

DFS60B-TENZ000S1

DFS60

INCREMENTAL ENCODERS

SICK
Sensor Intelligence.

Illustration may differ

Ordering information

Type	part no.
DFS60B-TENZ000S1	1127518

Other models and accessories → www.sick.com/DFS60

Detailed technical data

Features

Special device	✓
Specialty	No stator coupling (please order separately) No cable outlet (please order separately)
Standard reference device	DFS60B-TENK01024, 1073410

Safety-related parameters

MTTF_D (mean time to dangerous failure)	300 years (EN ISO 13849-1) ¹⁾
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¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40°C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Performance

Pulses per revolution	1,024
Measuring step	90°, electric/pulses per revolution
Measuring step deviation at non binary number of lines	± 0.008°
Error limits	± 0.05°

Interfaces

Communication interface	Incremental
Communication Interface detail	Sin/Cos ¹⁾
Number of signal channels	6-channel
Initialization time	40 ms
Output frequency	≤ 200 kHz
Operating current	≤ 40 mA (without load)
Load resistance	≤ 120 Ω

¹⁾ 1.0 V_{SS} (differential).

Electronics

Connection type	Special version
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¹⁾ Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

Connection type	Detail
Supply voltage	4.5 ... 5.5 V
Reference signal, number	1
Reference signal, position	90°, electronically, gated with Sinus and Cosinus
Short-circuit protection of the outputs	✓ ¹⁾

¹⁾ Short-circuit opposite to another channel, US or GND permissible for maximum 30 s.

Mechanics

Mechanical design	Through hollow shaft
Shaft diameter	12 mmFront clamp
Weight	+ 0.2 kg
Shaft material	Stainless steel
Flange material	Aluminum
Housing material	Aluminum die cast
Start up torque	0.8 Ncm (+20 °C)
Operating torque	0.6 Ncm (+20 °C)
Permissible movement dynamic	± 0.1 mm ± 0.2 mm
Operating speed	≤ 6,000 min ⁻¹ ¹⁾
Moment of inertia of the rotor	40 gcm ²
Bearing lifetime	3.6 x 10 ¹⁰ revolutions
Angular acceleration	≤ 500,000 rad/s ²

¹⁾ Allow for self-heating of 3.3 K per 1,000 rpm when designing the operating temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP65, shaft side (IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C ... +100 °C ¹⁾ -30 °C ... +100 °C ²⁾
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	70 g, 6 ms (EN 60068-2-27)
Resistance to vibration	30 g, 10 Hz ... 2,000 Hz (EN 60068-2-6)

¹⁾ Stationary position of the cable.

²⁾ Flexible position of the cable.

Certificates

EU declaration of conformity	✓
UK declaration of conformity	✓
ACMA declaration of conformity	✓
Moroccan declaration of conformity	✓
China-RoHS	✓
cULus certificate	✓

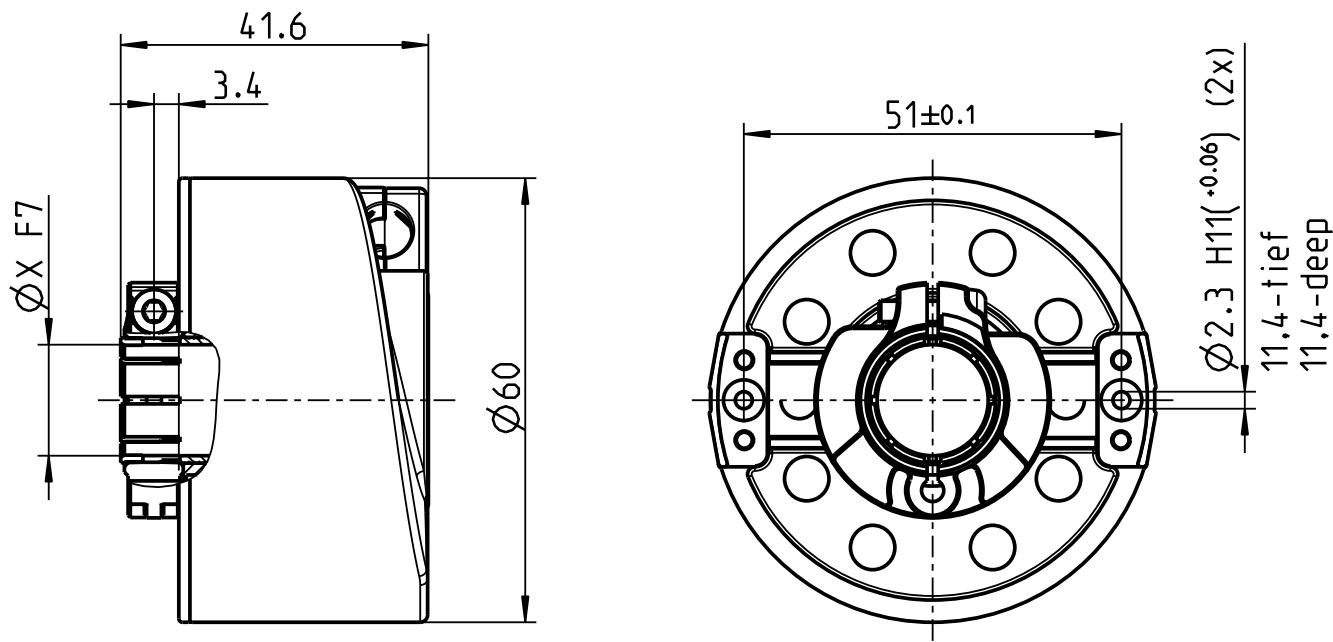
Information according to Art. 3 of Data Act
(Regulation EU 2023/2854)

✓

Classifications

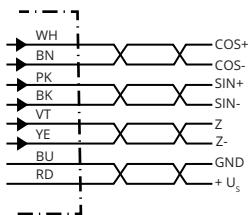
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ECLASS 5.1.4	27270501
ECLASS 6.0	27270590
ECLASS 6.2	27270590
ECLASS 7.0	27270501
ECLASS 8.0	27270501
ECLASS 8.1	27270501
ECLASS 9.0	27270501
ECLASS 10.0	27270501
ECLASS 11.0	27270501
ECLASS 12.0	27270501
ETIM 5.0	EC001486
ETIM 6.0	EC001486
ETIM 7.0	EC001486
ETIM 8.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing



Dimensions in mm (inch)

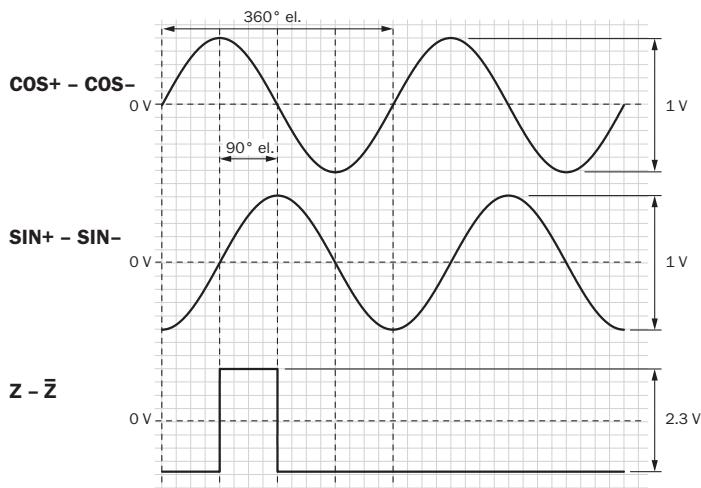
PIN assignment



PIN Male connector M12, 8-pin	PIN Male connector M23, 12-pin	Wire colors (cable connection)	TTL/HTL signal	Sin/Cos 1.0 V _{PP}	Explanation
1	6	Brown	\bar{A}	COS-	Signal wire
2	5	White	A	COS+	Signal wire
3	1	Black	\bar{B}	SIN-	Signal wire
4	8	Pink	B	SIN+	Signal wire
5	4	Yellow	\bar{Z}	\bar{Z}	Signal wire
6	3	Purple	Z	Z	Signal wire
7	10	Blue	GND	GND	Ground connection
8	12	Red	+Us	+Us	Supply voltage
-	9	-	N.c.	N.c.	Not assigned
-	2	-	N.c.	N.c.	Not assigned
-	11	-	N.c.	N.c.	Not assigned
-	7 ¹⁾	Orange	O-SET ¹⁾	N.c.	Set zero pulse ¹⁾
Screen	Screen	Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

¹⁾For electrical interfaces only: M, U, V, W with O-SET function on PIN 7 on M23 plug. The O-SET input is used to set the zero pulse to the current shaft position. If the O-SET input is applied to US for longer than 250 ms after it has previously been open or applied to GND for at least 1,000 ms, the current shaft position is assigned zero pulse signal "Z".

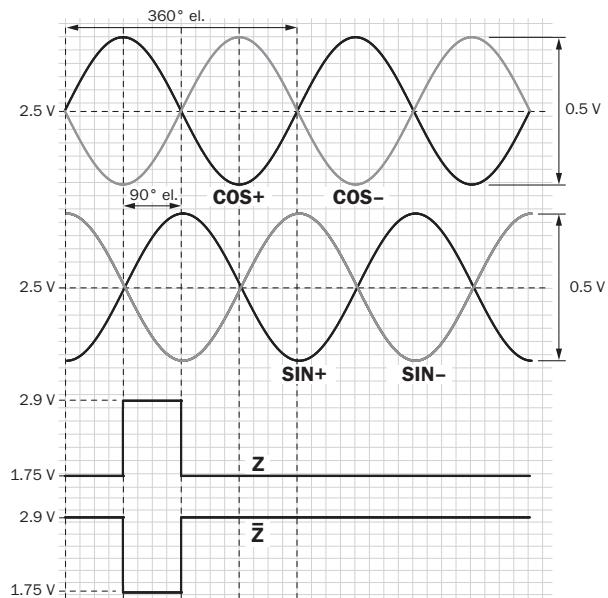
Diagrams Signal SIN/COS after differential generation



For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)

Supply voltage	Output
4,5 V ... 5,5 V	Sin/Cos 1.0 V _{PP}

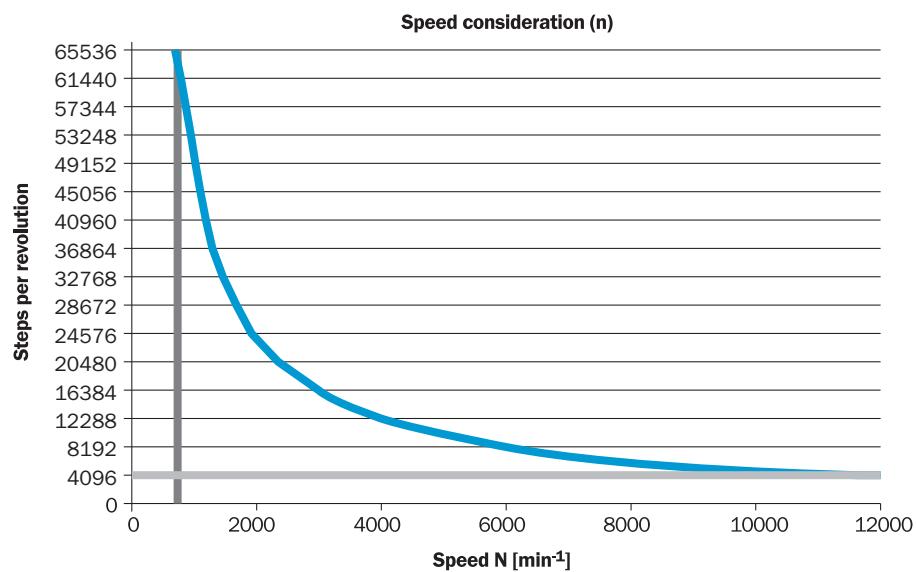
Diagrams Signal SIN/COS before differential generation



For clockwise shaft rotation, looking in direction "A" (see dimensional drawing)

Signal	Interface signals	Signal before differential generation At load 120 Ω	Signal offset
+ SIN- SIN+ COS- COS	Analog, differential	0,5 V _{SS} \pm 20 %	2,5 V \pm 10 %
ZZ_	Digital differential	Low: 1,75 V \pm 15 %, High: 2,90 V \pm 15 %	-

maximum revolution range



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