none"> Turn on this signal to reflect the changes of the following remote registers (RW_w) to the high-speed counter module in the coincidence output function. Point setting (Coincidence output 1 to 4)/Lower limit value setting (Coincidence output 1 to 4) (RW_w0 to RW_w1, RW_w4 to RW_w5, RW_w8 to RW_w9, RW_wC to RW_wD) Upper limit value setting (Coincidence output 1 to 4) (RW_w2 to RW_w3, RW_w6 to RW_w7, RW_wA to RW_wB, RW_wE to RW_wF) For Coincidence output 1, when Setting change request (Coincidence output 1) (RY14) is turned on, the changes of Point setting (Coincidence output 1)/Lower limit value setting (Coincidence output 1) (RW_w0 to RW_w1) and Upper limit value setting (Coincidence output 1) (RW_w2 to RW_w3) are reflected to the high-speed counter module. After the setting value is reflected, Setting change completed (Coincidence output 1) (RX14) turns on. For Coincidence output 2 to 4, each corresponding remote I/O signals and remote register (RW_w) are used. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY15	Setting change request (Coincidence output 2)		
RY16	Setting change request (Coincidence output 3)		
RY17	Setting change request (Coincidence output 4)		
RY1F	External power supply monitor request flag		<p>Turn on this signal to activate the external power supply monitoring function.</p> <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY20	CH1		<ul style="list-style-type: none"> Turn on this signal to enable output to coincidence output 1 to 4 terminals (EQU1 to EQU4) in the coincidence output function. This signal is valid to all the coincidence output 1 to 4 terminals (EQU1 to EQU4) assigned to the channel.
RY38	CH2		<ul style="list-style-type: none"> Up to ΔT_1*1 is taken until this signal has been turned on.

*1 For ΔT_1 , refer to Page 283, Appendix 4.

Remote output (RY) No.	Signal name	Operation timing	Description
RY21	CH1		<ul style="list-style-type: none"> Turn on this signal to replace a count value with the preset value. The value cannot be replaced by turning on this signal while CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) is on. Turn off CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) by using CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B). <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY39	CH2	Preset/replace command	 <ul style="list-style-type: none"> Turn on this signal to count down pulses. This signal is valid when 1-Phase Multiple of 1 (0) or 1-Phase Multiple of 2 (1) is selected for CH□ Pulse input mode (address: 0122_H, 0142_H). Inputting pulse in phase B can also start counting down pulses. The following figure shows the overview of the operation (when 1-Phase Multiple of 1 (0) is selected for CH1 Pulse input mode (address: 0122_H)). Up to ΔT_1^{*1} is taken until this signal has been turned on.
RY22	CH1		 <p>*1 For ΔT_1, refer to Page 283, Appendix 4.</p> <p>CH1 Count down command (RY22)</p> <p>CH1 Present value (RW_r10 to RW_r11)</p> 
RY3A	CH2	Count down command	
RY23	CH1	External preset/replace (Z Phase) request	 <ul style="list-style-type: none"> Turn on this signal to turn off CH□ External preset/replace (Z Phase) request detection (RX23, RX3B). A count value cannot be replaced with the preset value while CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) is on. For the overview of the operation, refer to Page 236, Appendix 1.1.
RY3B	CH2	request detection reset command	
RY24	CH1		 <ul style="list-style-type: none"> Turn on this signal to count pulses. The following figure shows the overview of the operation (when 1-Phase Multiple of 1 (0) is selected for CH1 Pulse input mode (address: 0122_H)).
RY3C	CH2	Count enable command	 <p>CH1 Count enable command (RY24)</p> <p>CH1 Present value (RW_r10 to RW_r11)</p> 

Remote output (RY) No.	Signal name		Operation timing	Description
RY25	CH1	Selected counter function start command		<ul style="list-style-type: none"> Turn on this signal to perform the selected counter functions. When Count Disable Function (0) or Periodic Pulse Counter Function (3) is selected for CH□ Counter function selection (address: 0126_H, 0146_H), this signal is valid while being on. When Sampling Counter Function (2) or Latch Counter Function (1) is selected for CH□ Counter function selection (address: 0126_H, 0146_H), this signal becomes valid at the rising edge (off to on). When Count disable/Preset/replace Function (4) or Latch counter/Preset/replace Function (5) is selected for CH□ Counter function selection (address: 0126_H, 0146_H), this signal is invalid. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY26	CH1	Cam switch execute command/PWM output start command		<ul style="list-style-type: none"> Turn on this signal to execute the cam switch function. Turn on this signal to start PWM output.
RY3E	CH2	Setting change request (Sampling counter/Periodic pulse counter)		<ul style="list-style-type: none"> Turn on this signal to activate the changes of CH□ Time unit setting (Sampling counter/Periodic pulse counter) (RWw16, RWw2E) and CH□ Cycle setting (Sampling counter/Periodic pulse counter) (RWw17, RWwF). When this signal is turned on, the setting values written into the above remote registers (RWw) are reflected to the high-speed counter module. After the setting values are reflected, CH□ Setting change completed (Sampling counter/Periodic pulse counter) (RX27, RX3F) turns on. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY27	CH1	Update flag reset command (Latch count value)		<ul style="list-style-type: none"> Turn on this signal to reset CH□ Update flag (Latch count value) (RX29, RX41). When this signal is turned on, CH□ Update flag (Latch count value) (RX29, RX41) turns off. After resetting is completed, CH□ Update flag reset completed (Latch count value) (RX28, RX40) turns on. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY28	CH1	Update flag reset command (Sampling count value)		<ul style="list-style-type: none"> Turn on this signal to reset CH□ Update flag (Sampling count value) (RX29, RX41). When this signal is turned on, CH□ Update flag (Sampling count value) (RX29, RX41) turns off. After resetting is completed, CH□ Update flag reset completed (Sampling count value) (RX28, RX40) turns on. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY40	CH2	Update flag reset command (Periodic pulse count value)		<ul style="list-style-type: none"> Turn on this signal to reset CH□ Update flag (Periodic pulse count value) (RX29, RX41). When this signal is turned on, CH□ Update flag (Periodic pulse count value) (RX29, RX41) turns off. After resetting is completed, CH□ Update flag reset completed (Periodic pulse count value) (RX28, RX40) turns on. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY2A	CH1	Latch count value update flag reset command (Latch counter input terminal)		<ul style="list-style-type: none"> Turn on this signal to reset CH□ Latch count value update flag (Latch counter input terminal) (RX2B, RX43). When this signal is turned on, CH□ Latch count value update flag (Latch counter input terminal) (RX2B, RX43) turns off. After resetting is completed, CH□ Latch count value update flag reset completed (Latch counter input terminal) (RX2A, RX42) turns on. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY42	CH2			

Remote output (RY) No.	Signal name	Operation timing	Description
RY2C	CH1	Update flag reset command (Measured frequency value)	 <ul style="list-style-type: none"> Turn on this signal to reset CH□ Update flag (Measured frequency value) (RX2D, RX45). When this signal is turned on, CH□ Update flag (Measured frequency value) (RX2D, RX45) turns off. After resetting is completed, CH□ Update flag reset completed (Measured frequency value) (RX2C, RX44) turns on. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY44	CH2	Update flag reset command (Measured rotation speed value)	 <ul style="list-style-type: none"> Turn on this signal to reset CH□ Update flag (Measured rotation speed value) (RX2D, RX45). When this signal is turned on, CH□ Update flag (Measured rotation speed value) (RX2D, RX45) turns off. After resetting is completed, CH□ Update flag reset completed (Measured rotation speed value) (RX2C, RX44) turns on. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY30	CH1	Pulse measurement start command (Function input terminal)	 <ul style="list-style-type: none"> Turn on this signal to start measuring pulses using CH□ Function input terminal (FUNC1, FUNC2). When this signal is turned on, the measurement of pulses using CH□ Function input terminal (FUNC1, FUNC2) starts. When the measurement starts, Operating (1) is set in CH□ Pulse measurement flag (Function input terminal) (RW_r20.b6, RW_r38.b6).
RY48	CH2		
RY31	CH1	Measured pulse value update flag reset command (Function input terminal)	 <ul style="list-style-type: none"> Turn on this signal to reset CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A). When this signal is turned on, CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A) turns off. After resetting is completed, CH□ Measured pulse value update flag reset completed (Function input terminal) (RX31, RX49) turns on. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY49	CH2		
RY32	CH1	Pulse measurement start command (Latch counter input terminal)	 <ul style="list-style-type: none"> Turn on this signal to start measuring pulses using CH□ Latch counter input terminal (LATCH1, LATCH2). When this signal is turned on, the measurement of pulses using CH□ Latch counter input terminal (LATCH1, LATCH2) starts. When the measurement starts, Operating (1) is set in CH□ Pulse measurement flag (Latch counter input terminal) (RW_r20.b7, RW_r38.b7).
RY4A	CH2		
RY33	CH1	Measured pulse value update flag reset command (Latch counter input terminal)	 <ul style="list-style-type: none"> Turn on this signal to reset CH□ Measured pulse value update flag (Latch counter input terminal) (RX34, RX4C). When this signal is turned on, CH□ Measured pulse value update flag (Latch counter input terminal) (RX34, RX4C) turns off. After resetting is completed, CH□ Measured pulse value update flag reset completed (Latch counter input terminal) (RX33, RX4B) turns on. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY4B	CH2		
RY35	CH1	ON width setting change request (PWM output)	 <ul style="list-style-type: none"> Turn on this signal to activate the changes of CH□ ON width setting (PWM output) (RW_w1E to RW_w1F, RW_w36 to RW_w37) during PWM output. When this signal is turned on, CH□ ON width setting (PWM output) (RW_w1E to RW_w1F, RW_w36 to RW_w37) is reflected to the high-speed counter module. After the setting values are reflected, CH□ ON width setting change completed (PWM output) (RX35, RX4D) turns on. <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY4D	CH2		
RY36	CH1	Error reset command	 <ul style="list-style-type: none"> Turn on this signal to reset CH□ Latest error code (RW_r22, RW_r3A) and CH□ Latest warning code (RW_r23, RW_r3B). <p>(For the overview of the operation, refer to Page 236, Appendix 1.1.)</p>
RY4E	CH2		

Remark

The figures in the operation timing indicate the following.



This signal is valid while being on.



This signal is valid at the rising edge (off to on).

Point

Set ΔT_1 or longer for the ON/OFF time of the remote output signals.

For ΔT_1 , refer to Page 283, Appendix 4.

Appendix 2 Details of Remote Registers

The following shows details of remote registers.

(1) Remote registers (RWr0 to RWr1)

Address (RWr)	Name	Description	Default																																																																
CH1	CH2																																																																		
0	Counter value greater/smaller signal	<ul style="list-style-type: none"> When the coincidence output function is selected and Coincidence output comparison condition setting (address: 0102_H) is set to "Coincidence Output (00)", this area stores the magnitude relation between the values in Point setting (Coincidence output 1 to 4) (RWr0 to RWr1, RWr4 to RWr5, RWr8 to RWr9, RWrC to RWrD) and CH□ Present value (RWr10 to RWr11, RWr28 to RWr29). <table border="1"> <tr> <td>b15</td><td>b14</td><td>b13</td><td>b12</td><td>b11</td><td>b10</td><td>b9</td><td>b8</td><td>b7</td><td>b6</td><td>b5</td><td>b4</td><td>b3</td><td>b2</td><td>b1</td><td>b0</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>Coincidence output 4</td><td>Coincidence output 3</td><td>Coincidence output 2</td><td>Coincidence output 1</td><td></td><td></td><td></td><td></td> </tr> <tr> <td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>-</td><td>Counter value greater</td><td>Counter value smaller</td><td>Counter value greater</td><td>Counter value smaller</td><td>Counter value greater</td><td>Counter value smaller</td><td>Counter value greater</td><td>Counter value smaller</td> </tr> <tr> <td colspan="8" style="text-align: center;">0 (fixed)</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td> </tr> </table> <p>Point setting (Coincidence output 1 to 4) > Present value ... Counter value greater: 0/Counter value smaller: 1 Point setting (Coincidence output 1 to 4) = Present value ... Counter value greater: 0/Counter value smaller: 0 Point setting (Coincidence output 1 to 4) < Present value ... Counter value greater: 1/Counter value smaller: 0</p> <ul style="list-style-type: none"> When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0	0	0	0	0	0	0	0	0	Coincidence output 4	Coincidence output 3	Coincidence output 2	Coincidence output 1					-	-	-	-	-	-	-	-	Counter value greater	Counter value smaller	Counter value greater	Counter value smaller	Counter value greater	Counter value smaller	Counter value greater	Counter value smaller	0 (fixed)																0000 _H
b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0																																																				
0	0	0	0	0	0	0	0	Coincidence output 4	Coincidence output 3	Coincidence output 2	Coincidence output 1																																																								
-	-	-	-	-	-	-	-	Counter value greater	Counter value smaller	Counter value greater	Counter value smaller	Counter value greater	Counter value smaller	Counter value greater	Counter value smaller																																																				
0 (fixed)																																																																			
1	EQU1 to EQU4 terminal status	<ul style="list-style-type: none"> This area stores the statuses of the coincidence output 1 to 4 terminals (EQU1 to EQU4). <table border="1"> <tr> <td>b15</td><td>b14</td><td>b13</td><td>b12</td><td>b11</td><td>b10</td><td>b9</td><td>b8</td><td>b7</td><td>b6</td><td>b5</td><td>b4</td><td>b3</td><td>b2</td><td>b1</td><td>b0</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>EQU4</td><td>EQU3</td><td>EQU2</td><td>EQU1</td> </tr> <tr> <td colspan="8" style="text-align: center;">0 (fixed)</td><td colspan="8" style="text-align: center;">0: OFF 1: ON</td> </tr> </table> <ul style="list-style-type: none"> When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0	0	0	0	0	0	0	0	0	0	0	0	0	EQU4	EQU3	EQU2	EQU1	0 (fixed)								0: OFF 1: ON								0000 _H																
b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0																																																				
0	0	0	0	0	0	0	0	0	0	0	0	EQU4	EQU3	EQU2	EQU1																																																				
0 (fixed)								0: OFF 1: ON																																																											

A

(2) Remote registers (RWr2 to RWr3)

Address (RWr)	Name	Description	Default
CH1	CH2		
2	Cam switch output signal	<ul style="list-style-type: none"> When the cam switch function is selected, this area stores the comparison result of "Cam switch function, step No.1 to No.16 setting (Output 1 to 16)" in the remote buffer memory and CH□ Present value (RWr10 to RWr11, RWr28 to RWr29). <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0 (16) (15) (14) (13) (12) (11) (10) (9) (8) (7) (6) (5) (4) (3) (2) (1)</p> <p>0: OFF 1: ON</p> <p>1) Cam switch status (Output 1) 2) Cam switch status (Output 2) : : 15) Cam switch status (Output 15) 16) Cam switch status (Output 16)</p> <ul style="list-style-type: none"> When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0000H
3	Cam switch output terminal status	<ul style="list-style-type: none"> This area stores the output terminal statuses of the extension output module assigned using the cam switch function. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0 (16) (15) (14) (13) (12) (11) (10) (9) (8) (7) (6) (5) (4) (3) (2) (1)</p> <p>0: OFF 1: ON</p> <p>1) Cam switch status (Output 1) 2) Cam switch status (Output 2) : : 15) Cam switch status (Output 15) 16) Cam switch status (Output 16)</p> <ul style="list-style-type: none"> When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0000H

(3) Remote registers (RWr10 to RWr17, RWr28 to RWr2F)

Address (RWr)		Item	Description	Default
CH1	CH2			
10	28	Present value	<ul style="list-style-type: none"> This area stores the counter present value. The update cycle of this area is ΔT_2.^{*1} When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0
11	29			
12	2A	Latch count value	<ul style="list-style-type: none"> This area stores the count value latched when the latch counter function (counter function selection) or the latch counter/preset/replace function is selected. (For the overview of the operation, refer to Page 133, Section 8.8 or Page 145, Section 8.12.) This area stores the value which is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) of when CH□ Function input terminal (FUNC1, FUNC2) or CH□ Selected counter function start command (RY25, RY3D) is input. When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0
13	2B	Sampling count value	<ul style="list-style-type: none"> This area stores the count values in the sampling period when the sampling counter function is selected. (For the overview of the operation, refer to Page 136, Section 8.9.) When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0
		Periodic pulse count, difference value	<ul style="list-style-type: none"> This area stores the count value per cycle time (the difference value) when the periodic pulse counter function is selected. (For the overview of the operation, refer to Page 139, Section 8.10.) When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	
14	2C	Periodic pulse count, present value	<ul style="list-style-type: none"> This area stores the value which is stored in CH□ Present value (RWr10 to RWr11, RWr28 to RWr29) after the cycle time elapsed when the periodic pulse counter function is selected. When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0
15	2D			
16	2E	Periodic pulse count value update check	<ul style="list-style-type: none"> This area stores the same value as the value in CH□ Periodic pulse count, difference value (RWr12 to RWr13, RWr2A to RWr2B) when the periodic pulse counter function is selected. When CH□ Periodic pulse count, difference value (RWr12 to RWr13, RWr2A to RWr2B) is not equivalent to CH□ Periodic pulse count value update check (RWr16 to RWr17, RWr2E to RWr2F), a data mismatch occurs. Read again CH□ Periodic pulse count, difference value (RWr12 to RWr13, RWr2A to RWr2B), CH□ Periodic pulse count, present value (RWr14 to RWr15, RWr2C to RWr2D), and CH□ Periodic pulse count value update check (RWr16 to RWr17, RWr2E to RWr2F). When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0
17	2F			

*1 For ΔT_2 , refer to Page 283, Appendix 4.

(4) Remote registers (RWr18 to RWr1F, RWr30 to RWr37)

Address (RWr)		Item	Description	Default
CH1	CH2			
18 19	30 31	Latch count value (Latch counter input terminal)	<ul style="list-style-type: none"> This area stores the count value latched when the latch counter function by latch counter input terminal is selected. (For the overview of the operation, refer to Page 127, Section 8.5.) When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0
1A 1B	32 33	Measured frequency value	<ul style="list-style-type: none"> This area stores the frequency value measured when the frequency measurement function is selected. When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0
		Measured rotation speed value	<ul style="list-style-type: none"> This area stores the rotation speed value measured when the rotation speed measurement function is selected. When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	
1C 1D	34 35	Measured pulse value (Function input terminal)	<ul style="list-style-type: none"> This area stores the value of the ON width or OFF width of pulses input to CH□ Function input terminal (FUNC1, FUNC2) measured when the pulse measurement function is selected. The following shows the range of values which can be stored. 0 to 2147483647 (increments of 0.1μs) When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0
1E 1F	36 37	Measured pulse value (Latch counter input terminal)	<ul style="list-style-type: none"> This area stores the value of the ON width or OFF width of pulses input to CH□ Latch counter input terminal (LATCH1, LATCH2) measured when the pulse measurement function is selected. The following shows the range of values which can be stored. 0 to 2147483647 (increments of 0.1μs) When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0

(5) Remote registers (RWr20, RWr38)

Address (RWr)		Item	Description	Default
CH1	CH2			
20	38	Status	<p>• This area stores various statuses as follows.</p> <p>• When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared.</p>	0000 _H

A

(6) Remote registers (RWr21 to RWr23, RWr39 to RWr3B)

Address (RWr)		Item	Description	Default
CH1	CH2			
21	39	External input status	<ul style="list-style-type: none"> This area stores the input statuses of phase Z, the function, the latch counter, phase A, and phase B of the external I/O connector. <ul style="list-style-type: none"> When CH□ Operation mode setting (address:0120_H, 0140_H) is set to either of Frequency Measurement Mode (1), Rotation Speed Measurement Mode (2), or PWM Output Mode (4), Function input status (RWr21.b1, RWr39.b1) is always OFF (0). With Negative Logic (1) being set in CH□ Function input logic setting (address: 0127_H, 0147_H) or CH□ Latch counter input logic setting (address: 0128_H, 0148_H), its input status changes to OFF (0) when a voltage is applied. When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0000 _H
22	3A	Latest error code	<ul style="list-style-type: none"> This area stores the latest error code of the generated major error or moderate error. When multiple errors in the same category occur, this area stores the error code of the later error. When a moderate error occurs while a major error is occurring, this area does not store the error code of the moderate error. For the error code, refer to Page 208, Section 11.2. 	0000 _H
23	3B	Latest warning code	<ul style="list-style-type: none"> This area stores the error code of the generated minor error. When multiple minor errors occur, this area stores the error code of the later error. For the error code, refer to Page 208, Section 11.2. 	0000 _H

(7) Remote registers (RWw0 to RWw1)

Address (RWw)		Item	Description	Default
CH1	CH2			
0	Point setting (Coincidence output 1)		<ul style="list-style-type: none"> When the coincidence output function is selected and a bit corresponding to Coincidence output 1 of Coincidence output comparison condition setting (address: 0102_H) is set to "Coincidence Output (00)", set the point of coincidence output. The following shows the setting range. -2147483648 to 2147483647 The reflection timing of the setting value <ol style="list-style-type: none"> When Initial data processing request flag (RX8) turns off When Initial data setting request flag (RY9) is turned off then on (only while Initial data processing request flag (RX8) is off) When Setting change request (Coincidence output 1) (RY14) is turned off then on 	0
	Lower limit value setting (Coincidence output 1)		<ul style="list-style-type: none"> When the coincidence output function is selected and a bit corresponding to Coincidence output 1 of Coincidence output comparison condition setting (address: 0102_H) is set to "Within-range Output (01)" or "Out-of-range Output (10)", set the lower limit value. The following shows the setting range. -2147483648 to 2147483647 The reflection timing of the setting value <ol style="list-style-type: none"> When Initial data processing request flag (RX8) turns off When Initial data setting request flag (RY9) is turned off then on (only while Initial data processing request flag (RX8) is off) When Setting change request (Coincidence output 1) (RY14) is turned off then on 	

A

(8) Remote registers (RWw2 to RWwF)

Address (RWw)		Item	Description	Default
CH1	CH2			
2	3	Upper limit value setting (Coincidence output 1)	<ul style="list-style-type: none"> When the coincidence output function is selected and a bit corresponding to Coincidence output 1 of Coincidence output comparison condition setting (address: 0102_H) is set to "Within-range Output (01)" or "Out-of-range Output (10)", set the upper limit value. When a bit corresponding to Coincidence output 1 of Coincidence output comparison condition setting (address: 0102_H) is set to "Coincidence Output (00)", this setting value is not used. The following shows the setting range. -2147483648 to 2147483647 The reflection timing of the setting value <ol style="list-style-type: none"> When Initial data processing request flag (RX8) turns off When Initial data setting request flag (RY9) is turned off then on (only while Initial data processing request flag (RX8) is off) When Setting change request (Coincidence output 1) (RY14) is turned off then on 	0
4	5	Point setting (Coincidence output 2) Lower limit value setting (Coincidence output 2)	<ul style="list-style-type: none"> This setting is for Coincidence output 2 of the coincidence output function. The details on this area such as the setting range are the same as those of Point setting (Coincidence output 1)/Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) except the coincidence output number. 	0
6	7	Upper limit value setting (Coincidence output 2)	<ul style="list-style-type: none"> This setting is for Coincidence output 2 of the coincidence output function. The details on this area such as the setting range are the same as those of Upper limit value setting (Coincidence output 1) (RWw2 to RWw3) except the coincidence output number. 	0
8	9	Point setting (Coincidence output 3) Lower limit value setting (Coincidence output 3)	<ul style="list-style-type: none"> This setting is for Coincidence output 3 of the coincidence output function. The details on this area such as the setting range are the same as those of Point setting (Coincidence output 1)/Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) except the coincidence output number. 	0
A	B	Upper limit value setting (Coincidence output 3)	<ul style="list-style-type: none"> This setting is for Coincidence output 3 of the coincidence output function. The details on this area such as the setting range are the same as those of Upper limit value setting (Coincidence output 1) (RWw2 to RWw3) except the coincidence output number. 	0
C	D	Point setting (Coincidence output 4) Lower limit value setting (Coincidence output 4)	<ul style="list-style-type: none"> This setting is for Coincidence output 4 of the coincidence output function. The details on this area such as the setting range are the same as those of Point setting (Coincidence output 1)/Lower limit value setting (Coincidence output 1) (RWw0 to RWw1) except the coincidence output number. 	0
E	F	Upper limit value setting (Coincidence output 4)	<ul style="list-style-type: none"> This setting is for Coincidence output 4 of the coincidence output function. The details on this area such as the setting range are the same as those of Upper limit value setting (Coincidence output 1) (RWw2 to RWw3) except the coincidence output number. 	0

(9) Remote registers (RWw10 to RWw13, RWw28 to RWw2B)

Address (RWw)		Item	Description	Default
CH1	CH2			
10	28	Ring counter lower limit value	<ul style="list-style-type: none"> When the ring counter function is selected and CH□ Counter format (address: 0124_H, 0144_H) is set to Ring Counter (1), set the count range. Set the ring counter upper limit value as well. The following shows the setting range. -2147483648 to 2147483647 The reflection timing of the setting value <ol style="list-style-type: none"> When Initial data processing request flag (RX8) turns off When Initial data setting request flag (RY9) is turned off then on (only while Initial data processing request flag (RX8) is off) When CH□ Count enable command (RY24, RY3C) is turned off then on 	0
11	29			A
12	2A	Ring counter upper limit value	<ul style="list-style-type: none"> When the ring counter function is selected and CH□ Counter format (address: 0124_H, 0144_H) is set to Ring Counter (1), set the count range. Set the ring counter lower limit value as well. The following shows the setting range. -2147483648 to 2147483647 The reflection timing of the setting value <ol style="list-style-type: none"> When Initial data processing request flag (RX8) turns off When Initial data setting request flag (RY9) is turned off then on (only while Initial data processing request flag (RX8) is off) When CH□ Count enable command (RY24, RY3C) is turned off then on 	0
13	2B			

(10) Remote registers (RWw14 to RWw15, RWw2C to RWw2D)

Address (RWw)		Item	Description	Default
CH1	CH2			
14	2C	Preset value setting	<ul style="list-style-type: none"> Set a count value to be replaced with the preset value for either of the preset/replace (at coincidence output) function, the preset/replace function, the count disable/preset/replace function, or the latch counter/preset/replace function. The following shows the setting range. -2147483648 to 2147483647 The reflection timing of the setting value <ol style="list-style-type: none"> When Initial data processing request flag (RX8) turns off When Initial data setting request flag (RY9) is turned off then on (only while Initial data processing request flag (RX8) is off) While Initial data processing request flag (RX8) and Initial data setting request flag (RY9) are off 	0
15	2D			

(11) Remote registers (RWw16 to RWw17, RWw2E to RWw2F)

Address (RWw)		Item	Description	Default
CH1	CH2			
16	2E	Time unit setting (Sampling counter/Periodic pulse counter)	<ul style="list-style-type: none"> Set a unit of time for the sampling counter function or the periodic pulse counter function. The following shows the setting range. <ul style="list-style-type: none"> 0: 1ms 1: 10ms The reflection timing of the setting value <ol style="list-style-type: none"> When Initial data processing request flag (RX8) turns off When Initial data setting request flag (RY9) is turned off then on (only while Initial data processing request flag (RX8) is off) When CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned off then on 	0
17	2F	Cycle setting (Sampling counter/Periodic pulse counter)	<ul style="list-style-type: none"> Set the sampling period for the sampling counter function or the cycle time of the periodic pulse counter function. The following shows the setting range. <ul style="list-style-type: none"> 1 to 65535 (When CH□ Time unit setting (Sampling counter/Periodic pulse counter) (RWw16, RWw2E) is set to 1ms (0), the sampling period or the cycle time is indicated in increments of 1ms and when set to 10ms (1), in increments of 10ms.) The reflection timing of the setting value <ol style="list-style-type: none"> When Initial data processing request flag (RX8) turns off When Initial data setting request flag (RY9) is turned off then on (only while Initial data processing request flag (RX8) is off) When CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F) is turned off then on 	0

(12)Remote registers (RWw18 to RWw19, RWw30 to RWw31)

Address (RWw)		Item	Description	Default
CH1	CH2			
18	30	Time unit setting (Frequency measurement)	<ul style="list-style-type: none"> Set a unit of time of frequency measurement for frequency measurement function. The following shows the setting range. 0: 0.01s 1: 0.1s 2: 1s The reflection timing of the setting value When CH□ Count enable command (RY24, RY3C) is turned off then on 	0
		Time unit setting (Rotation speed measurement)	<ul style="list-style-type: none"> Set a unit of time of rotation speed measurement for the rotation speed measurement function. The following shows the setting range. 0: 0.01s 1: 0.1s 2: 1s The reflection timing of the setting value When CH□ Count enable command (RY24, RY3C) is turned off then on 	
19	31	Moving average count (Frequency measurement)	<ul style="list-style-type: none"> Set the number of moving average count of frequency measurement for the frequency measurement function. The following shows the setting range. 1 to 100 (However, when 1 is set, the operation is performed with the moving average count regarded as not being done.) The reflection timing of the setting value When CH□ Count enable command (RY24, RY3C) is turned off then on 	0
		Moving average count (Rotation speed measurement)	<ul style="list-style-type: none"> Set the number of moving average count of rotation speed measurement for the rotation speed measurement function. The following shows the setting range. 1 to 100 (However, when 1 is set, the operation is performed with the moving average count regarded as not being done.) The reflection timing of the setting value When CH□ Count enable command (RY24, RY3C) is turned off then on 	

(13)Remote registers (RWw1A to RWw1B, RWw32 to RWw33)

Address (RWw)		Item	Description	Default
CH1	CH2			
1A 1B	32 33	Number of pulses per rotation	<ul style="list-style-type: none"> Set the number of pulses per rotation for the pulse measurement function. The following shows the setting range. 1 to 8000000 The reflection timing of the setting value When CH□ Count enable command (RY24, RY3C) is turned off then on 	0

(14)Remote registers (RWw1D to RWw21, RWw35 to RWw39)

Address (RWw)		Item	Description	Default
CH1	CH2			
1D	35	PWM output assignment setting	<ul style="list-style-type: none"> Select an output target from Coincidence output 1 to 4 to output the PWM waveform using the PWM output function. This setting applies only to coincidence outputs where the corresponding channels are assigned using Coincidence output channel assignment setting (address: 0101_H). Two or more points can be set. The following shows the setting range. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0</p> <p>0 (fixed) 0: No Assignment 1: Assignment</p> <ul style="list-style-type: none"> The reflection timing of the setting value When CH□ Cam switch execute command/PWM output start command (RY26, RY3E) is turned off then on 	0000 _H
1E 1F	36 37	ON width setting (PWM output)	<ul style="list-style-type: none"> Set the ON width of the PWM waveform for the PWM output function. The following shows the setting range. 0, and 10 to 10000000 (increments of 0.1μs) (Set a value that is equal to or smaller than the value in the cycle setting (PWM output).) The reflection timing of the setting value <ol style="list-style-type: none"> When CH□ Cam switch execute command/PWM output start command (RY26, RY3E) is turned off then on When CH□ ON width setting change request (PWM output) (RY35, RY4D) is turned off then on 	0
20 21	38 39	Cycle setting (PWM output)	<ul style="list-style-type: none"> Set the cycle of the PWM waveform for the PWM output function. The following shows the setting range. 50 to 10000000 (increments of 0.1μs) The reflection timing of the setting value When CH□ Cam switch execute command/PWM output start command (RY26, RY3E) is turned off then on 	0

Appendix 3 Details of Remote Buffer Memory Addresses

The following shows details of remote buffer memory addresses.

(1) Station-based parameter data (address: 0001_H)

Address	Name		Description	Default												
CH1	CH2															
0001 _H		Input response time setting	<ul style="list-style-type: none"> Set the input response time of the extension input module. The following shows the setting range. <table border="1"> <thead> <tr> <th>Setting value</th> <th>Input response time</th> </tr> </thead> <tbody> <tr> <td>3_H</td> <td>2ms</td> </tr> <tr> <td>4_H</td> <td>5ms</td> </tr> <tr> <td>5_H</td> <td>10ms</td> </tr> <tr> <td>6_H</td> <td>20ms</td> </tr> <tr> <td>7_H</td> <td>70ms</td> </tr> </tbody> </table> <ul style="list-style-type: none"> The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on When an extension I/O module is not installed, this setting is ignored. 	Setting value	Input response time	3 _H	2ms	4 _H	5ms	5 _H	10ms	6 _H	20ms	7 _H	70ms	0005 _H
Setting value	Input response time															
3 _H	2ms															
4 _H	5ms															
5 _H	10ms															
6 _H	20ms															
7 _H	70ms															

(2) Station-based parameter data (address: 0002_H to 0003_H)

Address	Name		Description	Default																																
CH1	CH2																																			
0002 _H		Output HOLD/CLEAR setting	<ul style="list-style-type: none"> Set whether to hold or clear the output of the high-speed counter module and the extension output module. The following shows the setting range. <table border="1"> <tr> <td>b15</td><td>b14</td><td>b13</td><td>b12</td><td>b11</td><td>b10</td><td>b9</td><td>b8</td><td>b7</td><td>b6</td><td>b5</td><td>b4</td><td>b3</td><td>b2</td><td>b1</td><td>b0</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td></td> </tr> </table> <p>0 (fixed) 0: CLEAR 1: HOLD</p> <ul style="list-style-type: none"> The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0		0000 _H
b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0																					
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0																						
0003 _H		Cyclic data update watch time setting	<ul style="list-style-type: none"> Set the time to monitor the data update interval of the cyclic transmission (watch time). When the cyclic transmission remains to be stopped over the cyclic data update watch time setting, the high-speed counter module is regarded as disconnected. Then the output status of the high-speed counter module and extension output module becomes HOLD or CLEAR. For details on output HOLD/CLEAR, refer to Page 167, Section 8.17. The following shows the setting range. 0 to 20 (increments of 100ms) (However, when 0 is set, monitoring is not performed.) The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0																																

A

(3) Module-based parameter data (address: 0100_H to 0101_H)

Address	Name	Description	Default																																
CH1	CH2																																		
0100 _H	Comparison output setting	<ul style="list-style-type: none"> Set the comparison output function. The following shows the setting range. <p>0: Coincidence Output Function 1: Cam Switch Function</p> <ul style="list-style-type: none"> The reflection timing of the setting value <p>When Initial data setting request flag (RY9) is turned off then on</p>	0																																
0101 _H	Coincidence output channel assignment setting	<ul style="list-style-type: none"> Set a channel to be compared for Coincidence output 1 to 4. The following shows the setting range. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0 <table border="1"> <tr><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>4)</td><td>3)</td><td>2)</td><td>1)</td></tr> <tr><td colspan="8" style="text-align: center;">0 (fixed)</td><td colspan="8" style="text-align: center;">0: CH1 1: CH2</td></tr> </table> </p> <ul style="list-style-type: none"> 1) Coincidence output 1 channel assignment setting 2) Coincidence output 2 channel assignment setting 3) Coincidence output 3 channel assignment setting 4) Coincidence output 4 channel assignment setting The reflection timing of the setting value <p>When Initial data setting request flag (RY9) is turned off then on</p>	0	0	0	0	0	0	0	0	0	0	0	0	4)	3)	2)	1)	0 (fixed)								0: CH1 1: CH2								0000 _H
0	0	0	0	0	0	0	0	0	0	0	0	4)	3)	2)	1)																				
0 (fixed)								0: CH1 1: CH2																											

(4) Module-based parameter data (address: 0102_H to 0103_H)

Address	Name	Description	Default																																
CH1	CH2																																		
0102 _H	Coincidence output comparison condition setting	<ul style="list-style-type: none"> Set the comparison condition for Coincidence output 1 to 4. The following shows the setting range. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0 <table border="1"> <tr><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td></tr> <tr><td colspan="8" style="text-align: center;">0 (fixed)</td><td colspan="8" style="text-align: center;">00: Coincidence Output 01: Within-range Output 10: Out-of-range Output</td></tr> </table> </p> <ul style="list-style-type: none"> The reflection timing of the setting value <p>When Initial data setting request flag (RY9) is turned off then on</p>	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (fixed)								00: Coincidence Output 01: Within-range Output 10: Out-of-range Output								0000 _H
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0																				
0 (fixed)								00: Coincidence Output 01: Within-range Output 10: Out-of-range Output																											
0103 _H	Preset/replace setting at coincidence output	<ul style="list-style-type: none"> Set whether to replace a count value with the preset value at coincidence output or not. The following shows the setting range. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0 <table border="1"> <tr><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td></tr> <tr><td colspan="8" style="text-align: center;">0 (fixed)</td><td colspan="8" style="text-align: center;">0: Present value not replaced 1: Present value replaced</td></tr> </table> </p> <ul style="list-style-type: none"> The reflection timing of the setting value <p>When Initial data setting request flag (RY9) is turned off then on</p>	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0 (fixed)								0: Present value not replaced 1: Present value replaced								0000 _H
0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0																				
0 (fixed)								0: Present value not replaced 1: Present value replaced																											

(5) Module-based parameter data (address: 0104_H to 0105_H)

Address	Name		Description	Default
CH1	CH2			
0104 _H		Cam switch output unit assignment setting	<ul style="list-style-type: none"> Set an extension output module to be used with the cam switch function. The following shows the setting range. 0: No Assignment 1: Stage 1 <ul style="list-style-type: none"> The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on	0
0105 _H		Cam switch output channel assignment setting	<ul style="list-style-type: none"> Set channels to be compared for the outputs of the cam switch function. The following shows the setting range. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0 (16) (15) (14) (13) (12) (11) (10) (9) (8) (7) (6) (5) (4) (3) (2) (1) { 0: CH1 1: CH2 </p> <ol style="list-style-type: none"> 1) Cam switch output 1 channel assignment setting 2) Cam switch output 2 channel assignment setting : 15) Cam switch output 15 channel assignment setting 16) Cam switch output 16 channel assignment setting <ul style="list-style-type: none"> The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on	0000 _H

(6) Module-based parameter data (address: 0120_H to 0121_H, 0140_H to 0141_H)

Address	Name		Description	Default
CH1	CH2			
0120 _H	0140 _H	Operation mode setting	<ul style="list-style-type: none"> Set the operation mode for channels. The following shows the setting range. 0: Normal Mode 1: Frequency Measurement Mode 2: Rotation Speed Measurement Mode 3: Pulse Measurement Mode 4: PWM Output Mode <ul style="list-style-type: none"> The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on	0
0121 _H	0141 _H	Count source selection	<ul style="list-style-type: none"> Set the count source. The following shows the setting range. 0: A Phase/B Phase 1: Coincidence Output 1 2: Coincidence Output 2 <ul style="list-style-type: none"> When CH□ Count source selection (address: 0121_H, 0141_H) is set to Coincidence Output 1 (1) or Coincidence Output 2 (2), pulses are counted up at the rising edge of the following signals. Normal mode: Coincidence output 1 to 2 (RX10 to RX11) PWM output mode: Coincidence output 1 to 2 terminals (EQU1 to EQU2) <ul style="list-style-type: none"> The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on	0

(7) Module-based parameter data (address: 0122_H to 0123_H, 0142_H to 0143_H)

Address		Name	Description	Default
CH1	CH2			
0122 _H	0142 _H	Pulse input mode	<ul style="list-style-type: none"> Set the pulse input mode. The following shows the setting range. 0: 1-Phase Multiple of 1 1: 1-Phase Multiple of 2 2: CW/CCW 3: 2-Phase Multiple of 1 4: 2-Phase Multiple of 2 5: 2-Phase Multiple of 4 <ul style="list-style-type: none"> The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0
0123 _H	0143 _H	Counting speed setting	<ul style="list-style-type: none"> Set the counting speed. The following shows the setting range. 0: 10kpps 1: 100kpps 2: 200kpps 3: 500kpps 4: 1Mpps 5: 2Mpps 6: 4Mpps 7: 8Mpps <ul style="list-style-type: none"> Always set 200kpps or slower to the counting speed when DC input is used for connecting. The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0

(8) Module-based parameter data (address: 0124_H to 0125_H, 0144_H to 0145_H)

Address		Name	Description	Default																															
CH1	CH2																																		
0124 _H	0144 _H	Counter format	<ul style="list-style-type: none"> Set the counter format. The following shows the setting range. 0: Linear Counter 1: Ring Counter The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0																															
0125 _H	0145 _H	Phase Z setting	<ul style="list-style-type: none"> Set the trigger condition to replace a count value with the preset value by CH□ Phase Z input terminal (Z1, Z2). Set whether to turn on CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) or not when a count value is replaced with the preset value by CH□ Phase Z input terminal (Z1, Z2). While CH□ Z phase (Preset) trigger setting (address: 0125_H.b0 to b1, 0145_H.b0 to b1) is on, CH□ External preset/replace (Z Phase) request detection setting (address: 0125_H.b4, 0145_H.b4) is disabled and CH□ External preset/replace (Z Phase) request detection (RX23, RX3B) is always off. The following shows the setting range. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0</p> <table border="1"> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>2)</td><td>0</td><td>0</td><td>1)</td> </tr> <tr> <td colspan="8" style="text-align: center;">0 (fixed)</td> <td colspan="8" style="text-align: center;">0 (fixed)</td> </tr> </table> <ol style="list-style-type: none"> Z phase (Preset) trigger setting <ul style="list-style-type: none"> 00: Rising 01: Falling 10: Rising + Falling 11: During ON External preset/replace (Z Phase) request detection setting <ul style="list-style-type: none"> 0: ON at detection 1: Not ON at detection The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0	0	0	0	0	0	0	0	0	0	0	2)	0	0	1)	0 (fixed)								0 (fixed)								0000 _H
0	0	0	0	0	0	0	0	0	0	0	2)	0	0	1)																					
0 (fixed)								0 (fixed)																											

A

(9) Module-based parameter data (address: 0126_H to 0128_H, 0146_H to 0148_H)

Address		Name	Description	Default
CH1	CH2			
0126 _H	0146 _H	Counter function selection	<ul style="list-style-type: none"> Set the counter function which becomes valid when the value in CH□ Operation mode setting (address: 0120_H, 0140_H) is Normal Mode (0). The following shows the setting range. <ul style="list-style-type: none"> 0: Count Disable Function 1: Latch Counter Function 2: Sampling Counter Function 3: Periodic Pulse Counter Function 4: Count disable/Preset/replace Function 5: Latch counter/Preset/replace Function The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0
0127 _H	0147 _H	Function input logic setting	<ul style="list-style-type: none"> Set the logic setting of CH□ Function input terminal (FUNC1, FUNC2). CH1 FNC LED and CH2 FNC LED turn on with any setting value when a voltage is applied. The following shows the setting range. <ul style="list-style-type: none"> 0: Positive Logic 1: Negative Logic The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0
0128 _H	0148 _H	Latch counter input logic setting	<ul style="list-style-type: none"> Set the logic setting of CH□ Latch counter input terminal (LATCH1, LATCH2). CH1 LAT LED and CH2 LAT LED turn on with any setting value when a voltage is applied. The following shows the setting range. <ul style="list-style-type: none"> 0: Positive Logic 1: Negative Logic The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0

(10)Module-based parameter data (address: 0129_H, 0149_H)

Address		Name	Description	Default																																																										
CH1	CH2																																																													
0129 _H	0149 _H	External control input response time setting	<ul style="list-style-type: none"> Set the input response time of CH□ Phase Z input terminal (Z1, Z2), CH□ Function input terminal (FUNC1, FUNC2), and CH□ Latch counter input terminal (LATCH1, LATCH2). The following shows the setting range. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0</p> <table border="1"> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>3)</td><td>2)</td><td>1)</td> </tr> </table> <p style="text-align: center;">0 (fixed)</p> <table border="1"> <thead> <tr> <th colspan="3">1) Z phase input response time setting</th> </tr> <tr> <th>Setting</th> <th>OFF → ON Response time</th> <th>ON → OFF Response time</th> </tr> </thead> <tbody> <tr> <td>00</td> <td>0.25μs</td> <td>2.5μs</td> </tr> <tr> <td>01</td> <td>0.1ms</td> <td>0.1ms</td> </tr> <tr> <td>10</td> <td>1.0ms</td> <td>1.0ms</td> </tr> </tbody> </table> <table border="1"> <thead> <tr> <th colspan="3">2) Function input response time setting</th> </tr> <tr> <th>Setting</th> <th>OFF → ON Response time</th> <th>ON → OFF Response time</th> </tr> </thead> <tbody> <tr> <td>00</td> <td>0.02ms</td> <td>0.1ms</td> </tr> <tr> <td>01</td> <td>0.1ms</td> <td>0.1ms</td> </tr> <tr> <td>10</td> <td>1.0ms</td> <td>1.0ms</td> </tr> </tbody> </table> <table border="1"> <thead> <tr> <th colspan="3">3) Latch counter input response time setting</th> </tr> <tr> <th>Setting</th> <th>OFF → ON Response time</th> <th>ON → OFF Response time</th> </tr> </thead> <tbody> <tr> <td>00</td> <td>0.02ms</td> <td>0.1ms</td> </tr> <tr> <td>01</td> <td>0.1ms</td> <td>0.1ms</td> </tr> <tr> <td>10</td> <td>1.0ms</td> <td>1.0ms</td> </tr> </tbody> </table> <ul style="list-style-type: none"> When CH□ Function input logic setting (address: 0127_H, 0147_H) and CH□ Latch counter input logic setting (address: 0128_H, 0148_H) are set to Negative Logic (1), the OFF → ON response time and the ON → OFF response time invert. For example, when CH□ Latch counter input logic setting (address: 0128_H, 0148_H) is set to Negative Logic (1) and corresponding bits for this area are set to 00, the OFF → ON response time is 0.1ms. The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0	0	0	0	0	0	0	0	0	0	3)	2)	1)	1) Z phase input response time setting			Setting	OFF → ON Response time	ON → OFF Response time	00	0.25μs	2.5μs	01	0.1ms	0.1ms	10	1.0ms	1.0ms	2) Function input response time setting			Setting	OFF → ON Response time	ON → OFF Response time	00	0.02ms	0.1ms	01	0.1ms	0.1ms	10	1.0ms	1.0ms	3) Latch counter input response time setting			Setting	OFF → ON Response time	ON → OFF Response time	00	0.02ms	0.1ms	01	0.1ms	0.1ms	10	1.0ms	1.0ms	002A _H
0	0	0	0	0	0	0	0	0	0	3)	2)	1)																																																		
1) Z phase input response time setting																																																														
Setting	OFF → ON Response time	ON → OFF Response time																																																												
00	0.25μs	2.5μs																																																												
01	0.1ms	0.1ms																																																												
10	1.0ms	1.0ms																																																												
2) Function input response time setting																																																														
Setting	OFF → ON Response time	ON → OFF Response time																																																												
00	0.02ms	0.1ms																																																												
01	0.1ms	0.1ms																																																												
10	1.0ms	1.0ms																																																												
3) Latch counter input response time setting																																																														
Setting	OFF → ON Response time	ON → OFF Response time																																																												
00	0.02ms	0.1ms																																																												
01	0.1ms	0.1ms																																																												
10	1.0ms	1.0ms																																																												

A

(11)Module-based parameter data (address: 012A_H to 012B_H, 014A_H to 014B_H)

Address		Name	Description	Default
CH1	CH2			
012A _H	014A _H	Pulse measurement setting (Function input terminal)	<ul style="list-style-type: none"> Set the pulse measurement target of CH□ Function input terminal (FUNC1, FUNC2). The following shows the setting range. 0: Pulse ON Width 1: Pulse OFF Width The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0
012B _H	014B _H	Pulse measurement setting (Latch counter input terminal)	<ul style="list-style-type: none"> Set the pulse measurement target of CH□ Latch counter input terminal (LATCH1, LATCH2). The following shows the setting range. 0: Pulse ON Width 1: Pulse OFF Width The reflection timing of the setting value When Initial data setting request flag (RY9) is turned off then on 	0

(12)Module-based monitoring data (address: 0600_H)

Address	Name	Description	Default																																																														
0600 _H	Channel assignment (Coincidence output 1 to 4)	<ul style="list-style-type: none"> This area stores the channel assignment statuses of coincidence outputs. The following shows the range of values which can be stored. <table border="1"> <tr> <td>b15</td><td>b14</td><td>b13</td><td>b12</td><td>b11</td><td>b10</td><td>b9</td><td>b8</td><td>b7</td><td>b6</td><td>b5</td><td>b4</td><td>b3</td><td>b2</td><td>b1</td><td>b0</td> </tr> <tr> <td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>Coincidence output 4</td><td>Coincidence output 3</td><td>Coincidence output 2</td><td>Coincidence output 1</td><td></td><td></td><td></td><td></td> </tr> <tr> <td colspan="15" style="text-align: center;">0 (fixed)</td> </tr> <tr> <td colspan="15" style="text-align: right;">00: No Assignment 01: CH1 10: CH2</td> </tr> </table> <ul style="list-style-type: none"> When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0	0	0	0	0	0	0	0	0	Coincidence output 4	Coincidence output 3	Coincidence output 2	Coincidence output 1					0 (fixed)															00: No Assignment 01: CH1 10: CH2															0000 _H
b15	b14	b13	b12	b11	b10	b9	b8	b7	b6	b5	b4	b3	b2	b1	b0																																																		
0	0	0	0	0	0	0	0	Coincidence output 4	Coincidence output 3	Coincidence output 2	Coincidence output 1																																																						
0 (fixed)																																																																	
00: No Assignment 01: CH1 10: CH2																																																																	

(13)Module-based monitoring data (address: 0620_H to 0621_H, 0640_H to 0641_H)

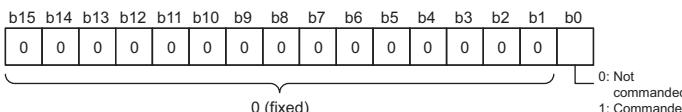
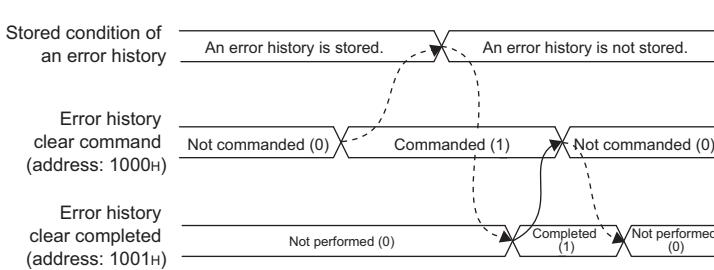
Address		Name	Description	Default
CH1	CH2			
0620 _H	0640 _H	Operation mode	<ul style="list-style-type: none"> This area stores the present operation mode. The following shows the range of values which can be stored. 0: Normal Mode 1: Frequency Measurement Mode 2: Rotation Speed Measurement Mode 3: Pulse Measurement Mode 4: PWM Output Mode <ul style="list-style-type: none"> When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0
0621 _H	0641 _H	Selected counter function	<ul style="list-style-type: none"> This area stores the counter function currently valid. The following shows the range of values which can be stored. 0: Count Disable Function 1: Latch Counter Function 2: Sampling Counter Function 3: Periodic Pulse Counter Function 4: Count disable/Preset/replace Function 5: Latch counter/Preset/replace Function <ul style="list-style-type: none"> When Initial data setting request flag (RY9) is turned off then on, the value in this area is cleared. 	0

A

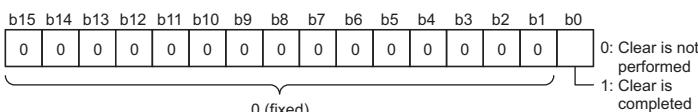
(14) Station-based error history data (address: 0A00_H to 0AEF_H)

Address	Name	Description	Default																																								
0A00 _H to 0A0F _H	Error history 1	<ul style="list-style-type: none"> This area stores the error history when an error or a warning occurs. Up to 15 errors are stored in the error history. The latest history is stored in Error history 1 (address: 0A00_H to 0A0F_H). Errors or warnings that occurred in the past are stored in Error history 2 to Error history 15 (address: 0A10_H to 0AEF_H) in reverse chronological order. If 16 or more errors or warnings occur, errors or warnings are deleted from the oldest. The following shows the format of the stored values. <table border="1" style="margin-left: 20px;"> <tr> <td colspan="2" style="text-align: center;">b15 to b8</td> <td colspan="2" style="text-align: center;">b7 to b0</td> </tr> <tr> <td colspan="2" style="text-align: center;">0A00_H</td> <td colspan="2" style="text-align: center;">Error code</td> </tr> <tr> <td colspan="2" style="text-align: center;">0A01_H</td> <td colspan="2" style="text-align: center;">Order of generation</td> </tr> <tr> <td style="text-align: center;">First two digits of the year</td> <td style="text-align: center;">Last two digits of the year</td> <td colspan="2" style="text-align: center;">The value of 0 to 65535 that indicates the order of error occurrence</td> </tr> <tr> <td style="text-align: center;">0A02_H</td> <td style="text-align: center;">0A03_H</td> <td colspan="2" style="text-align: center;">The date and time of error occurrence (upper 8 bits: first two digits of the year/lower 8 bits: last two digits of the year)</td> </tr> <tr> <td style="text-align: center;">0A04_H</td> <td style="text-align: center;">0A05_H</td> <td colspan="2" style="text-align: center;">The date and time of error occurrence (upper 8 bits: month/lower 8 bits: day)</td> </tr> <tr> <td style="text-align: center;">0A06_H</td> <td style="text-align: center;">0A07_H</td> <td colspan="2" style="text-align: center;">The date and time of error occurrence (upper 8 bits: hour/lower 8 bits: minute)</td> </tr> <tr> <td style="text-align: center;">0A08_H</td> <td style="text-align: center;">0A09_H</td> <td colspan="2" style="text-align: center;">The date and time of error occurrence (upper 8 bits: second/lower 8 bits: no use)</td> </tr> <tr> <td colspan="2" style="text-align: center;">0A0A_H to 0A0F_H</td> <td colspan="2" style="text-align: center;">Detail information of the error that has occurred^{*1}</td> </tr> <tr> <td colspan="2"></td> <td colspan="2" style="text-align: center;">0 (fixed)</td> </tr> </table> <p style="text-align: center;">^{*1} For the details on Error code details 1, refer to the following. Page 222, Section 11.2 (1) (a))</p> <ul style="list-style-type: none"> The clock information of the error that occurred is based on the clock information acquired from the CPU module of the master station. When an error has occurred before the clock information is acquired from the CPU module, the error time is not recorded. 	b15 to b8		b7 to b0		0A00 _H		Error code		0A01 _H		Order of generation		First two digits of the year	Last two digits of the year	The value of 0 to 65535 that indicates the order of error occurrence		0A02 _H	0A03 _H	The date and time of error occurrence (upper 8 bits: first two digits of the year/lower 8 bits: last two digits of the year)		0A04 _H	0A05 _H	The date and time of error occurrence (upper 8 bits: month/lower 8 bits: day)		0A06 _H	0A07 _H	The date and time of error occurrence (upper 8 bits: hour/lower 8 bits: minute)		0A08 _H	0A09 _H	The date and time of error occurrence (upper 8 bits: second/lower 8 bits: no use)		0A0A _H to 0A0F _H		Detail information of the error that has occurred ^{*1}				0 (fixed)		0000 _H
b15 to b8		b7 to b0																																									
0A00 _H		Error code																																									
0A01 _H		Order of generation																																									
First two digits of the year	Last two digits of the year	The value of 0 to 65535 that indicates the order of error occurrence																																									
0A02 _H	0A03 _H	The date and time of error occurrence (upper 8 bits: first two digits of the year/lower 8 bits: last two digits of the year)																																									
0A04 _H	0A05 _H	The date and time of error occurrence (upper 8 bits: month/lower 8 bits: day)																																									
0A06 _H	0A07 _H	The date and time of error occurrence (upper 8 bits: hour/lower 8 bits: minute)																																									
0A08 _H	0A09 _H	The date and time of error occurrence (upper 8 bits: second/lower 8 bits: no use)																																									
0A0A _H to 0A0F _H		Detail information of the error that has occurred ^{*1}																																									
		0 (fixed)																																									
⋮	⋮	⋮	⋮																																								
0AE0 _H to 0AEF _H	Error history 15	<ul style="list-style-type: none"> Same as Error history 1. 	0000 _H																																								

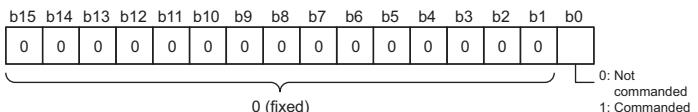
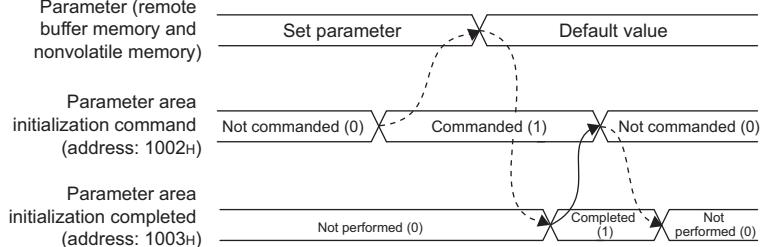
(15)Station-based control data (address: 1000H)

Address	Name	Description	Default
1000H	Error history clear command	<ul style="list-style-type: none"> The error history stored in the remote buffer memory and the nonvolatile memory is cleared by this command. The following shows the setting range. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0</p>  <ul style="list-style-type: none"> When Error history clear command (address: 1000H) is set to Commanded (1), the error history stored in the remote buffer memory and the nonvolatile memory is cleared and Error history clear completed (address: 1001H) changes to Clear is completed (1). <p>Controlled by the high-speed counter module Controlled by the program</p> <p>Stored condition of an error history</p>  <ul style="list-style-type: none"> Errors or warnings which have occurred are not reset even when Error history clear command (address: 1000H) is set to Commanded (1). Use CH□ Error reset command (RY36, RY4E) to reset them. 	0000H

(16)Station-based control data (address: 1001H)

Address	Name	Description	Default
1001H	Error history clear completed	<ul style="list-style-type: none"> When clearing the error history stored in the remote buffer memory and the nonvolatile memory is completed, Error history clear completed (address: 1001H) changes to Clear is completed (1). When Error history clear command (address: 1000H) is set to Not commanded (0), Error history clear completed (address: 1001H) changes to Clear is not performed (0). The following shows the range of values which can be stored. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0</p> 	0000H

(17)Station-based control data (address: 1002H)

Address	Name	Description	Default
1002H	Parameter area initialization command	<ul style="list-style-type: none"> The parameter information and the extended parameter information stored in the remote buffer memory and the nonvolatile memory are initialized by this command. The following shows the setting range.  <ul style="list-style-type: none"> When Parameter area initialization command (address: 1002H) is set to Commanded (1), the parameter information and the extended parameter information stored in the remote buffer memory and the nonvolatile memory are initialized and Parameter area initialization completed (address: 1003H) changes to Initialization is completed (1). <p>Controlled by the high-speed counter module Controlled by the program</p> 	0000H

Point

- When Parameter area initialization command (address: 1002H) is executed, the following remote input signals and remote registers are not cleared. (Note that the following are the target data to be cleared by Initial data setting request flag (RY9).)
 - Warning status flag (RX7)
 - Error status flag (RXA)
 - CH \square Error status (RX36, RX4E)
 - CH \square Warning status (RX37, RX4F)
 - CH \square Latest error code (RWr22, RWr3A)
 - CH \square Latest warning code (RWr23, RWr3B)
- When initialization of the parameter information and the extended parameter information is completed, Initial data processing request flag (RX8) turns on. Set parameters using Initial data setting request flag (RY9) and remote registers using Initial data processing completion flag (RY8).

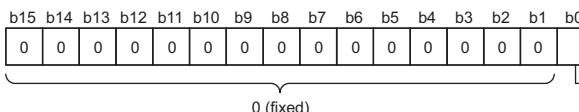
(18)Station-based control data (address: 1003_H)

Address	Name	Description	Default
1003 _H	Parameter area initialization completed	<ul style="list-style-type: none"> When initialization of the parameter information and the extended parameter information stored in the remote buffer memory and the nonvolatile memory is completed, Parameter area initialization completed (address: 1003_H) changes to Initialization is completed (1). When Parameter area initialization command (address: 1002_H) is set to Not commanded (0), Parameter area initialization completed (address: 1003_H) changes to Initialization is not performed (0). The following shows the range of values which can be stored. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0</p> <p>0 (fixed)</p> <p>0: Initialization is not performed 1: Initialization is completed</p>	0000 _H

(19)Station-based control data (address: 1004_H)

Address	Name	Description	Default
1004 _H	Module operation information initialization command	<ul style="list-style-type: none"> The module operation information stored in the remote buffer memory and the nonvolatile memory is initialized by this command. The module operation information can be initialized only when Nonvolatile memory data error (module operation information) (error code: 0110_H) has occurred. The following shows the setting range. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0</p> <p>0 (fixed)</p> <p>0: Not commanded 1: Commanded</p> <ul style="list-style-type: none"> When Module operation information initialization command (address: 1004_H) is set to Commanded (1), the module operation information stored in the remote buffer memory and the nonvolatile memory is cleared and Module operation information initialization completed (address: 1005_H) changes to Initialization is completed (1). <p>----> Controlled by the high-speed counter module -----> Controlled by the program</p> <p>Error data of module operation</p> <p>Module operation information</p> <p>Module operation information initialization command (address: 1004H)</p> <p>Module operation information initialization completed (address: 1005H)</p> <p>Default value</p> <p>Not commanded (0) Commanded (1) Not commanded (0)</p> <p>Not performed (0) Completed (1) Not performed (0)</p>	0000 _H

(20)Station-based control data (address: 1005_H)

Address	Name	Description	Default
1005 _H	Module operation information initialization completed	<ul style="list-style-type: none"> When initialization of the module operation information stored in the remote buffer memory and the nonvolatile memory is completed, Module operation information initialization completed (address: 1005_H) changes to Initialization is completed (1). When Module operation information initialization command (address: 1004_H) is set to Not commanded (0), Module operation information initialization completed (address: 1005_H) changes to Initialization is not performed (0). The following shows the range of values which can be stored. <p>b15 b14 b13 b12 b11 b10 b9 b8 b7 b6 b5 b4 b3 b2 b1 b0</p>  <p>0: Initialization is not performed 1: Initialization is completed</p>	0000 _H

(21)Extended parameter data (address: 1500_H to 1521_H)

Address	Name	Description	Default
1500 _H	Cam switch function, step type (Output 1)	<p>Set the step type for the cam of Output 1.</p> <ul style="list-style-type: none"> Setting range 0: Starts with output status being OFF 1: Starts with output status being ON The reflection timing of the setting value When CH□ Cam switch execute command/PWM output start command (RY26, RY3E) is turned off then on 	0
1501 _H	Cam switch function, number of steps (Output 1)	<p>Set the number of steps for the cam of Output 1.</p> <ul style="list-style-type: none"> Setting range 0 to 16 The reflection timing of the setting value When CH□ Cam switch execute command/PWM output start command (RY26, RY3E) is turned off then on 	0
1502 _H 1503 _H	Cam switch function, step No.1 setting (Output 1)	<p>Set the count value for switching ON and OFF of the output at the step No.1 of Output 1.</p> <ul style="list-style-type: none"> Setting range -2147483648 to 2147483647 The reflection timing of the setting value When CH□ Cam switch execute command/PWM output start command (RY26, RY3E) is turned off then on 	0
:	:	:	:
1520 _H 1521 _H	Cam switch function, step No.16 setting (Output 1)	<p>Set the count value for switching ON and OFF of the output at the step No.16 of Output 1.</p> <ul style="list-style-type: none"> Setting range -2147483648 to 2147483647 The reflection timing of the setting value When CH□ Cam switch execute command/PWM output start command (RY26, RY3E) is turned off then on 	0

(22)Extended parameter data (address: 1580_H to 1CA1_H)

Address	Name	Description	Default
1580 _H to 15A0 _H 15A1 _H	Cam switch function, step type (Output 2) to Cam switch function, step No.16 setting (Output 2)		0
1600 _H to 1620 _H 1621 _H	Cam switch function, step type (Output 3) to Cam switch function, step No.16 setting (Output 3)		0
1680 _H to 16A0 _H 16A1 _H	Cam switch function, step type (Output 4) to Cam switch function, step No.16 setting (Output 4)		0
1700 _H to 1720 _H 1721 _H	Cam switch function, step type (Output 5) to Cam switch function, step No.16 setting (Output 5)	For Output 2 to 16, set the step type and the number of steps for the cam, and set the count value for switching ON and OFF of the corresponding output at the step No.1 to No.16. Since the details on these settings are the same as those of Output 1, refer to the following.  Page 280, Appendix 3 (21)) • The reflection timing of the setting value When CH□ Cam switch execute command/PWM output start command (RY26, RY3E) is turned off then on	0
1780 _H to 17A0 _H 17A1 _H	Cam switch function, step type (Output 6) to Cam switch function, step No.16 setting (Output 6)		0
1800 _H to 1820 _H 1821 _H	Cam switch function, step type (Output 7) to Cam switch function, step No.16 setting (Output 7)		0
1880 _H to 18A0 _H 18A1 _H	Cam switch function, step type (Output 8) to Cam switch function, step No.16 setting (Output 8)		0
1900 _H to 1920 _H 1921 _H	Cam switch function, step type (Output 9) to Cam switch function, step No.16 setting (Output 9)		0

A

Address	Name	Description	Default
1980 _H to 19A0 _H 19A1 _H	Cam switch function, step type (Output 10) to Cam switch function, step No.16 setting (Output 10)		0
1A00 _H to 1A20 _H 1A21 _H	Cam switch function, step type (Output 11) to Cam switch function, step No.16 setting (Output 11)		0
1A80 _H to 1AA0 _H 1AA1 _H	Cam switch function, step type (Output 12) to Cam switch function, step No.16 setting (Output 12)		0
1B00 _H to 1B20 _H 1B21 _H	Cam switch function, step type (Output 13) to Cam switch function, step No.16 setting (Output 13)	For Output 2 to 16, set the step type and the number of steps for the cam, and set the count value for switching ON and OFF of the corresponding output at the step No.1 to No.16. Since the details on these settings are the same as those of Output 1, refer to the following.  Page 280, Appendix 3 (21)) • The reflection timing of the setting value When CH□ Cam switch execute command/PWM output start command (RY26, RY3E) is turned off then on	0
1B80 _H to 1BA0 _H 1BA1 _H	Cam switch function, step type (Output 14) to Cam switch function, step No.16 setting (Output 14)		0
1C00 _H to 1C20 _H 1C21 _H	Cam switch function, step type (Output 15) to Cam switch function, step No.16 setting (Output 15)		0
1C80 _H to 1CA0 _H 1CA1 _H	Cam switch function, step type (Output 16) to Cam switch function, step No.16 setting (Output 16)		0

Appendix 4 Internal Control Cycle and Response Delay Time

For the high-speed counter module, responses are delayed by the causes shown in (1) to (3).

(1) Scan time of the program in the master station (SM)

This scan time causes delays of remote I/O signals, remote registers, and remote buffer memory.

(2) Link scan time (LS)

This is the time taken for sending data from each station on the network and finishing the one cycle.

For details, refer to the following.

 User's manual for the master/local module used

A

(3) Control cycle of the high-speed counter module (ΔT_2)

Up to ΔT_1 ($\Delta T_2 \times 2$) delay occurs until the high-speed counter module completes processing after the module reads remote output signals, remote registers, and remote buffer memory updated by the program.

In addition, the update timing of remote input signals, remote registers, and remote buffer memory fluctuates within one control cycle.

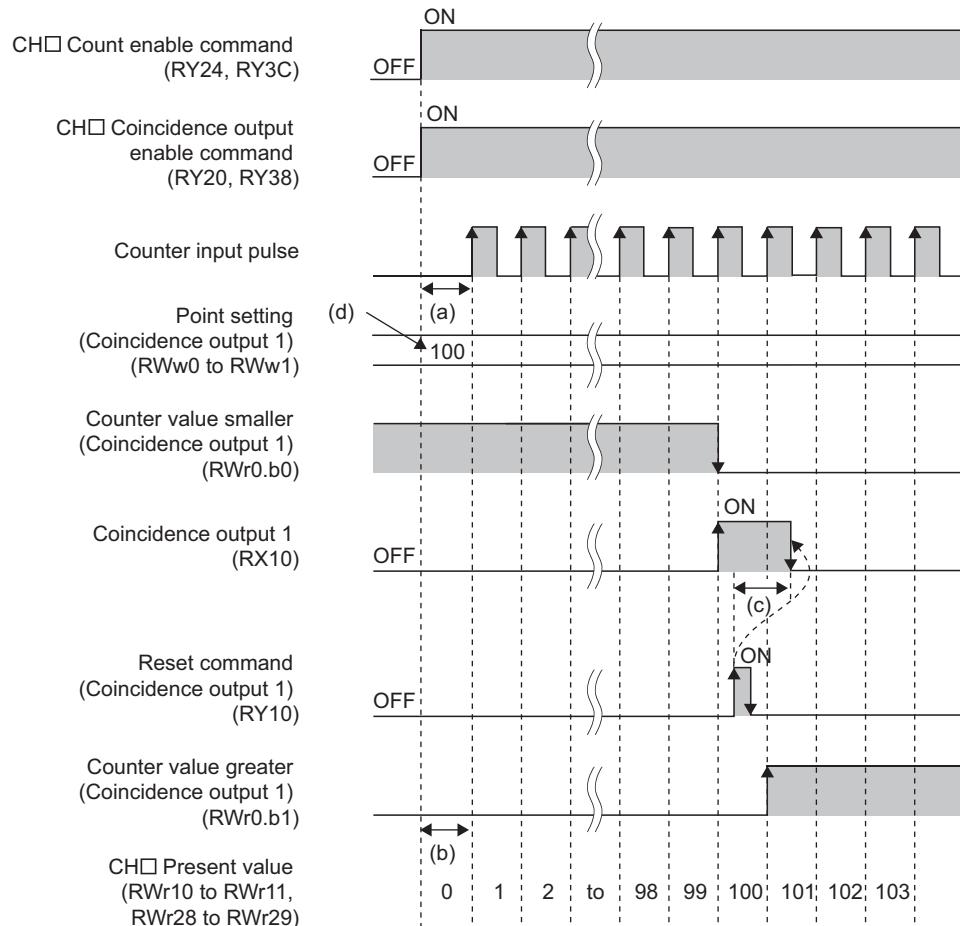
Abbreviation	Description	Remarks
ΔT_1	Indicates the maximum delay time of internal processing. ($\Delta T_2 \times 2$). Link scan time is not included in ΔT_1 .	—
ΔT_2	Internal control cycle time (0.5ms) Link scan time is not included in ΔT_2 .	—
ΔT_3	Processing time for acquiring data for the maximum setting number of steps of cam switches (16 points \times 16 steps) and analyzing them (40ms)	The smaller the number of steps, the shorter the processing time.

(4) Examples of response delay time

An example is described in (a) to (d) regarding the operation of the coincidence output function in the following condition.

- Master/local module is the QJ71GF11-T2
- Block data assurance per station is set
- Asynchronous mode

Ex. Operation of the coincidence output function



(a) Processing time (Normal value): Master station (RY) → Remote device station (RY)

The following shows the processing time required until the high-speed counter module starts pulse input after CH□ Count enable command (RY24, RY3C) is turned on.

$(SM \times n2) + (LS \times 1) + \text{Processing time of the high-speed counter module} (\Delta T_1)$

- SM: Scan time of the program in the master station
- LS: Link scan time
- n2: The value provided by rounding up the value after the decimal point of $(LS \div SM)$

(b) Processing time (Normal value): Master station (RWr) ← Remote device station (RWr)

The following shows the processing time required until a count value is read by the master station after the count value is counted by the high-speed counter module.

$$(SM \times 1) + (LS \times n1) + \text{Processing time of the high-speed counter module} (\Delta T_1)$$

- SM: Scan time of the program in the master station
- LS: Link scan time
- n1: The value provided by rounding up the value after the decimal point of $(SM \div LS)$

(c) Processing time (Normal value): Master station (RX) ← Remote device station (RX)

The following shows the processing time required until Coincidence output 1 (RX10) is transmitted to the master station after the high-speed counter module receives Reset command (Coincidence output 1) (RY10). (The processing time required for transmitting Reset command (Coincidence output 1) (RY10) to the high-speed counter module is not included.)

$$(SM \times 1) + (LS \times n1) + \text{Processing time of the high-speed counter module} (\Delta T_1)$$

- SM: Scan time of the program in the master station
- LS: Link scan time
- n1: The value provided by rounding up the value after the decimal point of $(SM \div LS)$

(d) Processing time (Normal value): Master station (RWw) → Remote device station (RWw)

The following shows the transmission time required for setting Point setting (Coincidence output 1) (RWw0 to RWw1) to the high-speed counter module. (The processing time required for transmitting Setting change request (Coincidence output 1) (RY14) to the high-speed counter module is not included.)

$$(SM \times n2) + (LS \times 1) + \text{Processing time of the high-speed counter module} (\Delta T_1)$$

- SM: Scan time of the program in the master station
- LS: Link scan time
- n2: The value provided by rounding up the value after the decimal point of $(LS \div SM)$

Appendix 5 EMC and Low Voltage Directives

Compliance to the EMC Directive, which is one of the EU Directives, has been a legal obligation for the products sold in European countries since 1996 as well as the Low Voltage Directive since 1997.

Manufacturers who recognize their products are compliant to the EMC and Low Voltage Directives are required to attach a "CE mark" on their products.

(1) Sales representative in EU member states

Authorized representative in EU member states is shown below.

Name: Mitsubishi Electric Europe BV

Address: Gothaer Strasse 8, 40880 Ratingen, Germany

Appendix 5.1 Measures to comply with the EMC directive

The EMC Directive specifies that "products placed on the market must be so constructed that they do not cause excessive electromagnetic interference (emissions) and are not unduly affected by electromagnetic interference (immunity)". This section summarizes the precautions on compliance with the EMC Directive of the machinery constructed with the module.

These precautions are based on the requirements and the standards of the regulation, however, it does not guarantee that the entire machinery constructed according to the descriptions will comply with abovementioned directives.

The method and judgement for complying with the EMC Directive must be determined by the person who constructs the entire machinery.

(1) EMC Directive related standards

(a) Emission requirements

Specification	Test item	Test details	Standard value
EN61131-2: 2007	CISPR16-2-3 Radiated emission ^{*2}	Radio waves from the product are measured.	<ul style="list-style-type: none">• 30M-230MHzQP: 40dBμV/m (10m in measurement range)^{*1}• 230M-1000MHzQP: 47dBμV/m (10m in measurement range)
	CISPR16-2-1, CISPR16-1-2 Conducted emission ^{*2}	Noise from the product to the power line is measured.	<ul style="list-style-type: none">• 150k-500kHzQP: 79dB, Mean: 66dB^{*1}• 500k-30MHzQP: 73dB, Mean: 60dB

^{*1} QP: Quasi-peak value, Mean: Average value

^{*2} The module is an open type device (a device designed to be housed in other equipment) and must be installed inside a conductive control panel. The tests were conducted with the module installed in a control panel.

(b) Immunity requirements

Specification	Test item	Test details	Standard value
EN61131-2: 2007	EN61000-4-2 Electrostatic discharge immunity ^{*1}	Immunity test in which electrostatic is applied to the cabinet of the equipment.	<ul style="list-style-type: none"> • 8kV Air discharge • 4kV Contact discharge
	EN61000-4-3 Radiated, radio-frequency, electromagnetic field immunity ^{*1}	Immunity test in which electric fields are irradiated to the product.	80% AM modulation@1kHz <ul style="list-style-type: none"> • 80M-1000MHz: 10V/m • 1.4G-2.0GHz: 3V/m • 2.0G-2.7GHz: 1V/m
	EN61000-4-4 Electrical fast transient/burst immunity ^{*1}	Immunity test in which burst noise is applied to the power line and signal line.	<ul style="list-style-type: none"> • AC/DC main power, I/O power, AC I/O (unshielded): 2kV • DC I/O, analog, communication: 1kV
	EN61000-4-5 Surge immunity ^{*1}	Immunity test in which lightning surge is applied to the power line and signal line.	<ul style="list-style-type: none"> • AC power line, AC I/O power, AC I/O (unshielded): 2kV CM, 1kV DM • DC power line, DC I/O power: 0.5kV CM, DM • DC I/O, AC I/O (shielded), analog^{*2}, communication: 1kV CM
	EN61000-4-6 Immunity to conducted disturbances, induced by radio-frequency fields ^{*1}	Immunity test in which high frequency noise is applied to the power line and signal line	0.15M-80MHz, 80% AM modulation @1kHz, 10Vrms
	EN61000-4-8 Power-frequency magnetic field immunity ^{*1}	Immunity test in which the product is installed in inductive magnetic field	50Hz/60Hz, 30A/m
	EN61000-4-11 Voltage dips and interruption immunity ^{*1}	Immunity test in which power supply voltage is momentarily interrupted	<ul style="list-style-type: none"> • Apply at 0%, 0.5 cycles and zero-cross point • 0%, 250/300 cycles (50/60Hz) • 40%, 10/12 cycles (50/60Hz) • 70%, 25/30 cycles (50/60Hz)

*1 The module is an open type device (a device designed to be housed in other equipment) and must be installed inside a conductive control panel. The tests were conducted with the programmable controller installed in a control panel.

*2 The accuracy of an analog-digital converter module may temporarily vary within ±10%.

(2) Installation in a control panel

The module is open type devices and must be installed inside a control panel. This ensures safety as well as effective shielding of programmable controller-generated electromagnetic noise.

(a) Control panel

- Use a conductive control panel.
- When securing the top or bottom plate using bolts, cover the grounding part on the control panel so that the part will not be painted.
- To ensure electrical contact between the inner plate and control panel, take measures such as covering the bolts so that conductivity can be ensured in the largest possible area.
- Ground the control panel with a thick ground cable so that low impedance can be ensured even at high frequencies.
- Holes in the control panel must be 10cm diameter or less. If the holes are larger than 10cm, radio wave may be emitted. In addition, because radio waves leak through a clearance between the control panel and its door, reduce the clearance as much as possible. The leakage of radio waves can be suppressed by the direct application of an EMI gasket on the paint surface.

Our tests have been carried out on a panel having the attenuation characteristics of 37 dB (max.) and 30 dB (mean) (measured by 3m method, 30 to 300MHz).

(b) Wiring of power cables and ground cables

- Near the power supply part, provide a ground point to the control panel. Ground the FG terminal with the thickest and shortest possible ground cable (30cm or shorter).

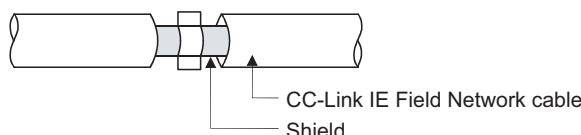
(3) Cables

Use shielded cables for the cables which are connected to the module and run out from the control panel. If a shielded cable is not used or not grounded correctly, the noise immunity will not meet the specified value.

(a) Cables for the CC-Link IE Field Network

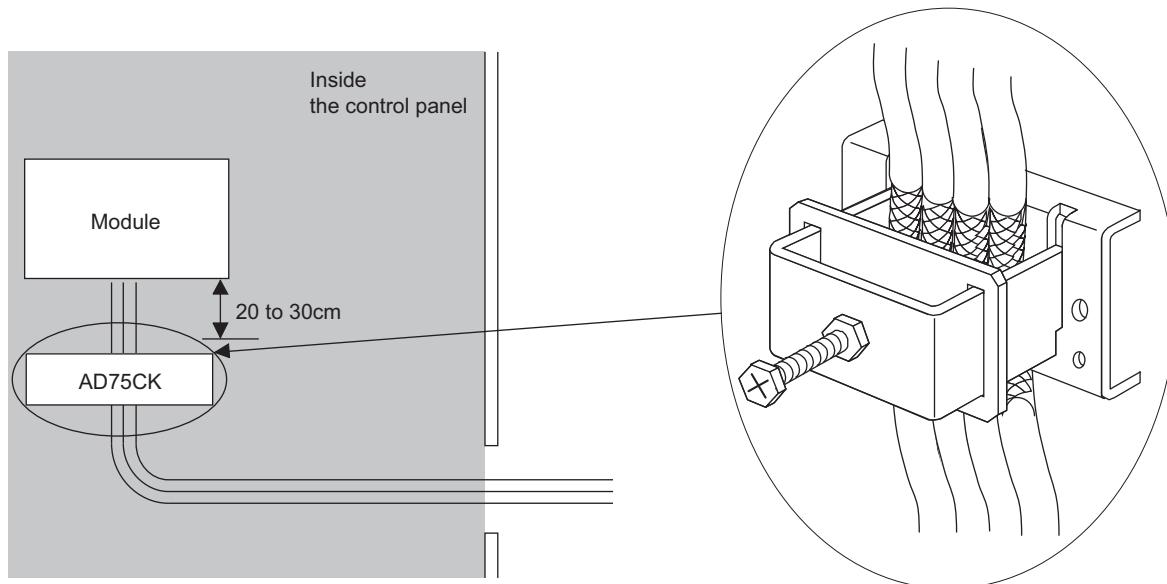
The precautions for using CC-Link IE Field Network cables are described below.

- Shielded cables should be used for the CC-Link IE Field Network. Strip a part of the jacket as shown below and ground the exposed shield in the largest possible area.



(b) Grounding the cable clamp

Use shielded cables for external wiring and ground the shields of the external wiring cables to the control panel with the AD75CK-type cable clamp (Mitsubishi). (Ground the shield section 20 to 30cm away from the module.)



For details of the AD75CK, refer to the following.

AD75CK-type Cable Clamping Instruction Manual

(4) External power supply

- Use a CE-marked product for an external power supply and always ground the FG terminal. (External power supply used for the tests conducted by Mitsubishi: TDK-Lambda DLP-120-24-1, IDEC PS5R-SF24, PS5R-F24)
- Use a power cable of 10m or shorter when connecting it to the module power supply terminal.

(5) Encoder and controller

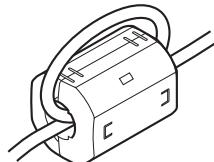
- Install the DC power connected to the encoder inside the same control panel as the high-speed counter module.
- Use a cable of 3m or shorter between the encoder for the open collector output and the pulse input terminal.
- Use a cable of 10m or shorter between the encoder for the differential output and the pulse input terminal.
- Use cables of 30m or shorter between the high-speed counter module and the external output/the high-speed counter module and the pulse input terminal.
- Be sure to attach ferrite cores to the DC power cables to be connected to the high-speed counter module and the controller. The ferrite core ZCAT3035-1330 (manufactured by TDK Corporation) is recommended.

(6) Others

(a) Ferrite core

A ferrite core has the effect of reducing radiated noise in the 30MHz to 100MHz band. It is recommended to attach ferrite cores if shield cables coming out of the control panel do not provide sufficient shielding effects. Note that the ferrite cores must be attached at the position closest to the cable hole inside the control panel. If attached at an improper position, the ferrite core will not produce any effect.

For the FG terminal on a main module that is connected to the external power supply, the external power supply of an extension module, and CC-Link IE Field Network cables, attach a ferrite core 4cm away from the module. (Ferrite core used for the tests conducted by Mitsubishi: NEC TOKIN ESD-SR-250, TDK ZCAT3035-1330)



Appendix 5.2 Requirements to compliance with the low voltage directive

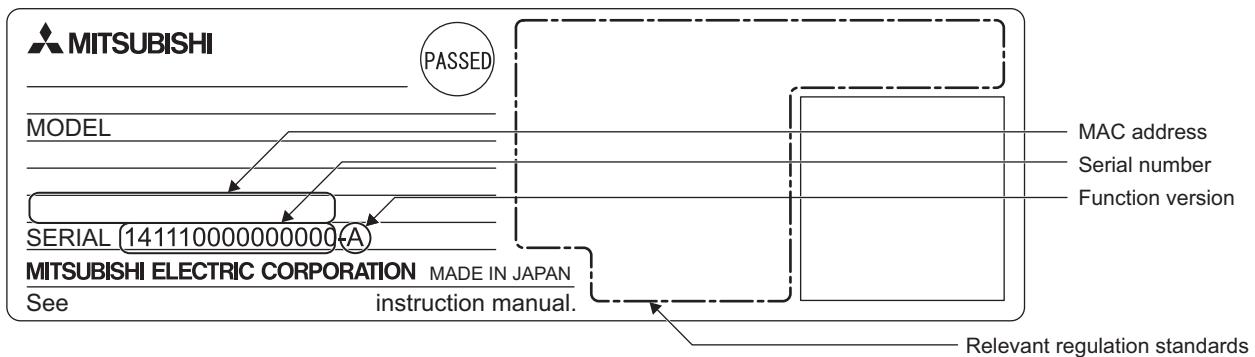
The module operates at the rated voltage of 24VDC. The Low Voltage Directive is not applied to the modules that operate at the rated voltage of less than 50VAC and 75VDC.

A

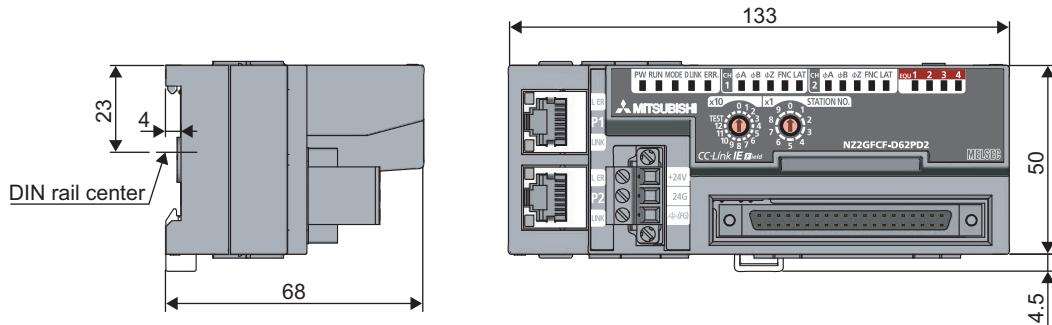
Appendix 5 EMC and Low Voltage Directives
Appendix 5.2 Requirements to compliance with the low voltage directive

Appendix 6 Checking Serial Number and Function Version

The serial number and function version of the high-speed counter module can be checked on the rating plate.



Appendix 7 External Dimensions



(Unit: mm)

A

INDEX

0 to 9

1-phase multiple of 1	92
1-phase multiple of 2	92
2-phase multiple of 1	93
2-phase multiple of 2	93
2-phase multiple of 4	93

A

Applicable DIN rail model (compliant with IEC 60715)	62
Applicable systems	54
Applicable master station	54
Connectable modules	54
Ethernet cable	54
Software package	54
Application	16

B

Bending radius of the Ethernet cable	67
--	----

C

Calculating current consumption	32
Cam switch function	117
Cam switch output channel assignment setting (address: 0105 _H)	269
Cam switch output signal (RW _r 2)	256
Cam switch output terminal status (RW _r 3)	256
Cam switch output unit assignment setting (address: 0104 _H)	269
CC-Link IE Field Network diagnostic function	175
Channel assignment (Coincidence output 1 to 4) (address: 0600 _H)	274
Checking for the error codes and the warning codes	205
Checking by CH□ Latest error code (RW _r 22, RW _r 3A)	207
Checking by CH□ Latest warning code (RW _r 23, RW _r 3B)	207
Checking by executing a command of the slave station	205
Checking the LEDs	224
CH□ Cam switch execute command/PWM output start command (RY26, RY3E)	252
CH□ Cam switch execute/PWM output (RX26, RX3E)	242
CH□ Coincidence output enable command (RY20, RY38)	250
CH□ Count down command (RY22, RY3A)	251
CH□ Count enable command (RY24, RY3C)	251
CH□ Count source selection (address: 0121 _H , 0141 _H)	269
CH□ Counter format (address: 0124 _H , 0144 _H)	271
CH□ Counter function detection (RX25, RX3D)	242
CH□ Counter function selection (address: 0126 _H , 0146 _H)	272

CH□ Counting speed setting (address: 0123 _H , 0143 _H)	270
CH□ Cycle setting (PWM output) (RW _w 20 to RW _w 21, RW _w 38 to RW _w 39)	266
CH□ Cycle setting (Sampling counter/ Periodic pulse counter) (RW _w 17, RW _w 2F)	264
CH□ Error reset command (RY36, RY4E)	253
CH□ Error status (RX36, RX4E)	248
CH□ External control input response time setting (address: 0129 _H , 0149 _H)	273
CH□ External input status (RW _r 21, RW _r 39)	260
CH□ External preset/replace (Z Phase) request detection (RX23, RX3B)	241
CH□ External preset/replace (Z Phase) request detection reset command (RY23, RY3B)	251
CH□ Function input logic setting (address: 0127 _H , 0147 _H)	272
CH□ Latch count value (Latch counter input terminal) (RW _r 18 to RW _r 19, RW _r 30 to RW _r 31)	258
CH□ Latch count value update flag (Latch counter input terminal) (RX2B, RX43)	245
CH□ Latch count value update flag reset command (Latch counter input terminal) (RY2A, RY42)	252
CH□ Latch count value update flag reset completed (Latch counter input terminal) (RX2A, RX42)	245
CH□ Latch count value/Sampling count value/ Periodic pulse count, difference value (RW _r 12 to RW _r 13, RW _r 2A to RW _r 2B)	257
CH□ Latch counter input logic setting (address: 0128 _H , 0148 _H)	272
CH□ Latest error code (RW _r 22, RW _r 3A)	260
CH□ Latest warning code (RW _r 23, RW _r 3B)	260
CH□ Measured frequency value/Measured rotation speed value (RW _r 1A to RW _r 1B, RW _r 32 to RW _r 33)	258
CH□ Measured pulse value (Function input terminal) (RW _r 1C to RW _r 1D, RW _r 34 to RW _r 35)	258
CH□ Measured pulse value (Latch counter input terminal) (RW _r 1E to RW _r 1F, RW _r 36 to RW _r 37)	258
CH□ Measured pulse value update flag (Function input terminal) (RX32, RX4A)	246
CH□ Measured pulse value update flag (Latch counter input terminal) (RX34, RX4C)	247
CH□ Measured pulse value update flag reset command (Function input terminal) (RY31, RY49)	253
CH□ Measured pulse value update flag reset command (Latch counter input terminal) (RY33, RY4B)	253
CH□ Measured pulse value update flag reset completed (Function input terminal) (RX31, RX49)	246
CH□ Measured pulse value update flag reset completed (Latch counter input terminal) (RX33, RX4B)	247
CH□ Moving average count (Frequency measurement/Rotation speed measurement) (RW _w 19, RW _w 31)	265
CH□ Number of pulses per rotation (RW _w 1A to RW _w 1B, RW _w 32 to RW _w 33)	265
CH□ ON width setting (PWM output) (RW _w 1E to RW _w 1F, RW _w 36 to RW _w 37)	266

CH□ ON width setting change completed (PWM output) (RX35, RX4D)	247
CH□ ON width setting change request (PWM output) (RY35, RY4D)	253
CH□ Operation mode (address: 0620 _H , 0640 _H)	275
CH□ Operation mode setting (address: 0120 _H , 0140 _H)	269
CH□ Periodic pulse count value update check (RW _r 16 to RW _r 17, RW _r 2E to RW _r 2F)	257
CH□ Periodic pulse count, present value (RW _r 14 to RW _r 15, RW _r 2C to RW _r 2D)	257
CH□ Phase Z setting (address: 0125 _H , 0145 _H)	271
CH□ Present value (RW _r 10 to RW _r 11, RW _r 28 to RW _r 29)	257
CH□ Preset value setting (RW _w 14 to RW _w 15, RW _w 2C to RW _w 2D)	263
CH□ Preset/replace command (RY21, RY39)	251
CH□ Preset/replace completion (RX21, RX39)	241
CH□ Pulse input mode (address: 0122 _H , 0142 _H)	270
CH□ Pulse measurement setting (Function input terminal) (address: 012A _H , 014A _H)	274
CH□ Pulse measurement setting (Latch counter input terminal) (address: 012B _H , 014B _H)	274
CH□ Pulse measurement start command (Function input terminal) (RY30, RY48)	253
CH□ Pulse measurement start command (Latch counter input terminal) (RY32, RY4A)	253
CH□ PWM output assignment setting (RW _w 1D, RW _w 35)	266
CH□ Ring counter lower limit value (RW _w 10 to RW _w 11, RW _w 28 to RW _w 29)	263
CH□ Ring counter upper limit value (RW _w 12 to RW _w 13, RW _w 2A to RW _w 2B)	263
CH□ Selected counter function (address: 0621 _H , 0641 _H)	275
CH□ Selected counter function start command (RY25, RY3D)	252
CH□ Setting change completed (Sampling counter/Periodic pulse counter) (RX27, RX3F)	242
CH□ Setting change request (Sampling counter/Periodic pulse counter) (RY27, RY3F)	252
CH□ Status (RW _r 20, RW _r 38)	259
CH□ Time unit setting (Frequency measurement/Rotation speed measurement) (RW _w 18, RW _w 30)	265
CH□ Time unit setting (Sampling counter/Periodic pulse counter) (RW _w 16, RW _w 2E)	264
CH□ Update flag (Latch count value/Sampling count value/Periodic pulse count value) (RX29, RX41)	244
CH□ Update flag (Measured frequency value/Measured rotation speed value) (RX2D, RX45)	246
CH□ Update flag reset command (Latch count value/Sampling count value/Periodic pulse count value) (RY28, RY40)	252
CH□ Update flag reset command (Measured frequency value/Measured rotation speed value) (RY2C, RY44)	253
CH□ Update flag reset completed (Latch count value/Sampling count value/Periodic pulse count value) (RX28, RX40)	243
CH□ Update flag reset completed (Measured frequency value/Measured rotation speed value) (RX2C, RX44)	245
CH□ Warning status (RX37, RX4F)	248

Coincidence output 1 to 4 (RX10 to RX13)	239
Coincidence output channel assignment setting (address: 0101 _H)	268
Coincidence output comparison condition setting (address: 0102 _H)	268
Coincidence output function	103
Comparison output function	102
Comparison output setting (address: 0100 _H)	268
Connecting extension modules	58
Connecting the Ethernet cable	65
Connector crimp tool	70
Connectors for external devices	23, 70
Control cycle of the high-speed counter module (ΔT ₂)	283
Count disable function	131
Count disable/preset/replace function	142
Counter function selection	129
Counter value greater/smaller signal (RW _r 0)	255
CW/CCW	92
Cyclic data update watch function	168
Cyclic data update watch time setting (address: 0003 _H)	267

D

D LINK LED	22
Details of remote buffer memory addresses	267
Details of remote I/O signals	236
Details of remote registers	255
DIN rail hook	23
DIN rail stopper	62
Disconnecting	66

E

Encoders that can be connected	75
EQU1 to EQU4 LED	22
EQU1 to EQU4 terminal status (RW _r 1)	255
ERR. LED	22
Error code list	208
Error history clear command (address: 1000 _H)	277
Error history clear completed (address: 1001 _H)	277
Error history (address: 0A00 _H to 0AFF _H)	276
Error notification function	169
Error status flag (RXA)	239
Extended parameter area (address: 1500 _H to 1FFF _H)	280
Extended parameter area (address: 1580 _H to 1CA1 _H)	281
External dimensions	293
External power supply monitor request flag (RY1F)	250
External power supply monitor state flag (RX1F)	240
External power supply monitoring function	173

F

Features	17
FNC/LAT LED	22
Frequency measurement function	148
Function at the extension module installation	172

G

General specifications	25
------------------------	----

I

I/O interfaces with external devices	71
Initial data processing completion flag (RY8)	249
Initial data processing request flag (RX8)	237
Initial data setting completion flag (RX9)	238
Initial data setting request flag (RY9)	249
Input response time setting (address: 0001 _H)	267
Input response time setting function	174
Installation and wiring	55
Installation direction	57
Installation environment	56
Installation position	56
Internal control cycle and response delay time	283

L

Latch counter function (counter function selection)	133
Latch counter function by latch counter input terminal	127
Latch counter/preset/replace function	145
Laying Ethernet cables	67
Linear counter function	95
List of remote buffer memory	41
List of remote I/O signals	35
List of remote register	39

M

Maintenance and inspection	203
Maximum station-to-station distance (Maximum Ethernet cable length)	67
MODE LED	22
Module operation information initialization command (address: 1004 _H)	279
Module operation information initialization completed (address: 1005 _H)	280
Mounting the modules on a DIN rail	60

O

Operation mode list	90
Output HOLD/CLEAR setting (address: 0002 _H)	267
Output HOLD/CLEAR setting function	167

P

Packing list	14
Parameter area initialization command (address: 1002 _H)	278
Parameter area initialization completed (address: 1003 _H)	279
Parameter setting	80
Changing the network configuration	86
Changing the parameter without changing the network configuration	88
Part names	21
Performance specifications	27

Periodic pulse counter function	139
φA/φB/φZ LED	22
Phase difference	31
Point setting (Coincidence output 1 to 4)/Lower limit value setting (Coincidence output 1 to 4) (RWw0 to RWw1, RWw4 to RWw5, RWw8 to RWw9, RWwC to RWwD)	261
Preset/replace (at coincidence output) function	114
Preset/replace function	122
Preset/replace setting at coincidence output (address: 0103 _H)	268
Program example	181
Program example of the frequency measurement mode	199
Program example of the pulse measurement mode	201
Program example of the PWM output mode	202
Program example of the rotation speed measurement mode	200
Program example under the normal mode (when the cam switch function is set with the comparison output function)	197
Program example under the normal mode (when the coincidence output is set with the comparison output function)	193
Programming	178
Precautions for programming	178
Procedure for programming	180
Pulse input mode	92
Pulse measurement function	156
PW LED	22
PWM output function	160

R

Remote READY (RXB)	239
Reset command	
(Coincidence output 1 to 4) (RY10 to RY13)	250
Ring counter function	97
Rotation speed measurement function	152
RUN LED	22

S

Sampling counter function	136
Setting change completed	
(Coincidence output 1 to 4) (RX14 to RX17)	240
Setting change request	
(Coincidence output 1 to 4) (RY14 to RY17)	250
Station number setting	55
Station number setting switch	22
System configuration	53

T

Term	12
Terminal block for module power supply and FG	23
The procedure before operation	51
To replace the module	51
Troubleshooting	205
Troubleshooting for each phenomenon	228

U

Unit test	227
Upper limit value setting (Coincidence output 1 to 4) (RWw2 to RWw3, RWw6 to RWw7, RWwA to RWwB, RWwE to RWwF)	262

W

Warning status flag (RX7)	236
Wiring of connectors for external devices	68
Wiring of Ethernet cable	65
Wiring with terminal block for module power supply and FG	63

I

REVISIONS

*The manual number is given on the bottom left of the back cover.

Print date	*Manual number	Revision
March, 2013	SH(NA)-081129ENG-A	First edition

Japanese manual version SH-081128-A

This manual confers no industrial property rights or any rights of any other kind, nor does it confer any patent licenses. Mitsubishi Electric Corporation cannot be held responsible for any problems involving industrial property rights which may occur as a result of using the contents noted in this manual.

© 2013 MITSUBISHI ELECTRIC CORPORATION

WARRANTY

Please confirm the following product warranty details before using this product.

1. Gratis Warranty Term and Gratis Warranty Range

If any faults or defects (hereinafter "Failure") found to be the responsibility of Mitsubishi occurs during use of the product within the gratis warranty term, the product shall be repaired at no cost via the sales representative or Mitsubishi Service Company.

However, if repairs are required onsite at domestic or overseas location, expenses to send an engineer will be solely at the customer's discretion. Mitsubishi shall not be held responsible for any re-commissioning, maintenance, or testing on-site that involves replacement of the failed module.

[Gratis Warranty Term]

The gratis warranty term of the product shall be for one year after the date of purchase or delivery to a designated place.

Note that after manufacture and shipment from Mitsubishi, the maximum distribution period shall be six (6) months, and the longest gratis warranty term after manufacturing shall be eighteen (18) months. The gratis warranty term of repair parts shall not exceed the gratis warranty term before repairs.

[Gratis Warranty Range]

- (1) The range shall be limited to normal use within the usage state, usage methods and usage environment, etc., which follow the conditions and precautions, etc., given in the instruction manual, user's manual and caution labels on the product.
- (2) Even within the gratis warranty term, repairs shall be charged for in the following cases.
 1. Failure occurring from inappropriate storage or handling, carelessness or negligence by the user. Failure caused by the user's hardware or software design.
 2. Failure caused by unapproved modifications, etc., to the product by the user.
 3. When the Mitsubishi product is assembled into a user's device, Failure that could have been avoided if functions or structures, judged as necessary in the legal safety measures the user's device is subject to or as necessary by industry standards, had been provided.
 4. Failure that could have been avoided if consumable parts (battery, backlight, fuse, etc.) designated in the instruction manual had been correctly serviced or replaced.
 5. Failure caused by external irresistible forces such as fires or abnormal voltages, and Failure caused by force majeure such as earthquakes, lightning, wind and water damage.
 6. Failure caused by reasons unpredictable by scientific technology standards at time of shipment from Mitsubishi.
 7. Any other failure found not to be the responsibility of Mitsubishi or that admitted not to be so by the user.

2. Onerous repair term after discontinuation of production

- (1) Mitsubishi shall accept onerous product repairs for seven (7) years after production of the product is discontinued.
Discontinuation of production shall be notified with Mitsubishi Technical Bulletins, etc.
- (2) Product supply (including repair parts) is not available after production is discontinued.

3. Overseas service

Overseas, repairs shall be accepted by Mitsubishi's local overseas FA Center. Note that the repair conditions at each FA Center may differ.

4. Exclusion of loss in opportunity and secondary loss from warranty liability

Regardless of the gratis warranty term, Mitsubishi shall not be liable for compensation of damages caused by any cause found not to be the responsibility of Mitsubishi, loss in opportunity, lost profits incurred to the user by Failures of Mitsubishi products, special damages and secondary damages whether foreseeable or not, compensation for accidents, and compensation for damages to products other than Mitsubishi products, replacement by the user, maintenance of on-site equipment, start-up test run and other tasks.

5. Changes in product specifications

The specifications given in the catalogs, manuals or technical documents are subject to change without prior notice.

Microsoft, Windows, Windows NT, and Windows Vista are registered trademarks of Microsoft Corporation in the United States and other countries.

Pentium is a trademark of Intel Corporation in the United States and other countries.

Ethernet is a trademark of Xerox Corporation.

The SD logo and SDHC logo are trademarks.

All other company names and product names used in this manual are trademarks or registered trademarks of their respective companies.



CC-Link IE Field Network High-Speed Counter Module User's Manual

MODEL	CCIEF-CT-U-E
MODEL CODE	13JZ83
SH(NA)-081129ENG-A(1303)MEE	



HEAD OFFICE : TOKYO BUILDING, 2-7-3 MARUNOUCHI, CHIYODA-KU, TOKYO 100-8310, JAPAN
NAGOYA WORKS : 1-14, YADA-MINAMI 5-CHOME, HIGASHI-KU, NAGOYA, JAPAN

When exported from Japan, this manual does not require application to the
Ministry of Economy, Trade and Industry for service transaction permission.

Specifications subject to change without notice.

HEADQUARTERS		EUROPEAN REPRESENTATIVES		EUROPEAN REPRESENTATIVES		EURASIAN REPRESENTATIVES	
MITSUBISHI ELECTRIC EUROPE B.V.	EUROPE	GEVA	AUSTRIA	ALFATRADE Ltd.	MALTA	TOO Kazpromavtomatika	KAZAKHSTAN
German Branch		Wiener Straße 89		99, Paola Hill		U.I. Zhambyla 28	
Gothaer Straße 8		AT-2500 Baden		Malta- Paola PLA 1702		KAZ-00017 Karaganda	
D-40880 Ratingen		Phone: +43 (0)2252 / 85 55 20		Phone: +356 (0)21 / 697 816		Phone: +7 7212 / 50 10 00	
Phone: +49 (0)2102 / 486-0		Fax: +43 (0)2252 / 488 60		Fax: +356 (0)21 / 697 817		Fax: +7 7212 / 50 11 50	
MITSUBISHI ELECTRIC EUROPE B.V.-org.sl. CZECH REP.		TECHNIKON	BELARUS	INTEHSIS srl	MOLDOVA		
Czech Branch		Okyabrskaya 19, Off. 705		bld. Traian 23/1			
Avenir Business Park, Radlická 714/113a		BY-220030 Minsk		MD-2060 Kishinev			
CZ-158 00 Praha 5		Phone: +375 (0)17 / 210 46 26		Phone: +373 (0)22 / 66 4242			
Phone: +420 - 251 551 470		Fax: +375 (0)17 / 210 46 26		Fax: +373 (0)22 / 66 4280			
Fax: +420 - 251-551-471		ESCO DRIVES & AUTOMATION	BELGIUM	HIFLEX AUTOM.TECHNIK B.V.	NETHERLANDS		
MITSUBISHI ELECTRIC EUROPE B.V.	FRANCE	BE-1831 Diegem		Wolveverstraat 22			
French Branch		Phone: +32 (0)2 / 717 64 30		NL-2984 CD Ridderkerk			
25, Boulevard des Bouvets		Fax: +32 (0)2 / 717 64 31		Phone: +31 (0)180 - 46 60 04			
F-92741 Nanterre Cedex		Koning & Hartman b.v.	BELGIUM	Fax: +31 (0)180 - 44 23 55			
Phone: +33 (0)1 / 55 68 55 68		Woluwelaan 31		Koning & Hartman b.v.	NETHERLANDS		
Fax: +33 (0)1 / 55 68 57 57		BE-1800 Vilvoorde		Haarlerbergweg 21-23			
MITSUBISHI ELECTRIC EUROPE B.V.	IRELAND	Phone: +32 (0)2 / 257 02 40		NL-1101 CH Amsterdam			
Irish Branch		Fax: +32 (0)2 / 257 02 49		Phone: +31 (0)20 / 587 76 00			
Westgate Business Park, Ballymount		INEA RBT d.o.o.	BOSNIA AND HERZEGOVINA	Fax: +31 (0)20 / 587 76 05			
IRL-Dublin 24		Aleja Lipa 56		Beijer Electronics AS	NORWAY		
Phone: +353 (0)1 4198800		BA-71000 Sarajevo		Postboks 487			
Fax: +353 (0)1 419890		Phone: +387 (0)33 / 921 164		NO-3002 Drammen			
MITSUBISHI ELECTRIC EUROPE B.V.	ITALY	Fax: +387 (0)33 / 524 539		Phone: +47 (0)32 / 24 30 00			
Italian Branch		AKHNATON	BULGARIA	Fax: +47 (0)32 / 84 85 77			
Viale Colleoni 7		4, Andrei Ljapchev Blvd., PO Box 21		Fonseca S.A.	PORTUGAL		
I-20864 Agrate Brianza (MB)		BG-1756 Sofia		R. João Francisco do Casal 87/89			
Phone: +39 039 / 60 53 1		Phone: +359 (0)2 / 817 6000		PT - 3801-997 Aveiro, Esgueira			
Fax: +39 039 / 60 53 312		Fax: +359 (0)2 / 97 44 06 1		Phone: +351 (0)234 / 303 900			
MITSUBISHI ELECTRIC EUROPE B.V.	POLAND	INEA RBT d.o.o.	CROATIA	Fax: +351 (0)234 / 303 910			
Poland Branch		Losinjska 4 a		Sirius Trading & Services srl	ROMANIA		
Krakowska 50		HR-10000 Zagreb		Aleea Lacul Morii Nr. 3			
PL-32-083 Balice		Phone: +385 (0)1 / 36 940 -01/-02/-03		RO-060841 Bucuresti, Sector 6			
Phone: +48 (0)12 / 630 47 00		Fax: +385 (0)1 / 36 940 -03		Phone: +40 (0)21 / 430 40 06			
Fax: +48 (0)12 / 630 47 01		AutoCont C.S. s.r.o.	CZECH REPUBLIC	Fax: +40 (0)21 / 430 40 02			
MITSUBISHI ELECTRIC EUROPE B.V.	RUSSIA	Technologická 374/6		INEA RBT d.o.o.	SERBIA		
52, bld. 3 Kosmodamianskaya nab 8 floor		CZ-708 00 Ostrava-Pustkovec		Izletnicka 10			
RU-115054 Moscow		Phone: +420 595 691 150		SER-11300 Smederevo			
Phone: +7 495 721-2070		Fax: +420 595 691 199		Phone: +381 (0)26 / 615 401			
Fax: +7 495 721-2071		Beijer Electronics A/S	DENMARK	Fax: +381 (0)26 / 615 401			
MITSUBISHI ELECTRIC EUROPE B.V.	SPAIN	Dykkegårdsvæj 17		SIMAP s.r.o.	SLOVAKIA		
Spanish Branch		DK-4000 Roskilde		Jána Derku 1671			
Carretera de Rubí 78-80		Phone: +45 (0)46 / 75 76 66		SK-911 01 Trenčín			
E-08190 San Cugat del Vallés (Barcelona)		Fax: +45 (0)46 / 75 56 26		Phone: +421 (0)32 743 04 72			
Phone: 902 131121 // +34 935653131		Beijer Electronics Eesti OÜ	ESTONIA	Fax: +421 (0)32 743 75 20			
Fax: +34 93581579		Pärnu mnt.160i		PROCONT, spol. s r.o. Prešov	SLOVAKIA		
MITSUBISHI ELECTRIC EUROPE B.V.	UK	EE-11317 Tallinn		Kúpelná 1/A			
UK Branch		Phone: +372 (0)6 / 51 81 40		SK-080 01 Prešov			
Travellers Lane		Fax: +372 (0)6 / 51 81 49		Phone: +421 (0)51 7580 611			
UK-Hatfield, Herts. AL10 8XB		Beijer Electronics OY	FINLAND	Fax: +421 (0)51 7580 650			
Phone: +44 (0)1707 / 27 61 00		Peltoja 37		INEA RBT d.o.o.	SLOVENIA		
Fax: +44 (0)1707 / 27 86 95		FIN-28400 Ulvila		Stegne 11			
MITSUBISHI ELECTRIC CORPORATION	JAPAN	Phone: +358 (0)207 / 463 540		SI-1000 Ljubljana			
Office Tower "Z" 14 F		Fax: +358 (0)207 / 463 541		Phone: +386 (0)1 / 513 8116			
8-12, 1 chome, Harumi Chuo-Ku		UTECO	GREECE	Fax: +386 (0)1 / 513 8170			
Tokyo 104-6212		5, Mavrogenous Str.		Beijer Electronics AB	SWEDEN		
Phone: +81 3 622 160 60		GR-18542 Piraeus		Box 426			
Fax: +81 3 622 160 75		Phone: +30 211 / 1206 900		SE-20124 Malmö			
MITSUBISHI ELECTRIC AUTOMATION, Inc.	USA	Fax: +30 211 / 1206 999		Phone: +46 (0)40 / 35 86 00			
500 Corporate Woods Parkway		MELTRADE Kft.	HUNGARY	Fax: +46 (0)40 / 93 23 01			
Vernon Hills, IL 60061		Fertő utca 14.		Omni Ray AG	SWITZERLAND		
Phone: +1 847 478 21 00		HU-1107 Budapest		Im Schörl 5			
Fax: +1 847 478 22 53		Phone: +36 (0)1 / 431-9726		CH-8600 Dübendorf			
		Fax: +36 (0)1 / 431-9727		Phone: +41 (0)44 / 802 28 80			
		Beijer Electronics SIA	LATVIA	Fax: +41 (0)44 / 802 28 28			
		Ritausmas iela 23		GTS	TURKEY		
		LV-1058 Riga		Bayraktar Bulvari Nutuk Sok. No:5			
		Phone: +371 (0)784 / 2280		TR-34775 Yukarı Dudullu-Ümraniye-İSTANBUL			
		Fax: +371 (0)784 / 2281		Phone: +90 (0)216 526 39 90			
		Beijer Electronics UAB	LITHUANIA	Fax: +90 (0)216 526 3995			
		Savanoriu Pr. 187		CSC Automation Ltd.	UKRAINE		
		LT-02300 Vilnius		4-B, M. Raskovoy St.			
		Phone: +370 (0)5 / 232 3101		UA-02660 Kiev			
		Fax: +370 (0)5 / 232 2980		Phone: +380 (0)44 / 494 33 55			
				Fax: +380 (0)44 / 494-33-66			