

DFS60B-TDAA00S37

DFS60

INCREMENTAL ENCODERS

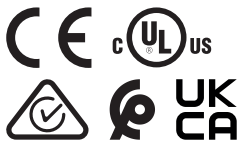
SICK
Sensor Intelligence.

Illustration may differ

Ordering information

Type	part no.
DFS60B-TDAA00S37	1070932

Other models and accessories → www.sick.com/DFS60



Detailed technical data

Features

Special device	✓
Specialty	Plug, M23, 12-pin, radial, customer-specific pin assignment
Standard reference device	DFS60B-TDAA05000, 1037960

Safety-related parameters

MTTF _D (mean time to dangerous failure)	300 years (EN ISO 13849-1) ¹⁾
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¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Pulses per revolution	5,000 ¹⁾
Measuring step	90°, electric/pulses per revolution
Measuring step deviation at non binary number of lines	± 0.01°
Error limits	± 0.05°

¹⁾ See maximum revolution range.

Interfaces

Communication interface	Incremental
Communication Interface detail	TTL / RS-422
Number of signal channels	6-channel
Initialization time	40 ms
Output frequency	≤ 600 kHz
Load current	≤ 30 mA
Operating current	40 mA (without load)

Electronics

Connection type	Male connector, M23, 12-pin, radial
Supply voltage	4.5 ... 5.5 V

¹⁾ Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

Reference signal, number	1
Reference signal, position	90 °, electric, logically gated with A and B
Short-circuit protection of the outputs	✓ ¹⁾

¹⁾ Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

Mechanics

Mechanical design	Through hollow shaft
Shaft diameter	10 mmFront clamp
Weight	+ 0.2 kg
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.8 Ncm (+20 °C)
Operating torque	0.6 Ncm (+20 °C)
Permissible movement static	± 0.3 mm (radial) ± 0.5 mm (axial)
Permissible movement dynamic	± 0.1 mm (radial) ± 0.2 mm (axial)
Operating speed	≤ 6,000 min ⁻¹ ¹⁾
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.6 x 10 ¹⁰ revolutions
Angular acceleration	≤ 500,000 rad/s ²

¹⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, Housing side, male connector (IEC 60529) ¹⁾ IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C ... +100 °C ²⁾ -30 °C ... +100 °C ³⁾
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	70 g, 6 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

¹⁾ With mating connector fitted.

²⁾ Stationary position of the cable.

³⁾ Flexible position of the cable.

Certificates

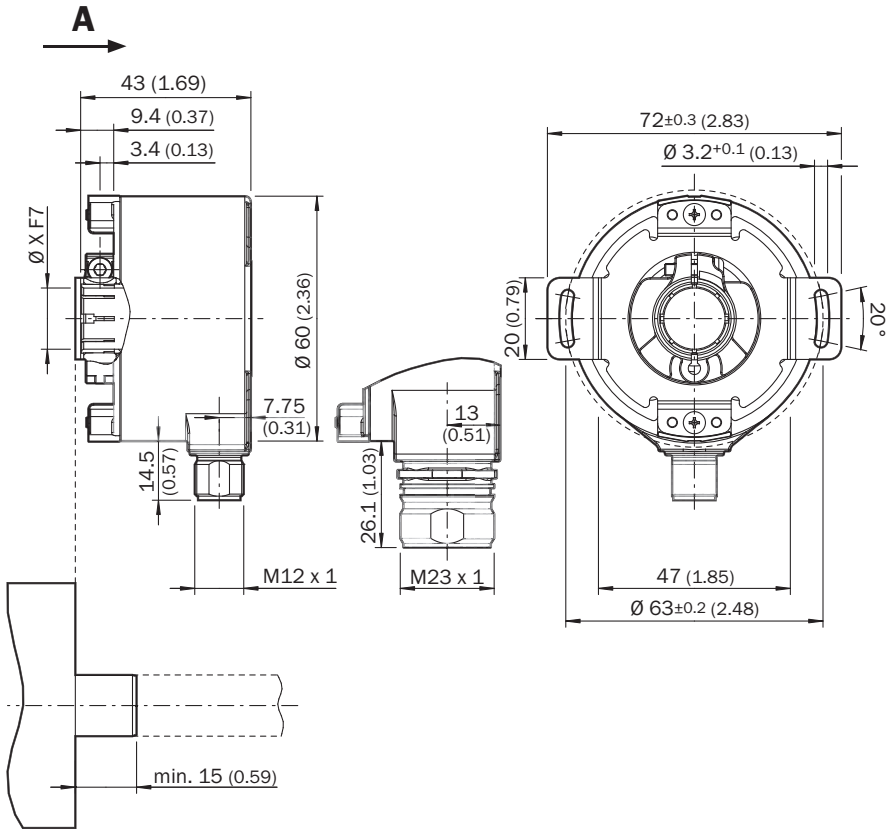
EU declaration of conformity	✓
UK declaration of conformity	✓
ACMA declaration of conformity	✓
Moroccan declaration of conformity	✓
China-RoHS	✓
cULus certificate	✓

Information according to Art. 3 of Data Act (Regulation EU 2023/2854)	✓
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Classifications

ECLASS 5.0	27270501
ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

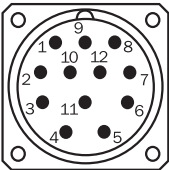
Dimensional drawing



Dimensions in mm (inch)
① cable diameter = 5.6 mm +/- 0.2 mm bend radius = 30 mm

TypeThrough hollow shaft	Shaft diameter XF7	Shaft diameter xj7
DFS60x-TAxxxxxxx	6 mm	Provided by customer
DFS60x-TBxxxxxxx	8 mm	
DFS60x-TCxxxxxxx	3/8"	
DFS60x-TDxxxxxxx	10 mm	
DFS60x-TExxxxxxx	12 mm	
DFS60x-TFxxxxxxx	1/2"	
DFS60x-TGxxxxxxx	14 mm	
DFS60x-THxxxxxxx	15 mm	
DFS60x-TJxxxxxxx	5/8"	

PIN assignment

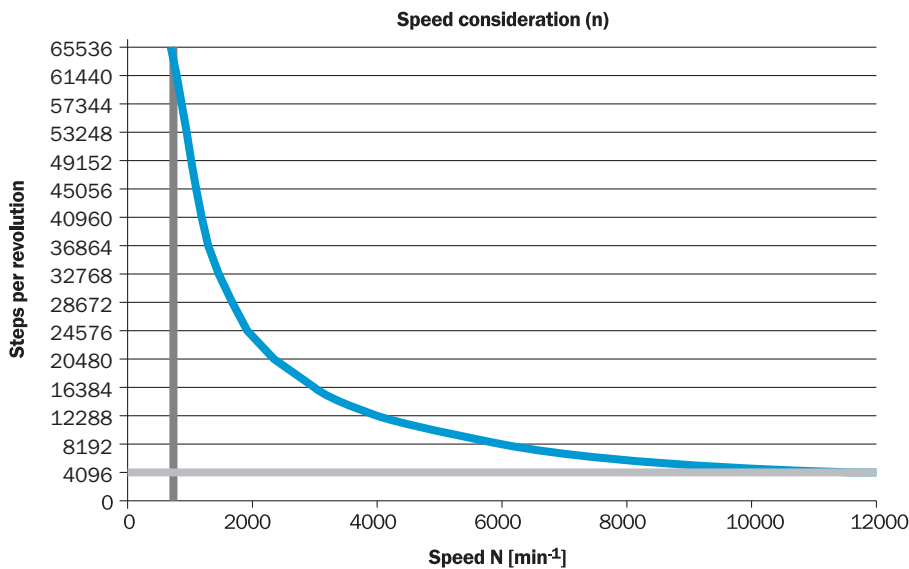


view of M23 male device connector on encoder

PIN Male connector M12, 8-pin	PIN Male connector M23, 12-pin	Wire colors (cable connection)	TTL/HTL signal	Sin/Cos 1.0 V _{pp}	Explanation
1	6	Brown	\overline{A}	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	\overline{B}	SIN-	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	\overline{Z}	\overline{Z}	Signal wire
6	3	Purple	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection
8	12	Red	+U _S	+U _S	Supply voltage
-	9	-	N.c.	N.c.	Not assigned
-	2	-	N.c.	N.c.	Not assigned
-	11	-	N.c.	N.c.	Not assigned
-	7 ¹⁾	Orange	0-SET ¹⁾	N.c.	Set zero pulse ¹⁾
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

¹⁾For electrical interfaces only: M, U, V, W with 0-SET function on PIN 7 on M23 plug. The 0-SET input is used to set the zero pulse to the current shaft position. If the 0-SET input is applied to U_S for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

maximum revolution range



SICK AT A GLANCE

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We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

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