



DFS60A-TEPZ00S09

DFS60

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

Type	part no.
DFS60A-TEPZ00S09	1081207

Other models and accessories → www.sick.com/DFS60

Detailed technical data

Features

Special device	✓
Specialty	Cable, 8-wire, with plug, M23, 12-pin, universal, 0.35 m, (2061621) Programmable resolution up to 65,536 lines, preprogrammed to 1,024 lines DOS-2312-G (6027538) included in delivery HTL preprogrammed
Standard reference device	DFS60A-TEPK65536, 1036964

Safety-related parameters

MTTF_D (mean time to dangerous failure)	300 years (EN ISO 13849-1) ¹⁾
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¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Pulses per revolution	1,024 ¹⁾
Measuring step	90°, electric/pulses per revolution
Measuring step deviation at binary number of lines	± 0.008°
Error limits	± 0.03°

¹⁾ See maximum revolution range.

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / HTL
Factory setting	Factory setting: output level TTL
Number of signal channels	6-channel
Programmable/configurable	✓

¹⁾ With mechanical zero pulse width.

Initialization time	32 ms, 30 ms ¹⁾
Output frequency	≤ 820 kHz
Load current	≤ 30 mA
Power consumption	≤ 0.7 W (without load)

¹⁾ With mechanical zero pulse width.

Electronics

Connection type	Special version
Connection type Detail	Cable, 8-wire, with plug, M23, 12-pin, universal, 0.35 m, (2061621)
Supply voltage	4.5 ... 32 V
Reference signal, number	1
Reference signal, position	90°, electric, logically gated with A and B
Reverse polarity protection	✓
Short-circuit protection of the outputs	✓ ¹⁾ ²⁾

¹⁾ Programming TTL with ≥ 5.5 V: short-circuit opposite to another channel or GND permissible for maximum 30 s.

²⁾ Programming HTL or TTL with < 5.5 V: short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

Mechanics

Mechanical design	Through hollow shaft
Shaft diameter	12 mmFront clamp
Weight	+ 0.2 kg
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.8 Ncm (+20 °C)
Operating torque	0.6 Ncm (+20 °C)
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial)
Permissible movement dynamic	± 0.05 mm (radial) ± 0.01 mm (axial)
Operating speed	≤ 6,000 min ⁻¹ ¹⁾
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.6 x 10 ¹⁰ revolutions
Angular acceleration	≤ 500,000 rad/s ²

¹⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, Housing side, male connector (IEC 60529) ¹⁾ IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)

¹⁾ With mating connector fitted.

²⁾ Stationary position of the cable.

³⁾ Flexible position of the cable.

Operating temperature range	-40 °C ... +100 °C ²⁾ -30 °C ... +100 °C ³⁾
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	100 g, 6 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

¹⁾ With mating connector fitted.

²⁾ Stationary position of the cable.

³⁾ Flexible position of the cable.

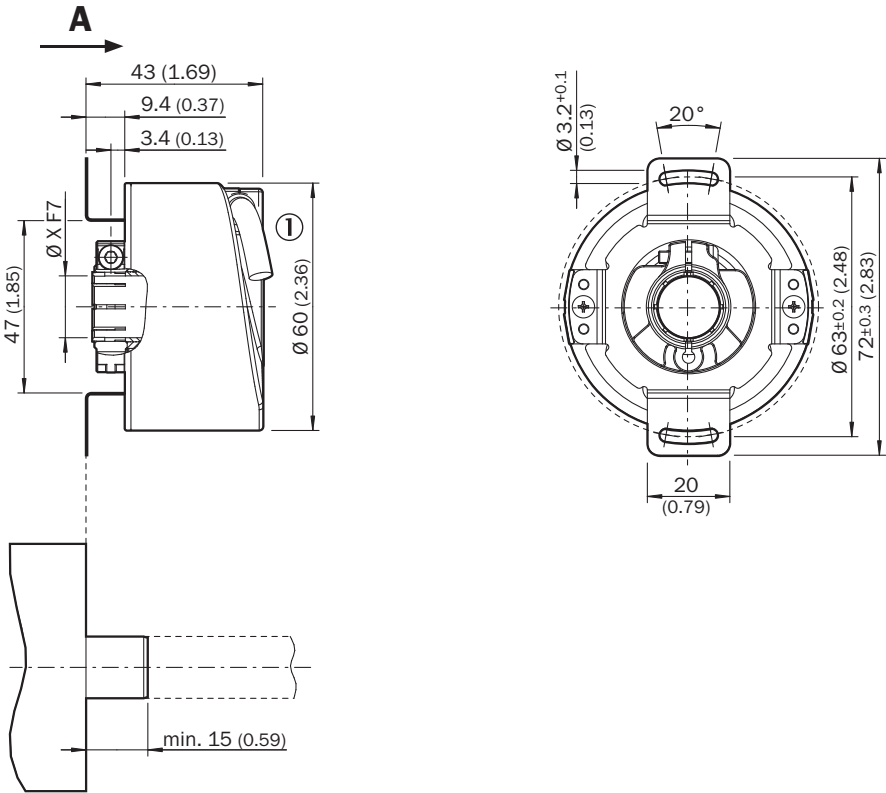
Certificates

EU declaration of conformity	✓
UK declaration of conformity	✓
ACMA declaration of conformity	✓
Moroccan declaration of conformity	✓
China-RoHS	✓
cULus certificate	✓
Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓

Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

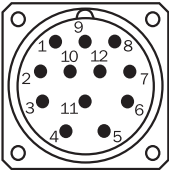
Dimensional drawing



Dimensions in mm (inch)
① cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

TypeThrough hollow shaft	Shaft diameter XF7	Shaft diameter xj7
DFS60x-TAxxxxxxx	6 mm	Provided by customer
DFS60x-TBxxxxxxx	8 mm	
DFS60x-TCxxxxxxx	3/8"	
DFS60x-TDxxxxxxx	10 mm	
DFS60x-TExxxxxxx	12 mm	
DFS60x-TFxxxxxxx	1/2"	
DFS60x-TGxxxxxxx	14 mm	
DFS60x-THxxxxxxx	15 mm	
DFS60x-TJxxxxxxx	5/8"	

PIN assignment



view of M23 male device connector on encoder

PINMale connector M12, 8-pin	PINMale connector M23, 12-pin	Wire colors (cable connection)	TTL/HTL signal	Sin/Cos 1.0 V _{pp}	Explanation
1	6	Brown	$\overline{A}$	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	$\overline{B}$	SIN-	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	$\overline{Z}$	$\overline{Z}$	Signal wire
6	3	Purple	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection
8	12	Red	+U _S	+U _S	Supply voltage
-	9	-	N.c.	N.c.	Not assigned
-	2	-	N.c.	N.c.	Not assigned
-	11	-	N.c.	N.c.	Not assigned
-	7 ¹⁾	Orange	0-SET ¹⁾	N.c.	Set zero pulse ¹⁾
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

¹⁾For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

maximum revolution range



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